

Lectures 5 to 6
Tue. 2.2.16 to Thur 2.4.2016

Kinetic Derivation of 1D Potentials and Force Fields

(Ch. 5 of Unit 1)

Review of $(V_1, V_2) \rightarrow (y_1, y_2)$ relations High mass ratio $M_1/m_2 = 49$

Force “field” or “pressure” due to many small bounces

Force defined as momentum transfer rate

The 1D-Isothermal force field $F(y) = \text{const.}/y$ and the 1D-Adiabatic force field $F(y) = \text{const.}/y^3$

Potential field due to many small bounces

Example of 1D-Adiabatic potential $U(y) = \text{const.}/y^2$

Physicist's Definition $F = -\Delta U/\Delta y$ vs. Mathematician's Definition $F = +\Delta U/\Delta y$

Example of 1D-Isothermal potential $U(y) = \text{const.} \ln(y)$

“Monster Mash” classical analog of Heisenberg action relations

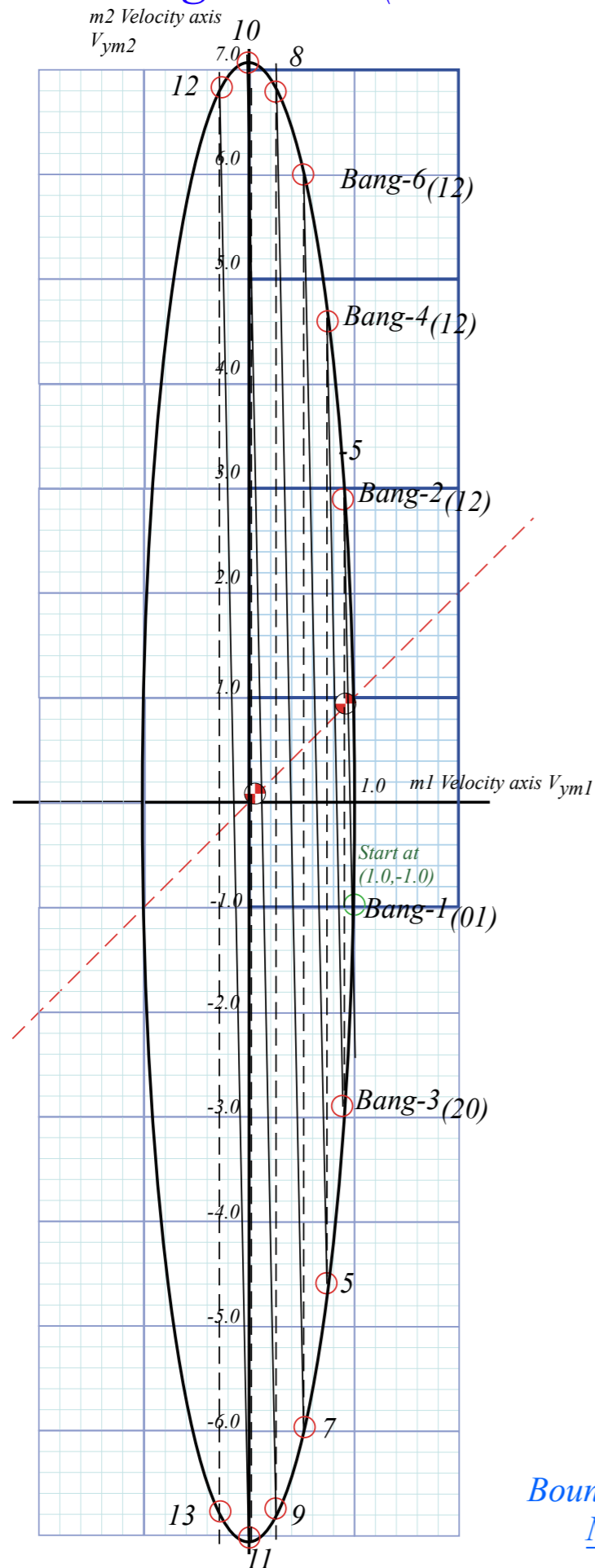
Example of very very large M_1 ball-wall(s) crushing a poor little m_2

How does m_2 conserve action ($\Delta x \Delta p$ or $\int p \cdot dx$) as its KE changes?

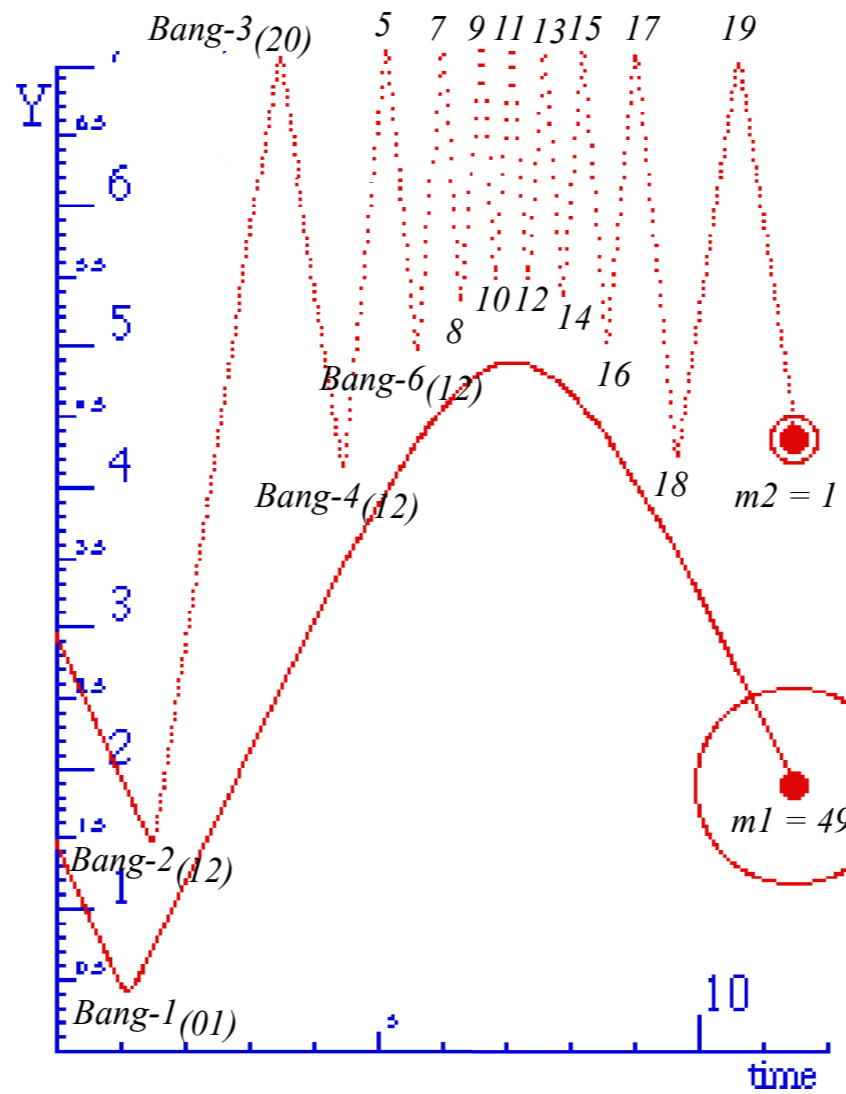
Review of $(V_1, V_2) \rightarrow (y_1, y_2)$ relations

 *High mass ratio $M_1/m_2 = 49$*

Geometric "Integration" (Converting Velocity data to Space-time trajectory)



Example with masses: $m_1=49$ and $m_2=1$



Kinetic Energy Ellipse

$$KE = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = \frac{49}{2} + \frac{1}{2} = 25$$

$$1 = \frac{v_1^2}{2KE/m_1} + \frac{v_2^2}{2KE/m_2} = \frac{x_1^2}{a_1^2} + \frac{x_2^2}{a_2^2}$$

Ellipse radius 1

$$\begin{aligned} a_1 &= \sqrt{2KE/m_1} \\ &= \sqrt{2KE/49} \\ &= \sqrt{50/49} \\ &= 1.01 \end{aligned}$$

Ellipse radius 2

$$\begin{aligned} a_2 &= \sqrt{2KE/m_2} \\ &= \sqrt{2KE/1} \\ &= \sqrt{50/1} \\ &= 7.07 \end{aligned}$$

BounceIt Superball Collision Web Simulator:
 $M_1=49, M_2=1$ with Newtonian time plot

Fig. 4.1
Unit 1

BounceIt Superball Collision Web Simulator:
 $M_1=49, M_2=1$ with V_2 vs V_1 plot

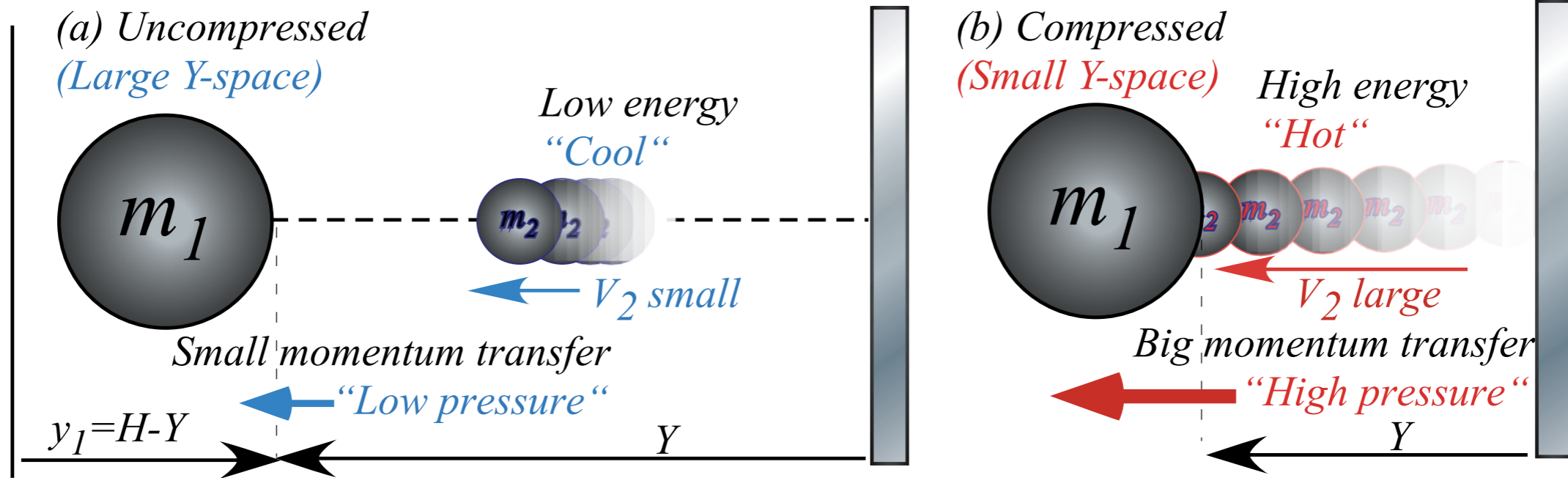
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 *Force defined as momentum transfer rate*

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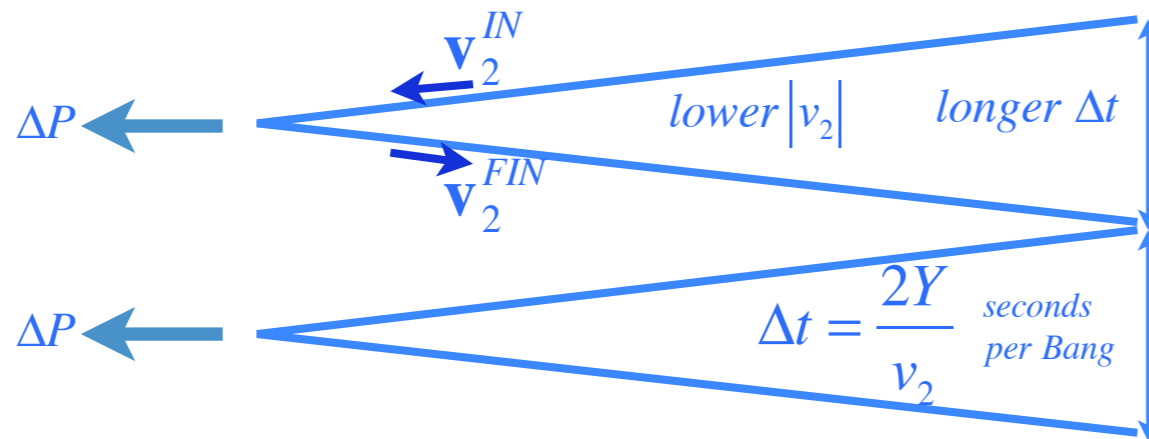
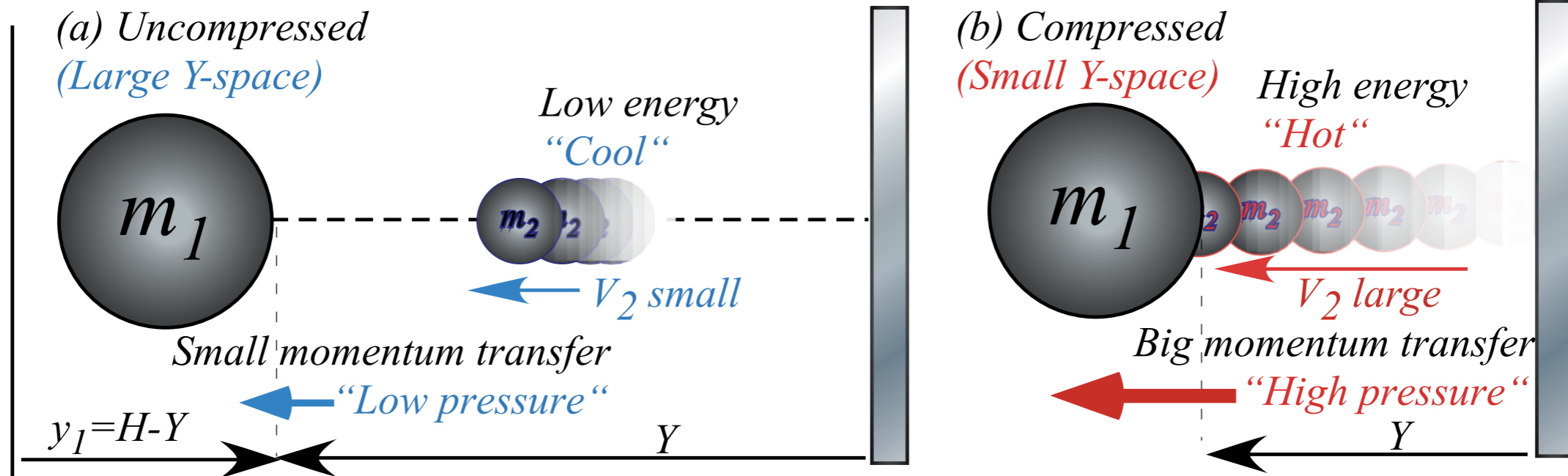
Big mass- m_1 ball feeling “force-field” or “pressure” of small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

Fig. 5.1
Unit 1



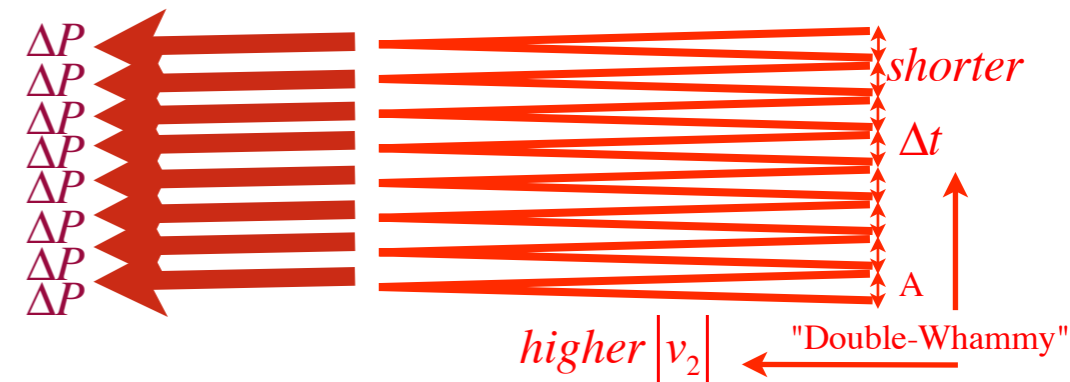
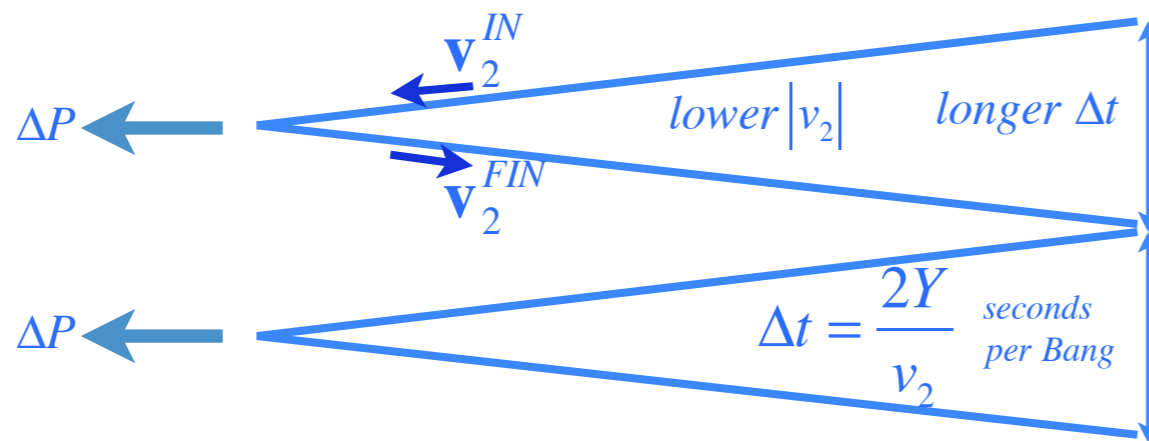
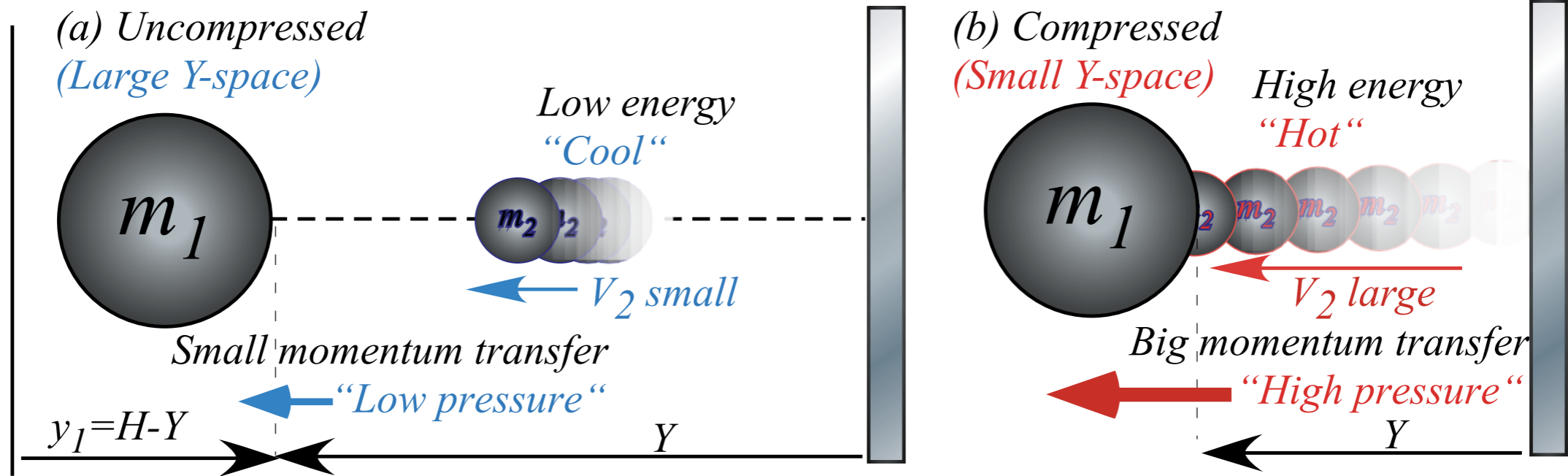
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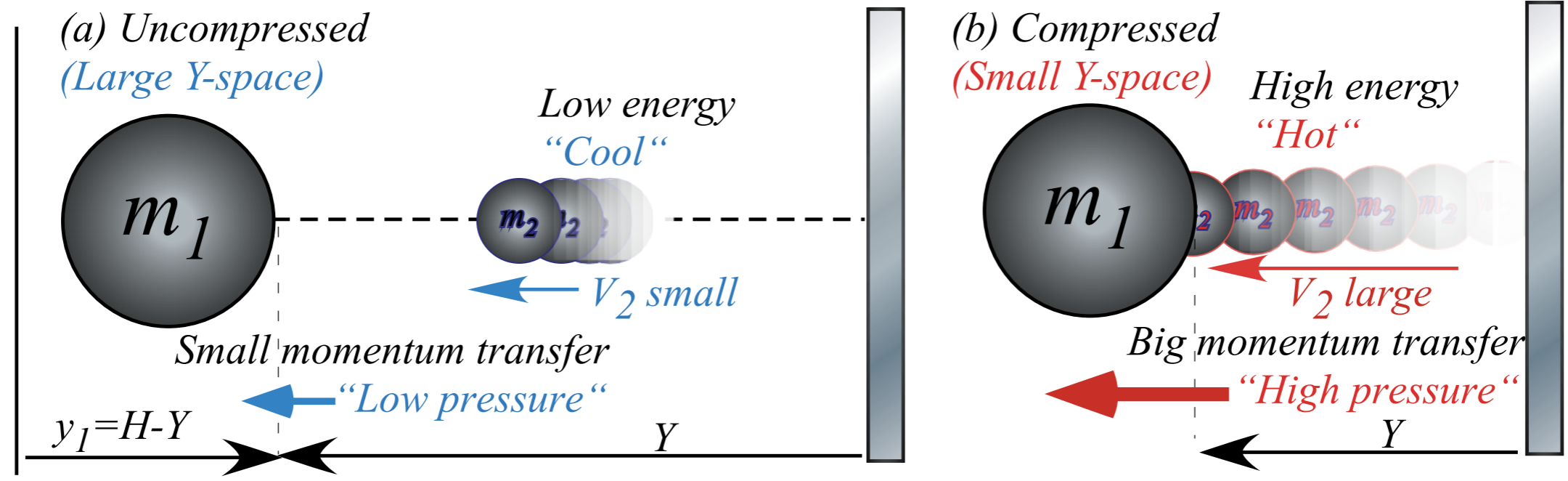
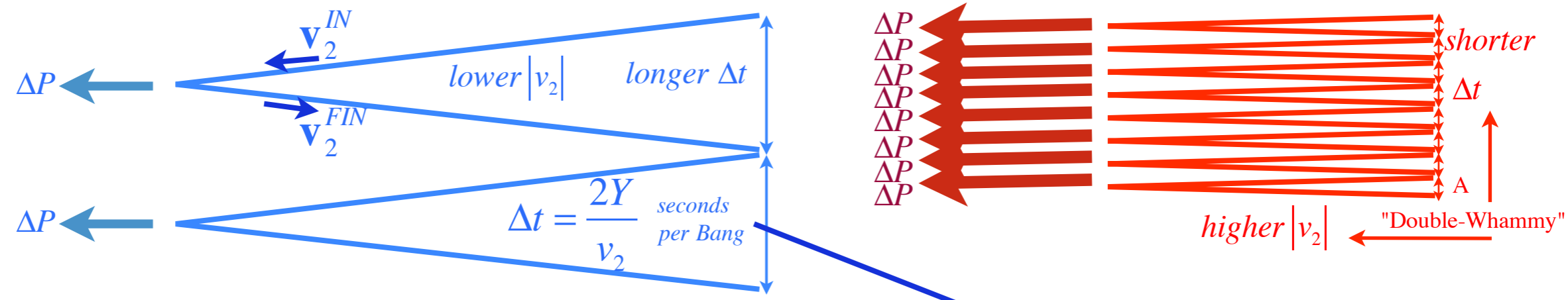


Fig. 5.1
Unit 1



This introduction of Force...

$$F = \frac{\Delta P}{\Delta t}$$

$$\Delta P = m_2 v_2^{IN} - m_2 v_2^{FIN}$$

$$\frac{1}{\Delta t} = \frac{v_2}{2Y}$$

Force F on $m_1 = (\text{Momentum per sec.}) = (\text{Momentum per Bang}) \cdot (\text{Bangs per second})$

