

AMOP Lecture 3.5
Tue 1.28-Thur 1.30.2014

Relativity of lightwaves and Lorentz-Minkowski coordinates IV.

(Ch. 0-3 of Unit 8)

5. *That “old-time” relativity (Circa 600BCE- 1905CE)*

(“Bouncing-photons” in smoke & mirrors and Thales, again)

The Ship and Lighthouse saga

Light-conic-sections make invariants

A politically incorrect analogy of rotational transformation and Lorentz transformation

The straight scoop on “angle” and “rapidity” (They’re area!)

*Galilean velocity addition becomes **rapidity** addition*

Introducing the “Sin-Tan Rosetta Stone” (Thanks, Thales!)

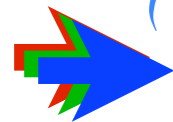
*Introducing the **stellar aberration angle** σ vs. **rapidity** ρ*

How Minkowski’s space-time graphs help visualize relativity

Group vs. phase velocity and tangent contacts

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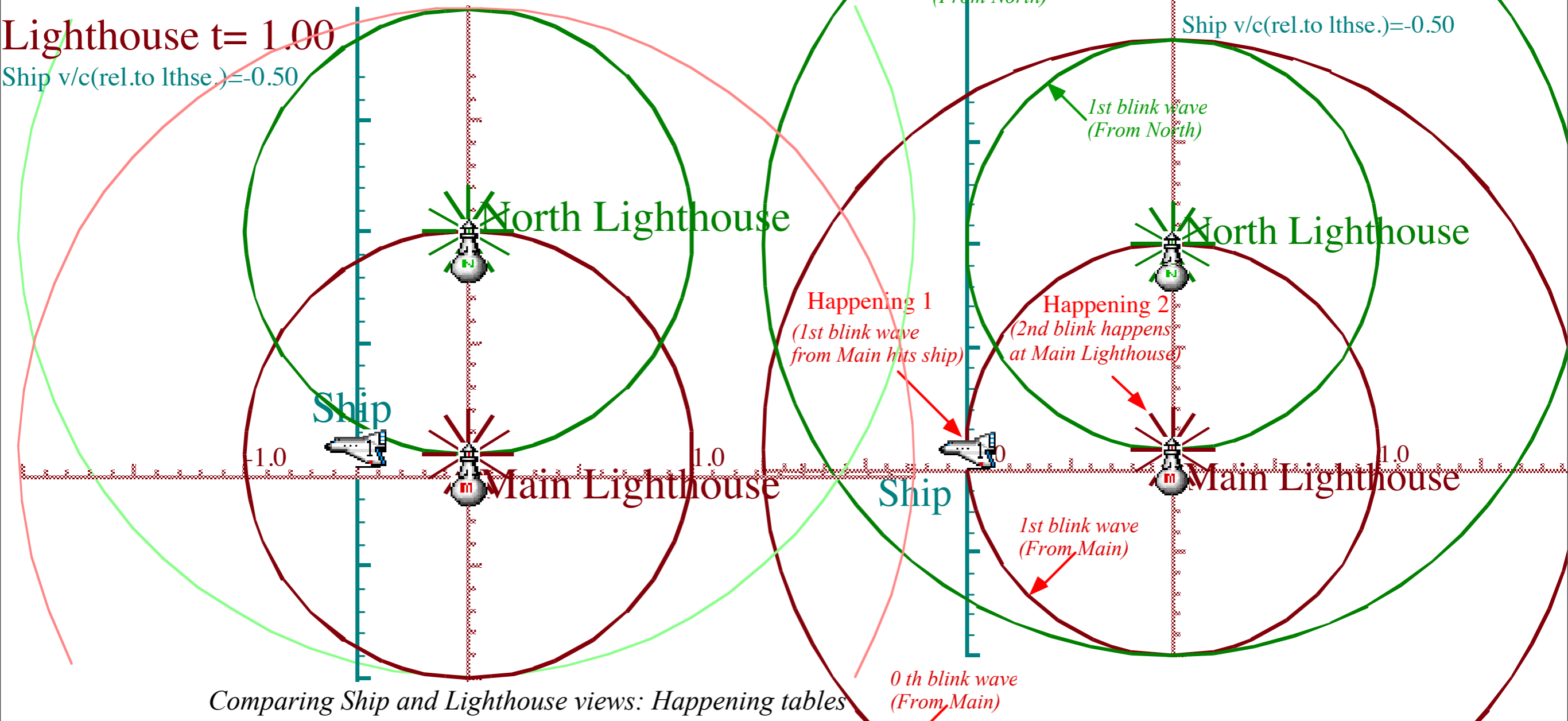
How Minkowski’s space-time graphs help visualize relativity

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Lighthouse $t = 1.00$

Ship $v/c(\text{rel. to lthse.}) = -0.50$

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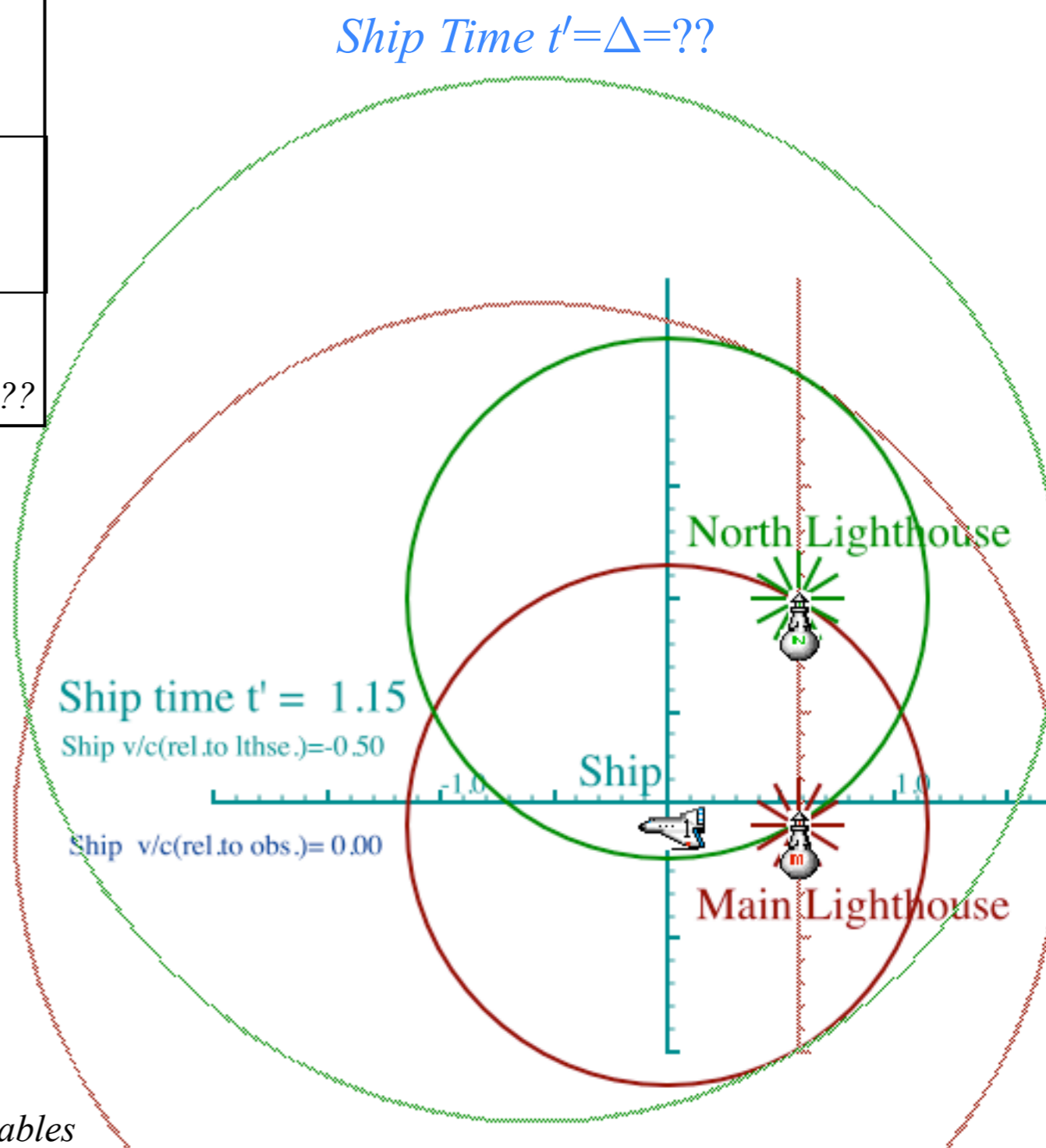
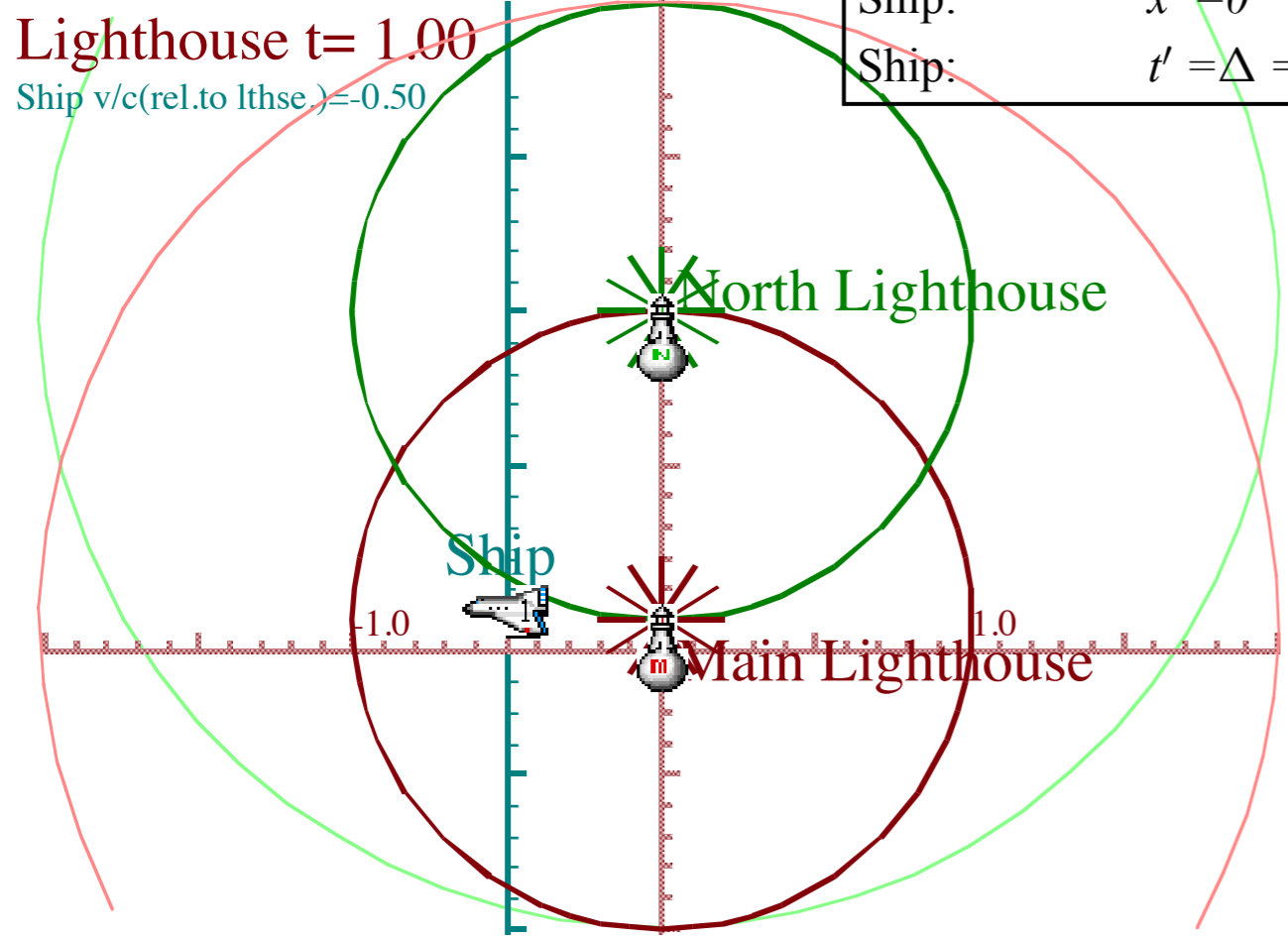
Comparing Ship and Lighthouse views: Happening tables

Happening 0: Ship passes Main Lighthouse.	Happening 1: Ship gets hit by first blink from Main Lighthouse.	Happening 2: Main Lighthouse blinks second time.
(Lighthouse space) $x = 0$	$x = -1.00 c$	$x = 0$
(Lighthouse time) $t = 0$	$t = 2.00$	$t = 2.00$
(Ship space) $x' = 0$	$x' = 0$	$x' = c \Delta$
(Ship time) $t' = 0$	$t' = 1.75$	$t' = 2\Delta = 2.30$

Fig. 2.A.3 Happening 1 (1st blink hits ship) and 2 (2nd blink at Main) both happen at $t=2$.