...is more of a definition than another axiom

Double-Bang Sequences
for $m_1 \gg m_2$

(a) After 2 Bangs

(b) After 4 Bangs

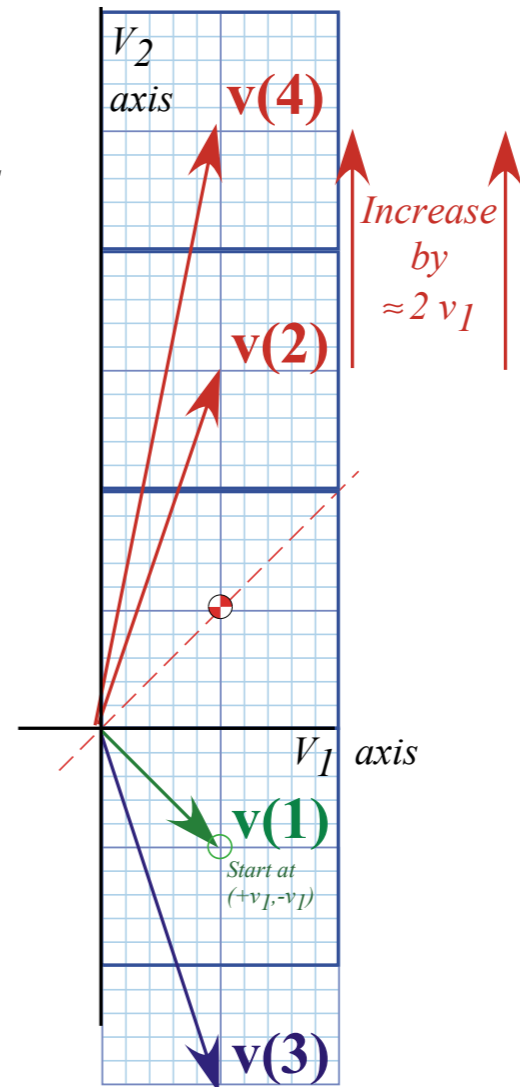
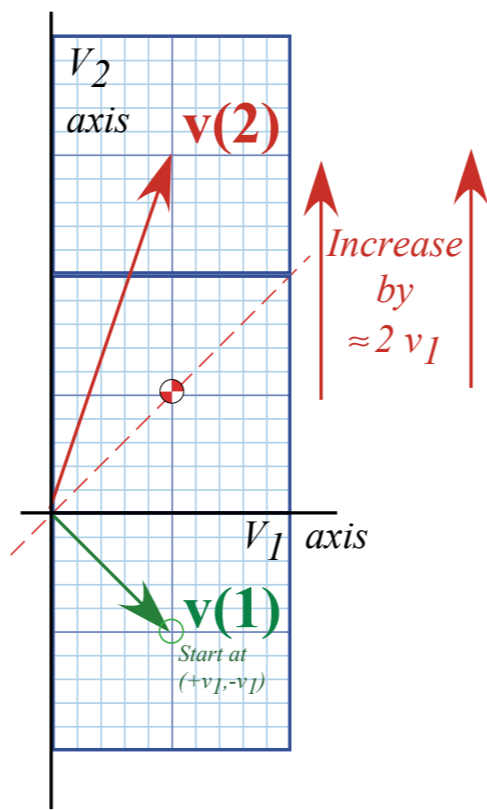
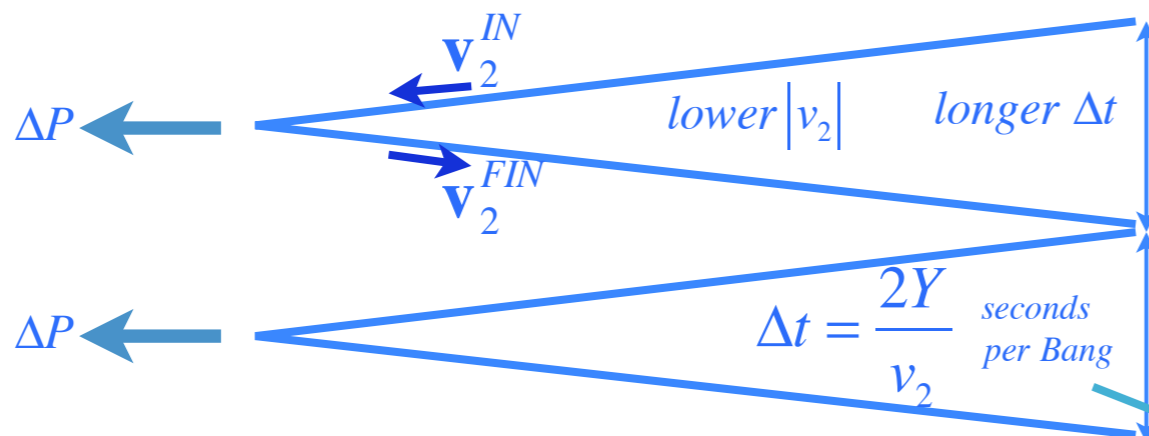
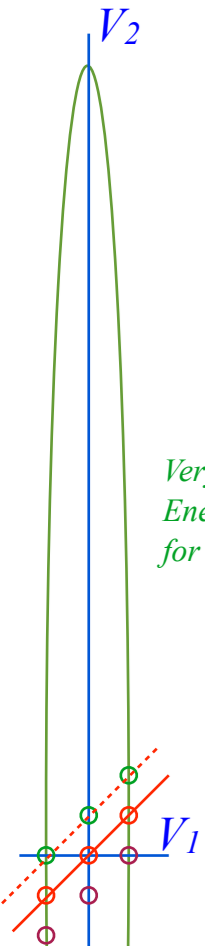


Fig. 5.2
Unit 1

Very skinny
Energy ellipse
for $m_1 \gg m_2$



$$|v_2^{FIN}| = |v_2^{IN}| + |2v_1| \quad \text{for: } m_1 \gg m_2$$

$$v_2^{FIN} = -v_2^{IN} - 2v_1$$

$$F = \frac{\Delta P}{\Delta t}$$

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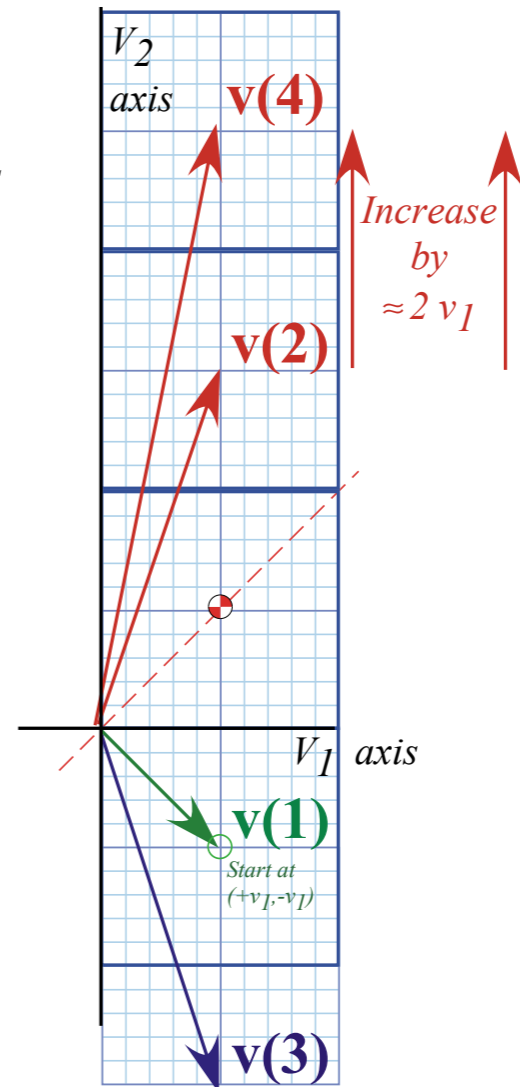
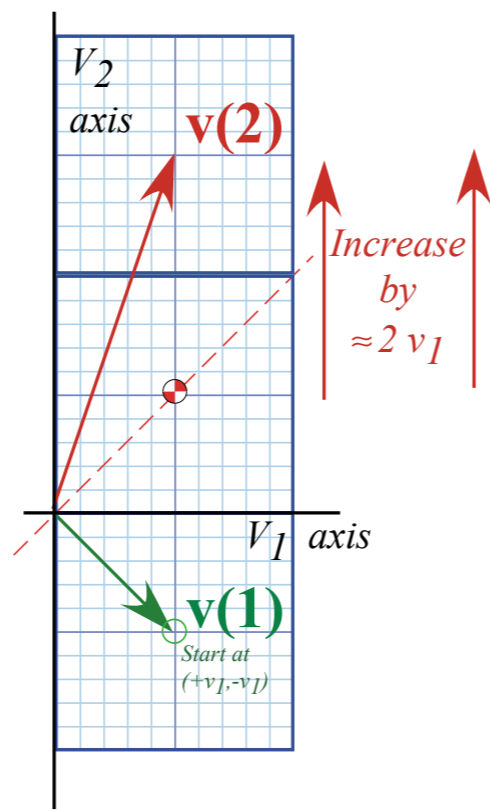
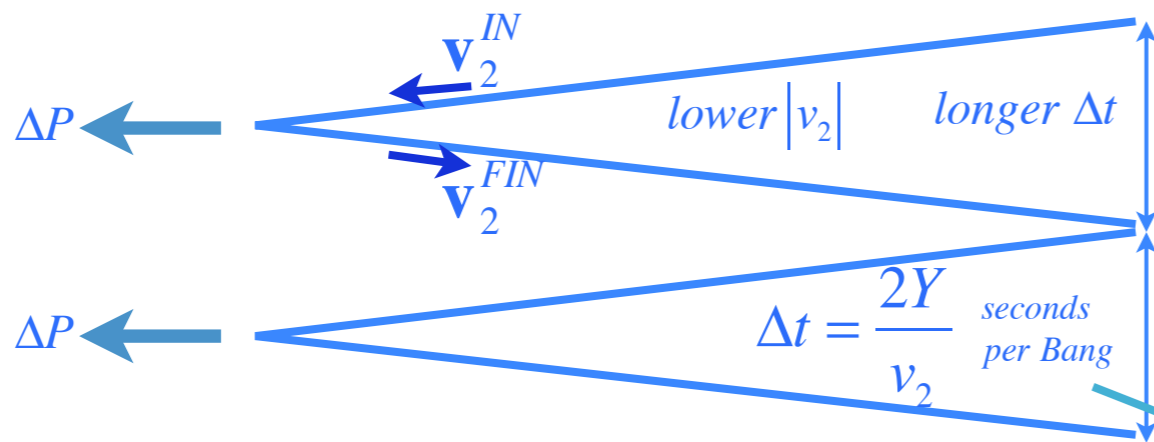
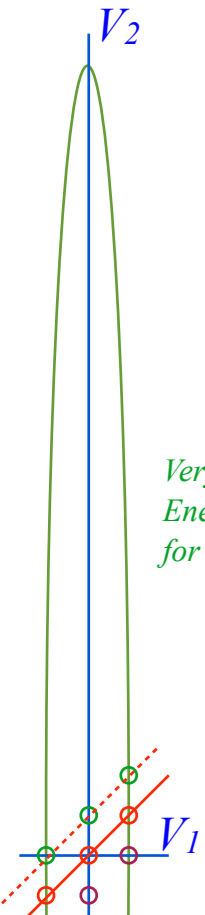


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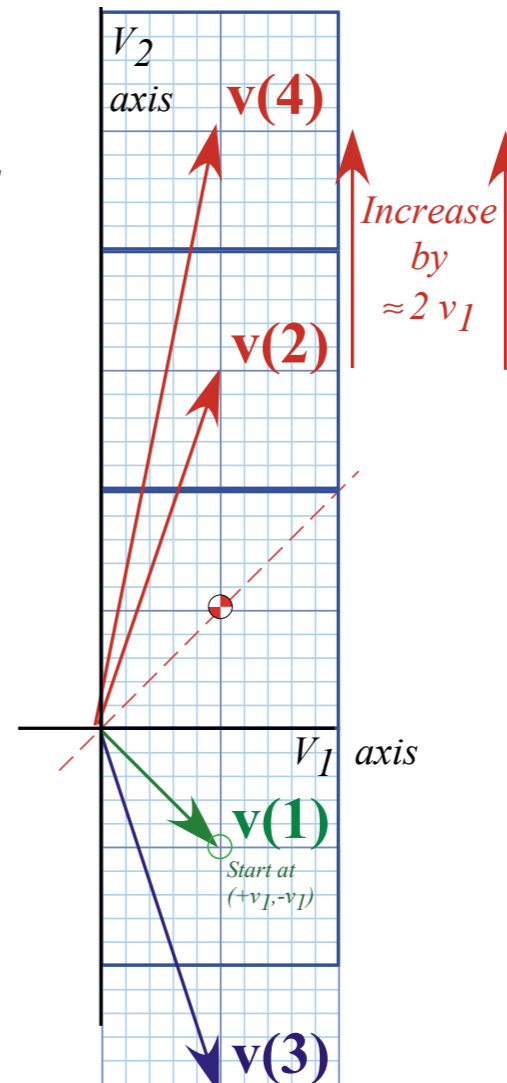
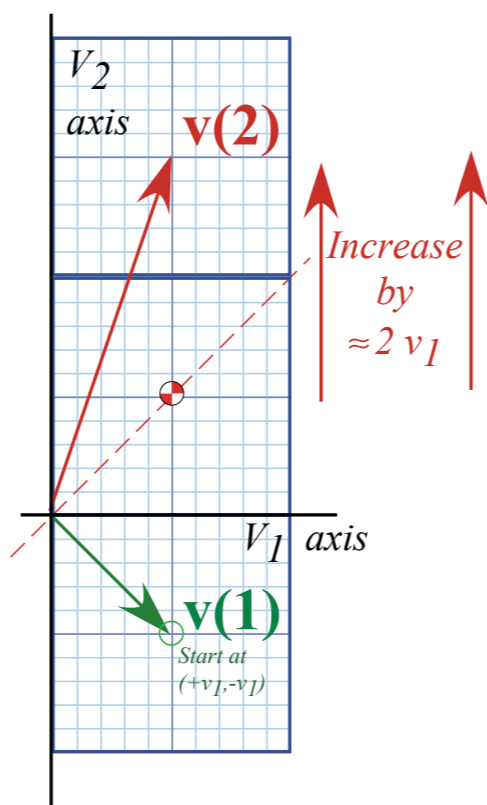
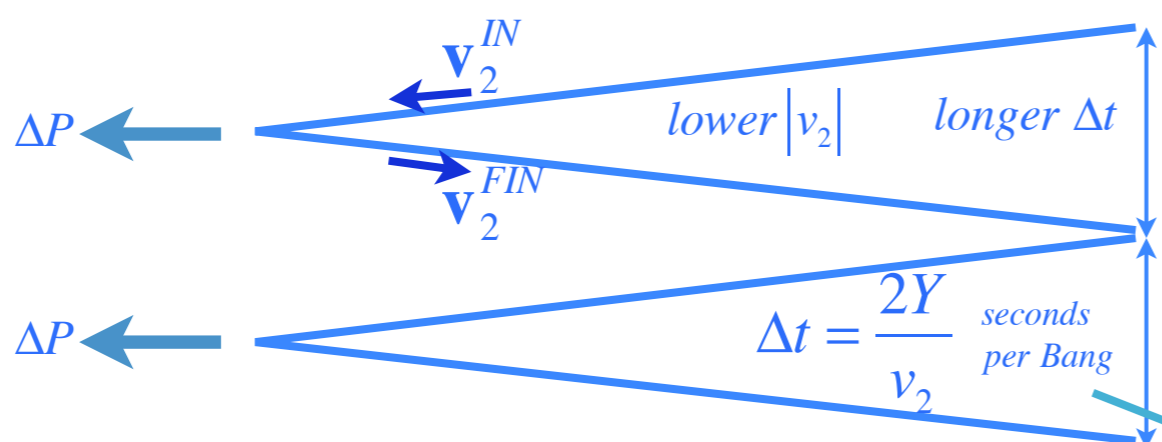
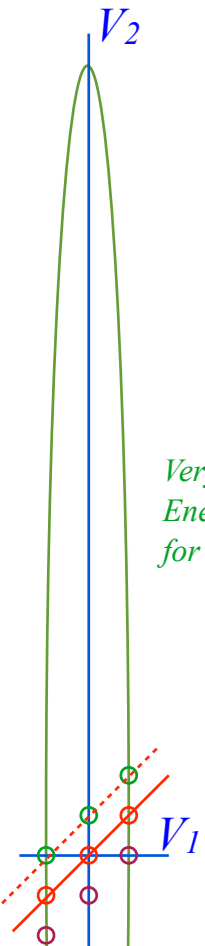


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Assuming slow $m_1 : v_1 \ll v_2$

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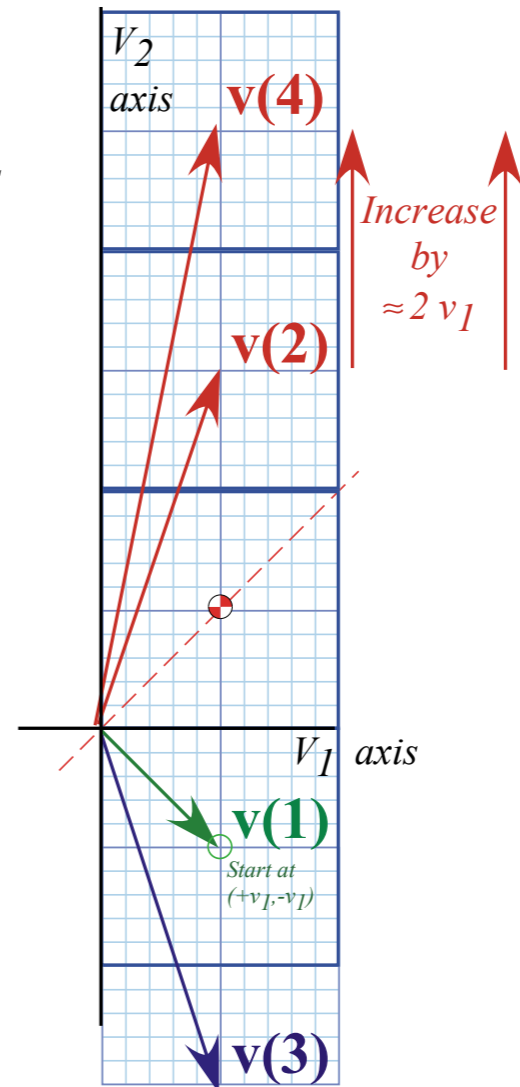
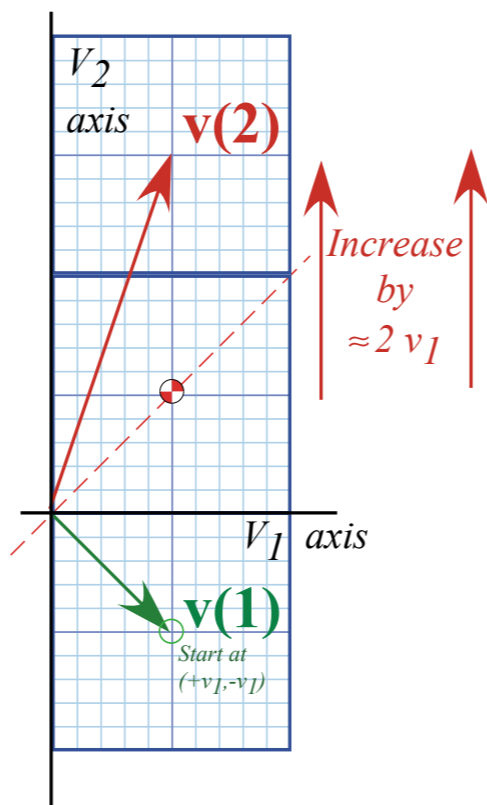
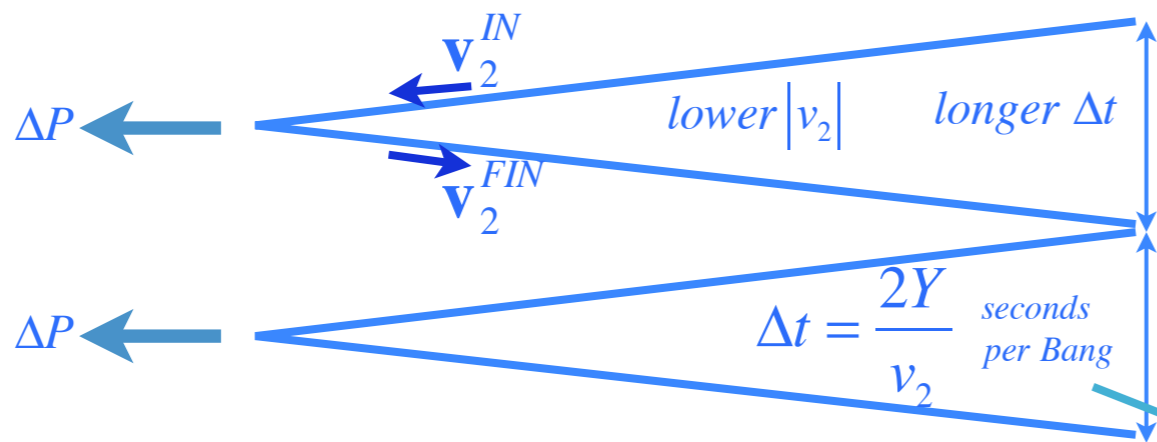
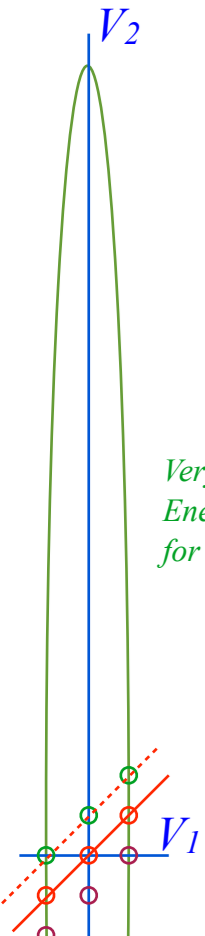


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$$F = \frac{\Delta P}{\Delta t} = (\Delta P \approx 2m_2 v_2) \cdot \left(\frac{1}{\Delta t} \approx \frac{v_2}{2Y} \right) \approx \frac{m_2 v_2^2}{Y}$$

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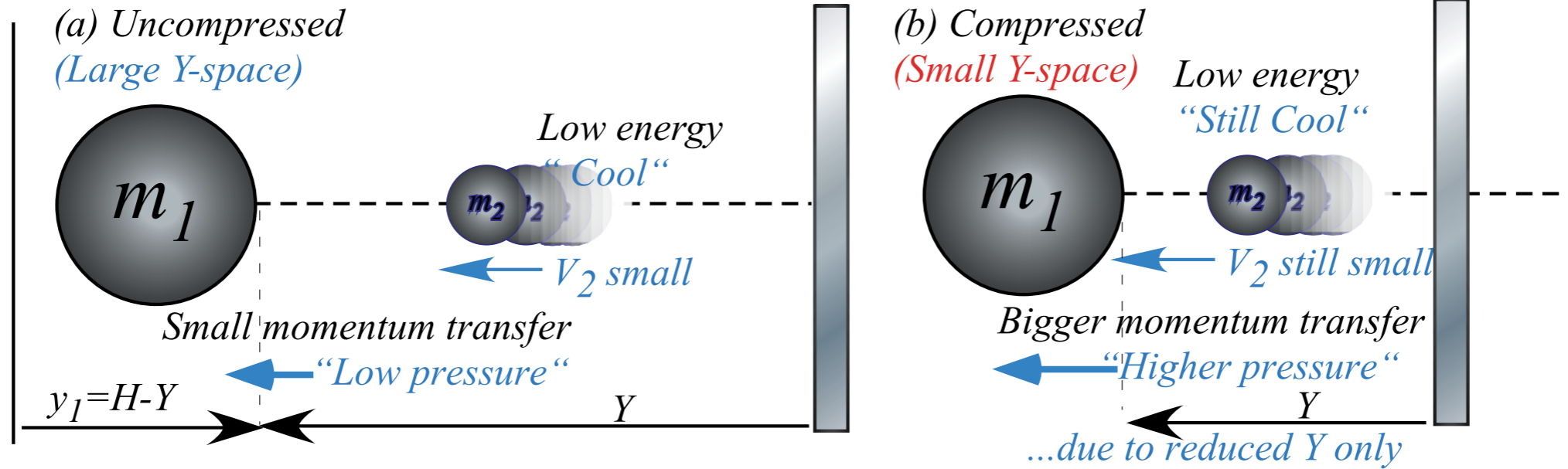
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Not a
"Double-Whammy" ...
...only a
"Single-Whammy"

1D-Isothermal Force Law (assume v_2 is constant for all Y):

$$F = \frac{m_2v_2^2}{Y} = \frac{\text{const.}}{Y}$$

Isothermal expansion or contraction: Wall serves as thermal bath to keep m_2 cool



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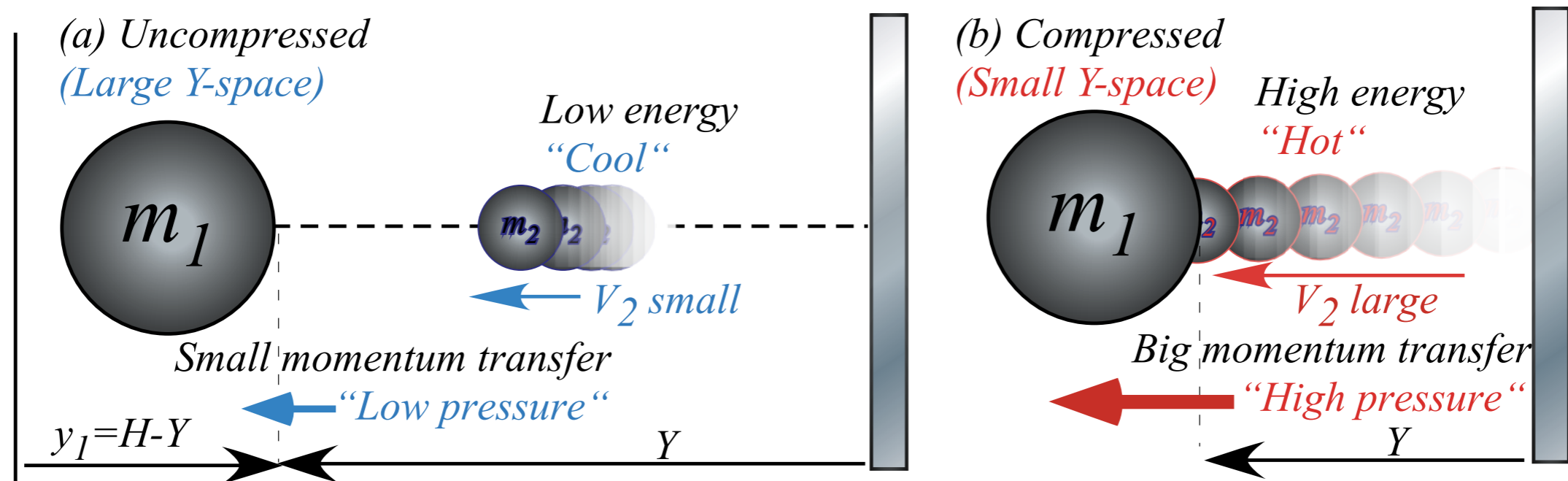
$$F = \frac{m_2v_2^2}{Y} = \frac{\text{const.}}{Y}$$

However, if ceiling is elastic, v_2 isn't constant if m_1 changes bounce range Y : $\frac{dy_1}{dt} \equiv v_1 = -\frac{dY}{dt}$

When m_1 collides with m_2 it adds twice its velocity ($2v_1$) to v_2 . This occurs at "bang-rate" $B=v_2/2Y$.

$$\frac{dv_2}{dt} = 2v_1B = 2v_1 \frac{v_2}{2Y} = -2 \frac{dY}{dt} \frac{v_2}{2Y}$$

Wall not given time to give or take KE



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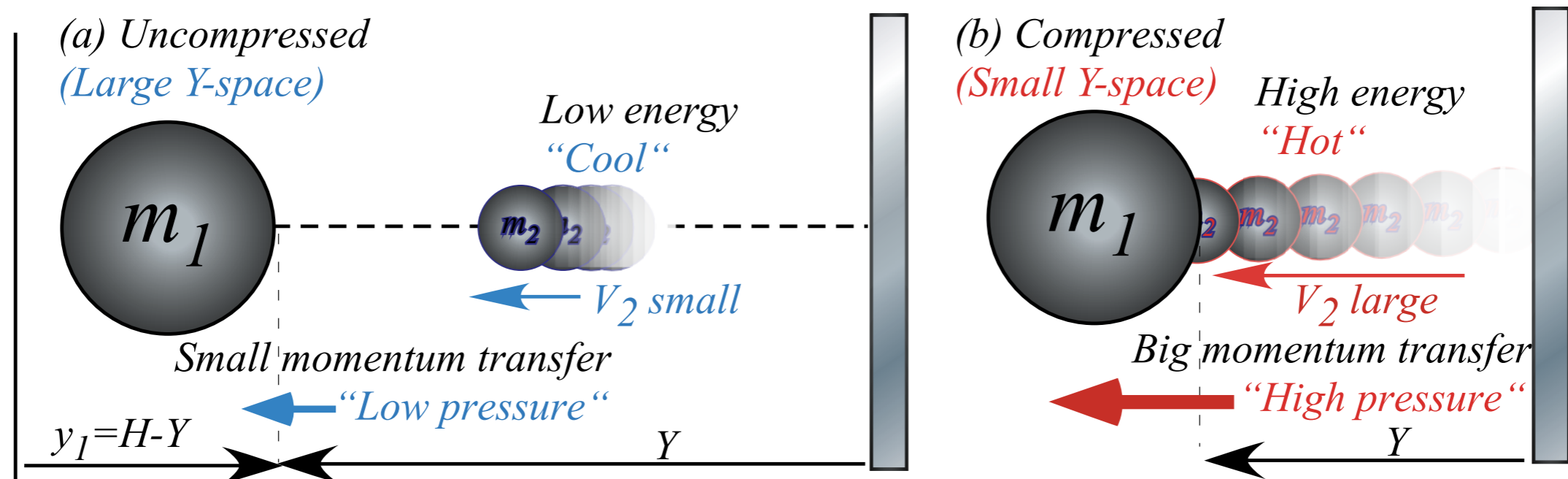
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$$\frac{dv_2}{dt} = 2v_1B = 2v_1 \frac{v_2}{2Y} = -\cancel{2} \frac{dY}{dt} \frac{v_2}{\cancel{2}Y} \quad \text{simplifies to:} \quad \frac{dv_2}{v_2} = -\frac{dY}{Y}$$

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$$F = \frac{\Delta P}{\Delta t} = (\Delta P \approx 2m_2v_2) \cdot \left(\frac{1}{\Delta t} \approx \frac{v_2}{2Y} \right) \approx \frac{m_2v_2^2}{Y}$$

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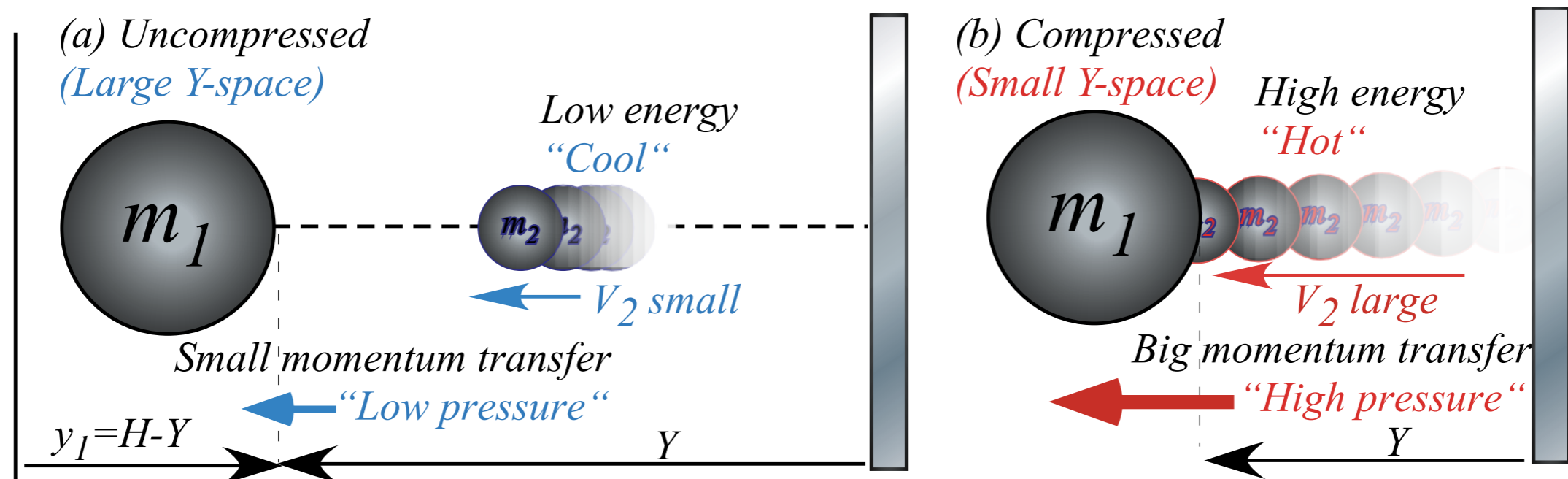
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Differential equation results and has logarithmic integral. $\int \frac{dx}{x} = \ln x + C = \log_e x + \log_e e^C = \log_e (e^C x)$

$$\frac{dv_2}{v_2} = -\frac{dY}{Y} \quad \text{integrates to:} \quad \ln v_2 = -\ln Y + C \quad \text{or:} \quad \ln v_2 = \ln \frac{\text{const.}}{Y} \quad \text{or:} \quad v_2 = \frac{\text{const.}}{Y}$$

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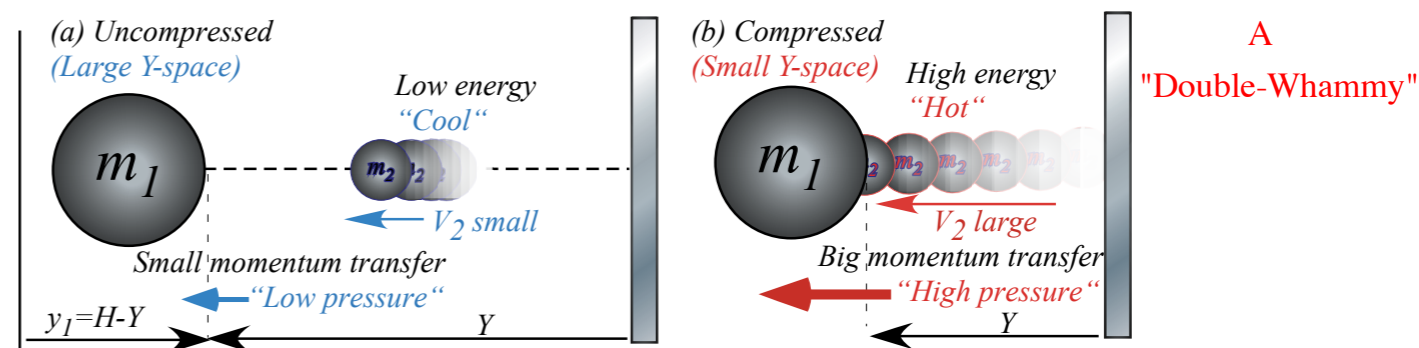
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Force law with this variable v_2 is called *adiabatic* or *not-diabatic* or *not-gradual*.

1D-Adiabatic Force Law (assume v_2 varies: $v_2 = \frac{const.}{Y} = \frac{v_2^{IN} Y(t=0)}{Y}$): $F = \frac{m_2 (v_2^{IN} Y(t=0))^2}{Y^3} = \frac{const.}{Y^3}$



$$F = \frac{\Delta P}{\Delta t} = (\Delta P \approx 2m_2v_2) \cdot \left(\frac{1}{\Delta t} \approx \frac{v_2}{2Y} \right) \approx \frac{m_2v_2^2}{Y}$$

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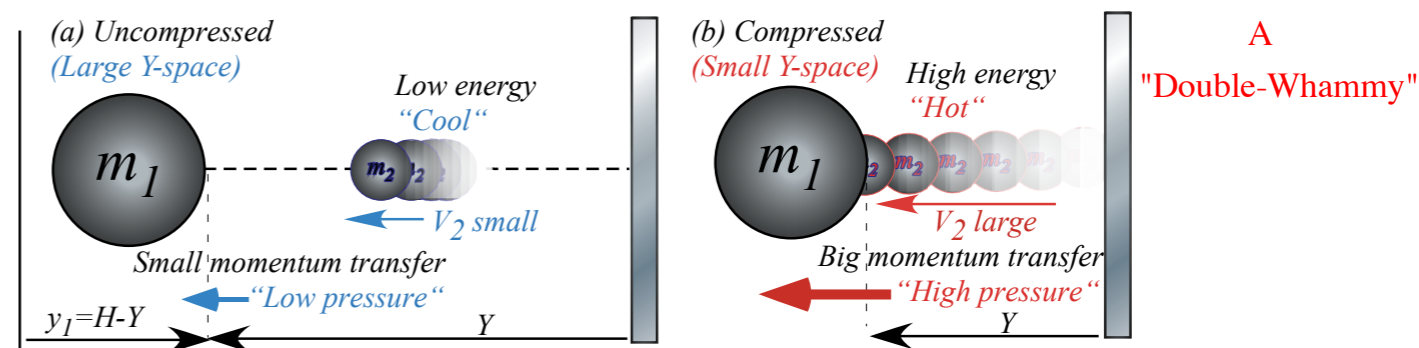
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$$F = \frac{m_2 (\bar{v}_2^{IN} Y_0)^2}{Y^3} = \frac{const.}{Y^3}$$

1D-Adiabatic Force Law



Potential field due to many small bounces



Example of 1D-Adiabatic potential $U(y)=\text{const.}/y^2$

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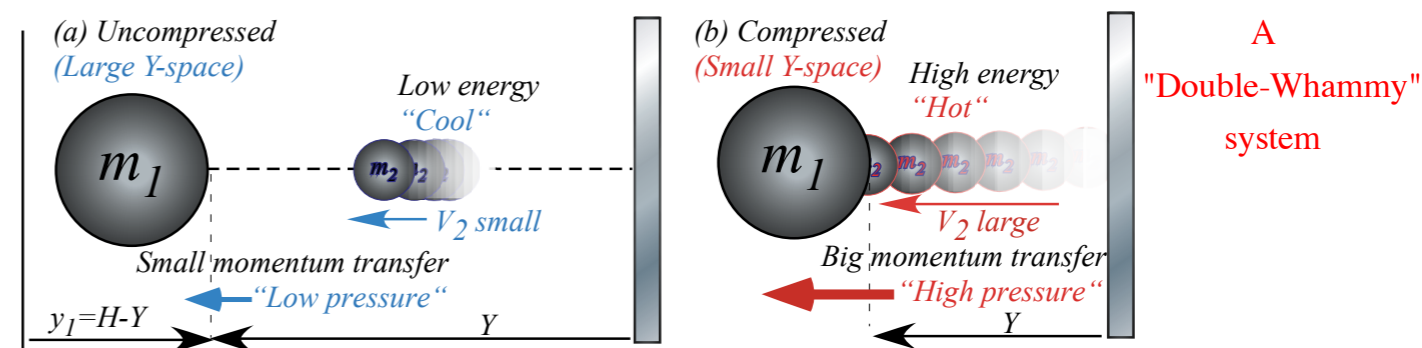
Big mass- m_1 ball feeling “potential-field” or “gradient” due to small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

In adiabatic case where $v_2 = \frac{\text{const.}}{Y}$ the total energy E is strictly conserved.

$$\text{const.} = E = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 \left(\frac{\text{const.}}{Y} \right)^2$$

Define for big mass m_1 : Kinetic energy $KE(v_1)$ vs Potential energy $PE(Y) = U(Y)$

$$\text{Potential energy } PE(Y) = U(Y) = \frac{1}{2} m_2 \left(\frac{\text{const.}}{Y} \right)^2$$



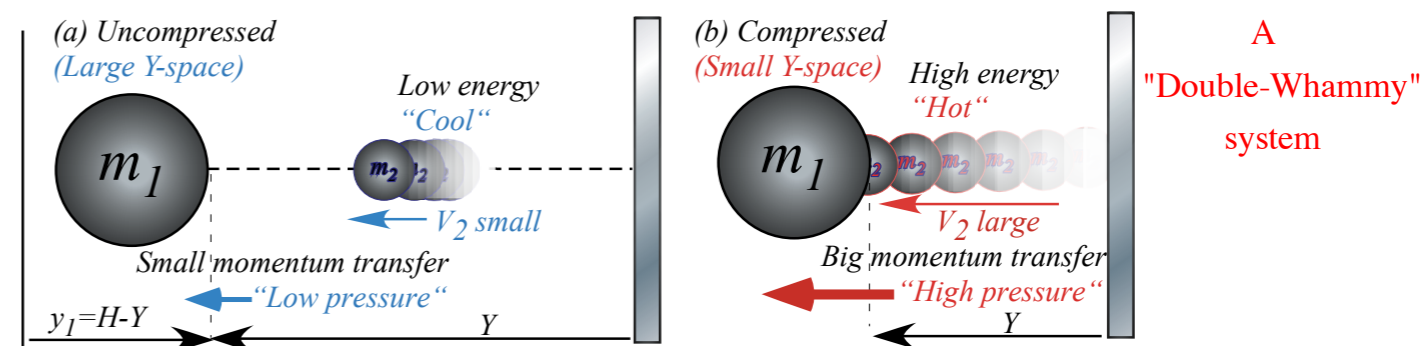
Big mass- m_1 ball feeling “potential-field” or “gradient” due to small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

In adiabatic case where $v_2 = \frac{\text{const.}}{Y}$ the total energy E is strictly conserved.

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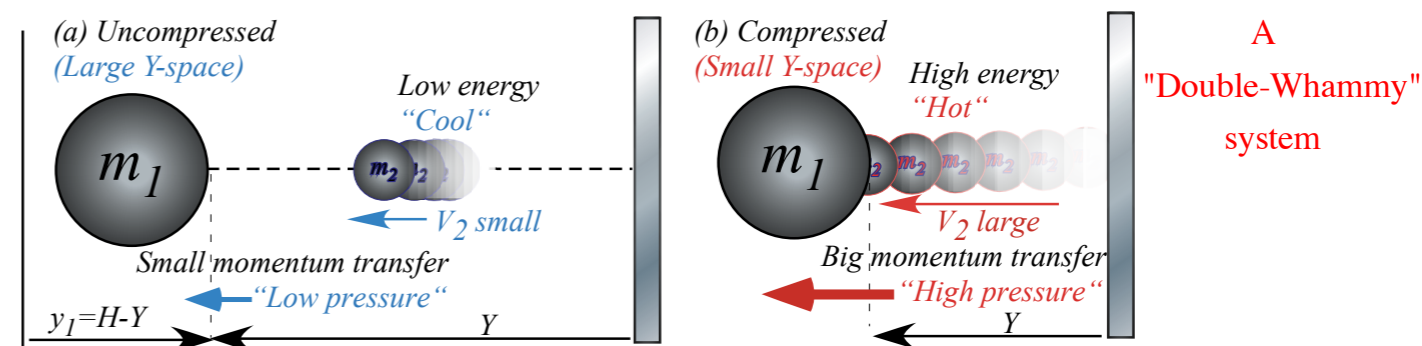
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Q? Another axiom?



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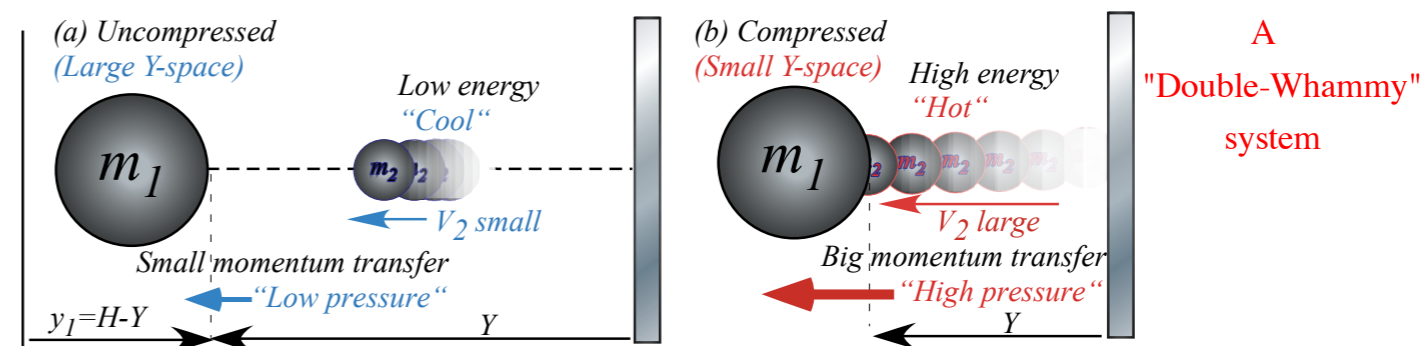
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Q? Another axiom? A: No.



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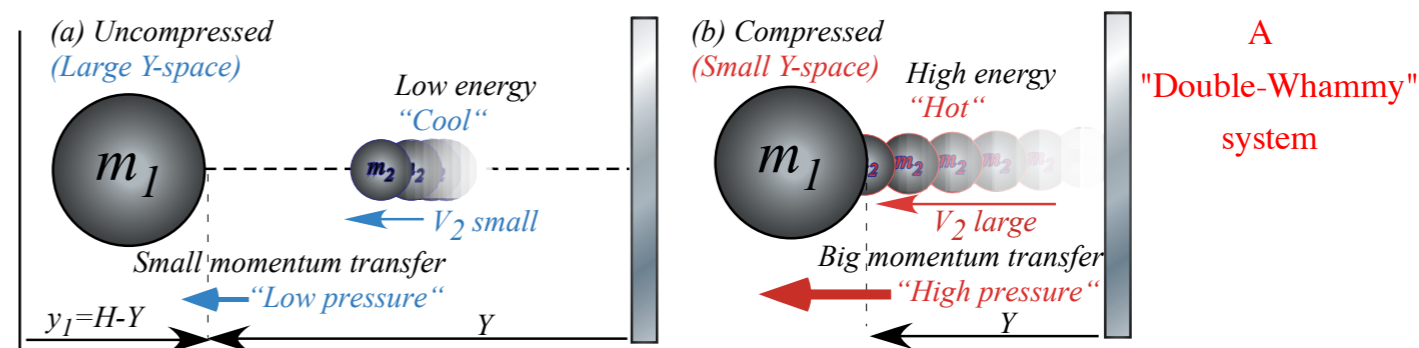
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Q? Another axiom? A: No. $\int F \cdot dY = \int \frac{dp}{dt} \cdot dY = \int \frac{dY}{dt} \cdot dp = \int V \cdot dp = \int V \cdot d(mV) = m \frac{V^2}{2} + \text{const} = U$

(Here: $V = v_2$)



Big mass- m_1 ball feeling “potential-field” or “gradient” due to small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

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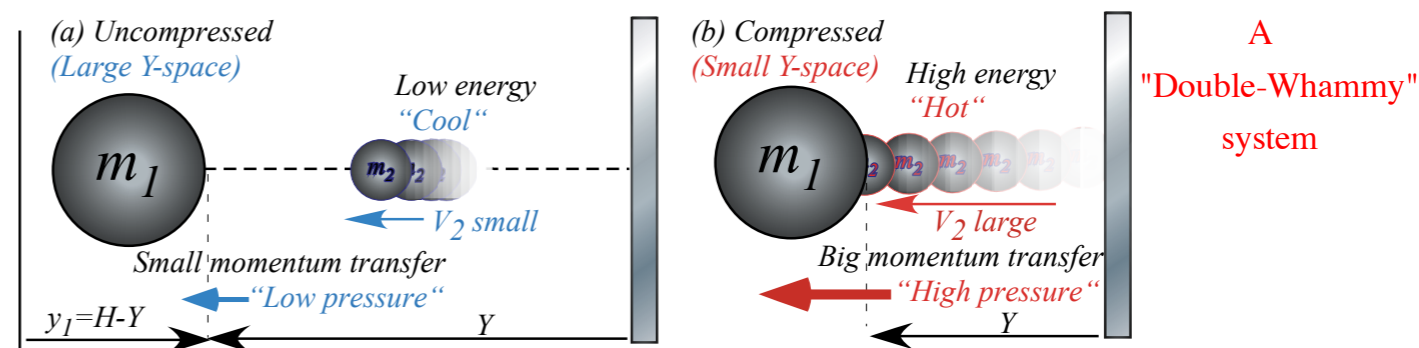
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or else : $F \cdot \frac{dY}{dt} = \frac{dp}{dt} \cdot V = \frac{d(mV)}{dt} \cdot V = \frac{d(mV^2)/2}{dt} = \frac{dU}{dt}$ (Here: $V = v_2$)



Potential field due to many small bounces

Example of 1D-Adiabatic potential $U(y)=\text{const.}/y^2$

 *Physicist's Definition $F=-\Delta U/\Delta y$ vs. Mathematician's Definition $F=+\Delta U/\Delta y$*

Example of 1D-Isothermal potential $U(y)=\text{const.} \ln(y)$

Big mass- m_1 ball feeling “potential-field” or “gradient” due to small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

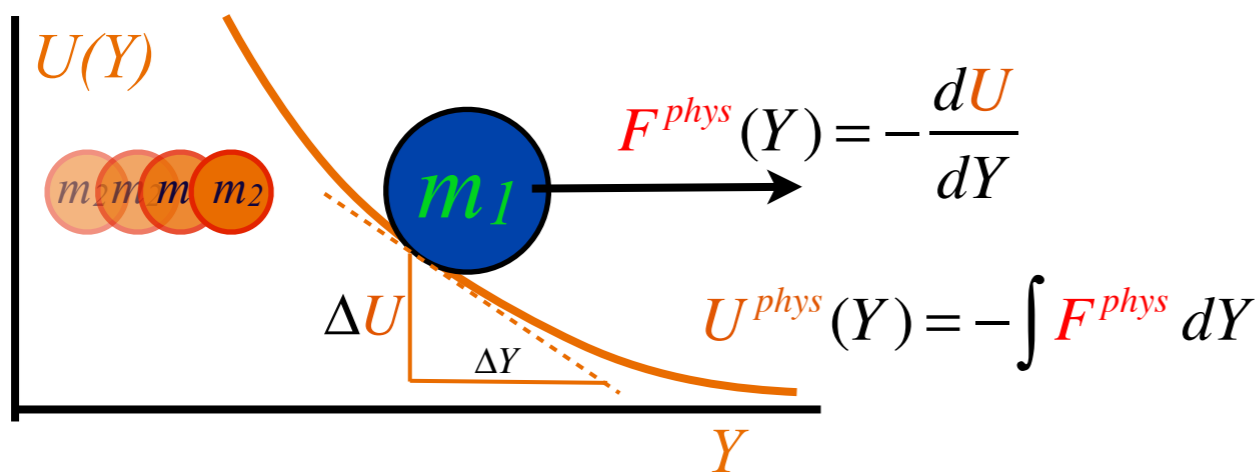
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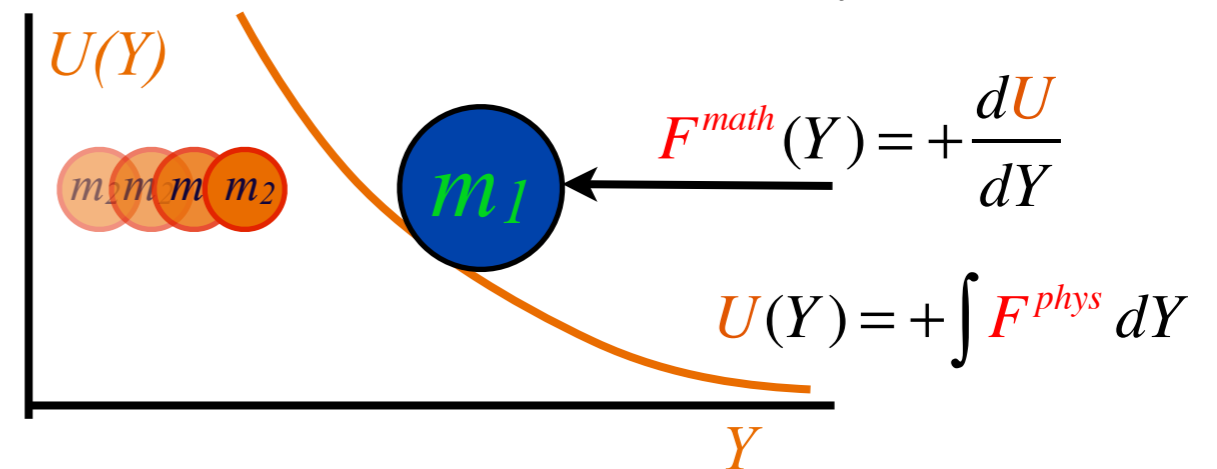
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The “Physicist” View of Force



The “Mathematician” View of Force



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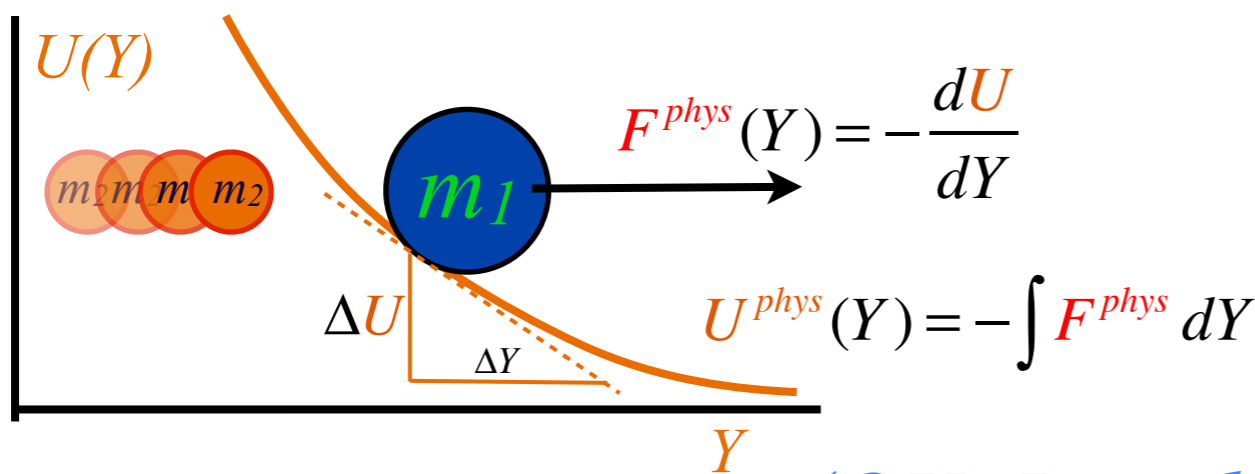
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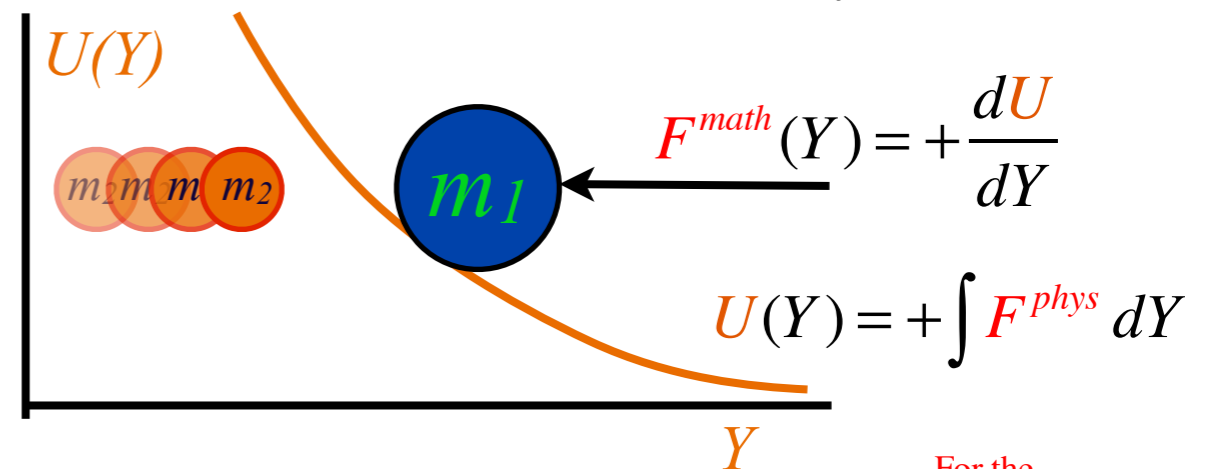
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The “Physicist” View of Force



The “Mathematician” View of Force



(OK, But, does it work?)