The ship and lighthouse saga

Happening 0.5: Main Lite blinks first time.	
Lighthouse:	$x = 0$
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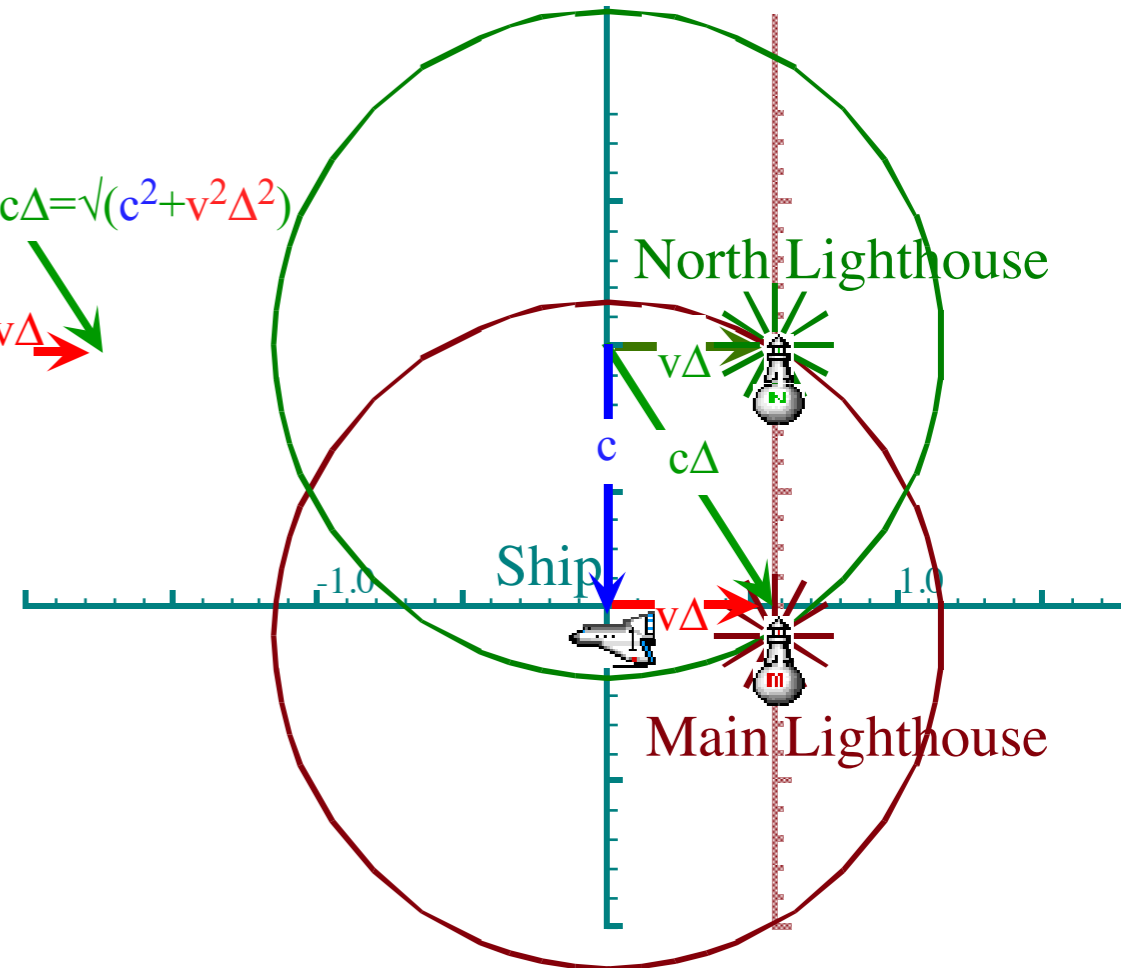
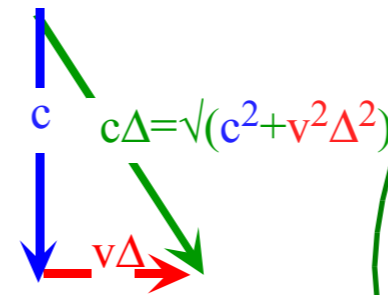
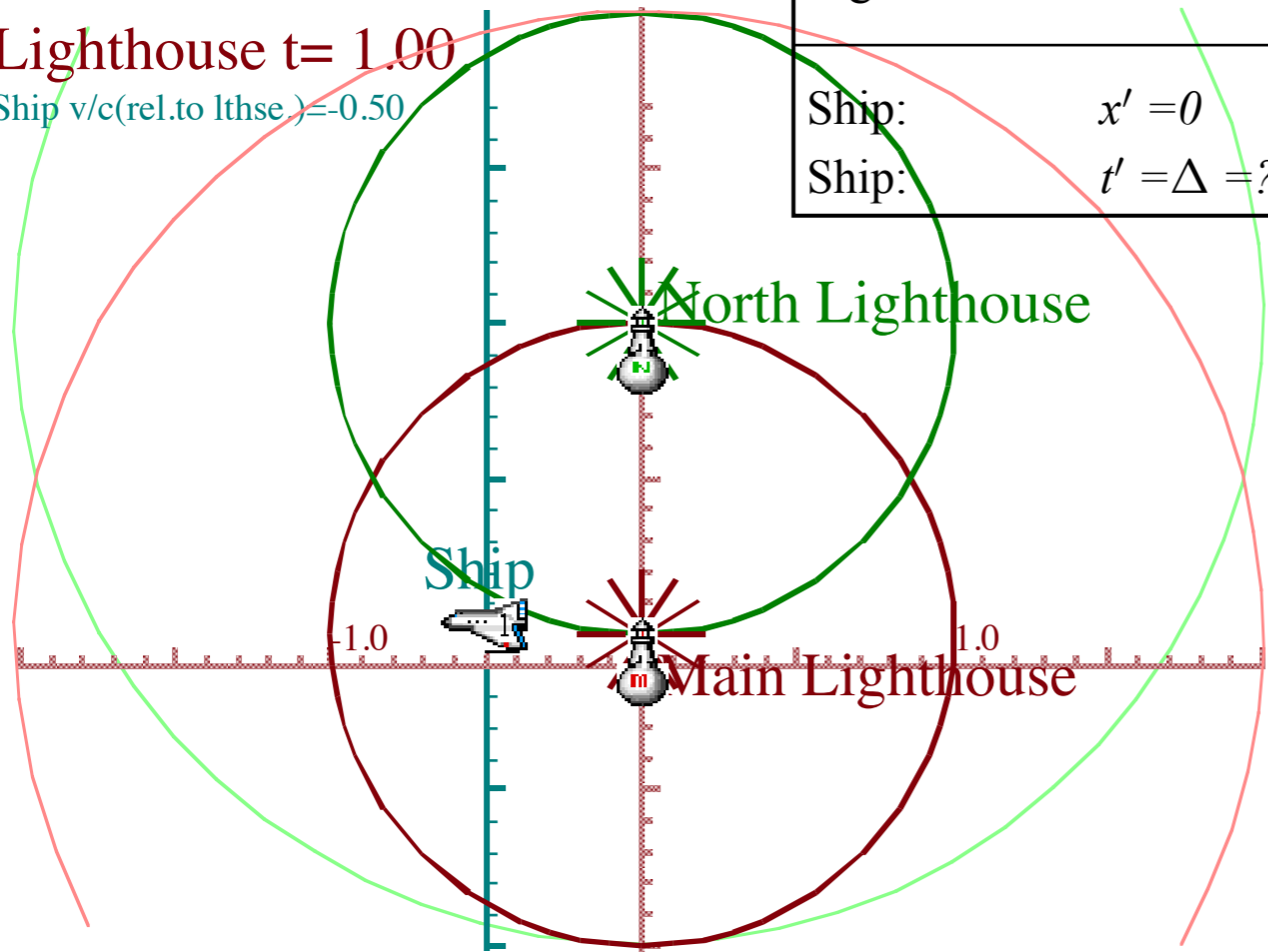
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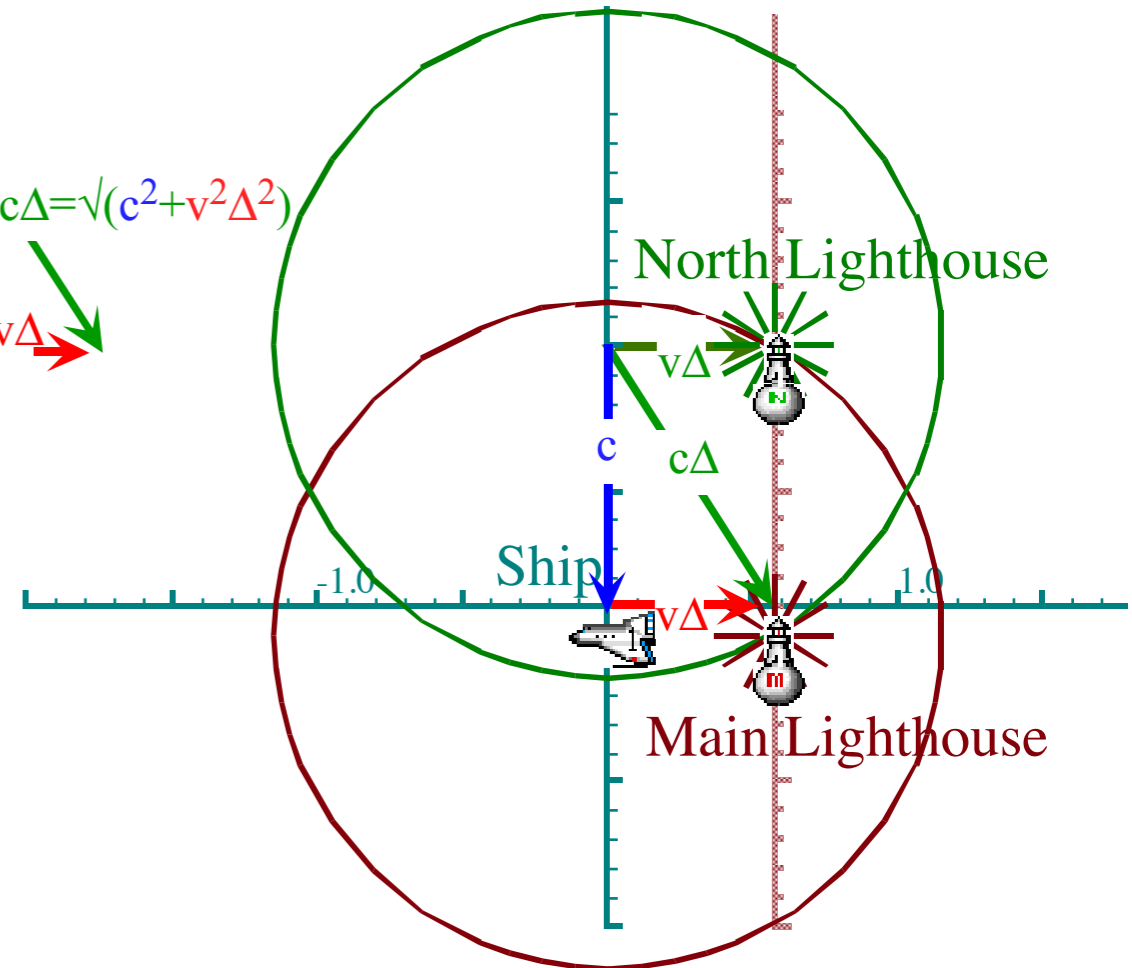
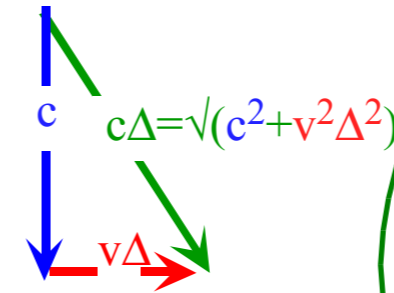
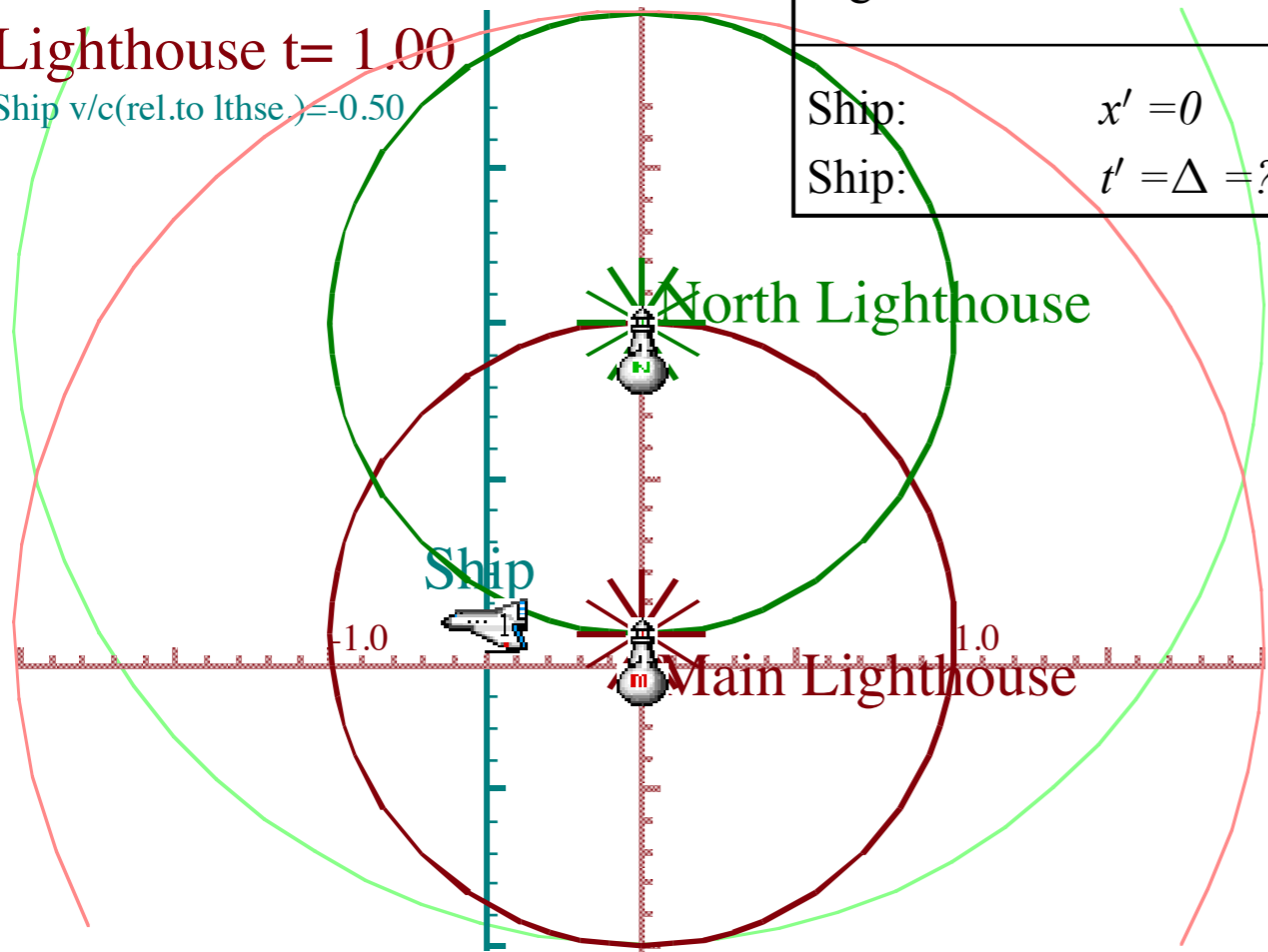
Ship Time $t' = \Delta = ???$

$$c^2 \Delta^2 = c^2 + v^2 \Delta^2$$

$$(c^2 - v^2) \Delta^2 = c^2$$

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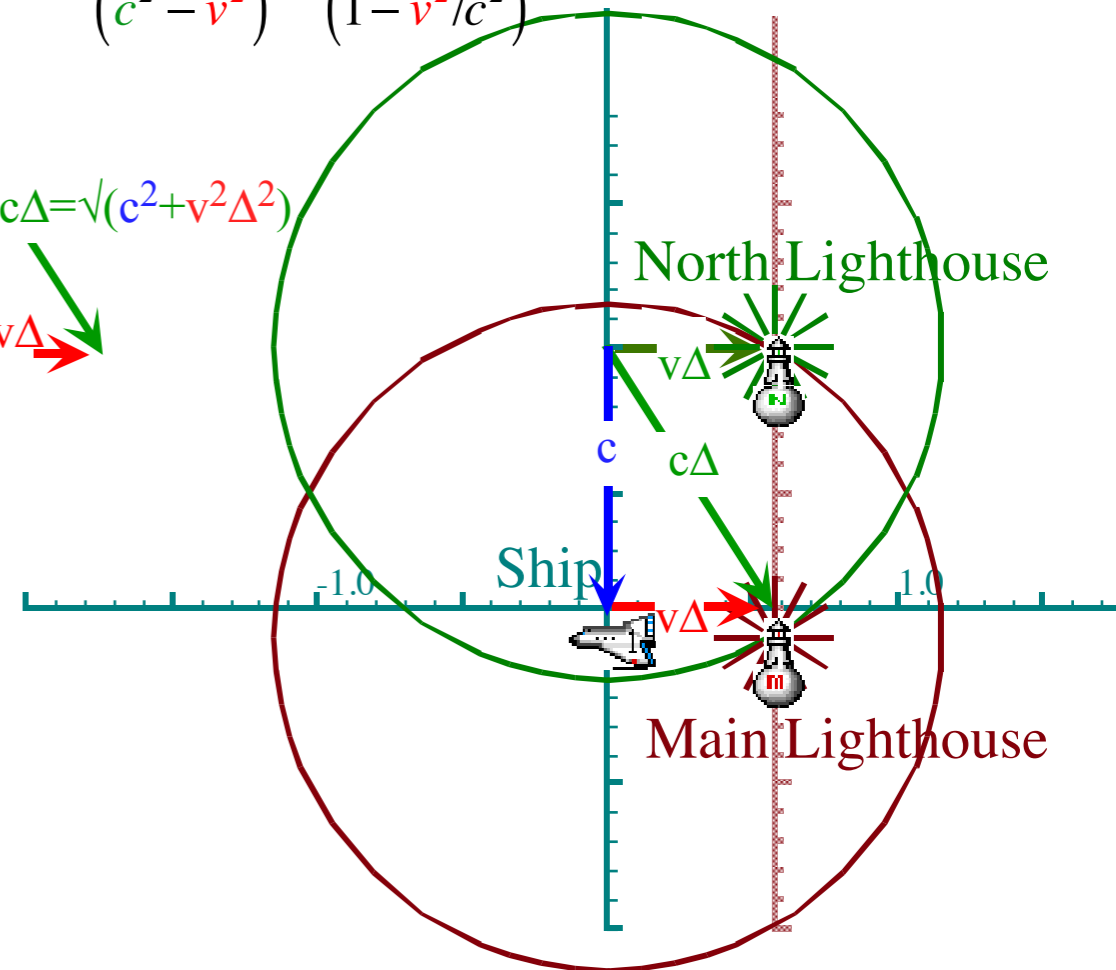
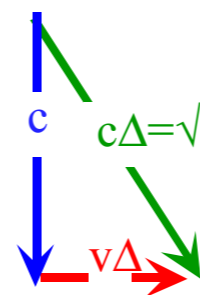
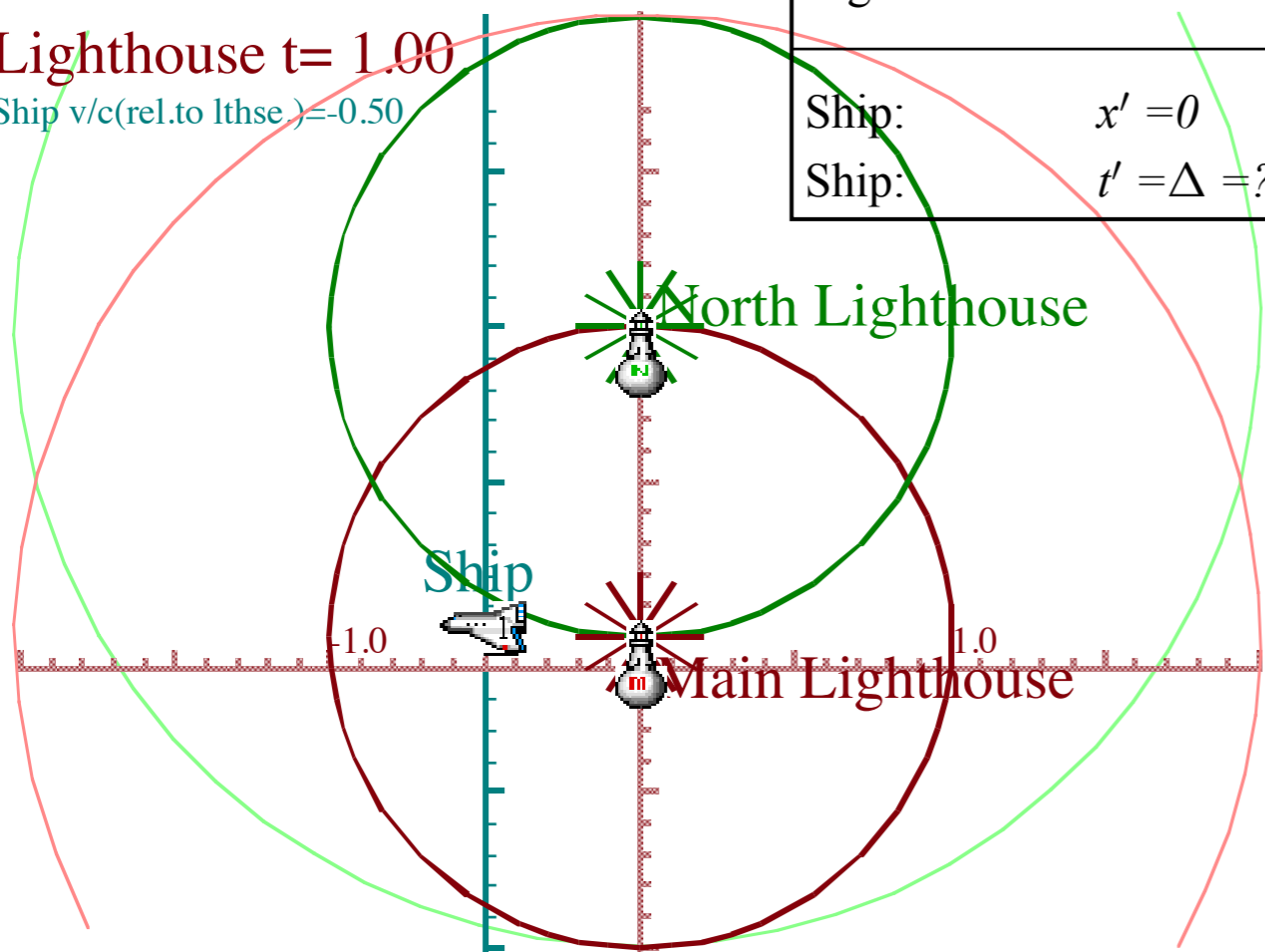
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$$\Delta^2 = \frac{c^2}{(c^2 - v^2)} = \frac{1}{(1 - v^2/c^2)}$$