For the "Double-Whammy" system

Big mass- m_1 ball feeling “potential-field” or “gradient” due to small ($m_2 \ll m_1$) rapidly ($v_2 \gg v_1$) bouncing ball

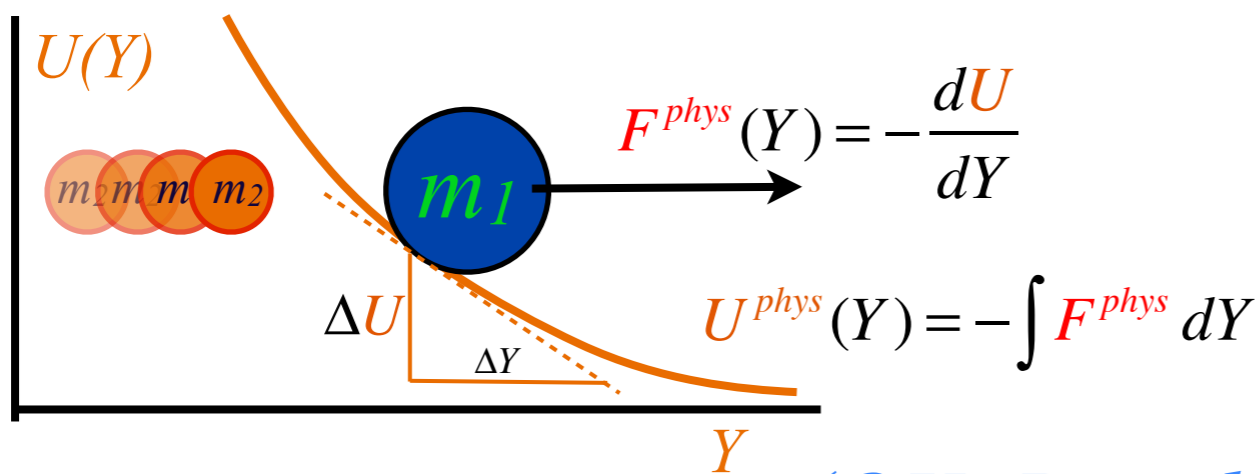
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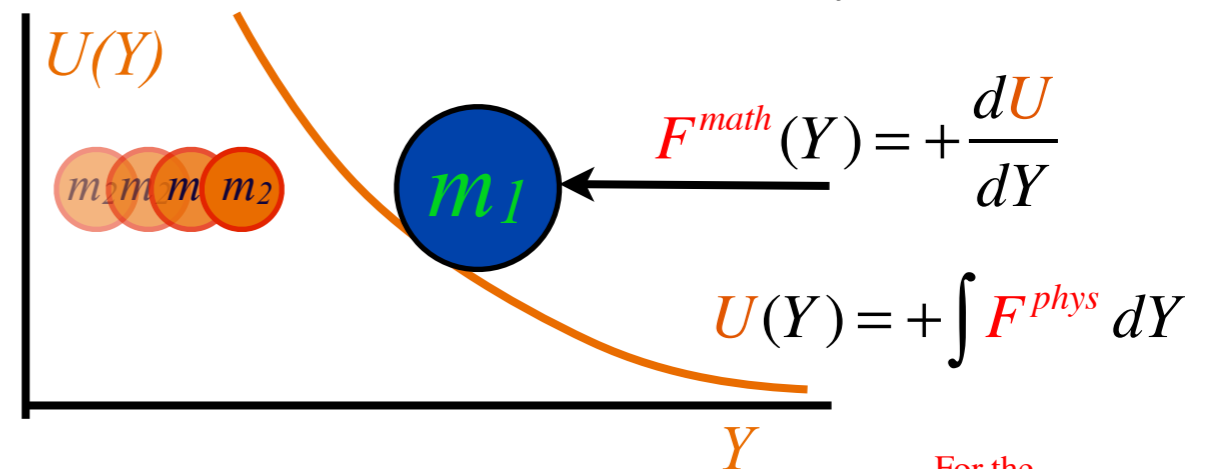
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The “Physicist” View of Force



The “Mathematician” View of Force



(OK, But, does it work?)

$$F^{phys} = m_2 \frac{(\text{const.})^2}{Y^3}$$

consistent
with :

$$F^{phys} = -\frac{\Delta U}{\Delta Y} = -\frac{d}{dY} \frac{1}{2} m_2 \left(\frac{\text{const.}}{Y} \right)^2 = m_2 \frac{(\text{const.})^2}{Y^3}$$

For the
"Double-Whammy"
system

(Hurrah!)

Potential field due to many small bounces

Example of 1D-Adiabatic potential $U(y)=\text{const.}/y^2$

Physicist's Definition $F=-\Delta U/\Delta y$ vs. Mathematician's Definition $F=+\Delta U/\Delta y$

 *Example of 1D-Isothermal potential $U(y)=\text{const.} \ln(y)$*

1D-Isothermal Force Law (assume v_2 is constant for all Y):

$$F = \frac{m_2 v_2^2}{Y} = \frac{\text{const.}}{Y}$$

Not a "Double-Whammy"...
...only a "Single-Whammy"

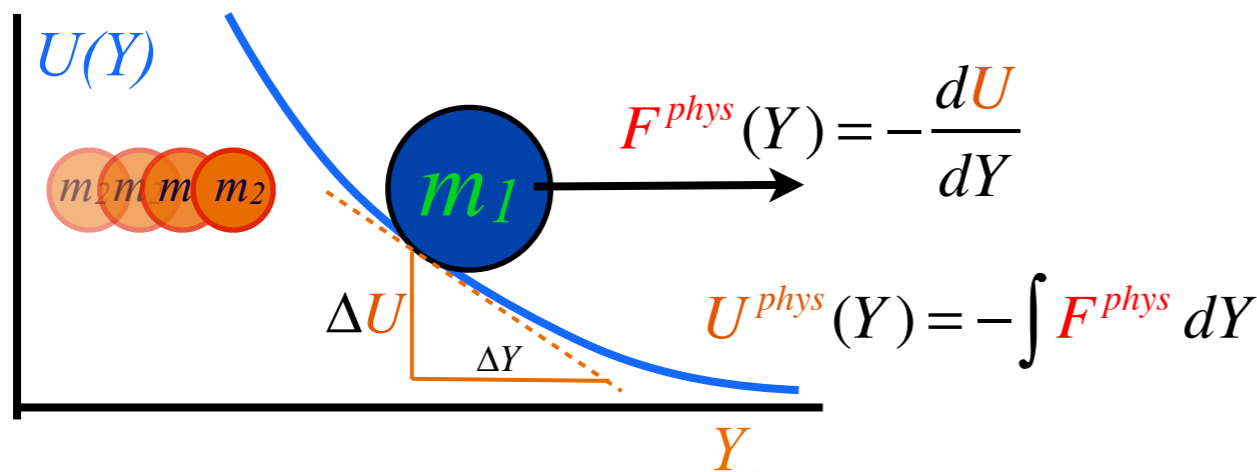
$$F^{phys} = \frac{m_2 v_2^2}{Y} = -\frac{\Delta U}{\Delta Y} \quad \text{implies:} \quad U(Y) = \int -F^{phys} dY = \int -\frac{m_2 v_2^2}{Y} dY = -m_2 v_2^2 \ln(Y)$$

$$\text{const.} = E = \frac{1}{2} m_1 v_1^2 + U(Y) \quad \text{where: } U(Y) = -m_2 v_2^2 \ln(Y)$$

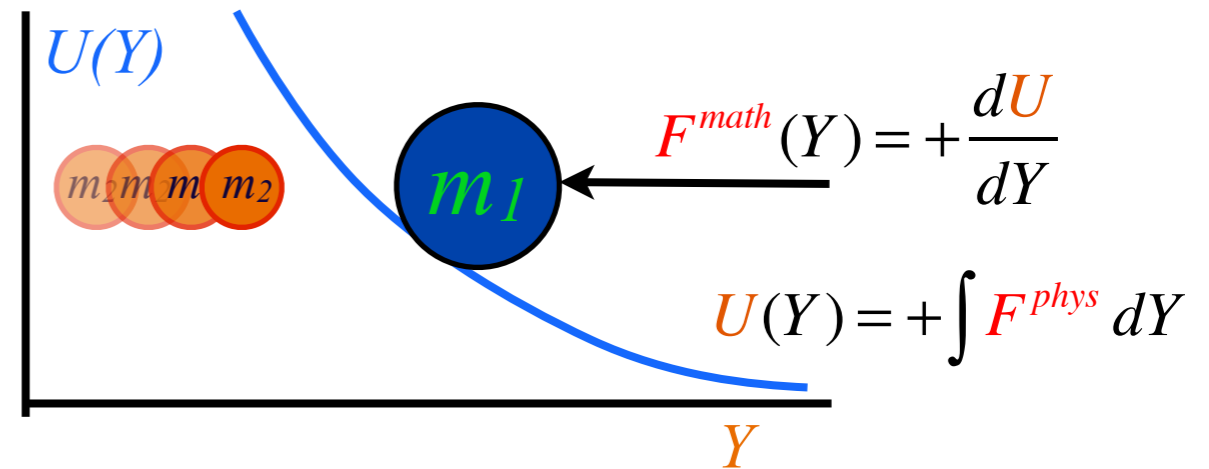
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The "Physicist" View of Force



The "Mathematician" View of Force



(Same integral/differential relations)

$$F^{phys} = \frac{m_2 v_2^2}{Y} = \frac{\text{const.}}{Y}$$

consistent
with:

$$F^{phys} = -\frac{\Delta U}{\Delta Y} = -\frac{d}{dY} (-\text{const.} \ln(Y)) = \frac{\text{const.}}{Y}$$

(Hurrah! again)

Potential field due to many small bounces

Example of 1D-Adiabatic potential $U(y)=\text{const.}/y^2$

Physicist's Definition $F=-\Delta U/\Delta y$ vs. Mathematician's Definition $F=+\Delta U/\Delta y$

Example of 1D-Isothermal potential $U(y)=\text{const.} \ln(y)$

 *Example of oscillator with opposing Isothermal potentials*

Example of oscillator with opposing Isothermal potentials

1D-Isothermal Force Law (assume v_2 is constant for all Y):

$$F = \frac{m_2 v_2^2}{Y} = \frac{\text{const.}}{Y}$$

$$F^{phys} = \frac{m_2 v_2^2}{Y} = - \frac{\Delta U}{\Delta Y}$$

implies :

$$U = -m_2 v_2^2 \ln(Y)$$

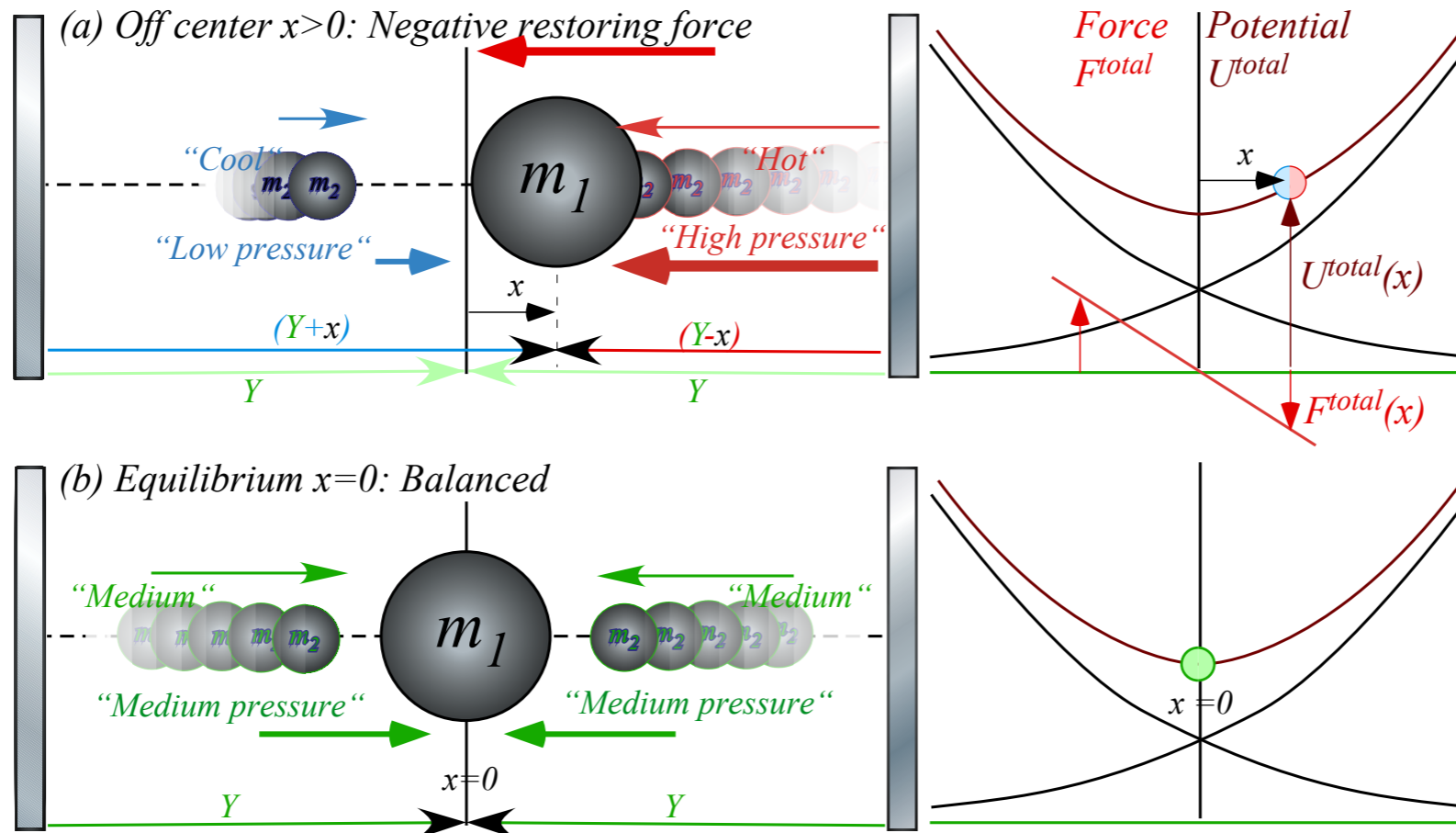


Fig. 5.3
Unit 1

Two opposing 1D-Isothermal Force fields

$$F^{total} = \frac{f}{Y_0 + x} - \frac{f}{Y_0 - x}$$

Example of oscillator with opposing Isothermal potentials

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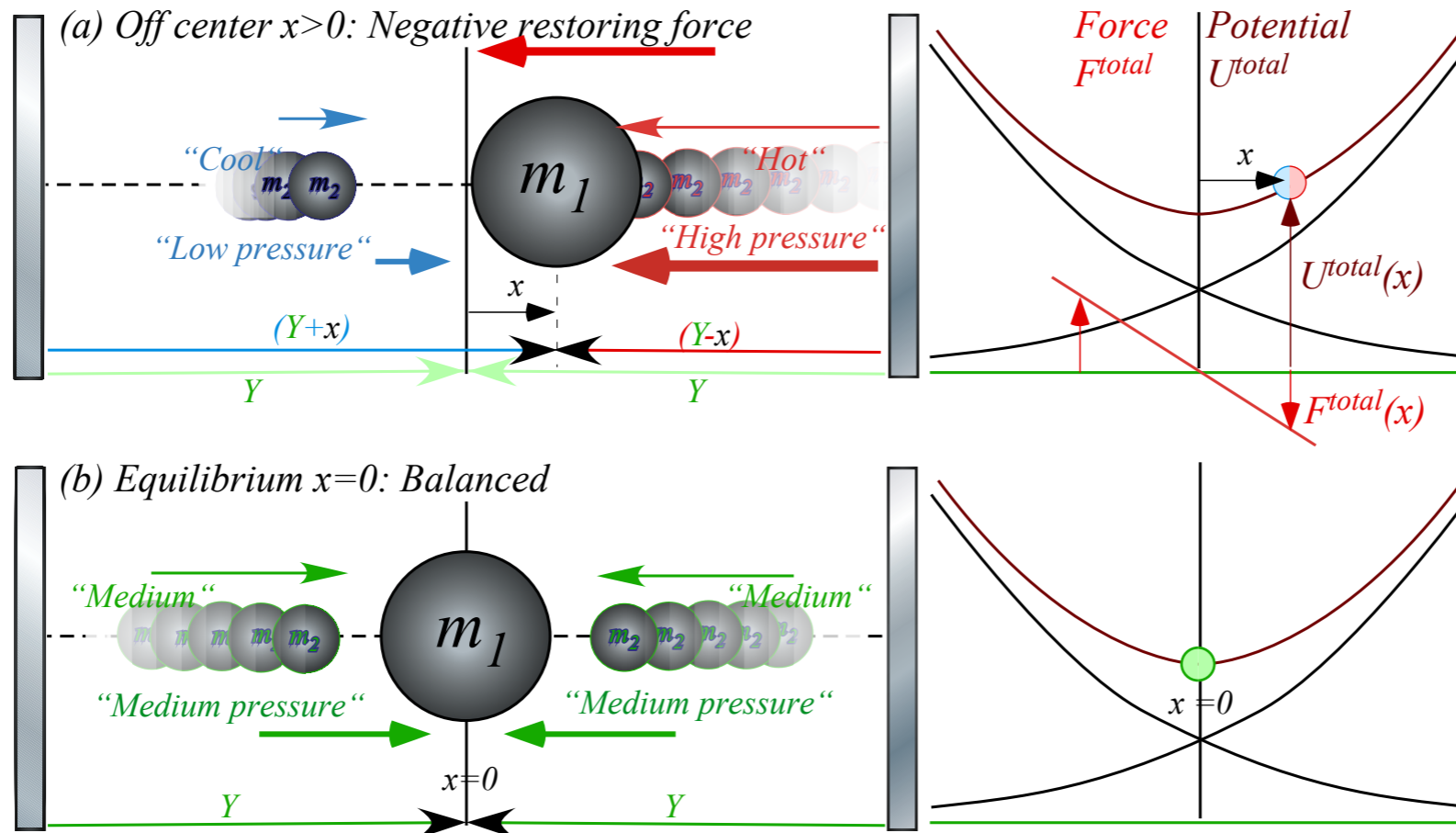


Fig. 5.3
Unit 1

Two opposing 1D-Isothermal Force fields

$$F^{total} = \frac{f}{Y_0 + x} - \frac{f}{Y_0 - x}$$

$$(Y_0 + x)^{-1} = Y_0^{-1} - xY_0^{-2} + x^2Y_0^{-3} - x^3Y_0^{-4} \dots$$

$$(Y_0 + x)^n = Y_0^n + nY_0^{n-1}x + \frac{n(n-1)}{2}Y_0^{n-2}x^2 + \frac{n(n-1)(n-2)}{2 \cdot 3}Y_0^{n-3}x^3 + \frac{n(n-1)(n-2)(n-3)}{2 \cdot 3 \cdot 4}Y_0^{n-4}x^4 \dots$$

Binomial Theorem

Example of oscillator with opposing Isothermal potentials

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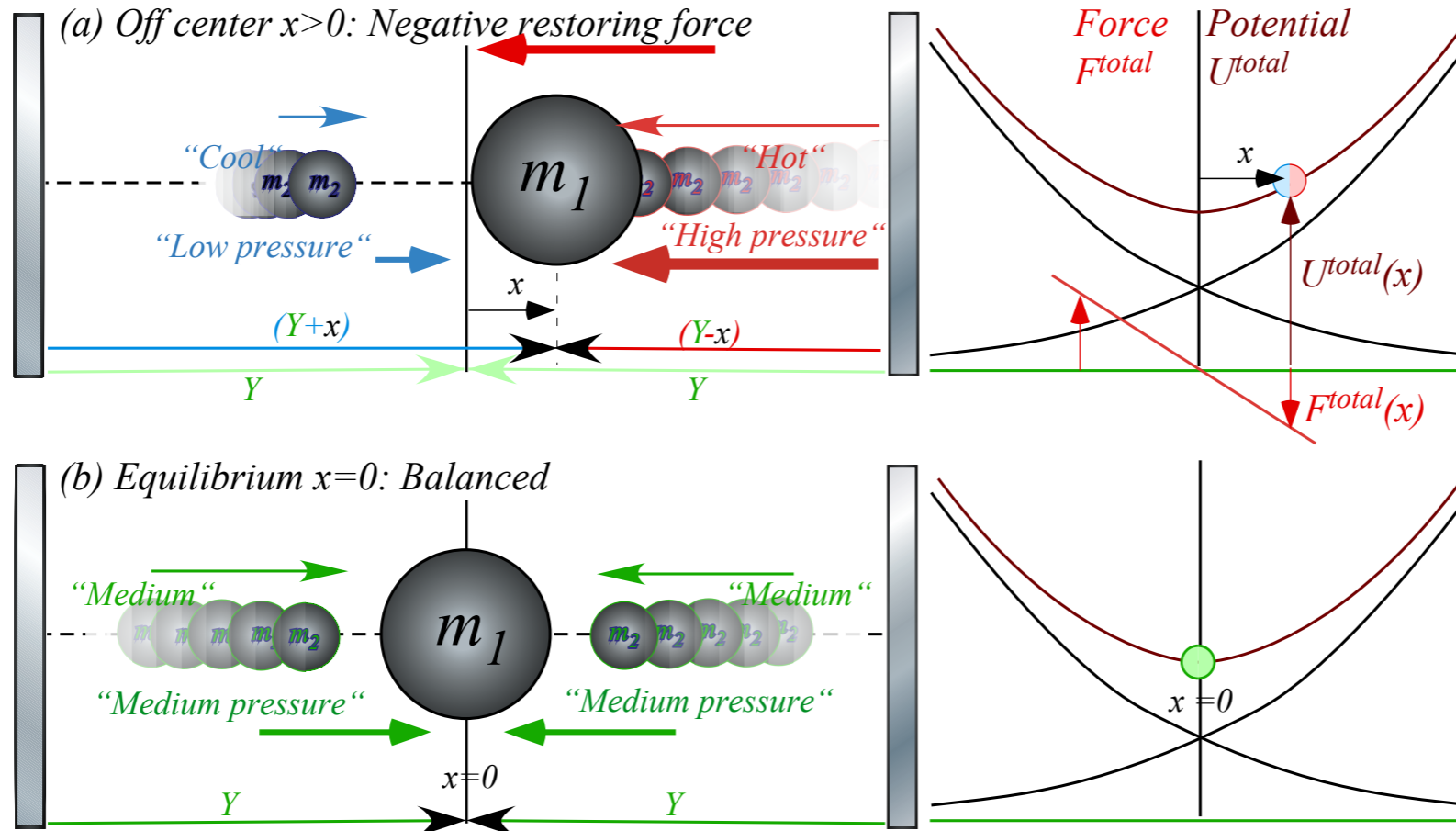


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Unit 1

Two opposing 1D-Isothermal Force fields

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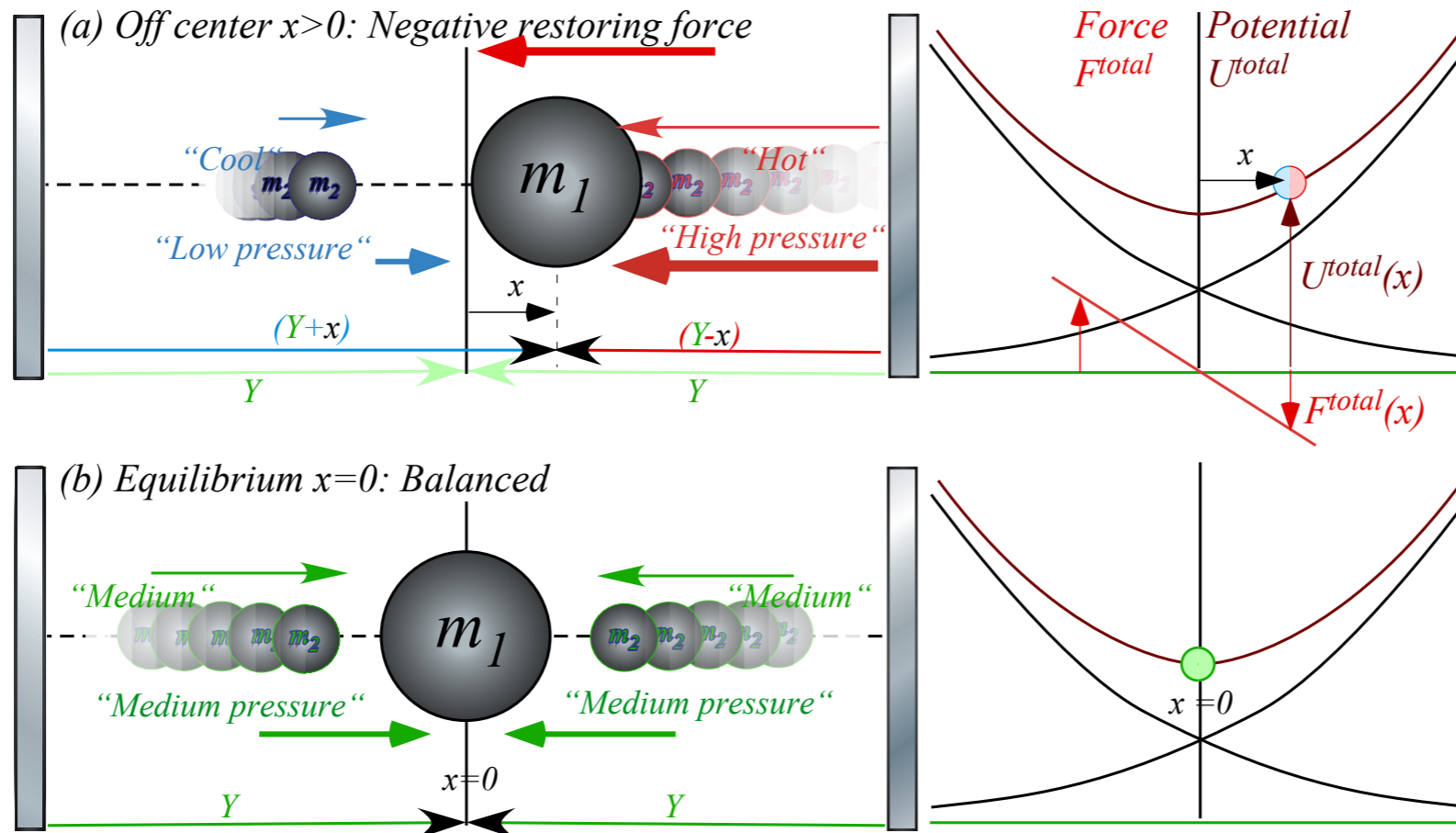


Fig. 5.3
Unit 1

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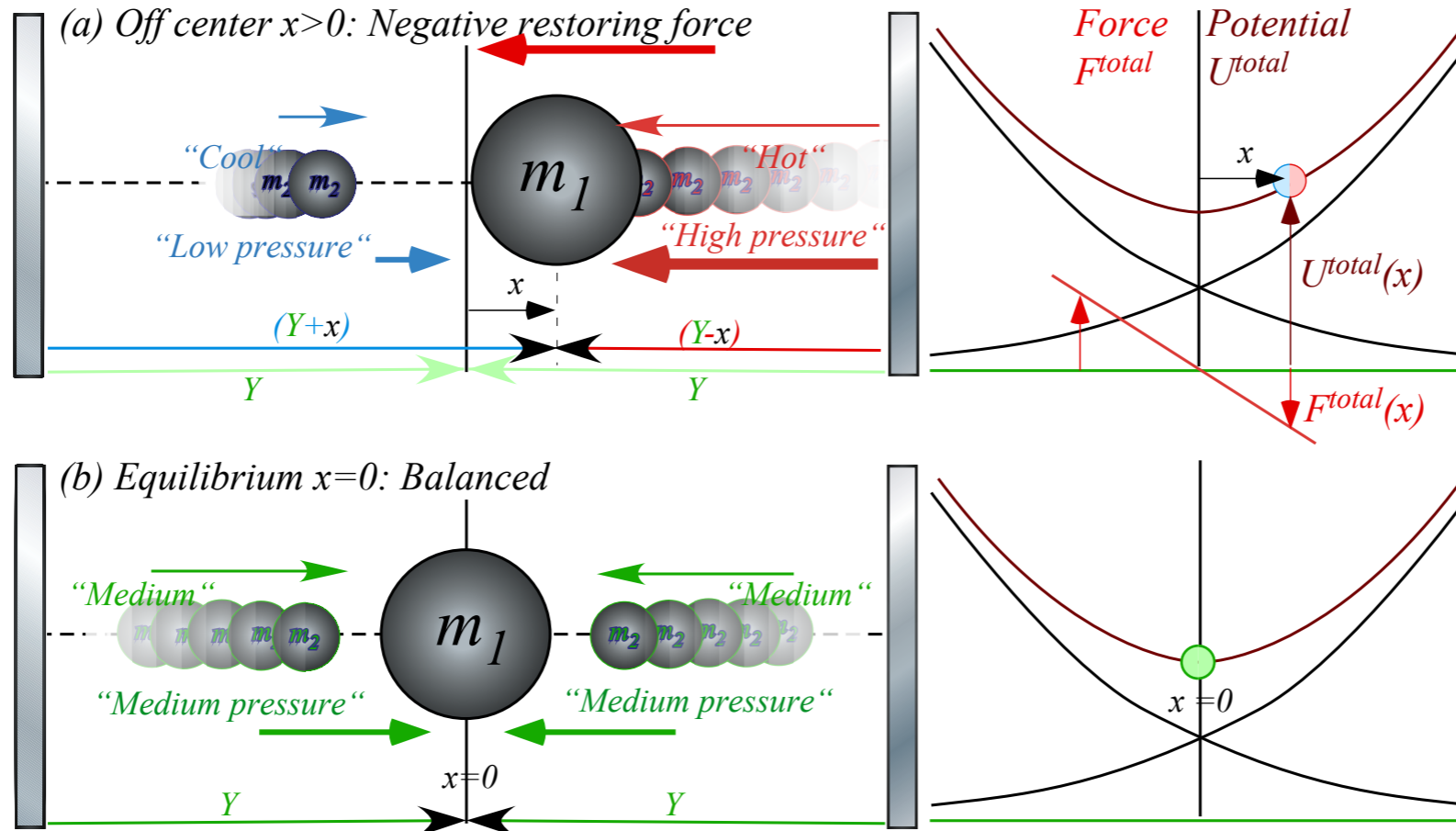


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Unit 1

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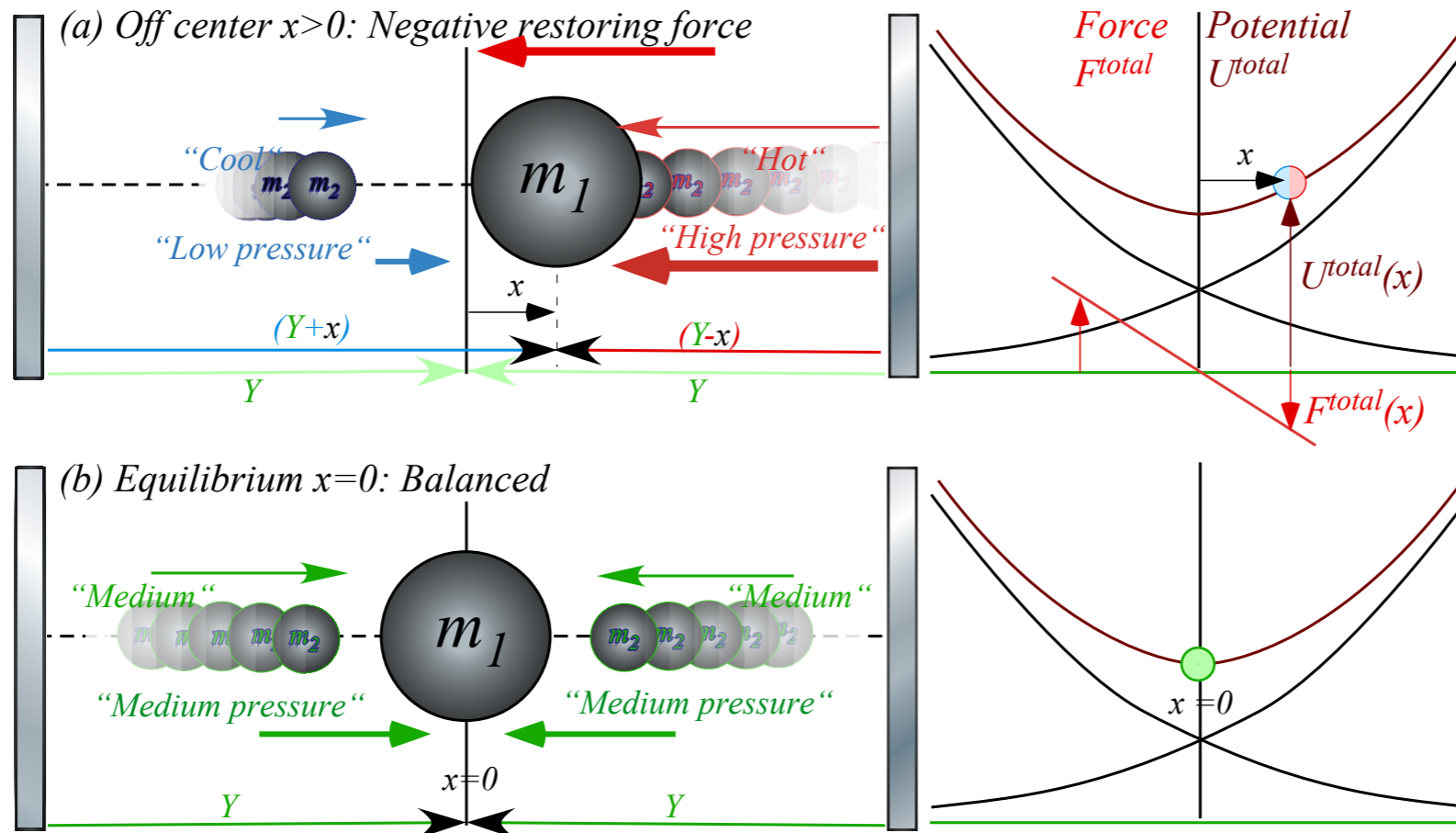


Fig. 5.3
Unit 1

Two opposing 1D-Isothermal Force fields approximate harmonic oscillator

$$F^{total} = \frac{f}{Y_0 + x} - \frac{f}{Y_0 - x} = f \left[\frac{1}{Y_0} - \frac{x}{Y_0^2} + \frac{x^2}{Y_0^3} - \frac{x^3}{Y_0^4} + \dots \right] - f \left[\frac{1}{Y_0} + \frac{x}{Y_0^2} + \frac{x^2}{Y_0^3} + \frac{x^3}{Y_0^4} + \dots \right] = -2f \frac{x}{Y_0^2} - 2f \frac{x^3}{Y_0^4} - \dots$$

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Binomial Theorem

Harmonic oscillator term
Anharmonic oscillator terms...

Example of oscillator with opposing Isothermal potentials

1D-Isothermal Force Law (assume v_2 is constant for all Y):

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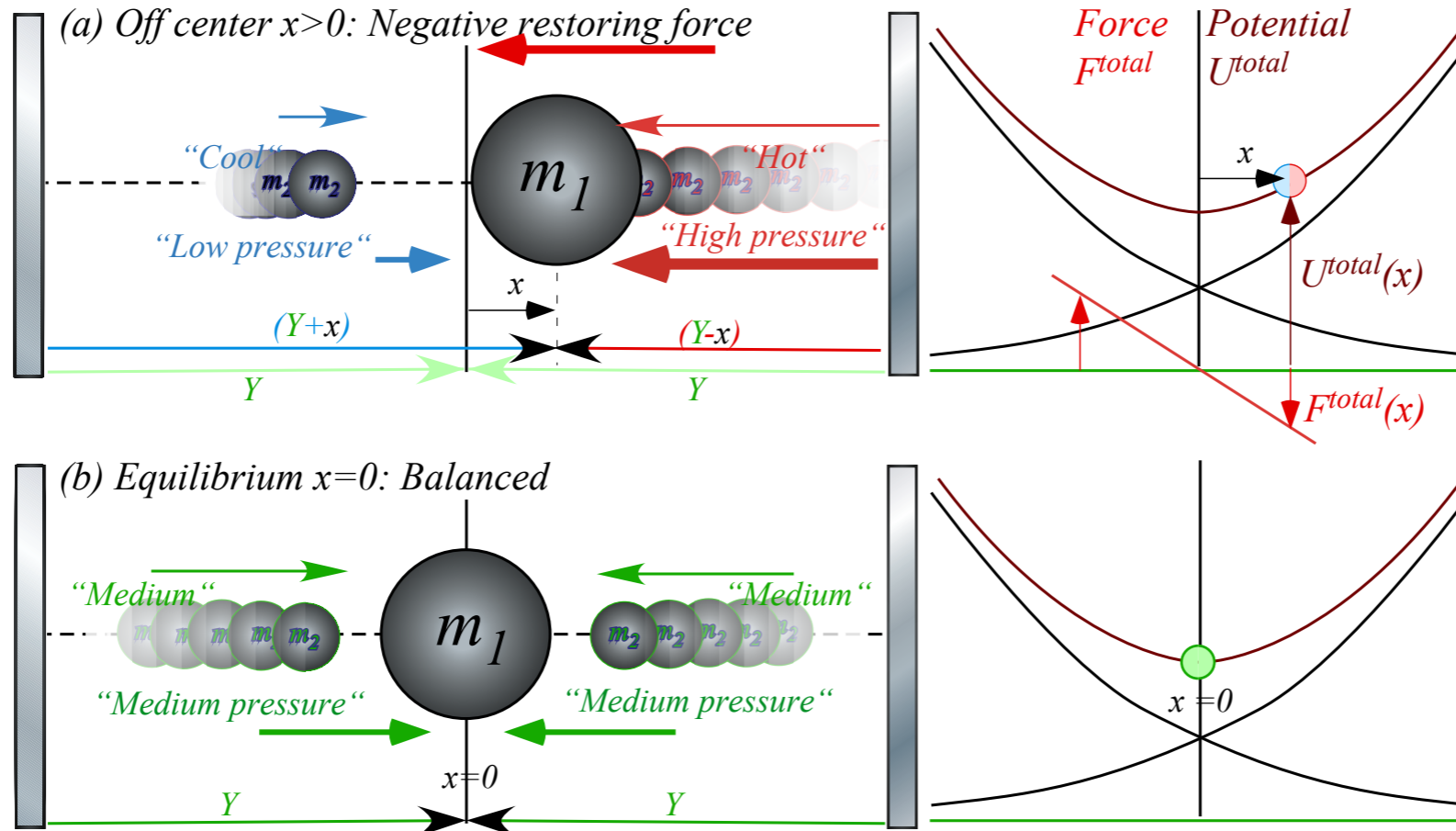


Fig. 5.3
Unit 1

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Harmonic oscillator force constant : $k = 2f/Y_0^2 = 2m_2 v_2^2 / Y_0^2$

Harmonic oscillator term
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Example of oscillator with opposing Isothermal potentials

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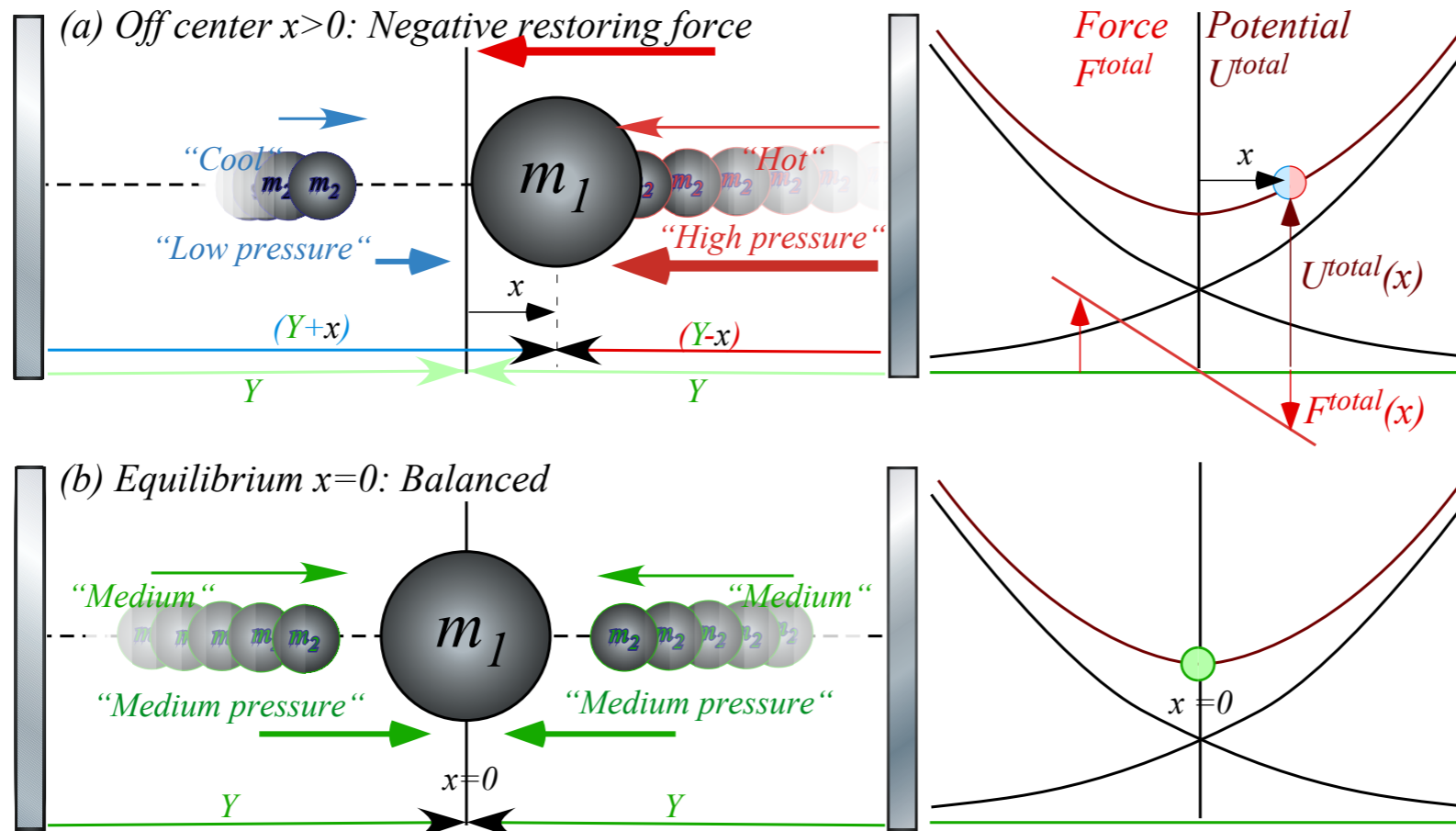


Fig. 5.3
Unit 1

Two opposing 1D-Isothermal Force fields approximate harmonic oscillator

$$F^{total} = \frac{f}{Y_0 + x} - \frac{f}{Y_0 - x} = f \left[\frac{1}{Y_0} - \frac{x}{Y_0^2} + \frac{x^2}{Y_0^3} - \frac{x^3}{Y_0^4} + \dots \right] - f \left[\frac{1}{Y_0} + \frac{x}{Y_0^2} + \frac{x^2}{Y_0^3} + \frac{x^3}{Y_0^4} + \dots \right] = -2f \frac{x}{Y_0^2} - 2f \frac{x^3}{Y_0^4} - \dots$$

Harmonic oscillator force constant : $k = 2f/Y_0^2 = 2m_2 v_2^2 / Y_0^2$

Harmonic oscillator term
Anharmonic oscillator terms...

$$F^{HO} = -k \cdot x = - \frac{\partial U^{HO}}{\partial x}$$

Example of oscillator with opposing Isothermal potentials

1D-Isothermal Force Law (assume v_2 is constant for all Y):

$$F = \frac{m_2 v_2^2}{Y} = \frac{\text{const.}}{Y}$$

$$F^{phys} = \frac{m_2 v_2^2}{Y} = - \frac{\Delta U}{\Delta Y}$$

implies :

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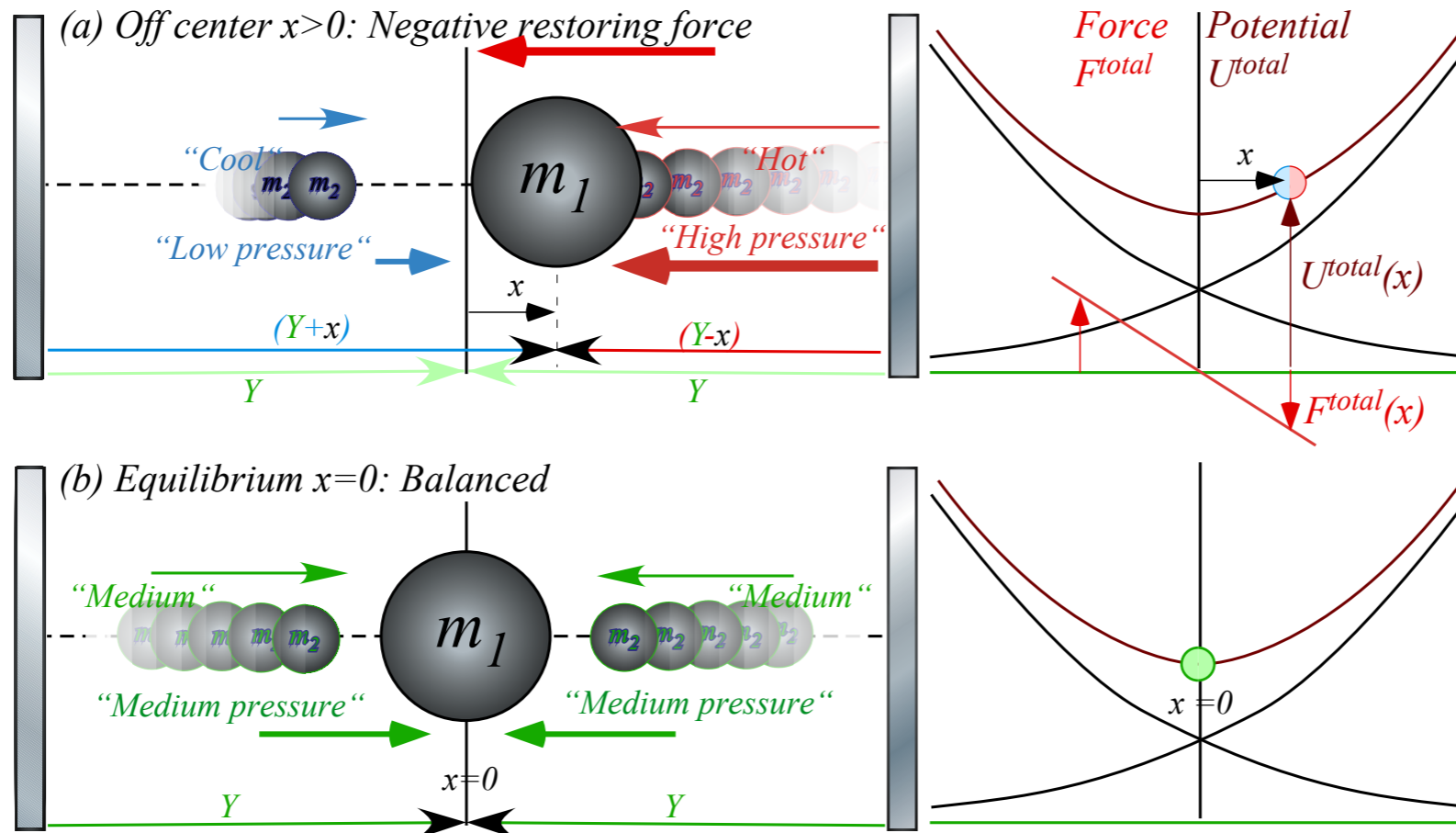