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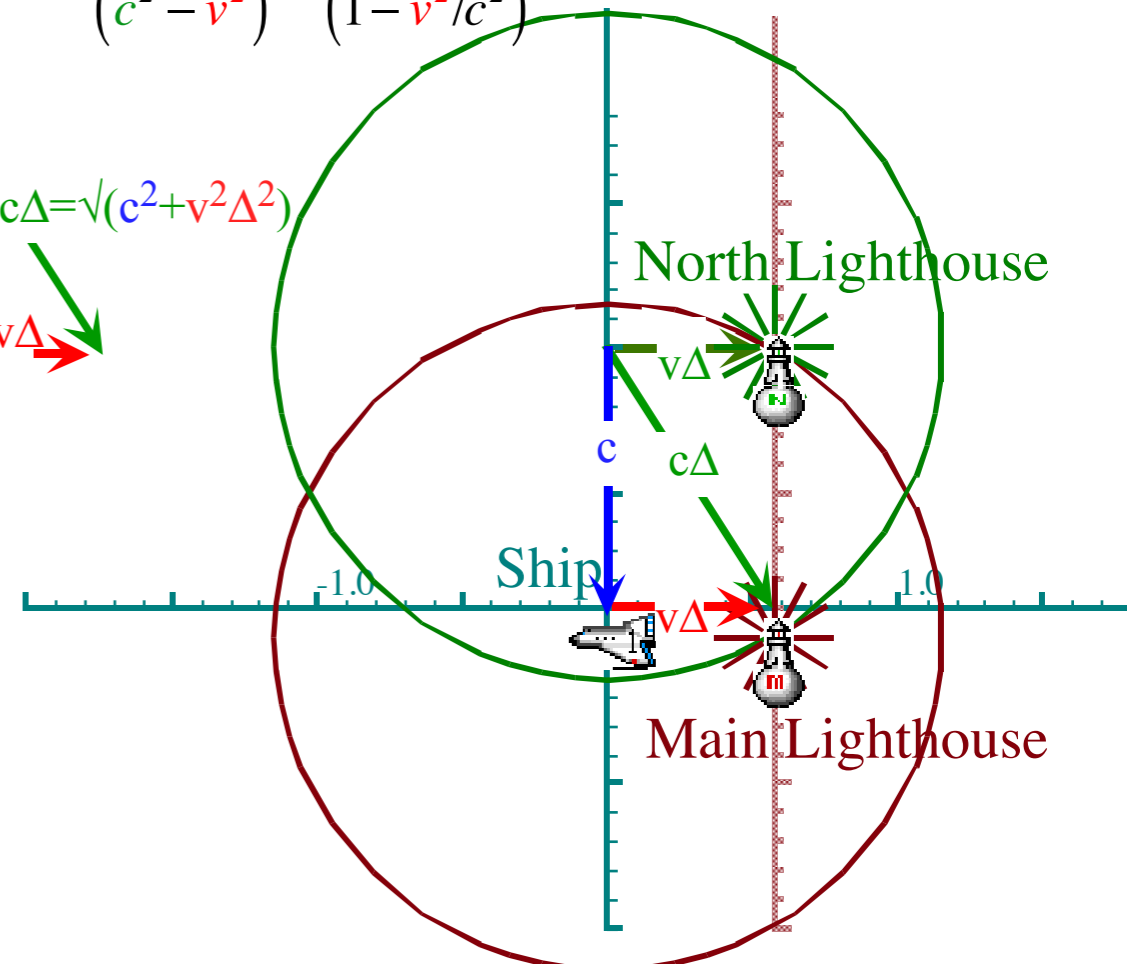
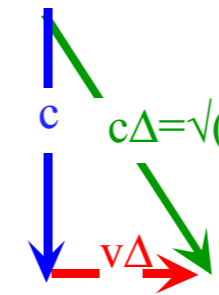
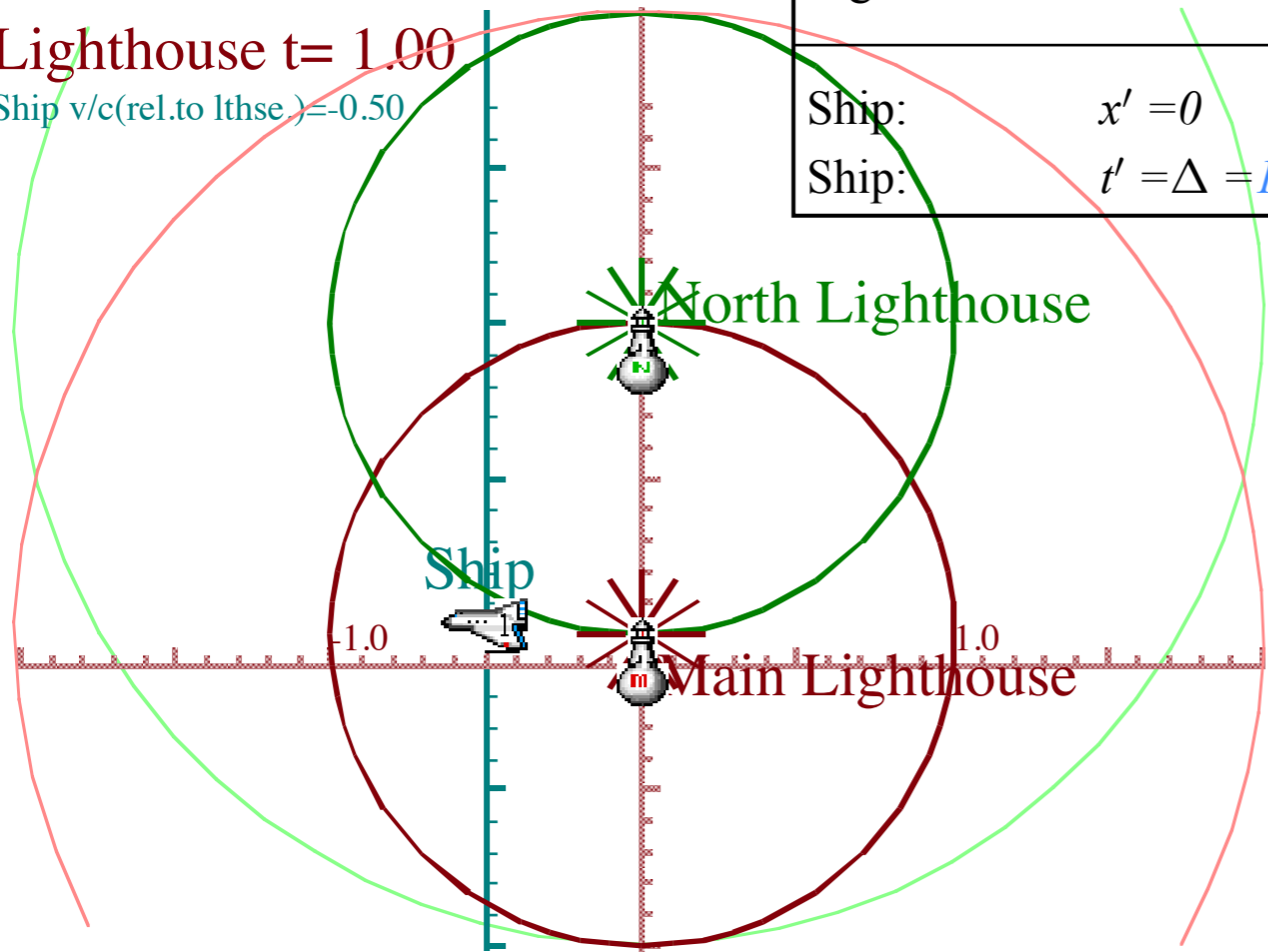
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$$\Delta = 1/\sqrt{1-1/4} = 2/\sqrt{3} = 1.15..$$

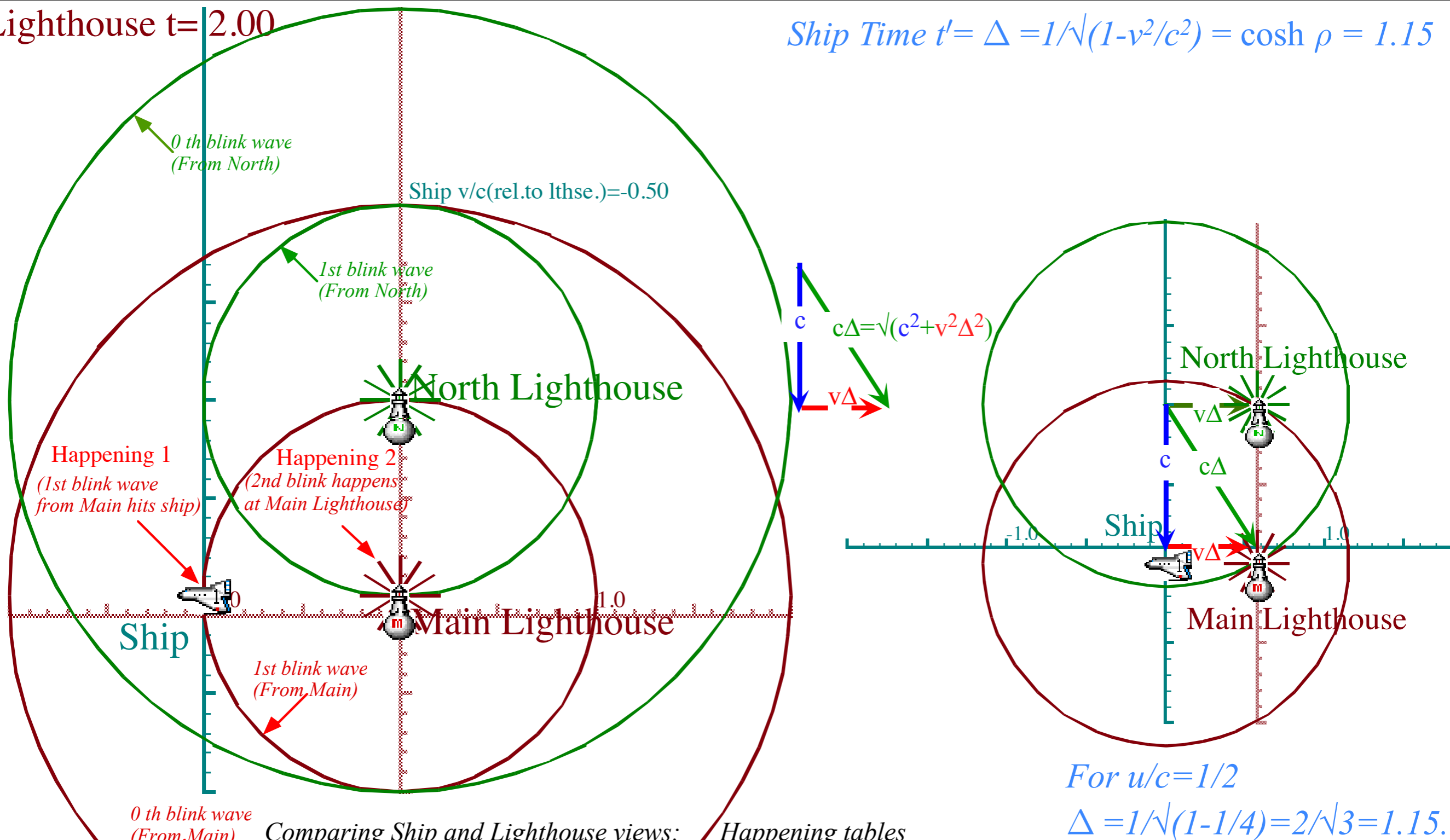
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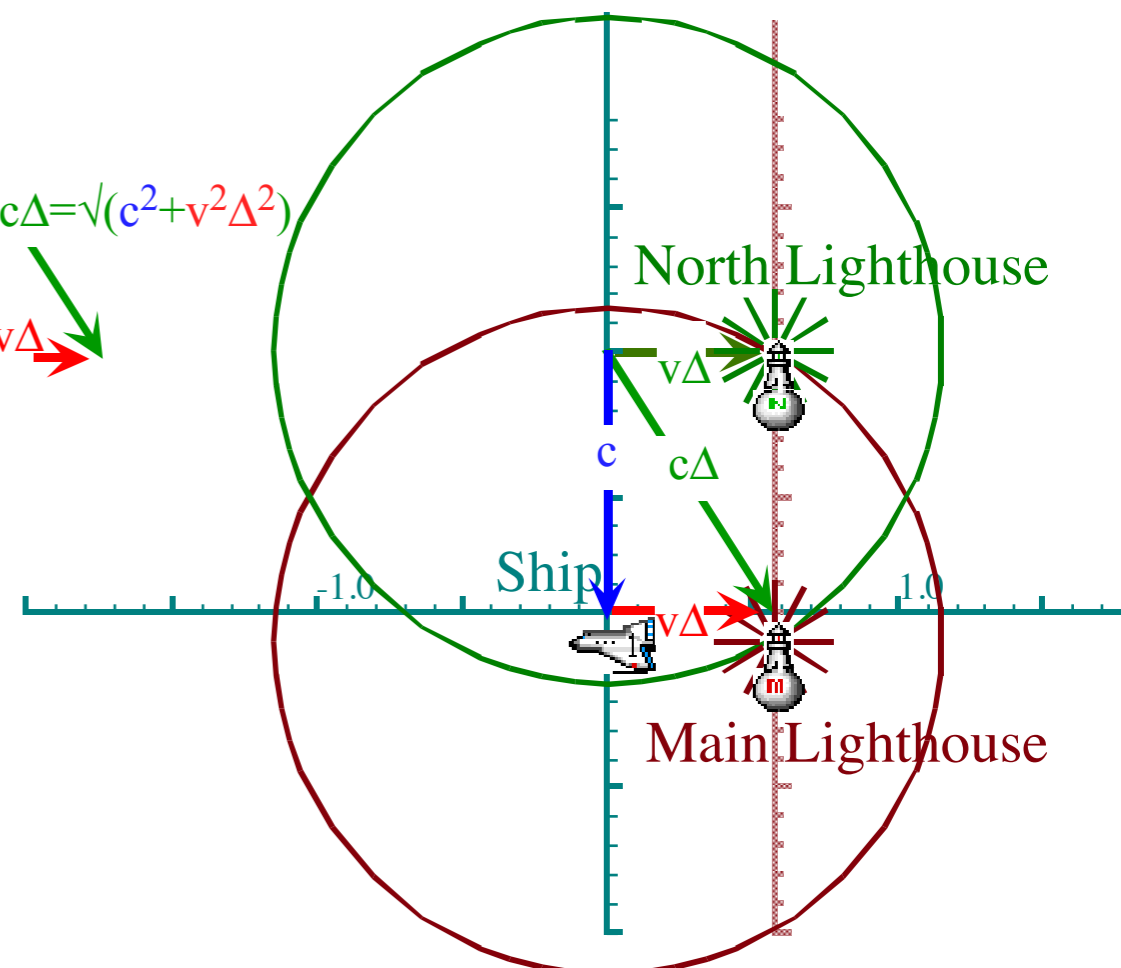
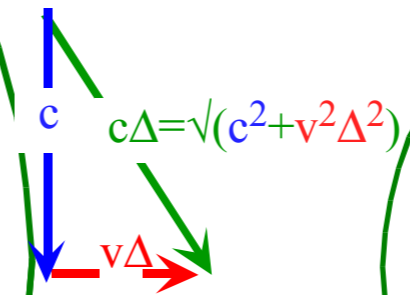
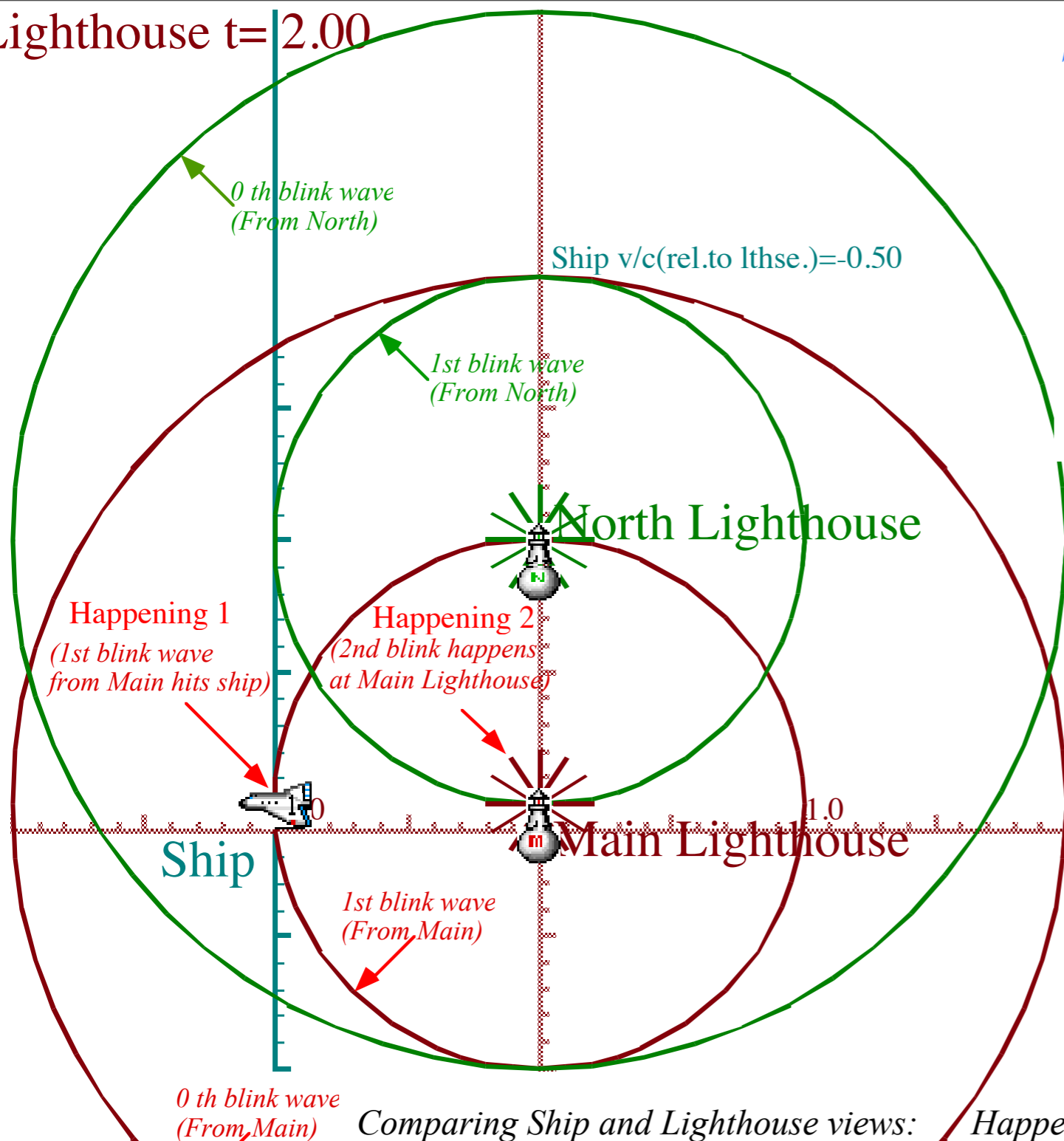
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(Ship space) $x' = 0$	$x' = 0$	$x' = 2v\Delta$
(Ship time) $t' = 0$	$t' = (v+c)\Delta/c$	$t' = 2\Delta$

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Lecture 24 ended here

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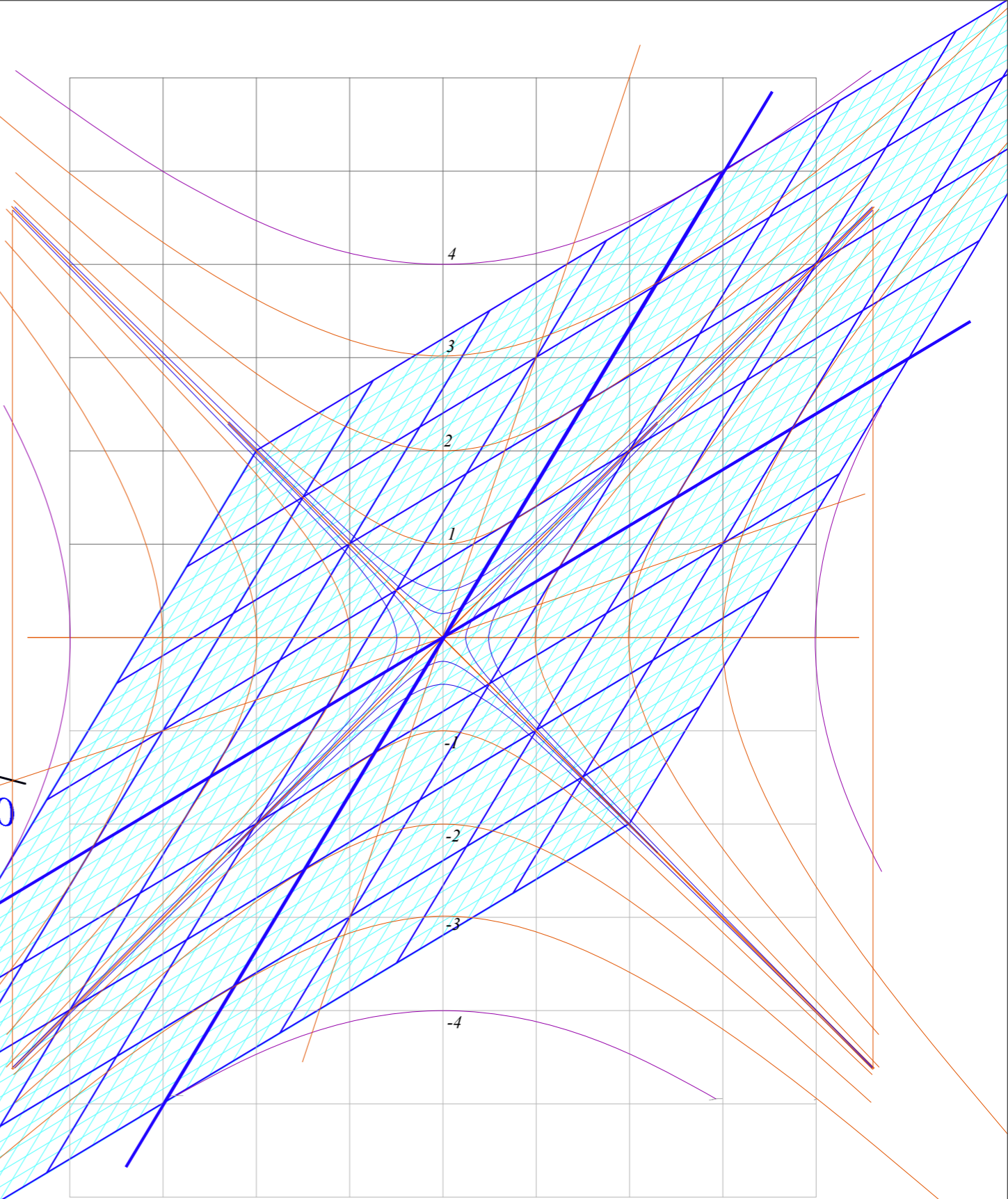
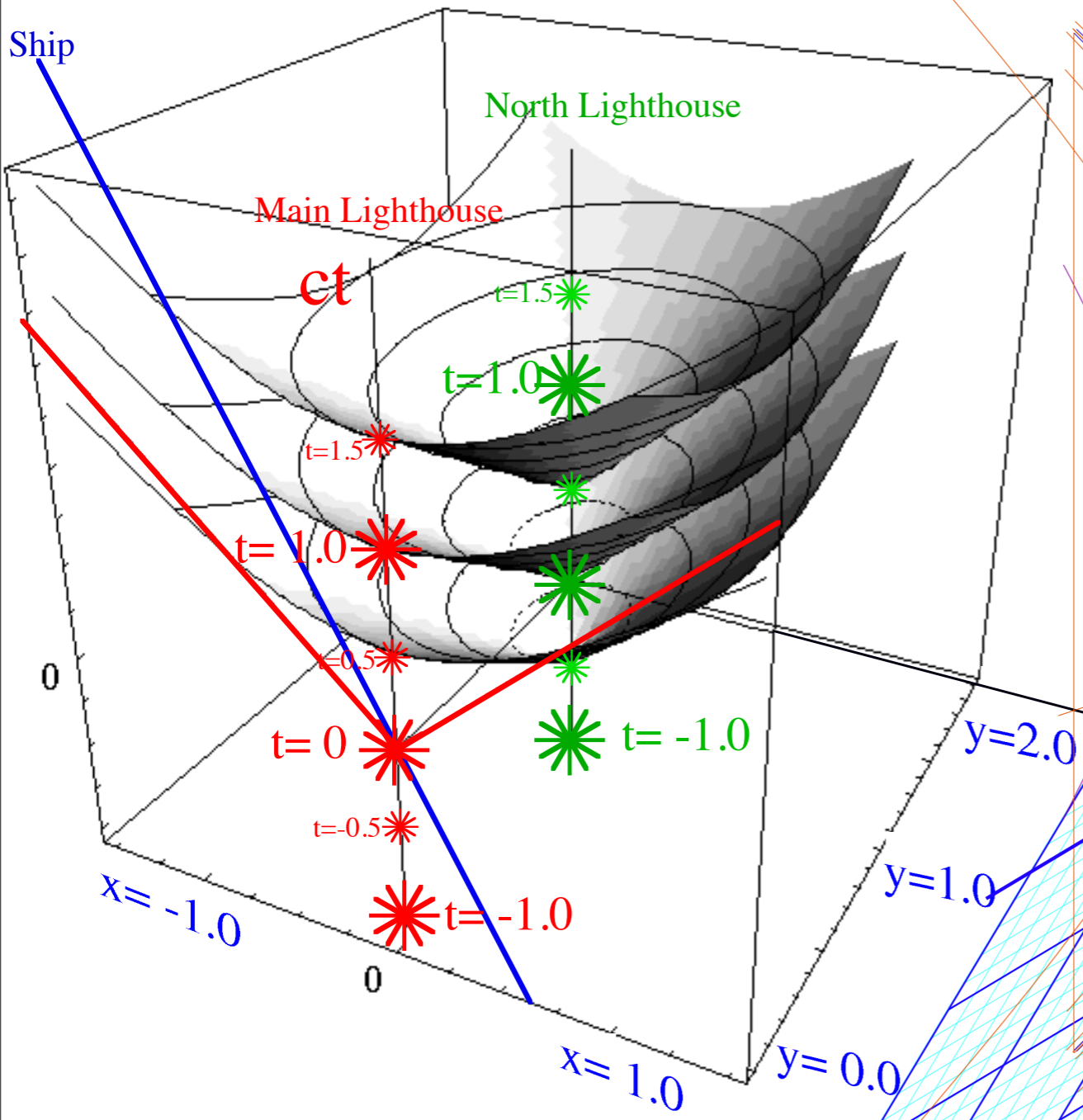


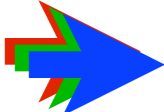
Fig. 2.B.5 Space-Space-Time plot of world lines for Lighthouses. North Lighthouse blink waves trace light cones.

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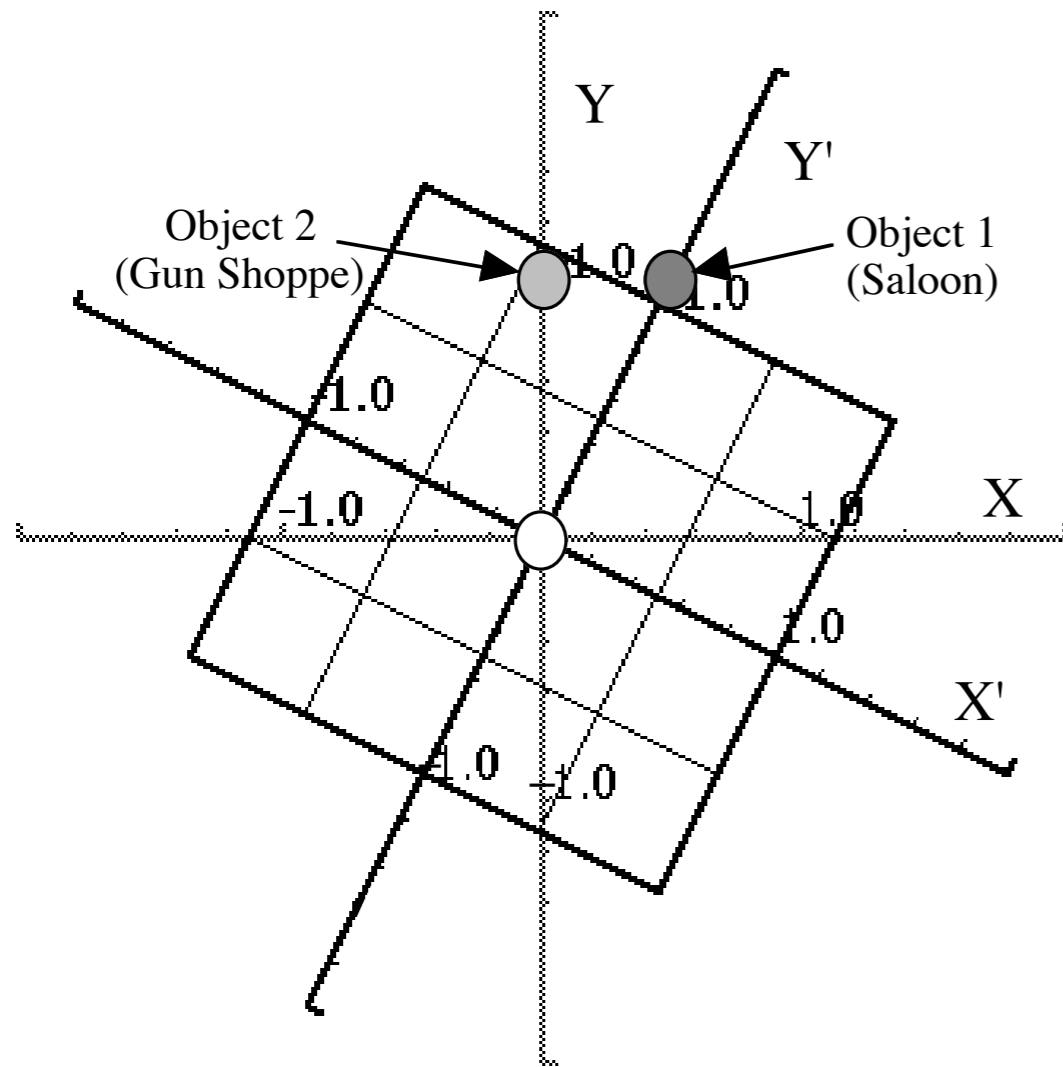
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Fig. 2.B.1 Town map according to a "tipsy" surveyor.

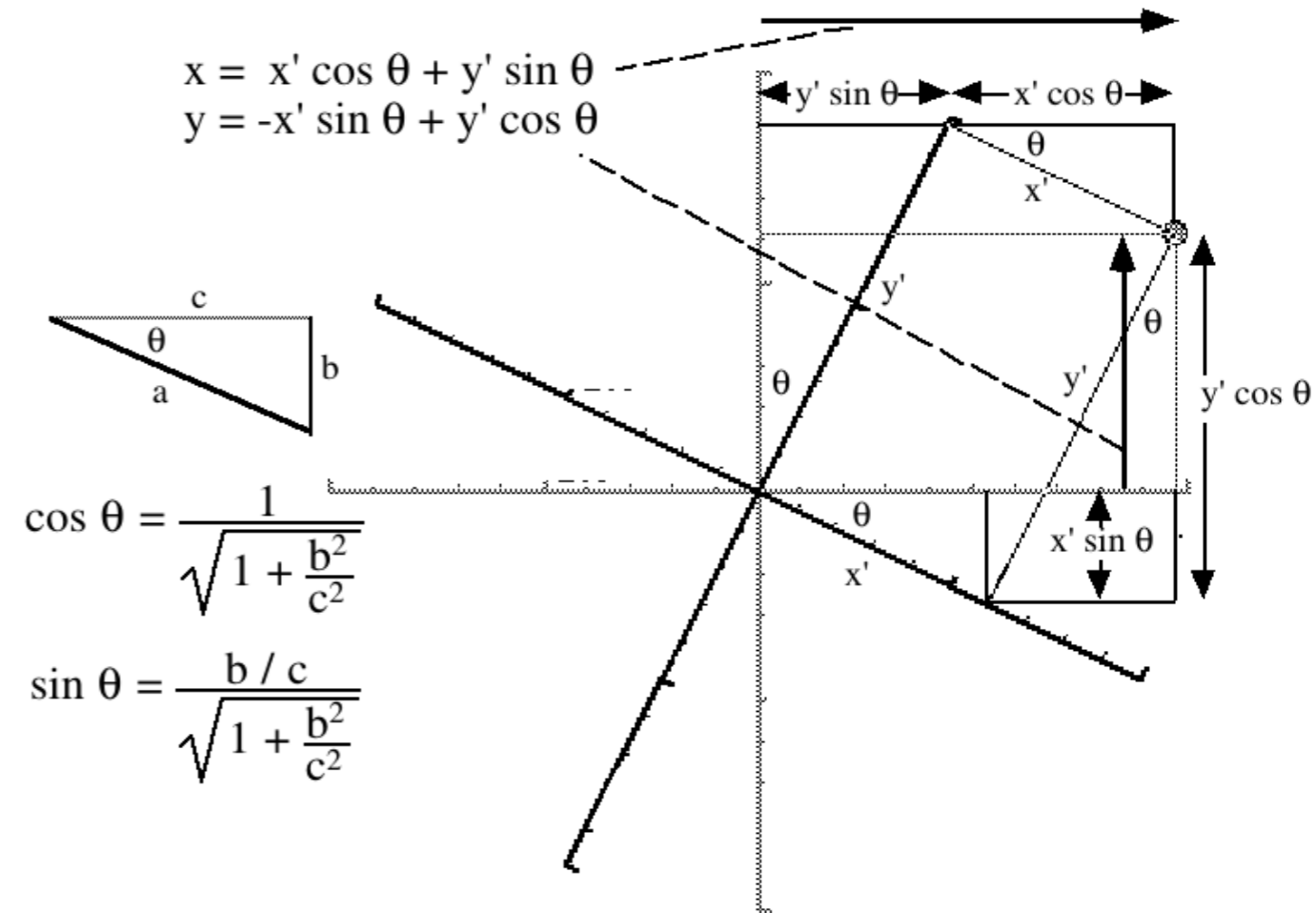
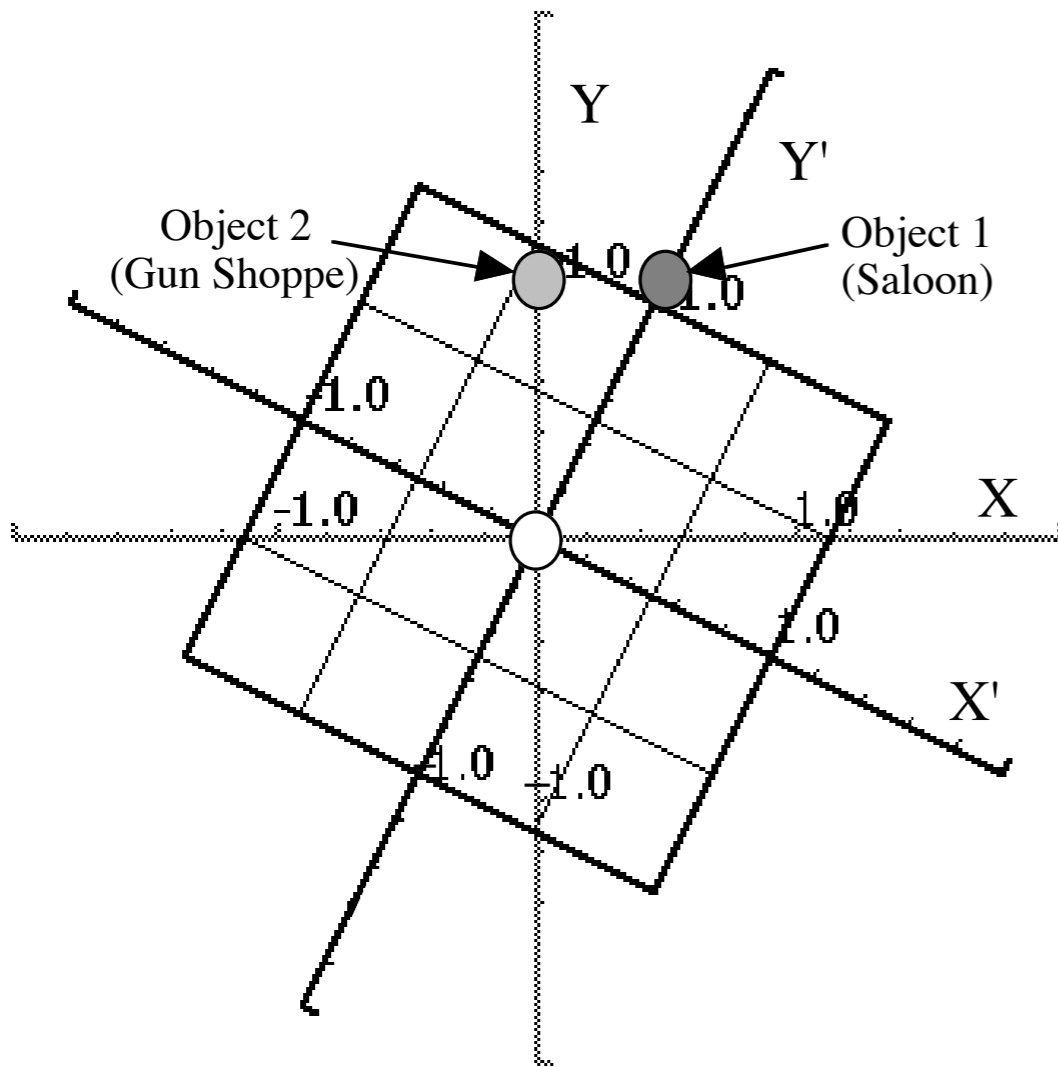


Object 0: Town Square.	Object 1: Saloon.	Object 2: Gun Shoppe.
<i>(US surveyor)</i> $x = 0$ $y = 0$	$x = 0.5$ $y = 1.0$	$x = 0$ $y = 1.0$
<i>(French surveyor)</i> $x' = 0$ $y' = 0$	$x' = 0$ $y' = 1.1$	$x' = -0.45$ $y' = 0.89$

A politically incorrect analogy of rotational transformation and Lorentz transformation

Fig. 2.B.1 Town map according to a "tipsy" surveyor.