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Unit 1

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Harmonic Oscillator Force

$$F^{HO} = -k \cdot x = - \frac{\partial U^{HO}}{\partial x}$$

Potential

$$U^{HO} = \frac{1}{2} k \cdot x^2 = - \int F^{HO} dx$$

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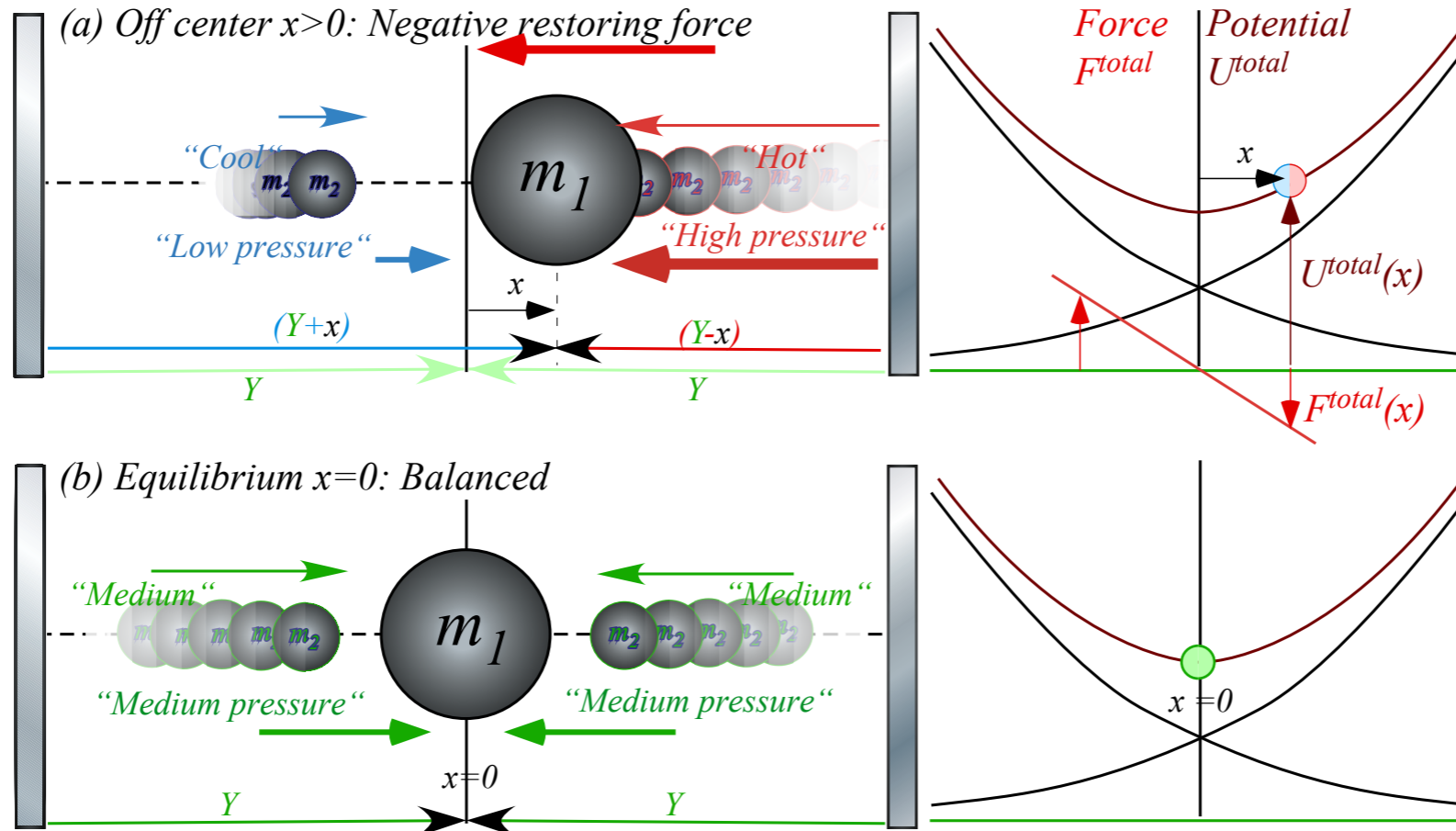


Fig. 5.3
Unit 1

Two opposing 1D-Isothermal Force fields approximate harmonic oscillator

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Frequency

HO Δ frequency: $\omega = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{2m_2}{m_1}} \frac{v_2}{Y_0} = 2\pi\nu$

Harmonic oscillator term

Anharmonic oscillator terms...

What does *Harmonic* mean?

Given total energy $E = KE+PE = \frac{1}{2}mV^2 + \frac{1}{2}kY^2$

E is *same* constant for *any* amplitude A of sine-oscillation where:

$$Y = A \sin \omega t \quad \text{with velocity} \quad V = A\omega \cos \omega t$$

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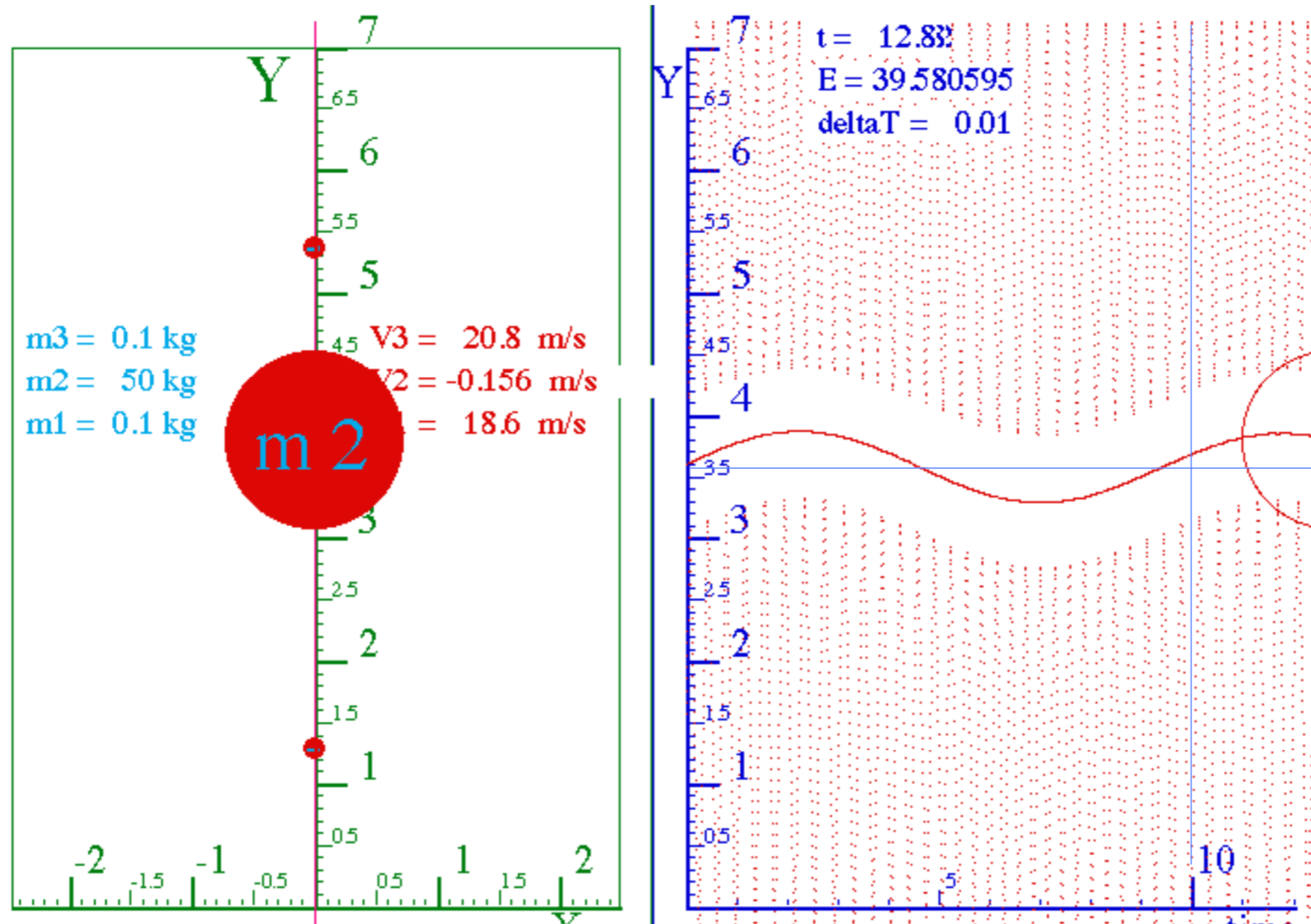
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$$= \frac{1}{2}m\omega^2 A^2 \quad \text{if: } \omega = \sqrt{\frac{k}{m}}$$



BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios (Small Amplitude)

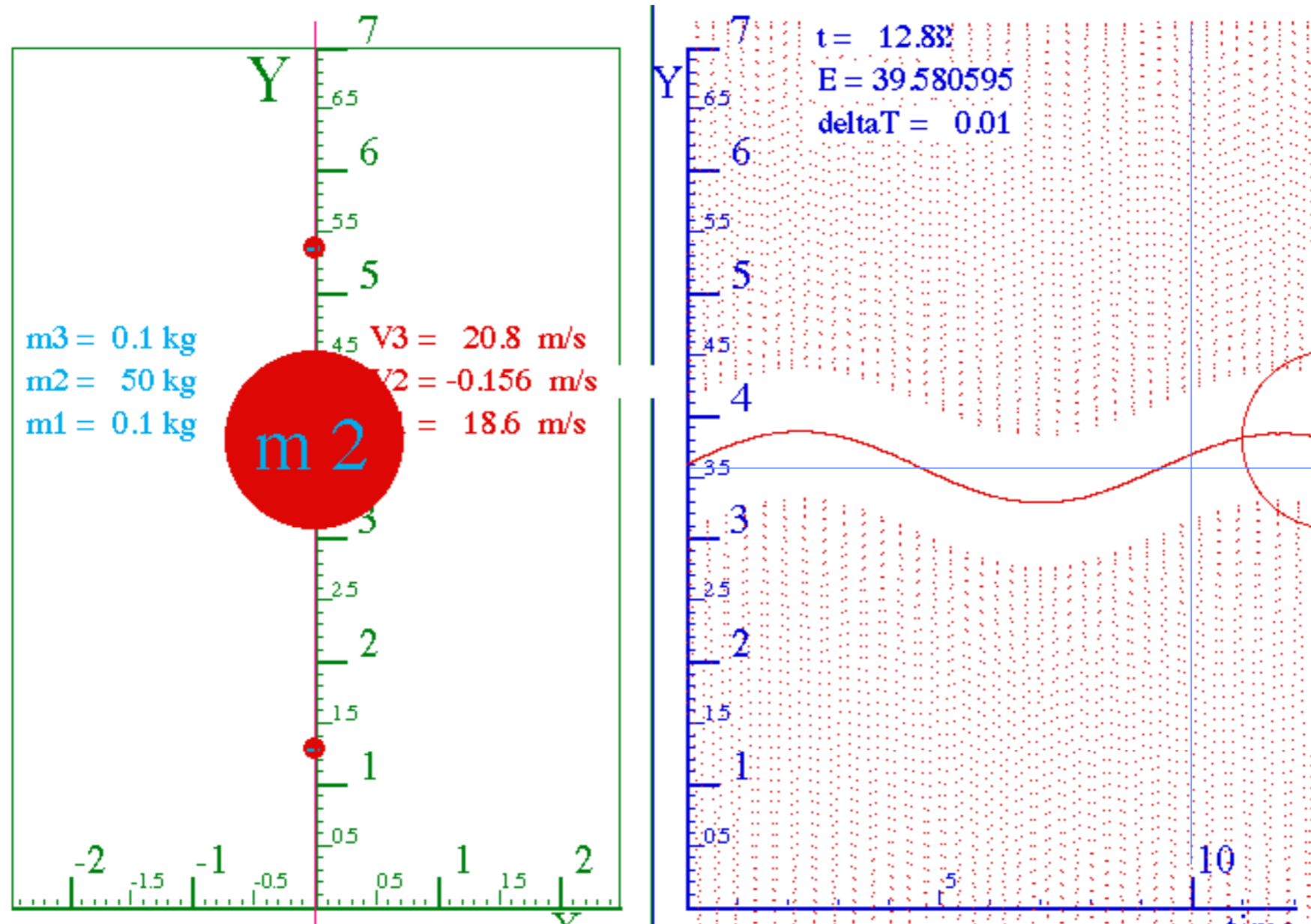
*Fig. 5.3
Unit 1*

Simulation of
the **adiabatic case**

Sample problem: *Compute frequency and/or period*

Frequency

$$\text{HO } \Delta \text{ frequency: } \omega = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{2m_2}{m_1} \frac{v_2}{Y_0}} = 2\pi\nu$$



*Fig. 5.3
Unit 1*

Simulation of
the **adiabatic case**

BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios (Small Amplitude)

Sample problem: *Compute frequency and/or period*

Period:
$$\tau = \frac{1}{\nu} = 2\pi \sqrt{\frac{m_1}{k}} = 2\pi \sqrt{\frac{m_1}{2m_2} \frac{Y_0}{v_2}}$$

Frequency

HO ∇ frequency:
$$\omega = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{2m_2}{m_1} \frac{v_2}{Y_0}} = 2\pi\nu$$

Switch
 $m_1 = m_3$
 with
 m_2
 to match
 formula

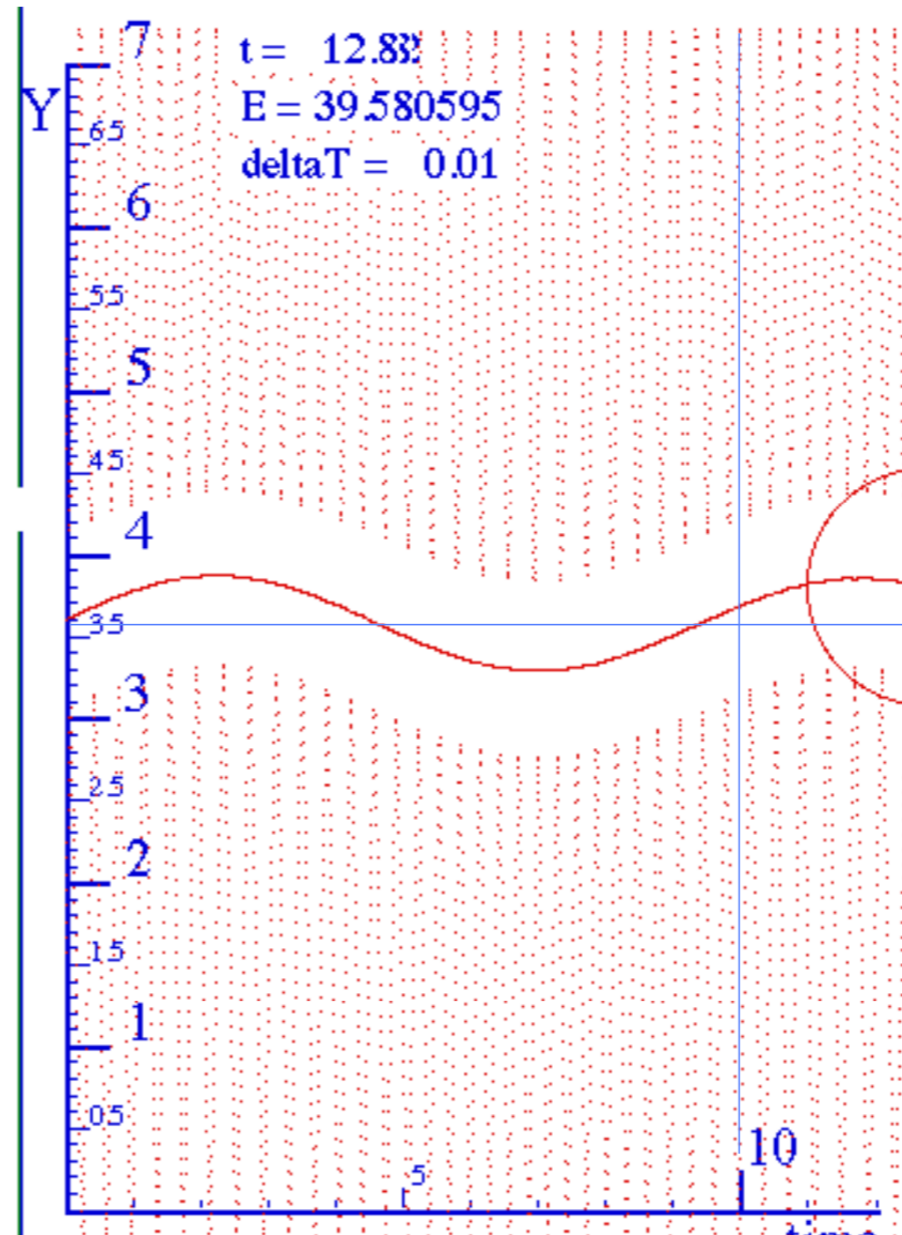
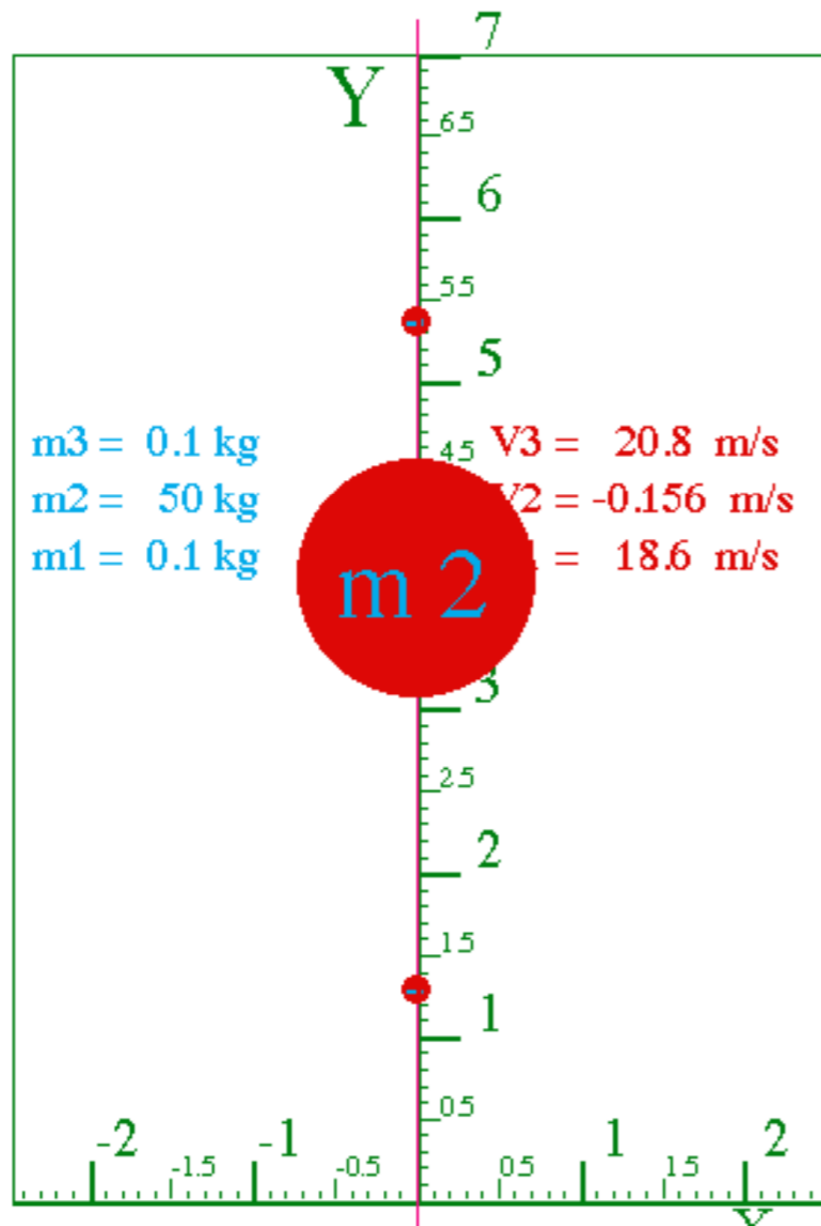


Fig. 5.3
 Unit 1

Simulation of
 the **adiabatic case**

BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios (Small Amplitude)

Sample problem: Compute period given $m_1 = 50$, $m_2 = 0.1 = m_3$, $v_2 = 20$, $Y_0 = 3.5$

Period :

$$\tau = 2\pi \sqrt{\frac{m_1}{2m_2} \frac{Y_0}{v_2}} = 6.28 \sqrt{\frac{50}{2 \cdot (0.1)} \frac{3.5}{20}}$$

$$= 17.38$$

$$\text{Period : } \tau = \frac{1}{\nu} = 2\pi \sqrt{\frac{m_1}{k}} = 2\pi \sqrt{\frac{m_1}{2m_2} \frac{Y_0}{v_2}}$$

Frequency

$$\text{HO } \angle \text{frequency: } \omega = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{2m_2}{m_1} \frac{v_2}{Y_0}} = 2\pi\nu$$

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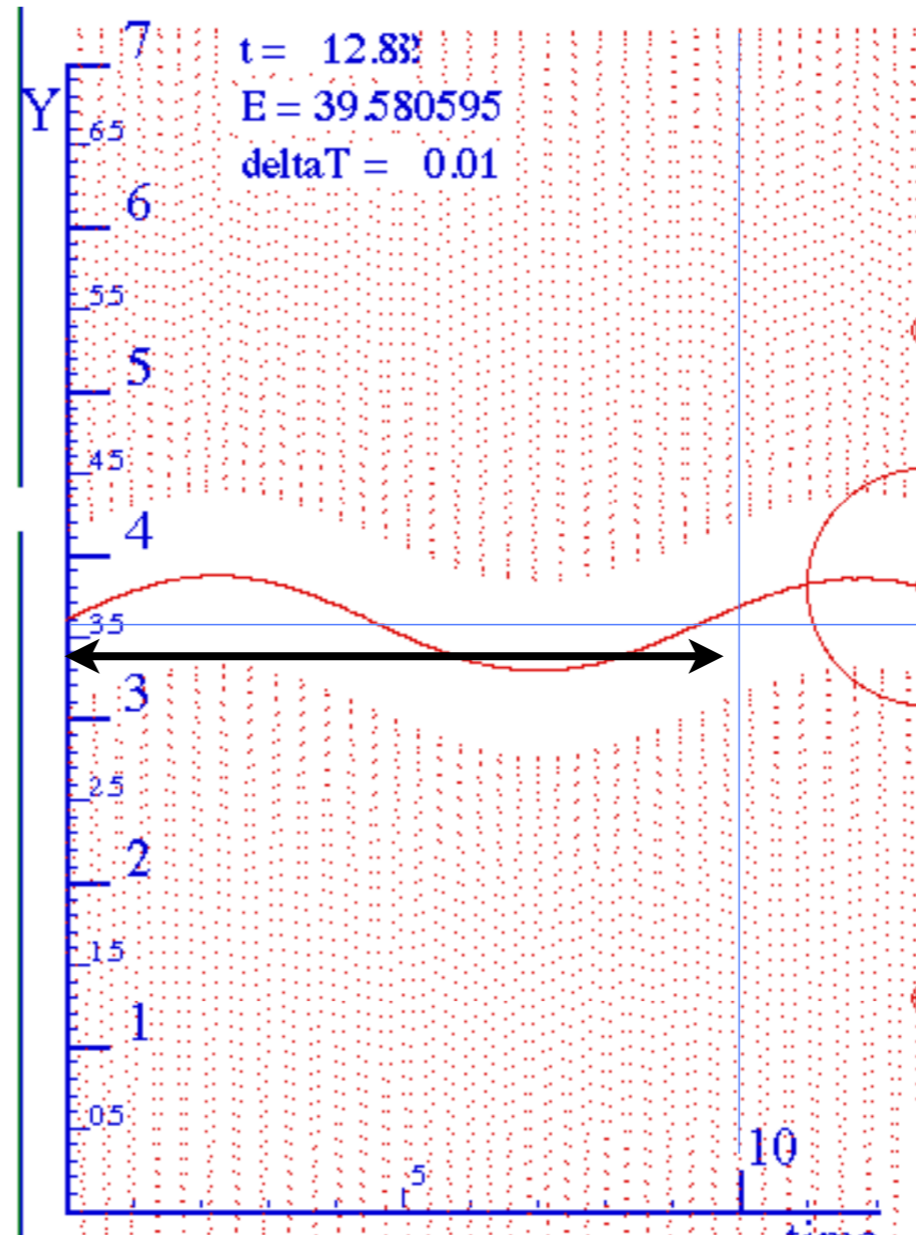
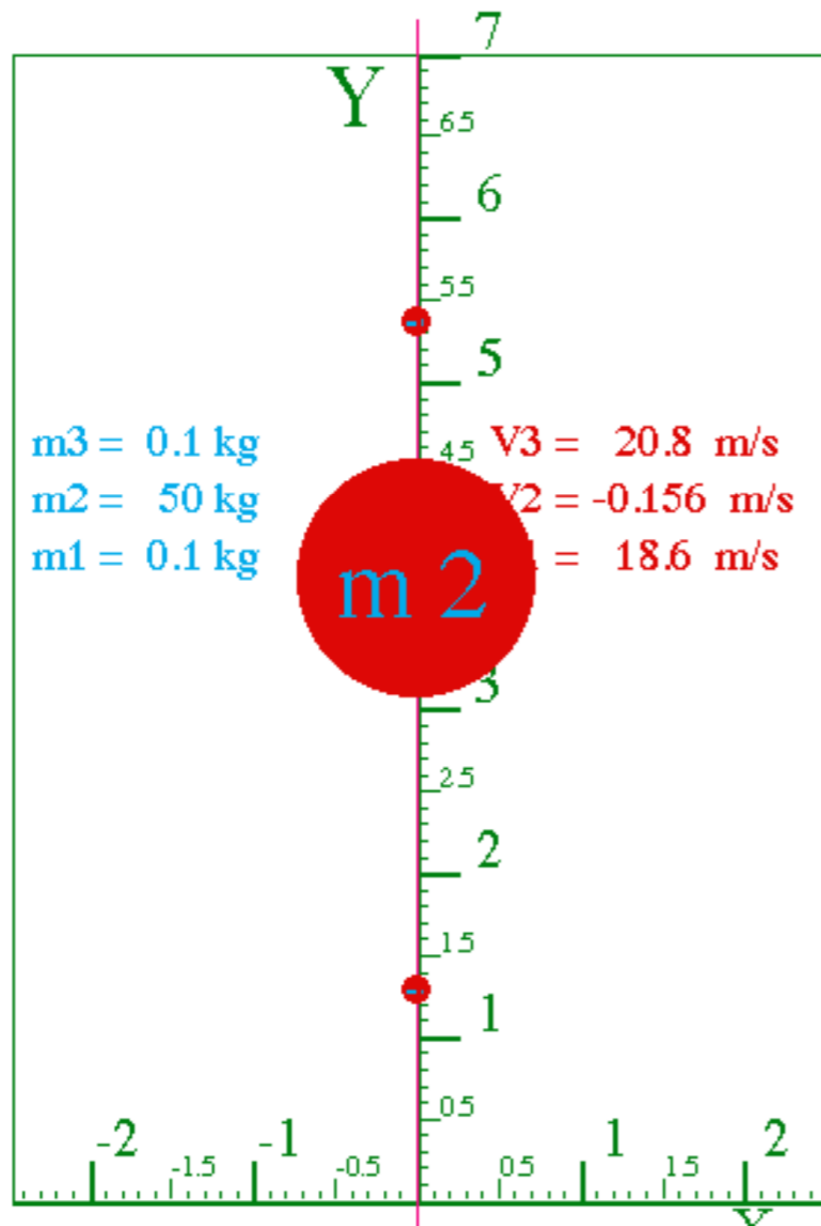