Fig. 2.B.2 Diagram and formulas for reconciliation of the two surveyor's data.



$$\cos \theta = \frac{1}{\sqrt{1 + \frac{b^2}{c^2}}}$$

$$\sin \theta = \frac{b/c}{\sqrt{1 + \frac{b^2}{c^2}}}$$

$$x' = x \cos \theta - y \sin \theta = \frac{x}{\sqrt{1 + \frac{b^2}{c^2}}} + \frac{-(b/c)y}{\sqrt{1 + \frac{b^2}{c^2}}}$$

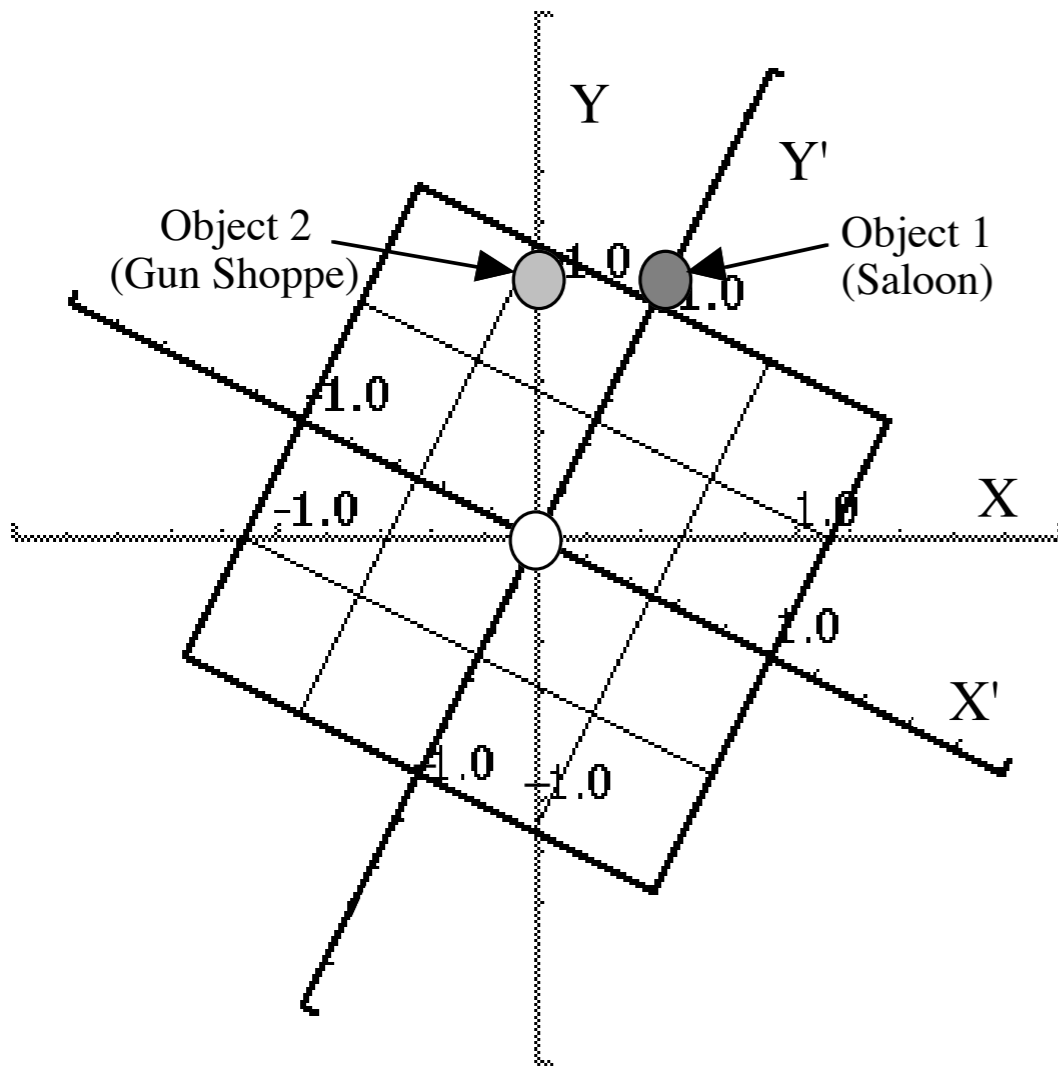
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(2nd surveyor)		
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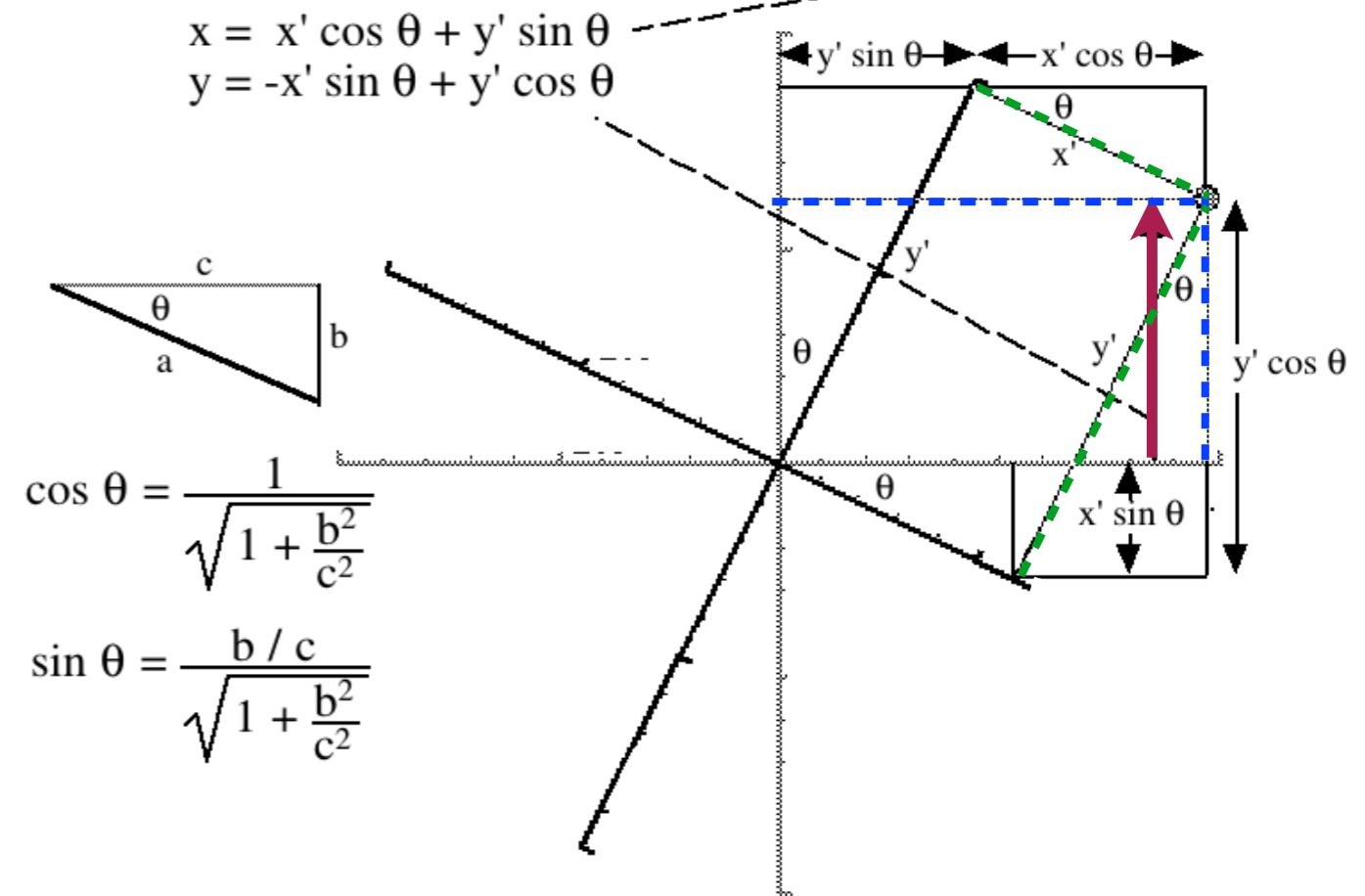
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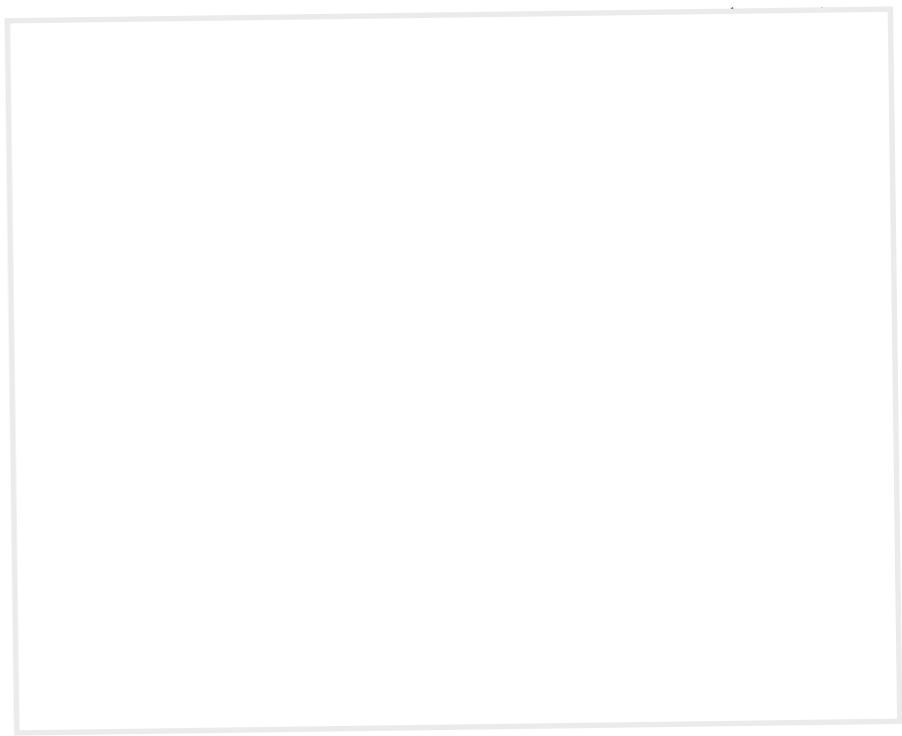
Fig. 2.B.2 Diagram and formulas for reconciliation of the two surveyor's data.



Reminder: Component-based derivation is clumsy!



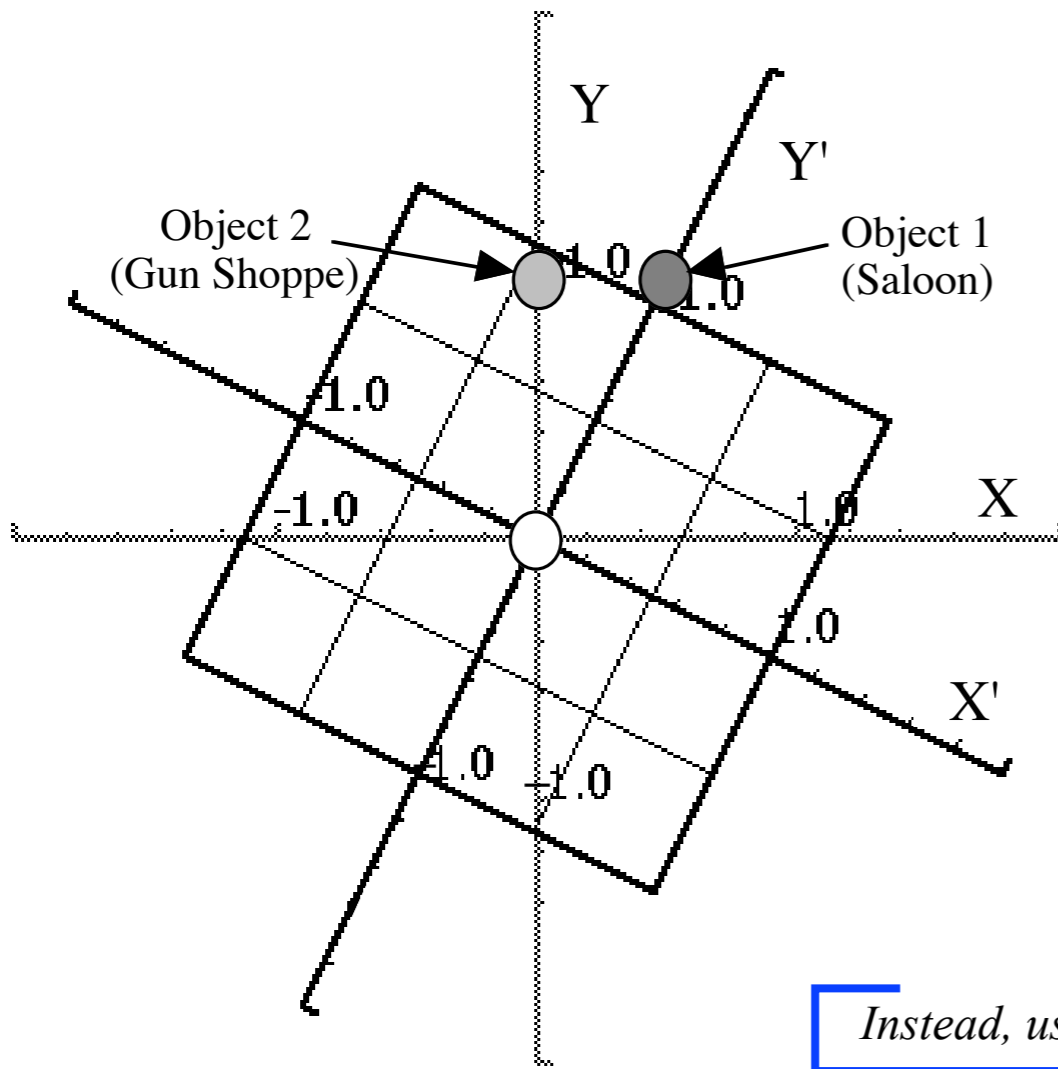
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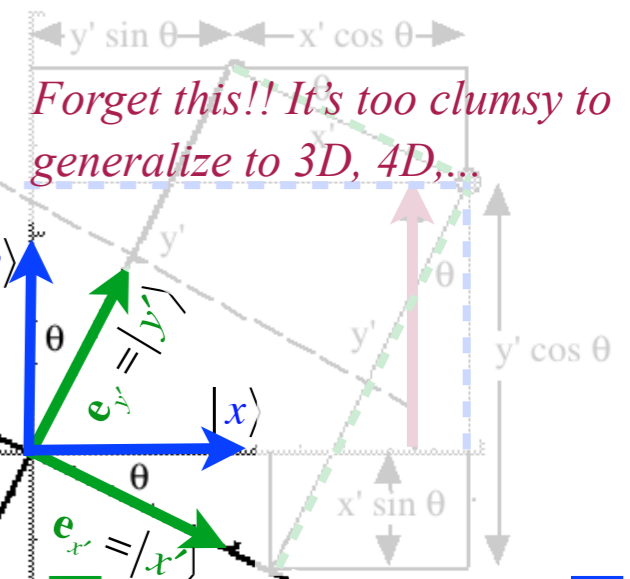
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Reminder: Component-based derivation is clumsy!

$$x = x' \cos \theta + y' \sin \theta$$

$$y = -x' \sin \theta + y' \cos \theta$$



Forget this!! It's too clumsy to generalize to 3D, 4D,...

$$\cos \theta = \frac{1}{\sqrt{1 + \frac{b^2}{c^2}}}$$

$$\sin \theta = \frac{b/c}{\sqrt{1 + \frac{b^2}{c^2}}}$$

Instead, use Dirac unit vectors $|x\rangle, |y\rangle$ and $|x'\rangle, |y'\rangle$

$$e_{x'} = |x'\rangle = \cos \theta |x\rangle - \sin \theta |y\rangle$$

$$e_{y'} = |y'\rangle = \sin \theta |x\rangle + \cos \theta |y\rangle$$

or the inverse relation:

$$e_x = |x\rangle = \cos \theta |x'\rangle + \sin \theta |y'\rangle$$

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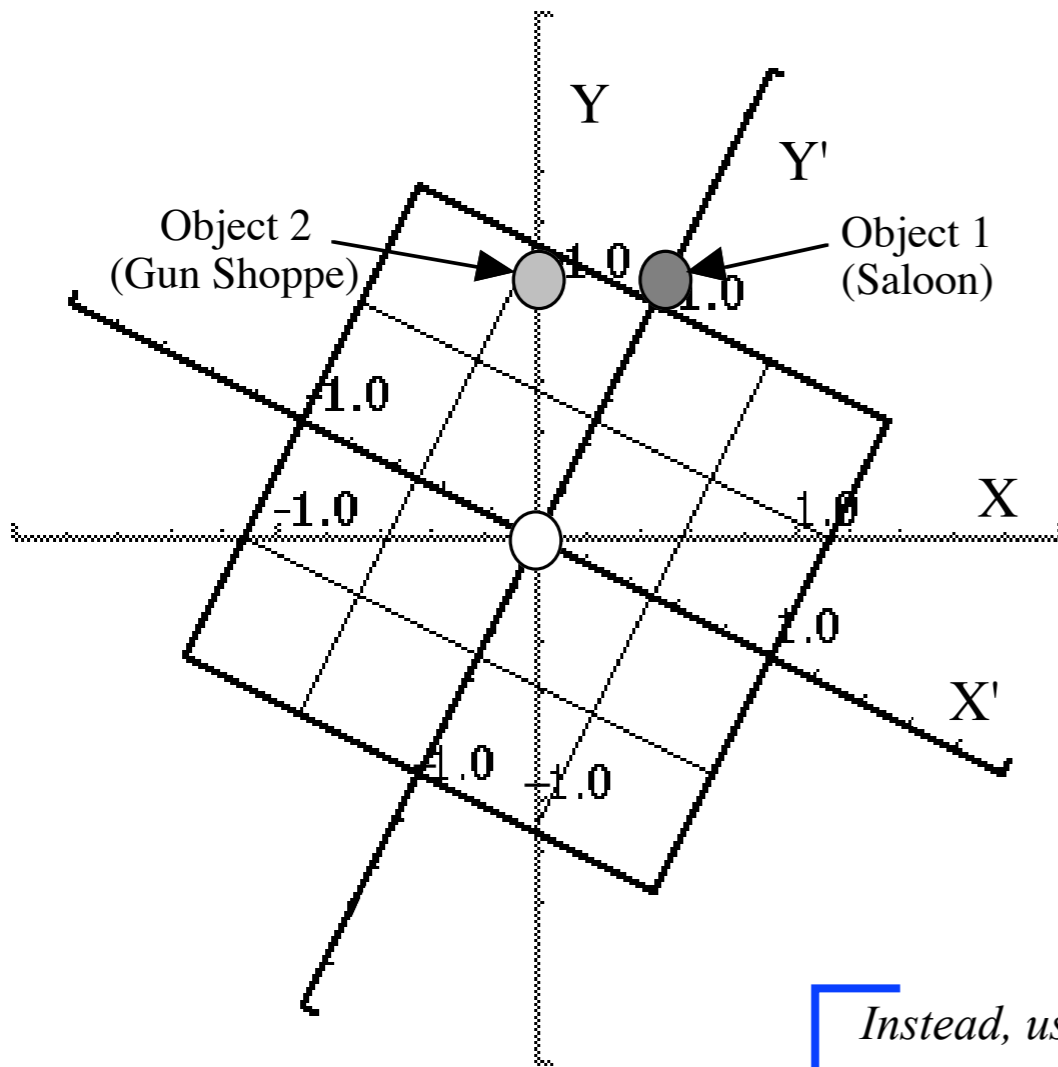