Fig. 5.3
 Unit 1

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BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios (Small Amplitude)

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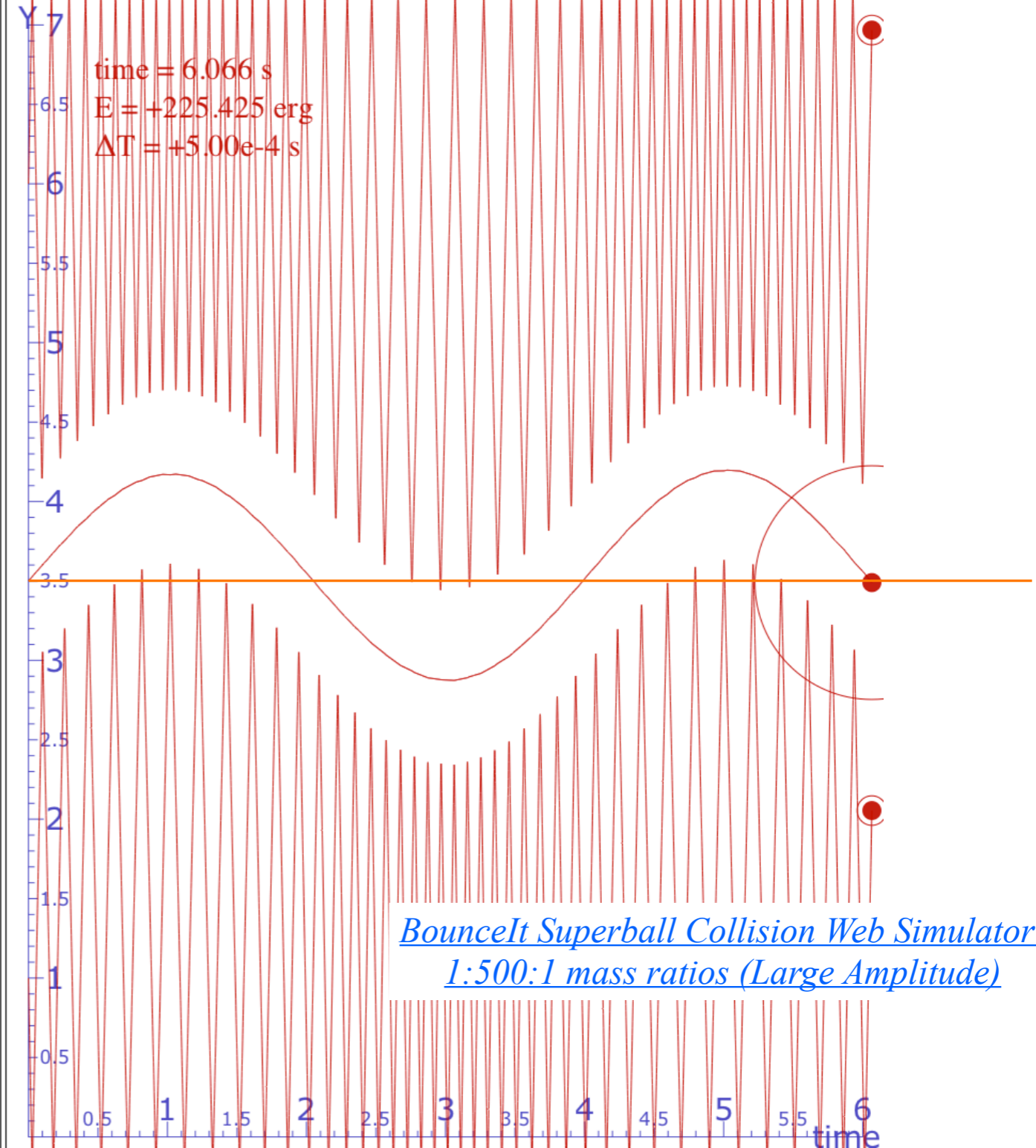
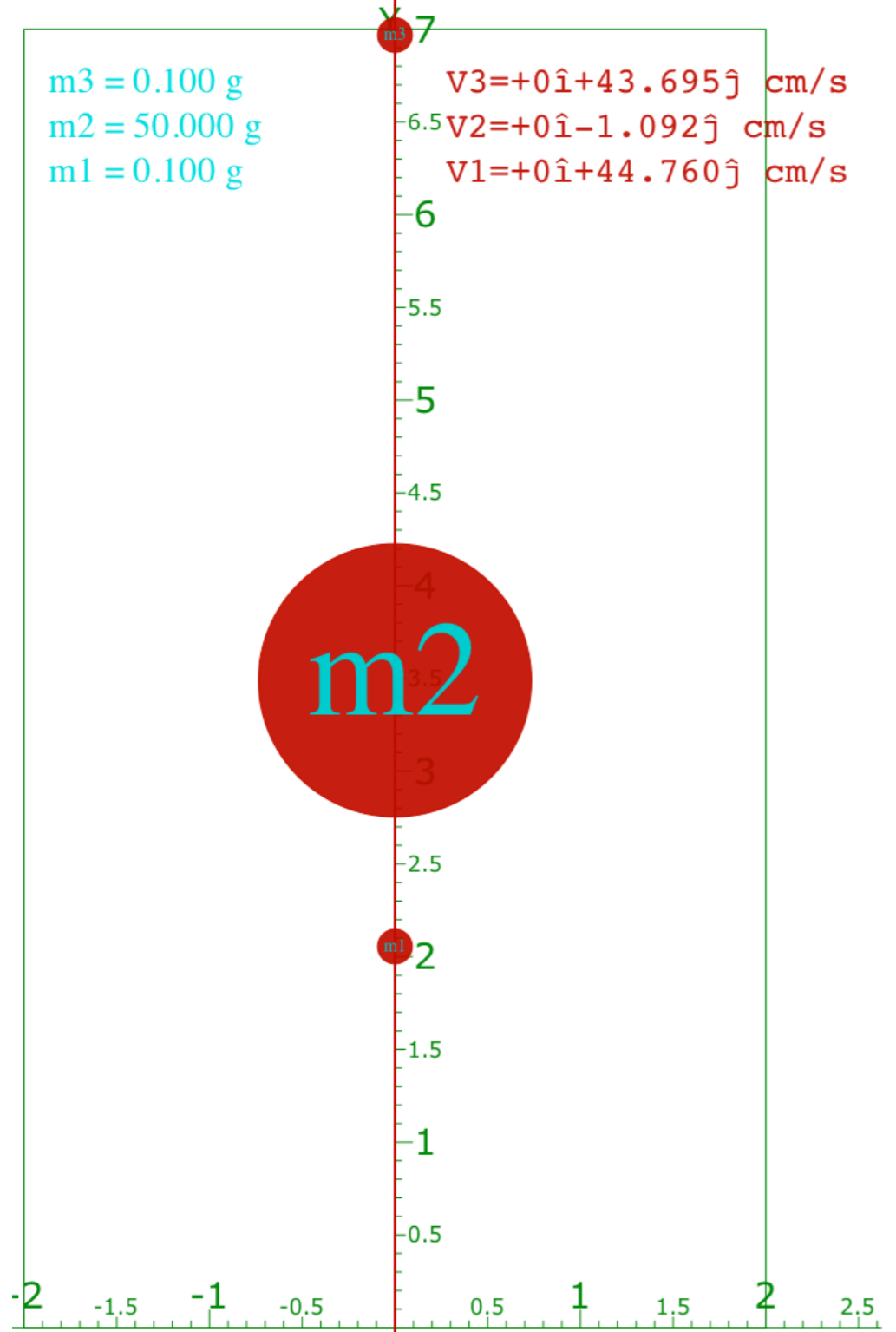
$$\tau = 2\pi \sqrt{\frac{m_1}{2m_2} \frac{Y_0}{v_2}} = 6.28 \sqrt{\frac{50}{2 \cdot (0.1)} \frac{3.5}{20}}$$

$$= 17.38 \quad \text{That's about } \sqrt{3} \text{ times too big!}$$

Period : $\tau = \frac{1}{\nu} = 2\pi \sqrt{\frac{m_1}{k}} = 2\pi \sqrt{\frac{m_1}{2m_2} \frac{Y_0}{v_2}}$

Frequency

HO ∇ frequency: $\omega = \sqrt{\frac{k}{m_1}} = \sqrt{\frac{2m_2}{m_1} \frac{v_2}{Y_0}} = 2\pi\nu$



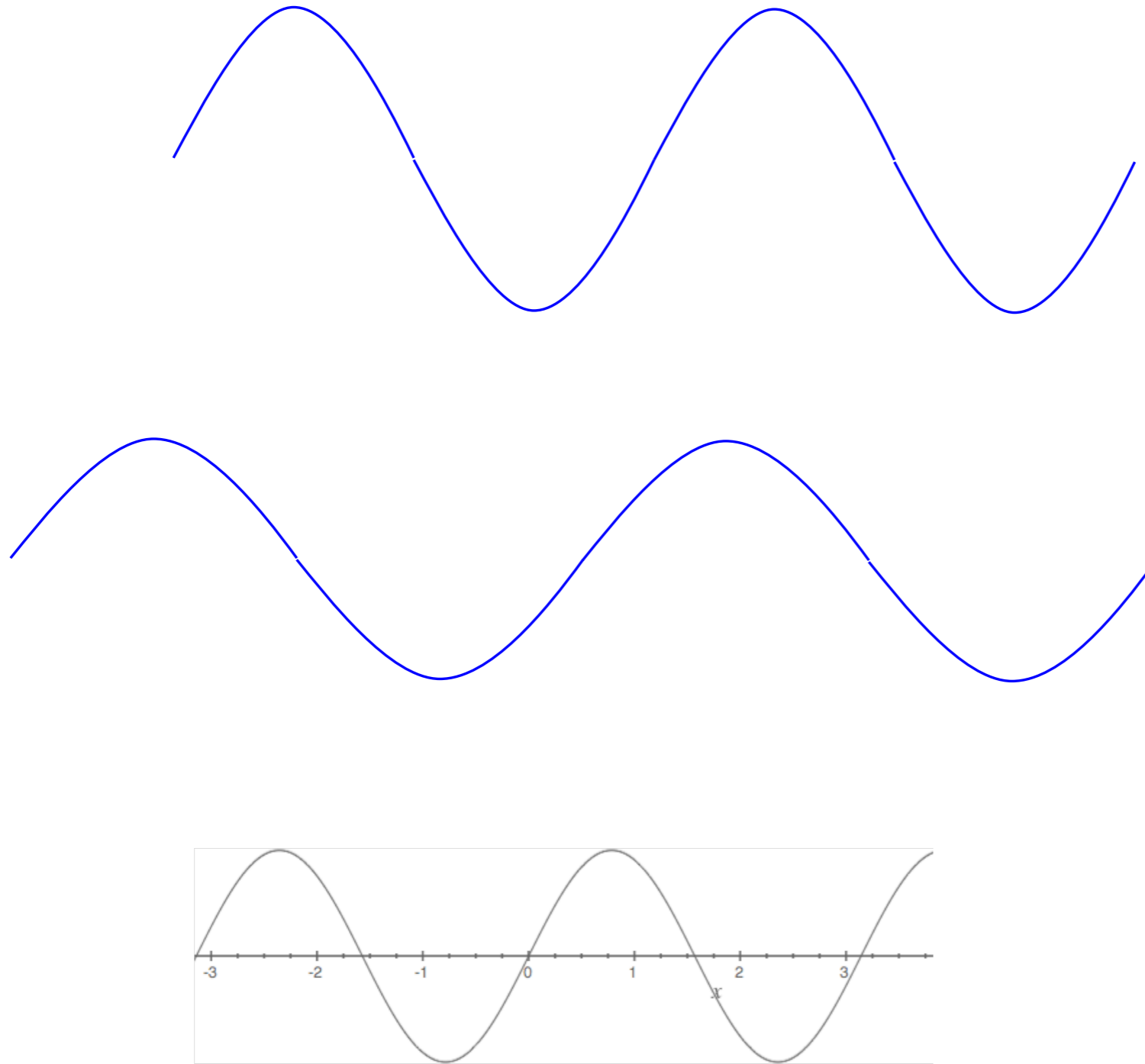
*BounceIt Superball Collision Web Simulator:
1:500:1 mass ratios (Large Amplitude)*

Initial x1 = y Max =
 Max x PE plot = y Min =
 F-Vector scale = T Max =
 Error step = V2y Max =
 V2y Min =

Adiabatic force scenarios

- Quasi-harmonic oscillation (m1:m2 = 100:1)
- Quasi-harmonic oscillation (m1:m2 = 50:1)
- Quasi-harmonic oscillation (m1:m2 = 25:1)
- Large amplitude (m1:m2 = 100:1)

$m_1 =$ $\times 10^$ g $X_{1_0} =$ $\times 10^$ cm $V_{1_0} =$ $\times 10^$ cm/s
 $m_2 =$ $\times 10^$ g $X_{2_0} =$ $\times 10^$ cm $V_{2_0} =$ $\times 10^$ cm/s
 $m_3 =$ $\times 10^$ g $X_{3_0} =$ $\times 10^$ cm $V_{3_0} =$ $\times 10^$ cm/s

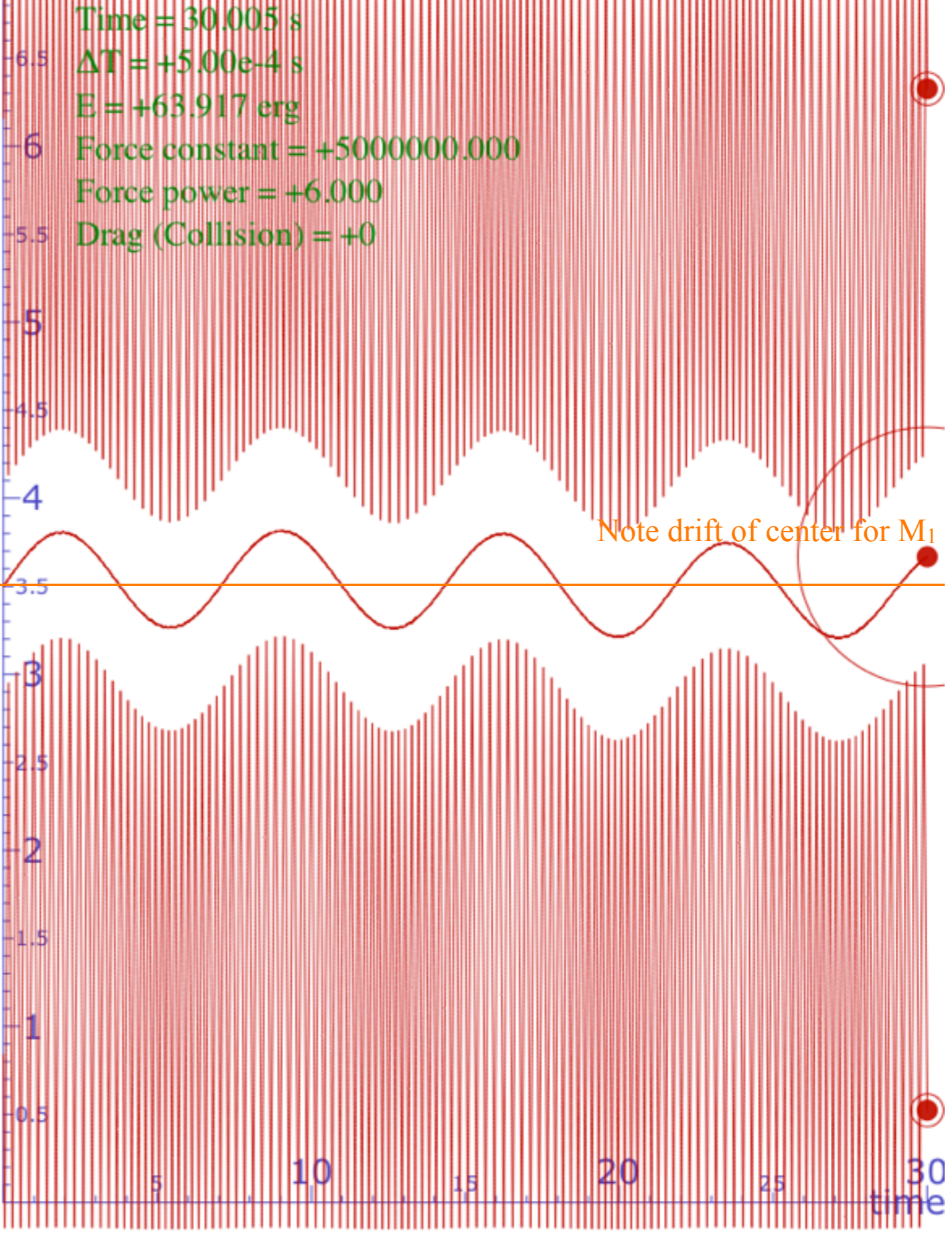


[BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios \(Small Amplitude\)](#)

m3 = 0.100 g
m2 = 50.000 g
m1 = 0.100 g

V3 = +0i - 27.079j cm/s
V2 = +0i + 0.143j cm/s
V1 = +0i - 23.127j cm/s

Note drift of total E
from 64.052
to 63.917



Time = 30.005 s
 $\Delta T = +5.00e-4$ s
E = +63.917 erg
Force constant = +5000000.000
Force power = +6.000
Drag (Collision) = +0

Note drift of center for M1

BounceIt Superball Collision Web Simulator: 1:500:1 mass ratios (Small Amplitude)

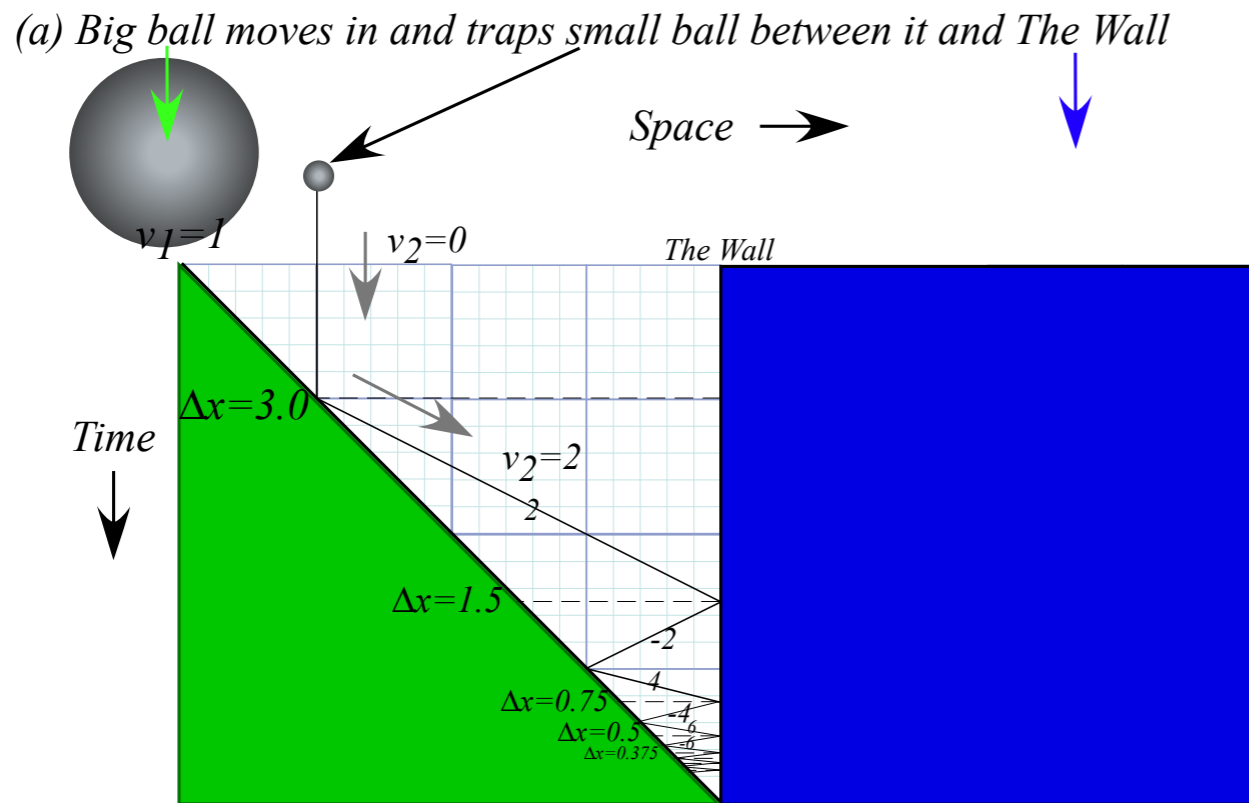
“Monster Mash” classical analog of Heisenberg action relations

Example of very very large M_1 ball-wall(s) crushing a poor little m_2

 *How does m_2 conserve action ($\Delta x \Delta p$ or $\int p \cdot dx$) as its KE changes?*

The Classical "Monster Mash"

Classical introduction to
Heisenberg "Uncertainty" Relations



$$v_2 = \frac{\text{const.}}{Y} \quad \text{or:} \quad Y \cdot v_2 = \text{const.}$$

is analogous to: $\Delta x \cdot \Delta p = N \cdot \hbar$

(b) Trajectory geometry exposed

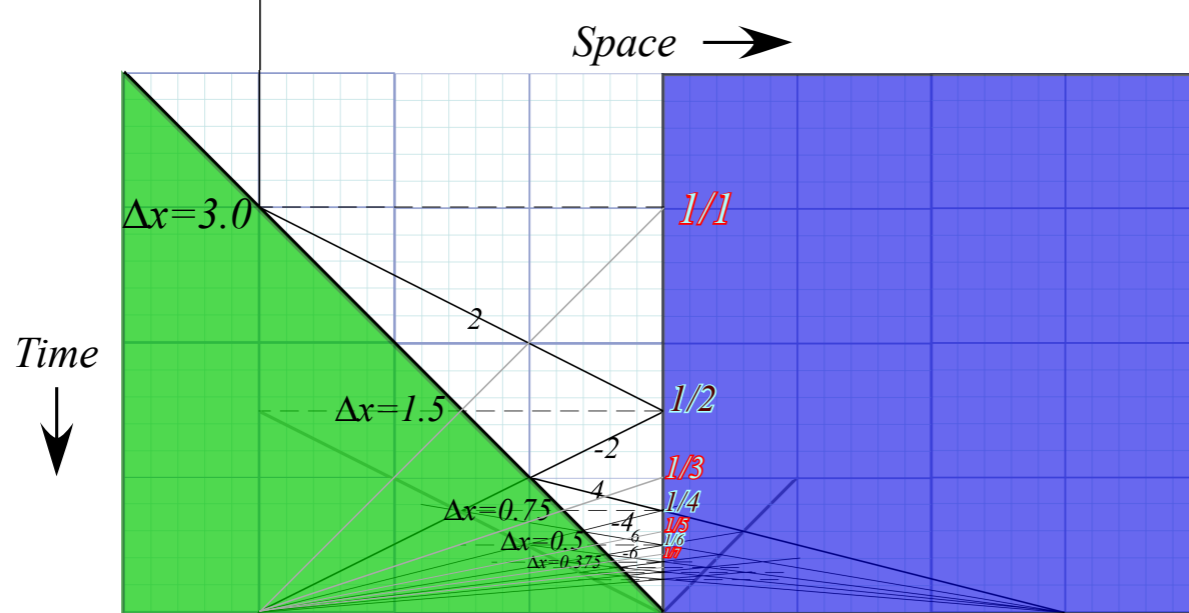
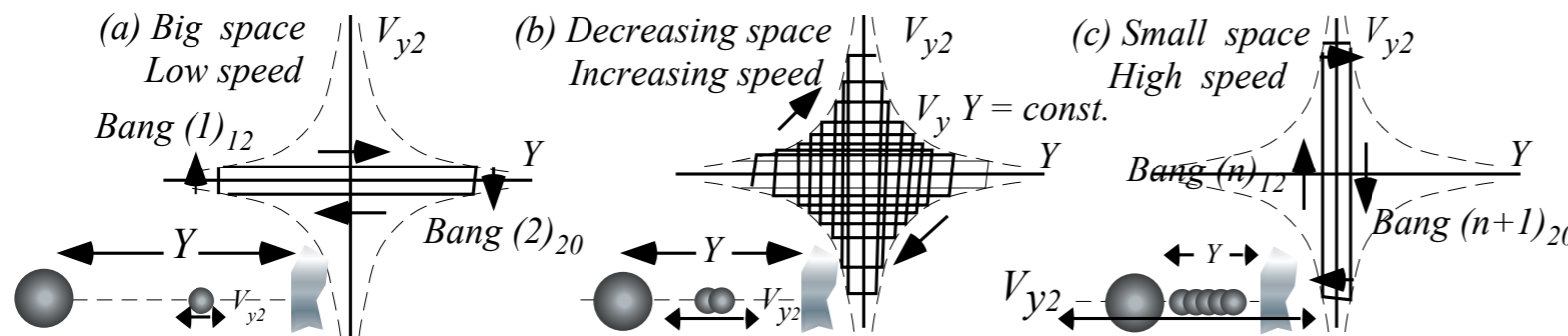