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You may apply (Jacobian) transform matrix:

$$\begin{pmatrix} \langle x|x'\rangle & \langle x|y'\rangle \\ \langle y|x'\rangle & \langle y|y'\rangle \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

or the inverse (Kajobian) transformation:

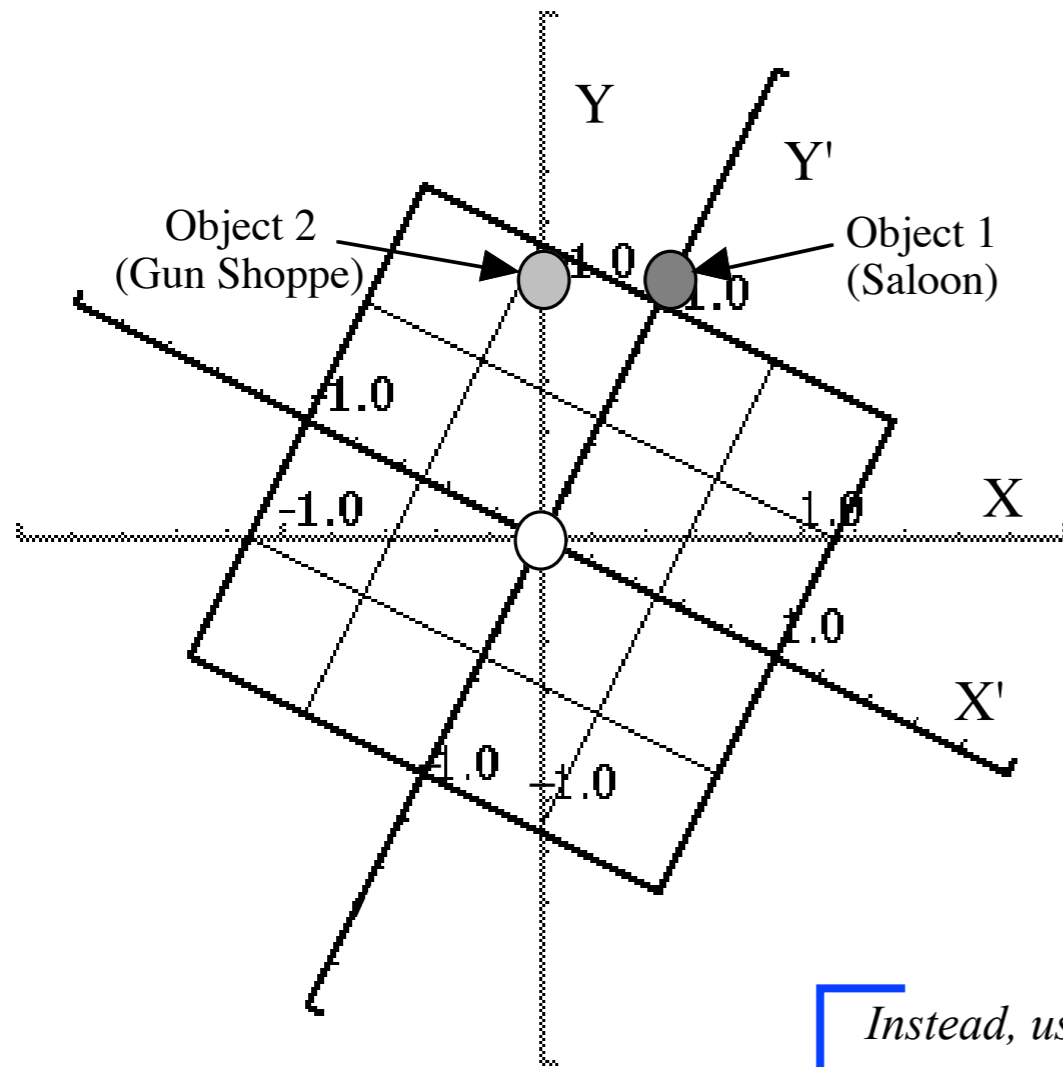
$$\begin{pmatrix} \langle x'|x\rangle & \langle x'|y\rangle \\ \langle y'|x\rangle & \langle y'|y\rangle \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

to any vector $\mathbf{V} = |V\rangle = |x\rangle \langle x|V\rangle + |y\rangle \langle y|V\rangle$
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A politically incorrect analogy of rotational transformation and Lorentz transformation

Fig. 2.B.1 Town map according to a "tipsy" surveyor.

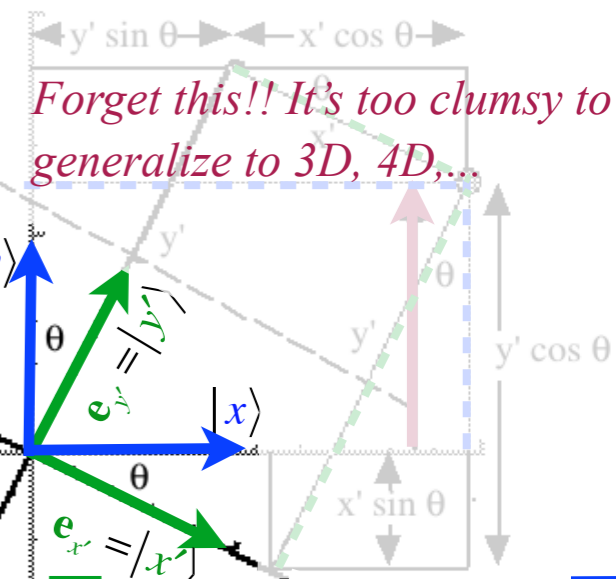
Fig. 2.B.2 Diagram and formulas for reconciliation of the two surveyor's data.



Reminder: Component-based derivation is clumsy!

$$x = x' \cos \theta + y' \sin \theta$$

$$y = -x' \sin \theta + y' \cos \theta$$



$$\cos \theta = \frac{1}{\sqrt{1 + \frac{b^2}{c^2}}}$$

$$\sin \theta = \frac{b/c}{\sqrt{1 + \frac{b^2}{c^2}}}$$

Instead, use Dirac unit vectors $|x\rangle, |y\rangle$ and $|x'\rangle, |y'\rangle$

$$e_{x'} = |x'\rangle = \cos \theta |x\rangle - \sin \theta |y\rangle$$

$$e_{y'} = |y'\rangle = \sin \theta |x\rangle + \cos \theta |y\rangle$$

or the inverse relation:

$$e_x = |x\rangle = \cos \theta |x'\rangle + \sin \theta |y'\rangle$$

$$e_y = |y\rangle = -\sin \theta |x'\rangle + \cos \theta |y'\rangle$$

Object 0: Town Square.	Object 1: Saloon.	Object 2: Gun Shoppe.
(US surveyor)	$x = 0$	$x = 0$
	$y = 0$	$y = 1.0$
(2nd surveyor)	$x' = 0$	$x' = -0.45$
	$y' = 0$	$y' = 0.89$

You may apply (Jacobian) transform matrix:

$$\begin{pmatrix} \langle x|x'\rangle & \langle x|y'\rangle \\ \langle y|x'\rangle & \langle y|y'\rangle \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

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 $= |x'\rangle \langle x'|V\rangle + |y'\rangle \langle y'|V\rangle$

(Jacobian) transformation $\{V_x V_y\}$ from $\{V_{x'} V_{y'}\}$:

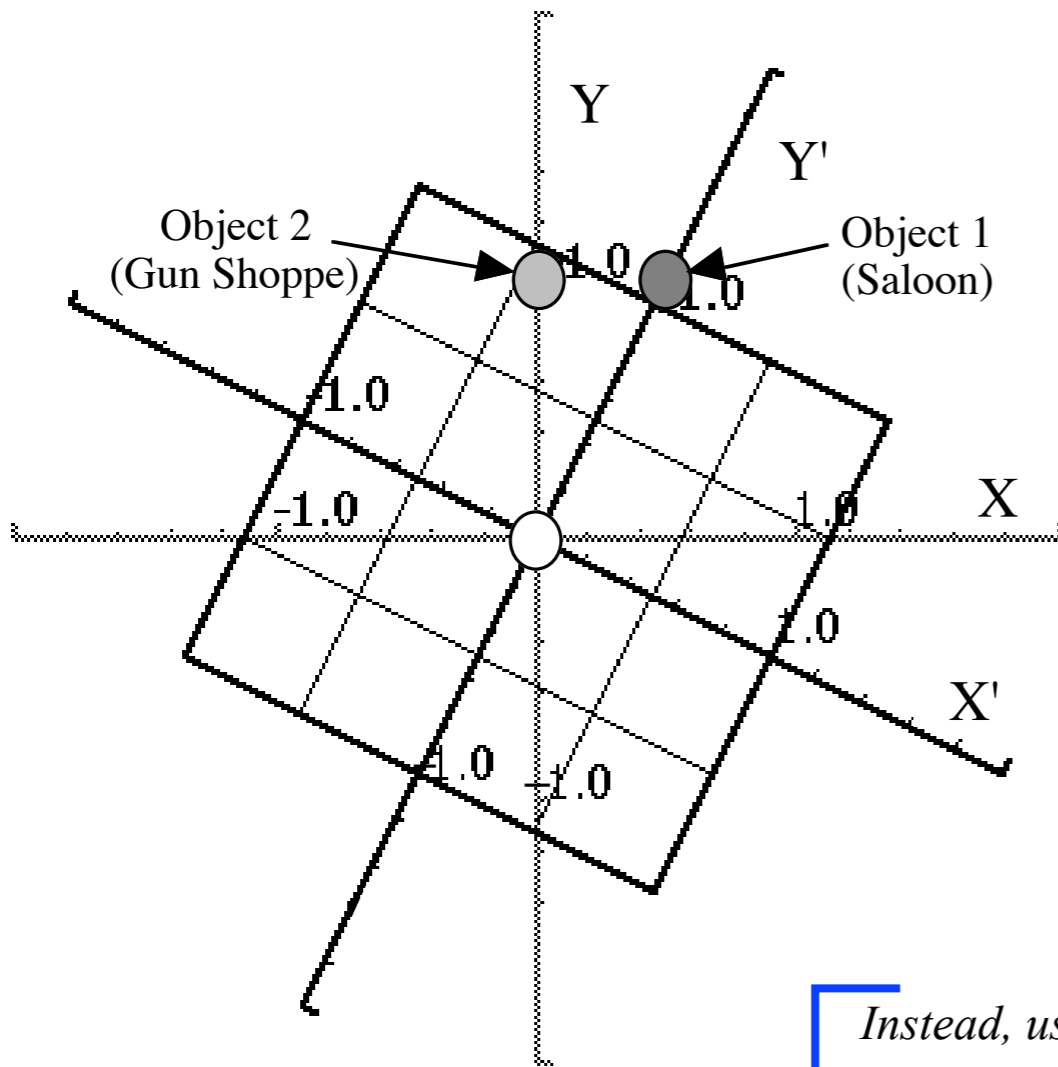
$$V_x = \langle x|V\rangle = \langle x|1|V\rangle = \langle x|x'\rangle \langle x'|V\rangle + \langle x|y'\rangle \langle y'|V\rangle$$

$$V_y = \langle y|V\rangle = \langle y|1|V\rangle = \langle y|x'\rangle \langle x'|V\rangle + \langle y|y'\rangle \langle y'|V\rangle$$

A politically incorrect analogy of rotational transformation and Lorentz transformation

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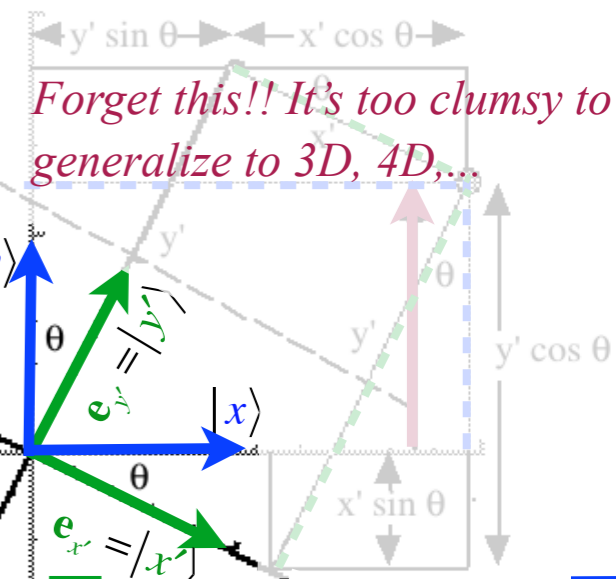
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$$V_y = \langle y|V\rangle = \langle y|1|V\rangle = \langle y|x'\rangle \langle x'|V\rangle + \langle y|y'\rangle \langle y'|V\rangle$$

in matrix form:

$$\begin{pmatrix} V_x \\ V_y \end{pmatrix} = \begin{pmatrix} \langle x|x'\rangle & \langle x|y'\rangle \\ \langle y|x'\rangle & \langle y|y'\rangle \end{pmatrix} \begin{pmatrix} V_{x'} \\ V_{y'} \end{pmatrix}$$

PLEASE!

Do *NOT* ever write

this:

$$\begin{aligned} \mathbf{e}_{x'} = |x'\rangle &= \cos\theta |x\rangle - \sin\theta |y\rangle \\ \mathbf{e}_{y'} = |y'\rangle &= \sin\theta |x\rangle + \cos\theta |y\rangle \end{aligned}$$

like this:

$$\begin{pmatrix} \mathbf{e}_{x'} \\ \mathbf{e}_{y'} \end{pmatrix} = \begin{pmatrix} |x'\rangle \\ |y'\rangle \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} |x\rangle \\ |y\rangle \end{pmatrix}$$

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(This is an abstract definition.)

like this:

This is GARBAGE!

$$\begin{pmatrix} \mathbf{e}_{x'} \\ \mathbf{e}_{y'} \end{pmatrix} = \begin{pmatrix} |x'\rangle \\ |y'\rangle \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} |x\rangle \\ |y\rangle \end{pmatrix}$$

PLEASE!

Do *NOT* ever write

this:

$$\begin{aligned} \mathbf{e}_{x'} = |x'\rangle &= \cos\theta |x\rangle - \sin\theta |y\rangle \equiv \mathbf{R}|x\rangle \\ \mathbf{e}_{y'} = |y'\rangle &= \sin\theta |x\rangle + \cos\theta |y\rangle \equiv \mathbf{R}|y\rangle \end{aligned}$$

(This is an abstract definition.)

like this:

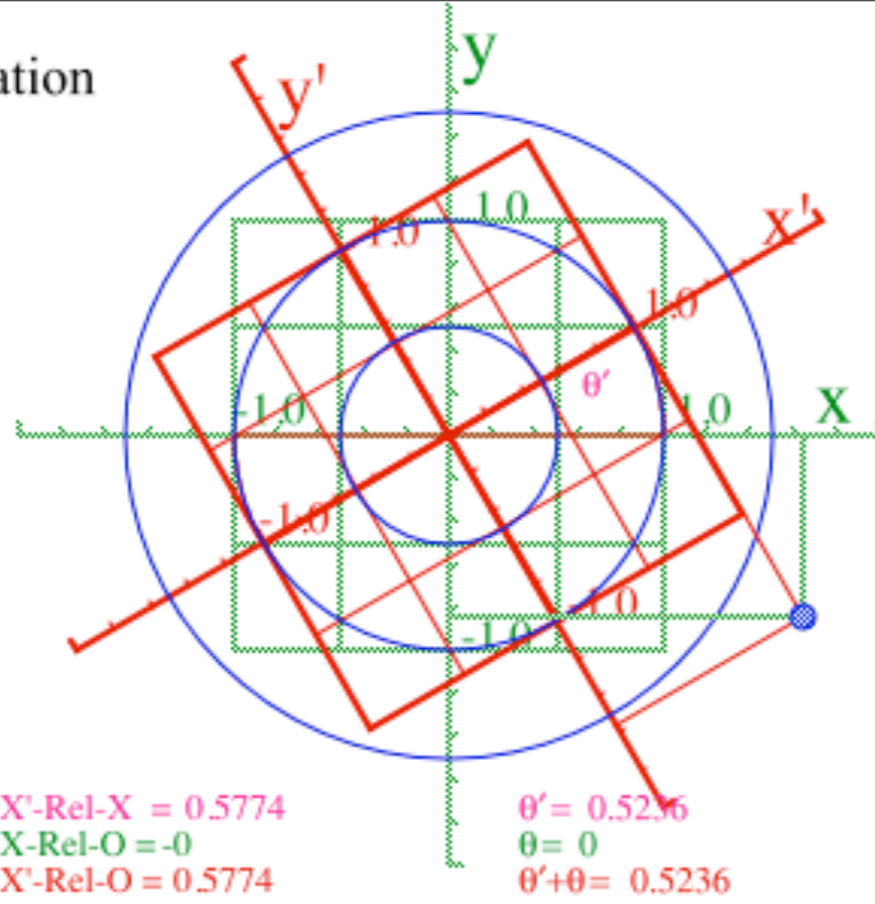
(This is GARBAGE!)

$$\begin{pmatrix} \mathbf{e}_{x'} \\ \mathbf{e}_{y'} \end{pmatrix} = \begin{pmatrix} |x'\rangle \\ |y'\rangle \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} |x\rangle \\ |y\rangle \end{pmatrix}$$

Here is a matrix representation of abstract definitions: $|x'\rangle \equiv \mathbf{R}|x\rangle$, $|y'\rangle \equiv \mathbf{R}|y\rangle$

$$\begin{pmatrix} V_x \\ V_y \end{pmatrix} = \begin{pmatrix} \langle x|x'\rangle & \langle x|y'\rangle \\ \langle y|x'\rangle & \langle y|y'\rangle \end{pmatrix} \begin{pmatrix} V_{x'} \\ V_{y'} \end{pmatrix} = \begin{pmatrix} \langle x|\mathbf{R}|x\rangle & \langle x|\mathbf{R}|y\rangle \\ \langle y|\mathbf{R}|x\rangle & \langle y|\mathbf{R}|y\rangle \end{pmatrix} \begin{pmatrix} V_{x'} \\ V_{y'} \end{pmatrix} = \begin{pmatrix} \langle x'|\mathbf{R}|x'\rangle & \langle x'|\mathbf{R}|y'\rangle \\ \langle y'|\mathbf{R}|x'\rangle & \langle y'|\mathbf{R}|y'\rangle \end{pmatrix} \begin{pmatrix} V_{x'} \\ V_{y'} \end{pmatrix}$$

(a) Rotation Transformation and Invariants



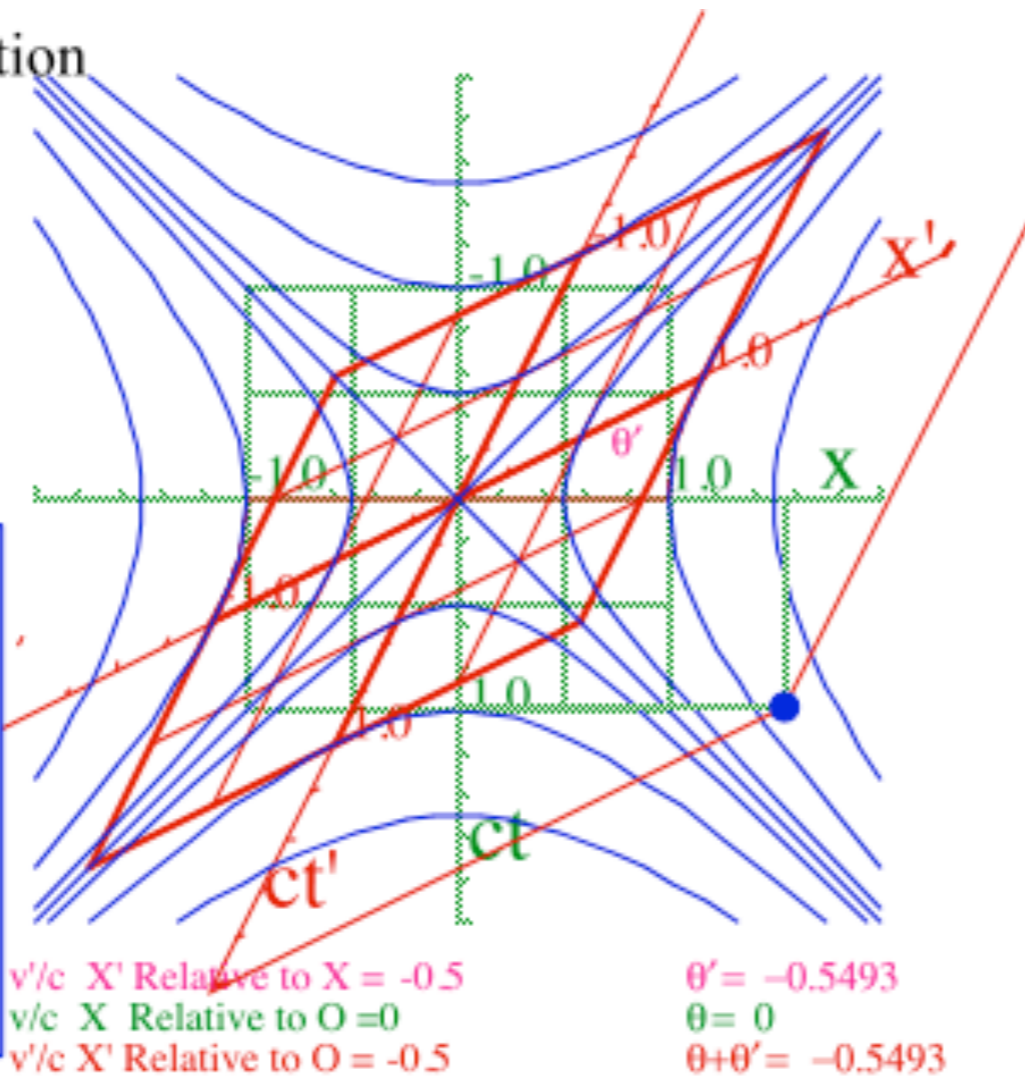
$$\begin{aligned}
 x &= 1.65 \\
 y &= -0.85 \\
 x^2 + y^2 &= 3.43 \\
 x' &= 1.00 \\
 y' &= -1.56 \\
 x'^2 + y'^2 &= 3.43
 \end{aligned}$$

Slope X'-Rel-X = 0.5774
 Slope X-Rel-O = 0
 Slope X'-Rel-O = 0.5774

$\theta' = 0.5236$
 $\theta = 0$
 $\theta' + \theta = 0.5236$

$$\begin{aligned}
 x' &= x \cos \theta - y \sin \theta = \frac{x}{\sqrt{1 + \frac{b^2}{c^2}}} + \frac{-(b/c)y}{\sqrt{1 + \frac{b^2}{c^2}}} \\
 y' &= x \sin \theta + y \cos \theta = \frac{(b/c)x}{\sqrt{1 + \frac{b^2}{c^2}}} + \frac{y}{\sqrt{1 + \frac{b^2}{c^2}}}
 \end{aligned}$$

(b) Lorentz Transformation and Invariants



$$\begin{aligned}
 x &= 1.5453 \\
 ct &= 0.9819 \\
 x^2 - (ct)^2 &= 1.42 \\
 x' &= 2.3512 \\
 ct' &= 2.0260 \\
 x'^2 - (ct')^2 &= 1.42
 \end{aligned}$$

v/c X' Relative to X = -0.5
 v/c X Relative to O = 0
 v/c X' Relative to O = -0.5

$\theta' = -0.5493$
 $\theta = 0$
 $\theta + \theta' = -0.5493$

$$\begin{aligned}
 x' &= \frac{x}{\sqrt{1 - \frac{v^2}{c^2}}} + \frac{\frac{v}{c}ct}{\sqrt{1 - \frac{v^2}{c^2}}} = x \cosh \rho + y \sinh \rho \\
 ct' &= \frac{\frac{v}{c}x}{\sqrt{1 - \frac{v^2}{c^2}}} + \frac{ct}{\sqrt{1 - \frac{v^2}{c^2}}} = x \sinh \rho + y \cosh \rho
 \end{aligned}$$

5. That “old-time” relativity (Circa 600BCE- 1905CE)

(“Bouncing-photons” in smoke & mirrors and Thales, again)

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The straight scoop on “angle” and “rapidity” (They’re area!)

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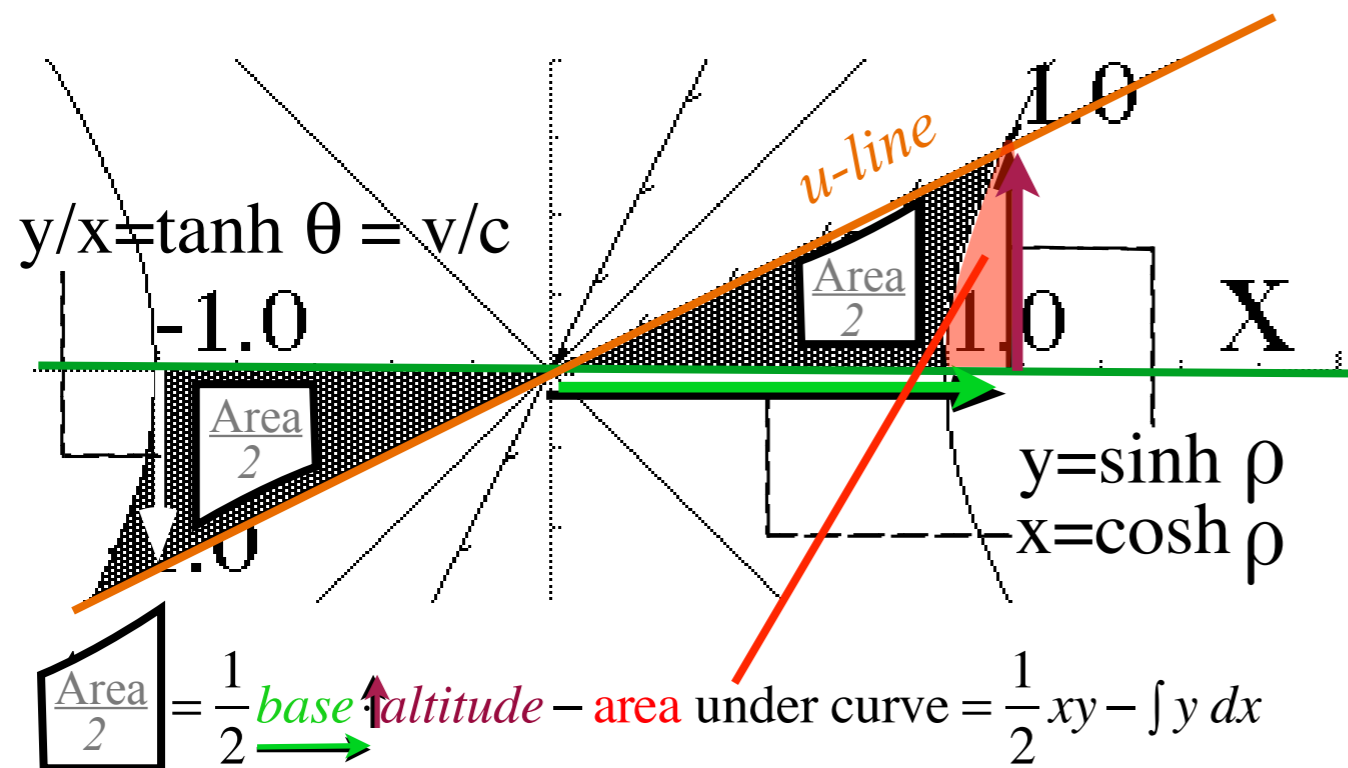
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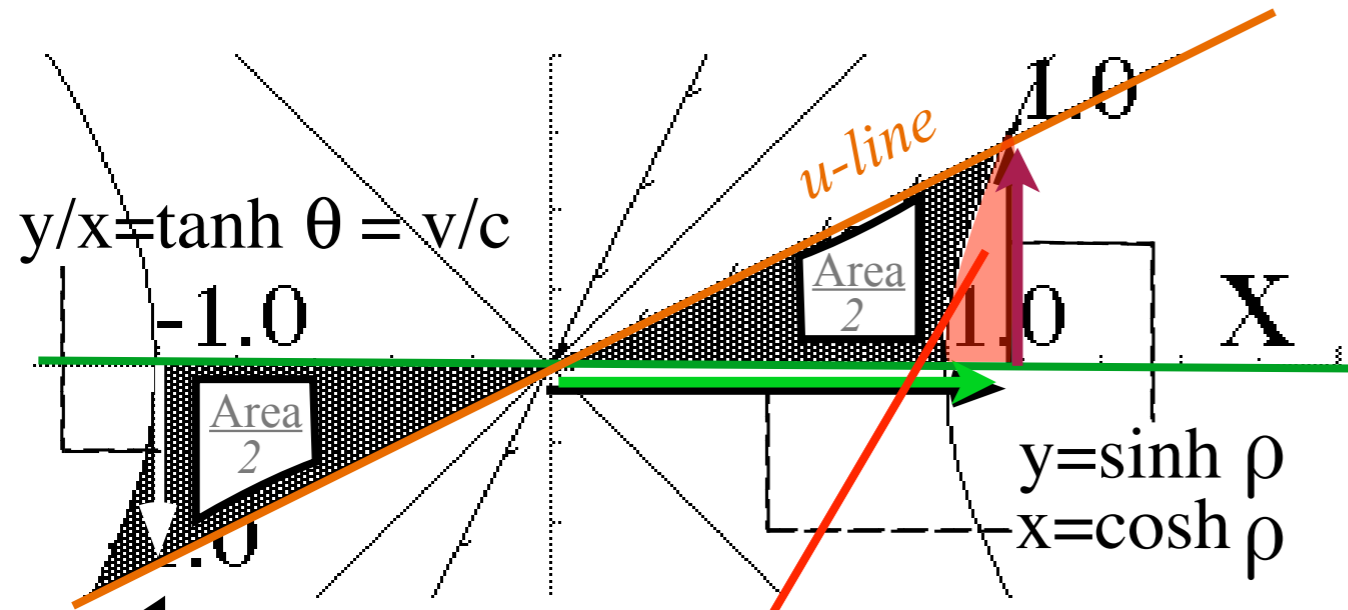
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The “Area” being calculated is the total Gray Area between hyperbola pairs, X axis, and sloping u -line

The straight scoop on “angle” and “rapidity” (They’re area!)



The “Area” being calculated is the total Gray Area between hyperbola pairs, X axis, and sloping u-line

$$\frac{\text{Area}}{2} = \frac{1}{2} \text{base} \uparrow \text{altitude} - \text{area under curve} = \frac{1}{2} xy - \int y dx$$

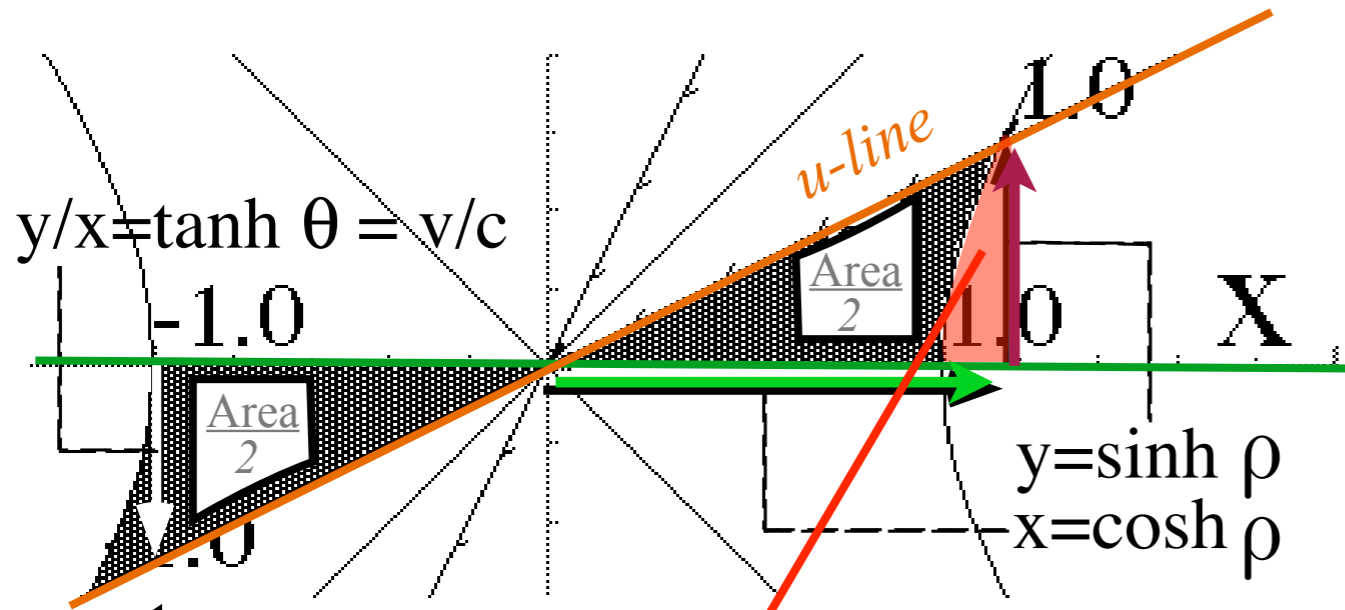
$$\frac{\text{Area}}{2} = \frac{1}{2} \sinh \rho \cosh \rho - \int \sinh \rho d(\cosh \rho)$$

Useful hyperbolic identities

$$\sinh^2 \rho = \left(\frac{e^\rho - e^{-\rho}}{2} \right)^2 = \frac{1}{4} (e^{2\rho} + e^{-2\rho} - 2) = \frac{\cosh 2\rho - 1}{2}$$

$$\sinh \rho \cosh \rho = \left(\frac{e^\rho - e^{-\rho}}{2} \right) \left(\frac{e^\rho + e^{-\rho}}{2} \right) = \frac{1}{4} (e^{2\rho} - e^{-2\rho}) = \frac{1}{2} \sinh 2\rho$$

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$$\sinh \theta \cosh \theta = \left(\frac{e^\theta - e^{-\theta}}{2} \right) \left(\frac{e^\theta + e^{-\theta}}{2} \right) = \frac{1}{4} (e^{2\theta} - e^{-2\theta}) = \frac{1}{2} \sinh 2\theta$$

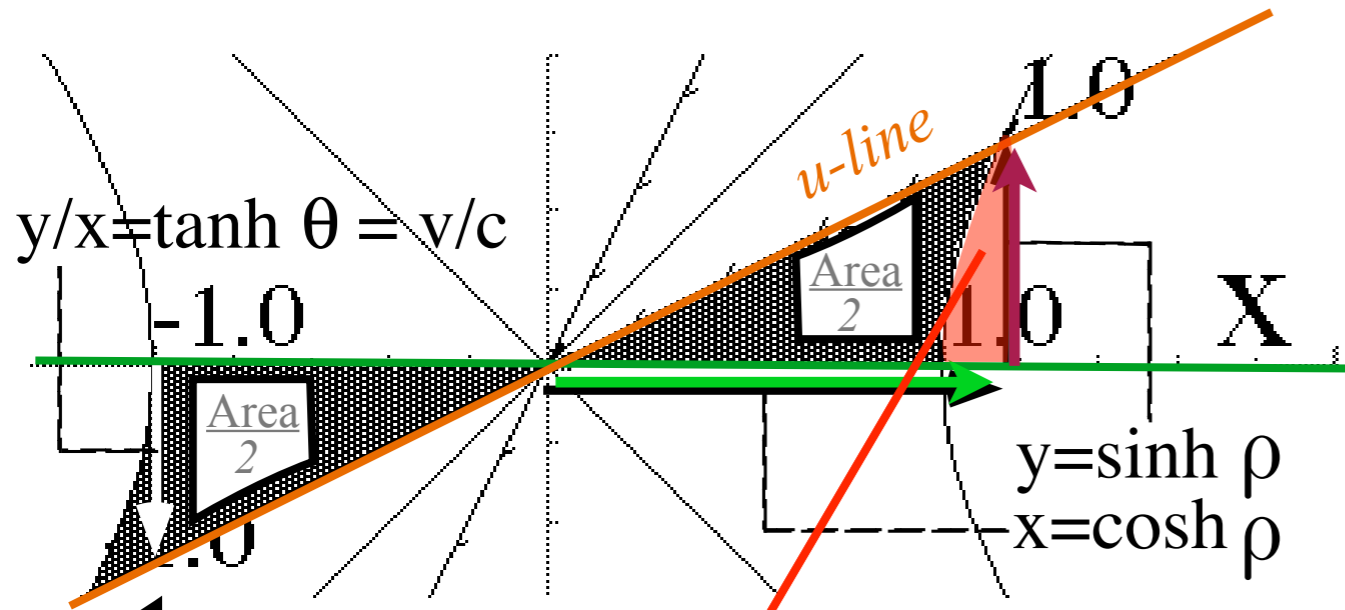
$$\int \cosh a\rho \, d\rho = \frac{1}{a} \sinh a\rho$$

$$\frac{\text{Area}}{2} = \frac{1}{2} \text{base} \cdot \text{altitude} - \text{area under curve} = \frac{1}{2} xy - \int y \, dx$$

$$\frac{\text{Area}}{2} = \frac{1}{2} \sinh \rho \cosh \rho - \int \sinh \rho \, d(\cosh \rho)$$