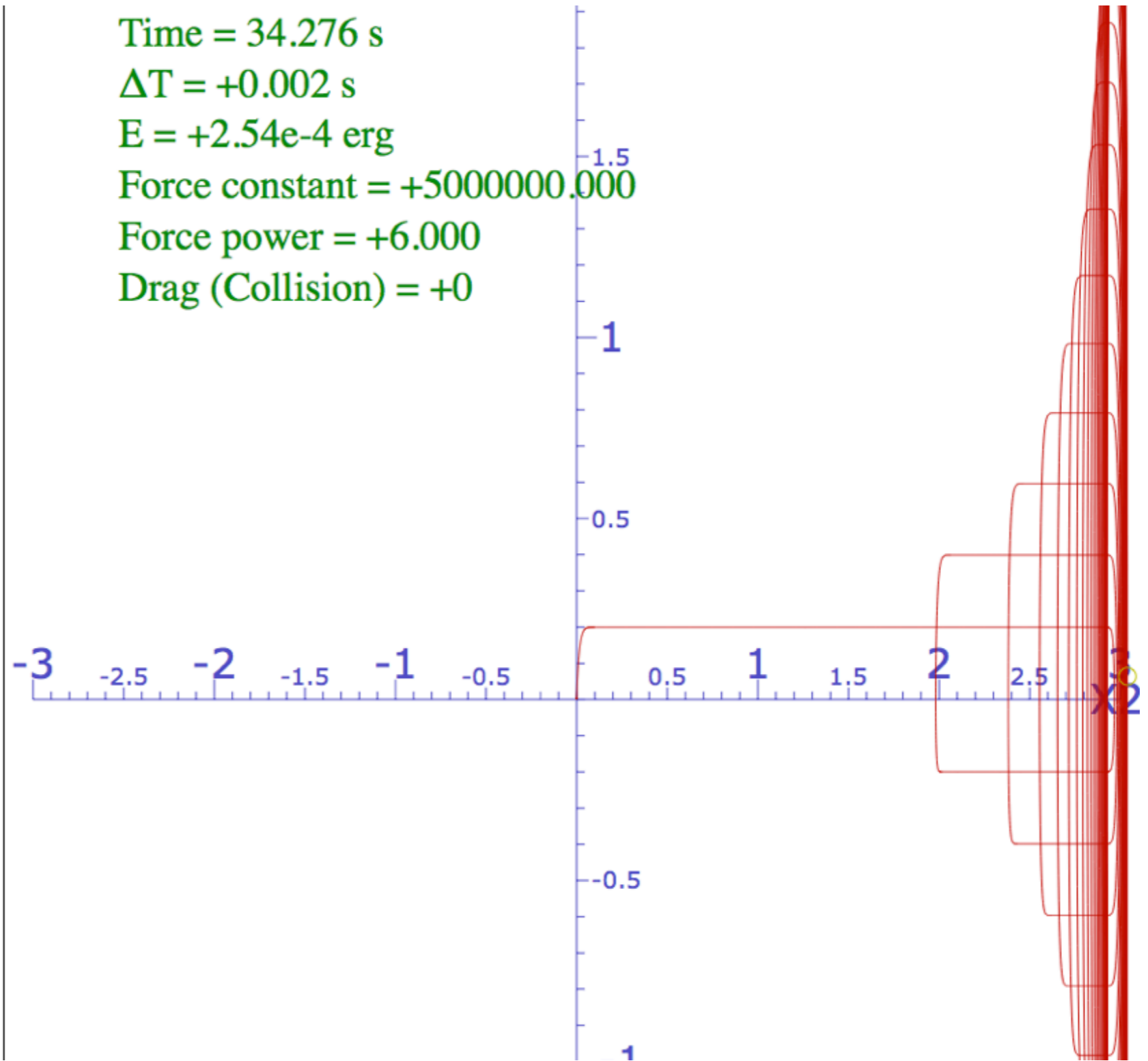
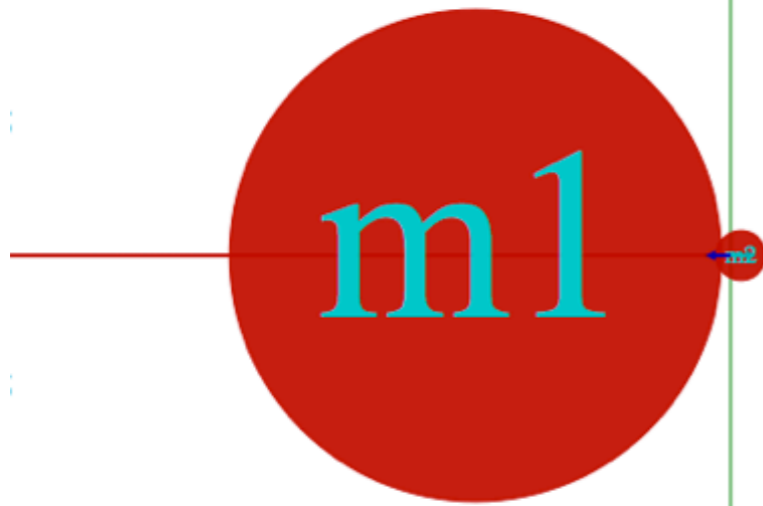
Fig. 5.4
Unit 1

BounceIt "Monster Mash" $x_2(t)$ animation
(Note: Time sense is inverted)



$V_2 = +0.064\hat{i} + 0\hat{j}$ cm/s
 $V_1 = -9.98e-4\hat{i} + 0\hat{j}$ cm/s

Time = 34.276 s
 $\Delta T = +0.002$ s
E = $+2.54e-4$ erg
Force constant = $+5000000.000$
Force power = $+6.000$
Drag (Collision) = $+0$



BounceIt "Monster Mash" V_{x2} vs x_2 animation

Double "Monster Mash"

Realizes reflection symmetry of perfect wall bounces

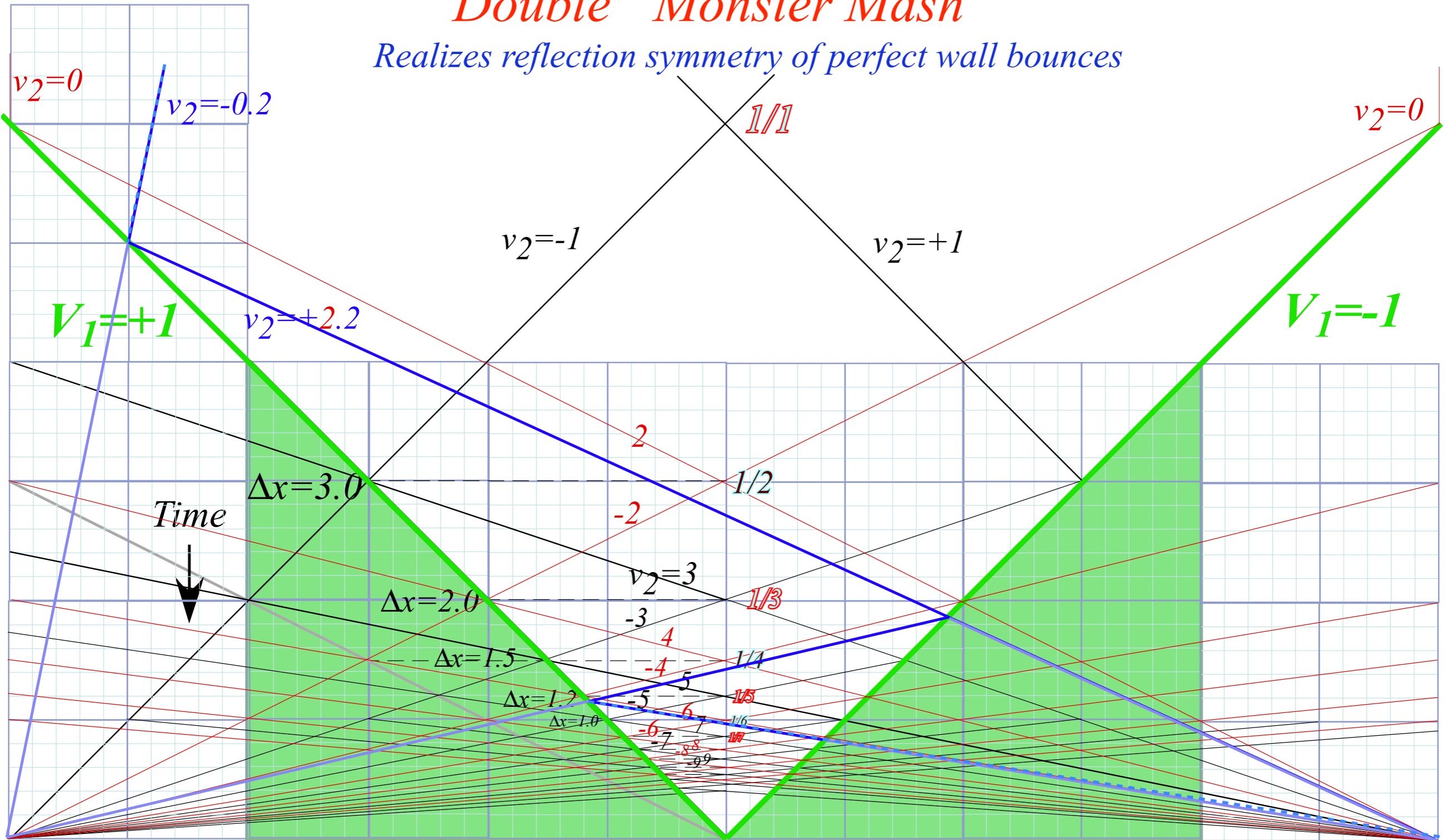


Fig. 5.5
Unit 1

See Homework problem 1.6.2: Construct related spacetime case

Double "Monster Mash"

Realizes reflection symmetry of perfect wall bounces

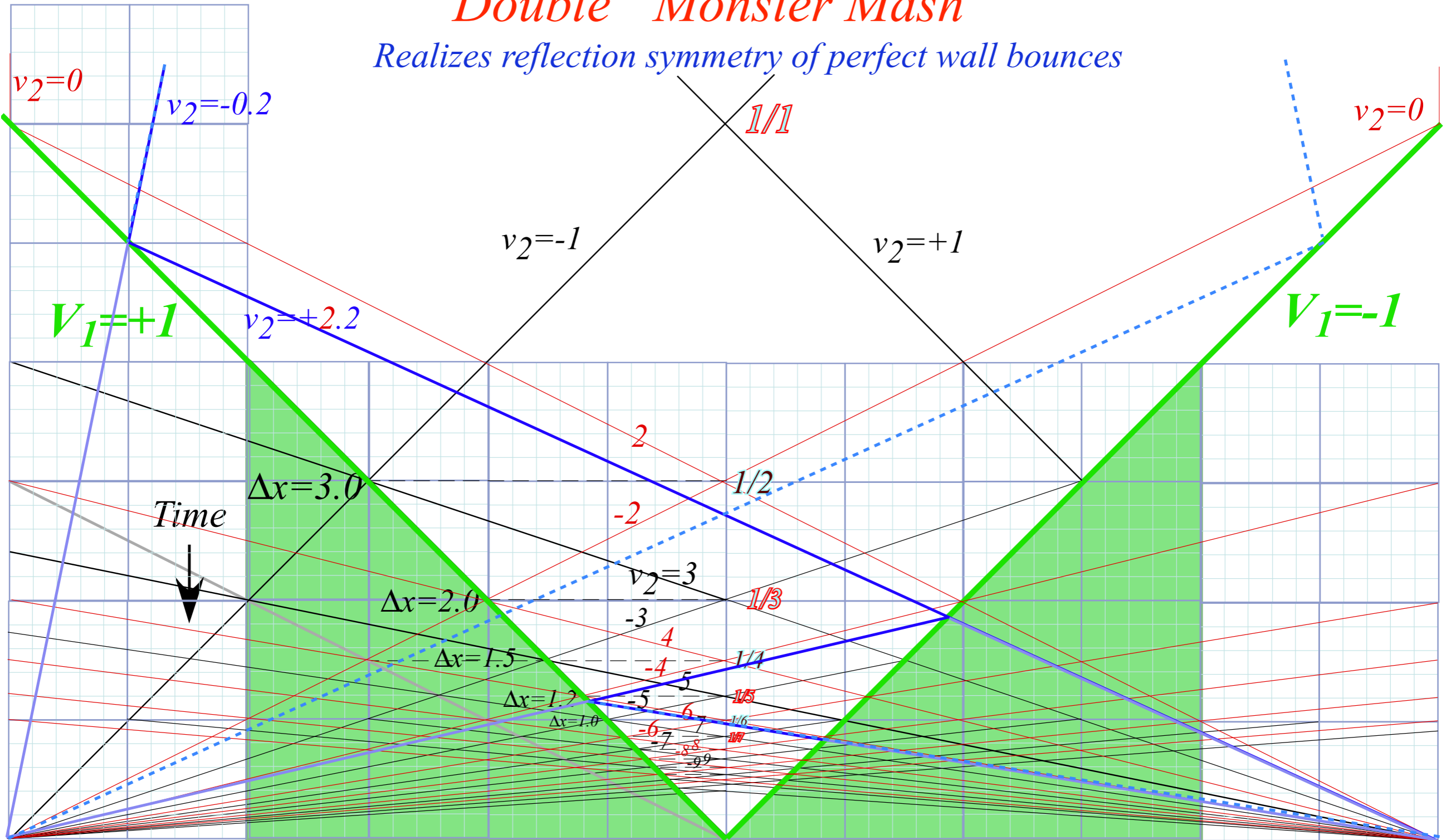


Fig. 5.5
Unit 1

See Homework problem 1.6.2: Construct related spacetime case

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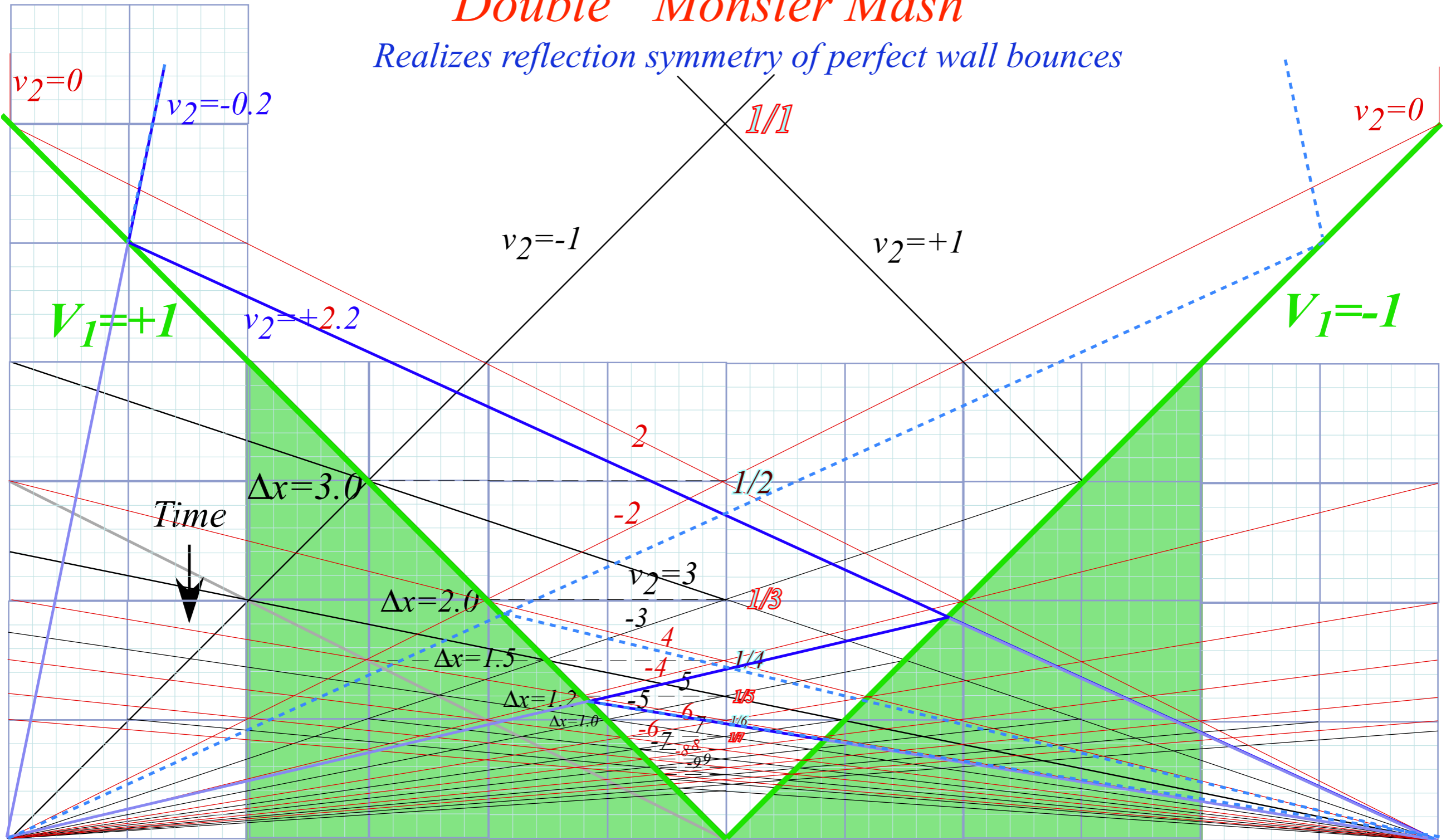


Fig. 5.5
Unit 1

See Homework problem 1.6.2: Construct related spacetime case

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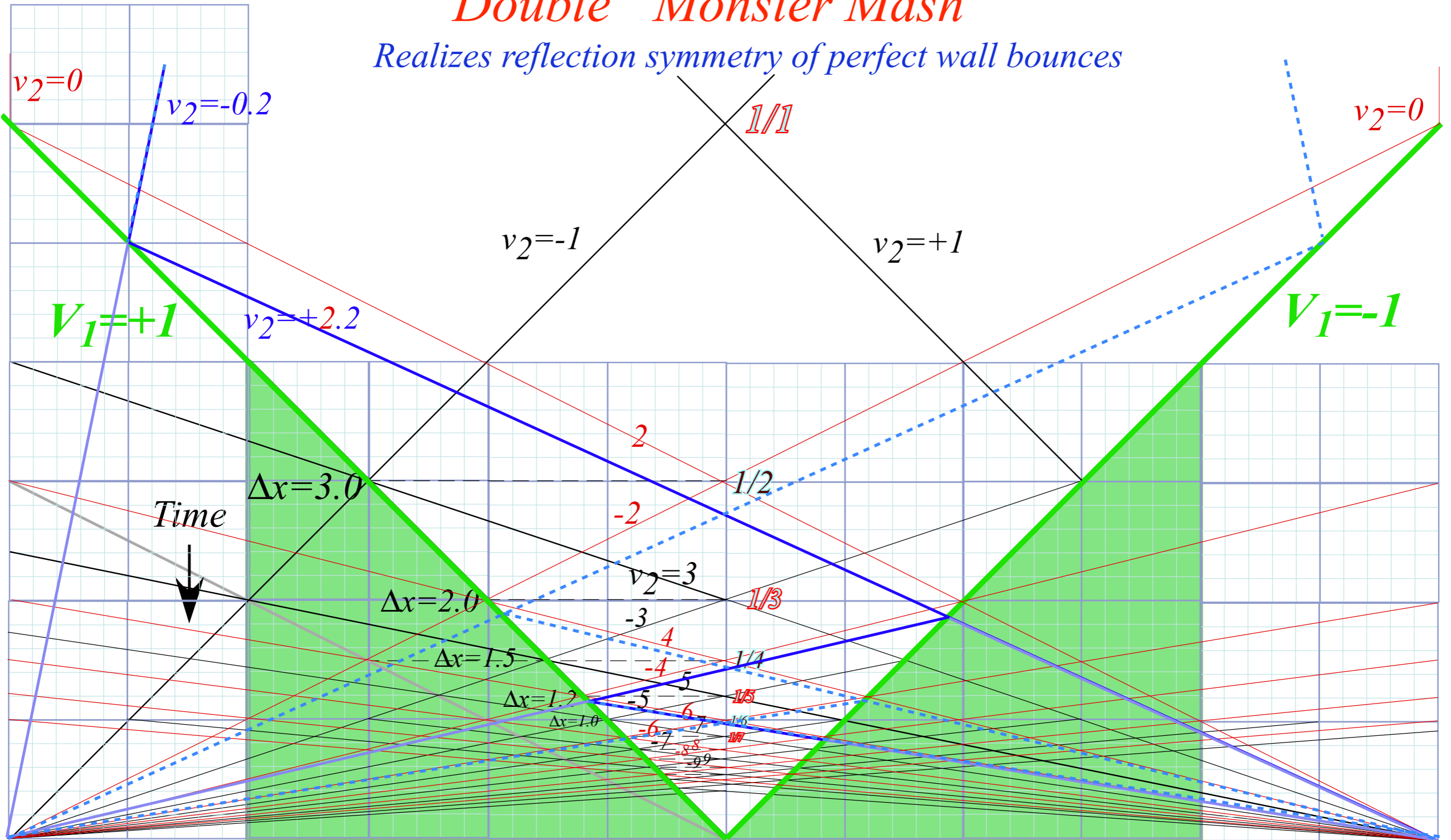
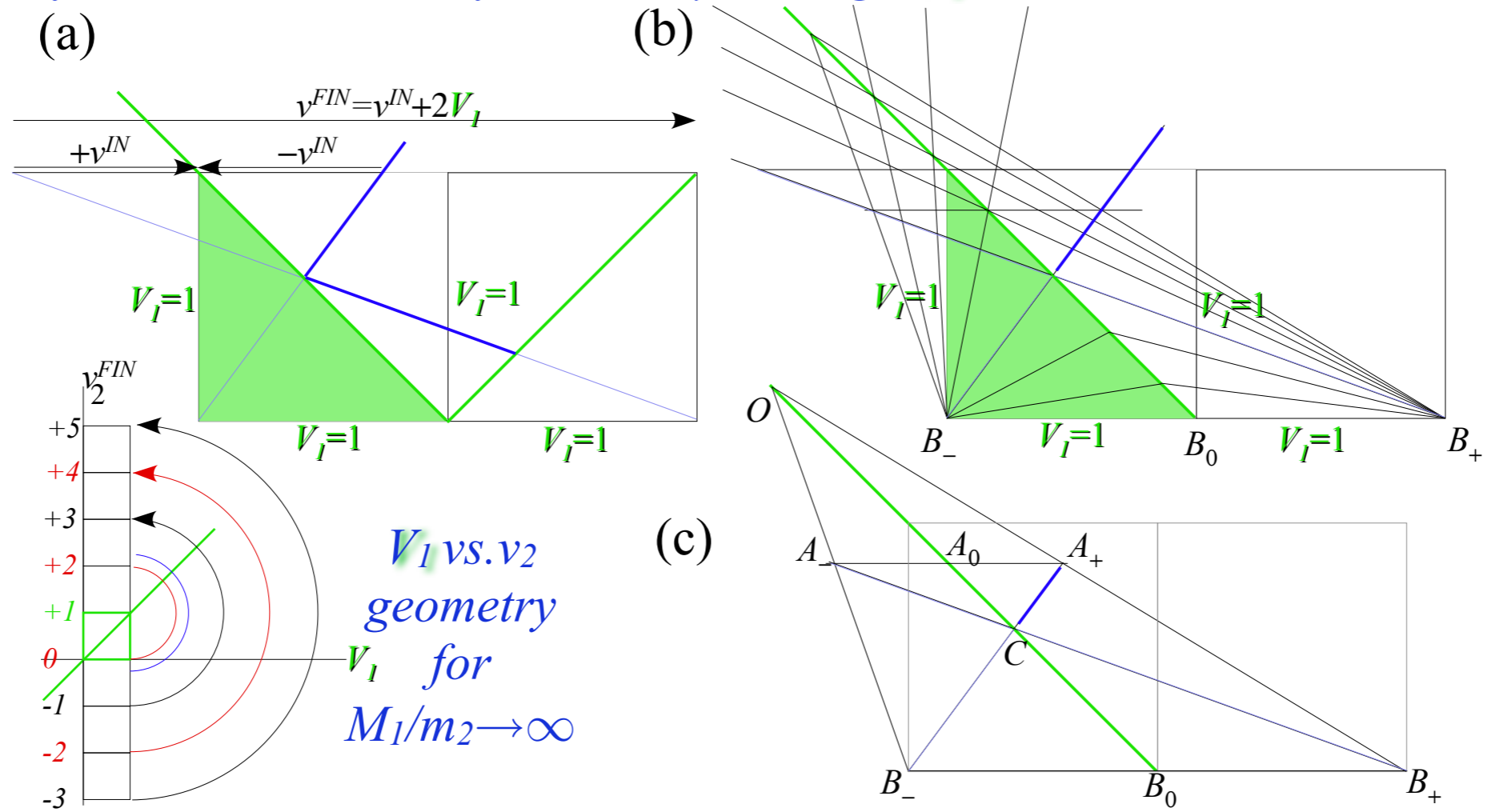


Fig. 5.5
Unit 1

Exercise 1.6.2: Construct similar spacetime case

Geometry of reflection $-v_2^{IN} \rightarrow +v_2^{IN}$ followed by adding $2V_1$ to $+v_2^{IN}$

Fig. 5.6
and
Fig. 5.7
Unit 1



V_1 vs. v_2
geometry
 V_I for
 $M_1/m_2 \rightarrow \infty$

(a) Galilean shift by $V=1$