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$$\int \cosh a\theta d\theta = \frac{1}{a} \sinh a\theta$$

$$= \frac{1}{4} \sinh 2\rho - \frac{1}{4} \sinh 2\rho + \int \frac{1}{2} d\rho$$

$$= \frac{\rho}{2}$$

Amazing result: **Area = ρ is rapidity**

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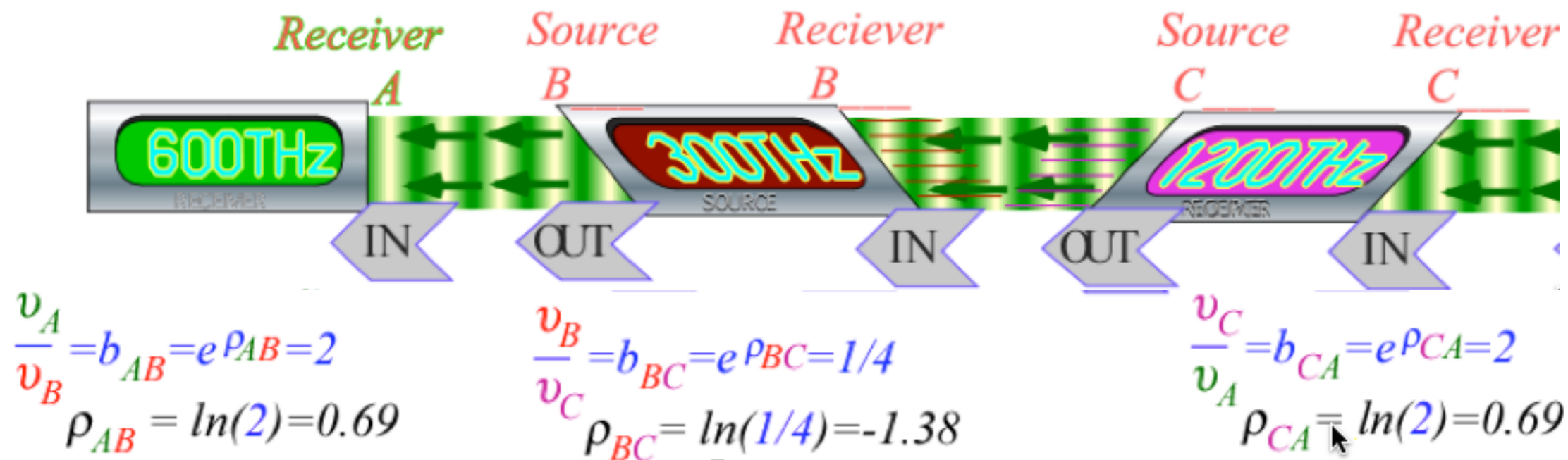
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From Lect. 22 p. 27 or eq. (3.6) in Ch. 3 of Unit 2:

Evenson axiom requires *geometric* Doppler transform: $e^{\rho_{AB}} \cdot e^{\rho_{BC}} = e^{\rho_{AC}} = e^{\rho_{AB} + \rho_{BC}}$

Easy to combine frame velocities using *rapidity addition*: $\rho_{u+v} = \rho_u + \rho_v$



$$\rho_{AB} + \rho_{BC} = \rho_{AC} = -\rho_{CA}$$

$$0.69 - 1.38 = -0.69$$

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$$\frac{u'}{c} = \tanh(\rho_u + \rho_v) = \frac{\tanh \rho_u + \tanh \rho_v}{1 + \tanh \rho_u \tanh \rho_v} = \frac{\frac{u}{c} + \frac{v}{c}}{1 + \frac{u}{c} \frac{v}{c}}$$

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No longer does $(1/2 + 1/2)c$ equal $(1)c$...

Relativistic result is:
$$\frac{\frac{1}{2} + \frac{1}{2}}{1 + \frac{1}{2} \frac{1}{2}} c = \frac{1}{1 + \frac{1}{4}} c = \frac{1}{\frac{5}{4}} c = \frac{4}{5} c$$

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...but, $(1/2 + 1)c$ does equal $(1)c$...

$$\frac{\frac{1}{2} + 1}{1 + \frac{1}{2} \cdot 1} c = c$$

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(a) Circular Functions
(plane geometry)

www.uark.edu/ua/pirelli/php/complex_phasors_1.php

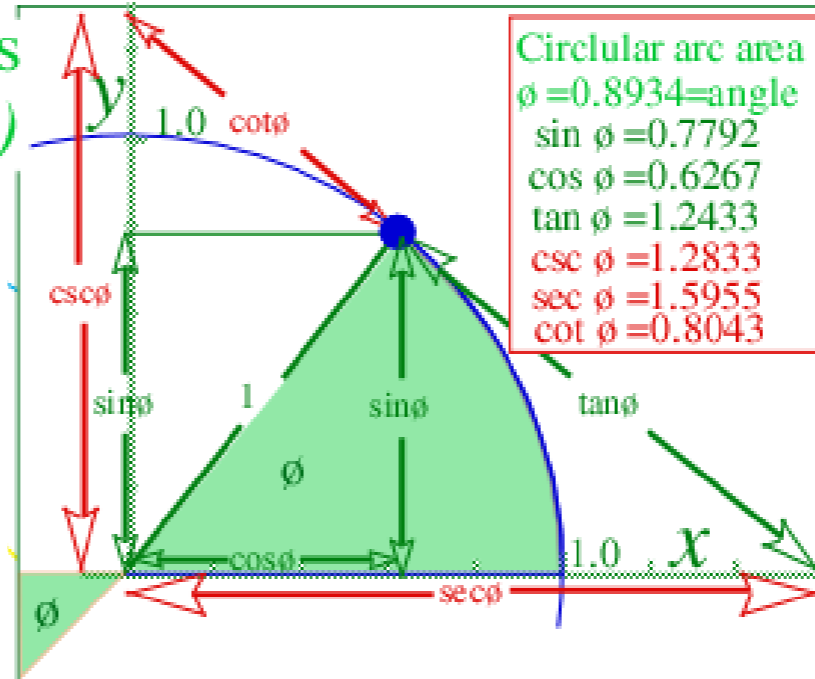


Fig. C.2-3
and
Fig. 5.4
in Unit 2

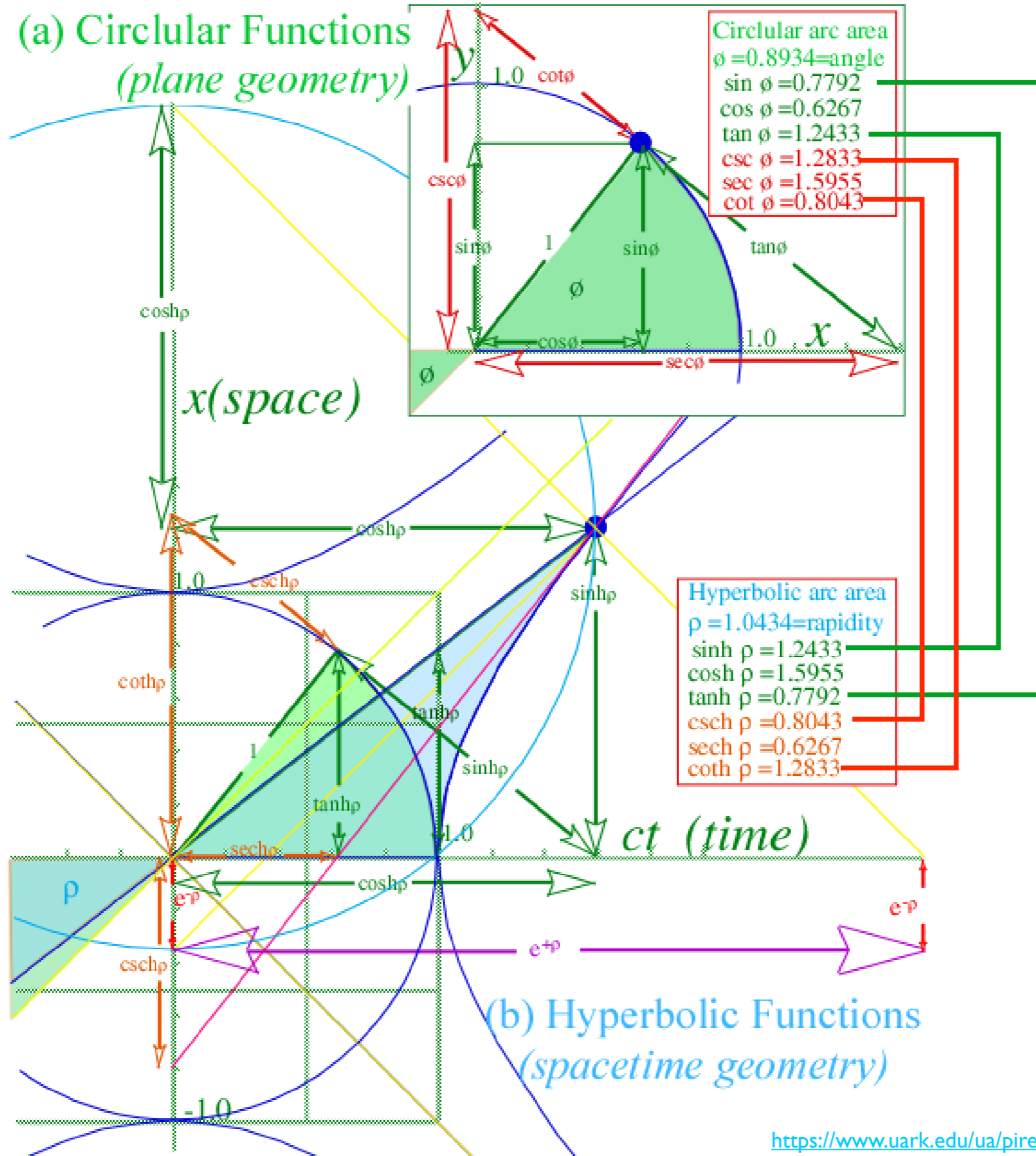
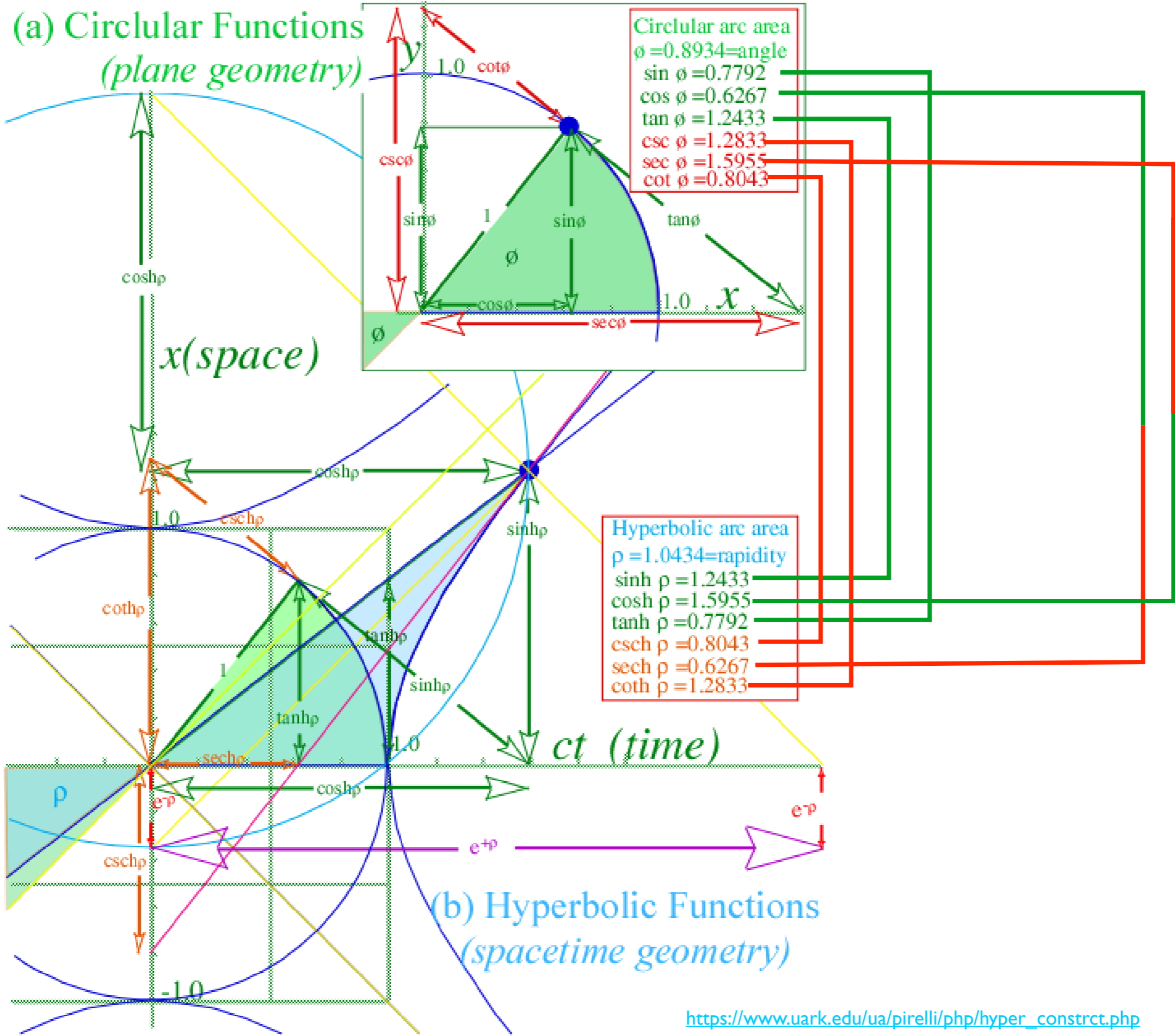


Fig. C.2-3
and
Fig. 5.4
in Unit 2



https://www.uark.edu/ua/pirelli/php/hyper_constrct.php

Circular Function Values

*More about the
"Sin-Tan Rosetta"*

$$m\angle(\sigma) = 0.9722 \text{ \{radians\}}$$

$$\text{Arclength}(\sigma) = 0.9722 \text{ \{radii\}}$$

$$\text{Section Area}(\sigma) = 0.9722 \text{ \{radii}^2\}}$$

$$\sin\sigma = 0.8261$$

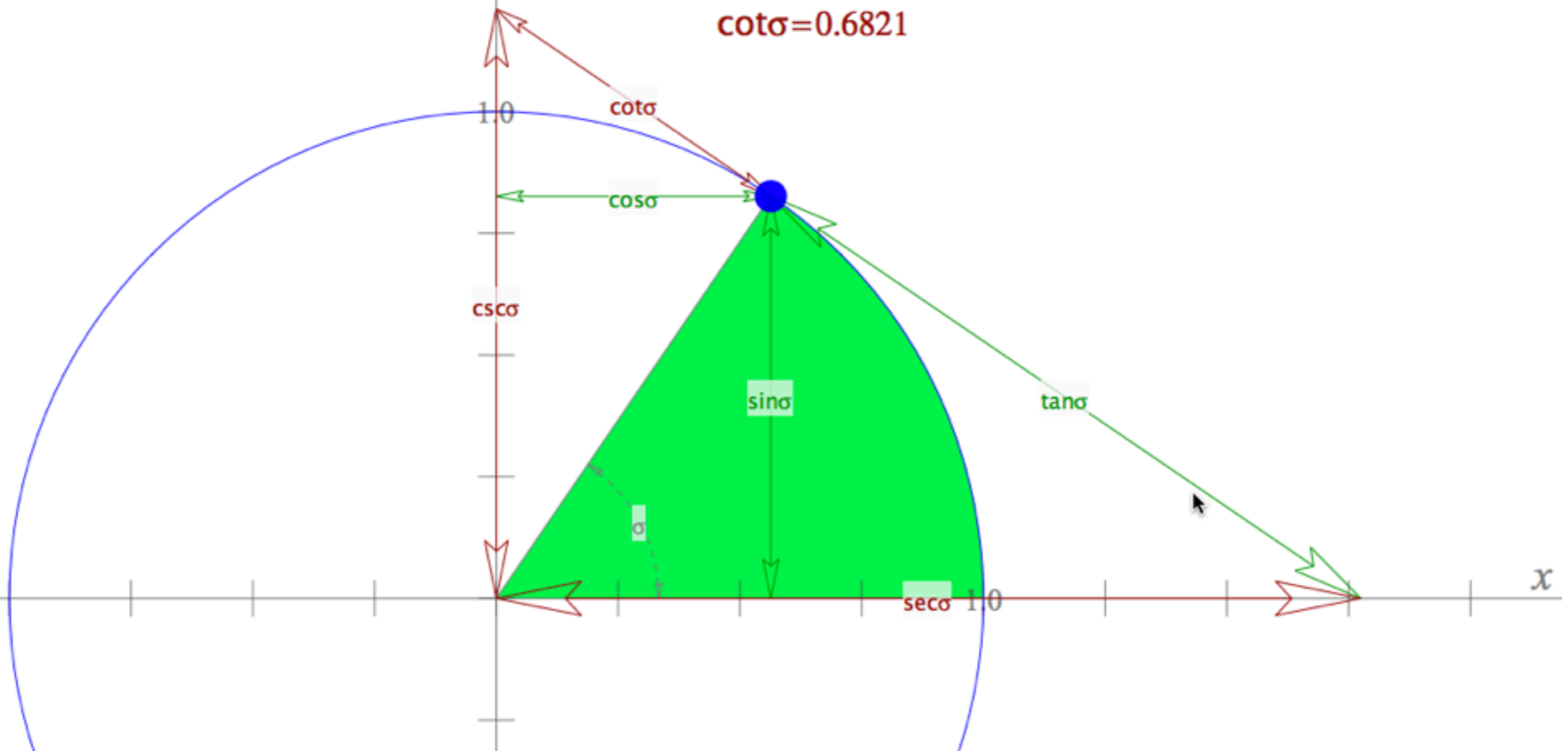
$$\cos\sigma = 0.5635$$

$$\tan\sigma = 1.4660$$

$$\csc\sigma = 1.2105$$

$$\sec\sigma = 1.7746$$

$$\cot\sigma = 0.6821$$



Hyperbolic Function Values

Arc Area = $\rho = 1.1758$ {radii²}

$\sinh \rho = 1.4660$

$\cosh \rho = 1.7746$

$\tanh \rho = 0.8261$

$\operatorname{csch} \rho = 0.6821$

$\operatorname{sech} \rho = 0.5635$

$\operatorname{coth} \rho = 1.2105$

$\exp(\rho) = 3.2406$

$\exp(-\rho) = 0.3086$

Circular Function Values

$m\angle(\sigma) = 0.9722$ {radians}

Arc length(σ) = 0.9722 {radii}

Section Area(σ) = 0.9722 {radii²}

$\sin \sigma = 0.8261$

$\cos \sigma = 0.5635$

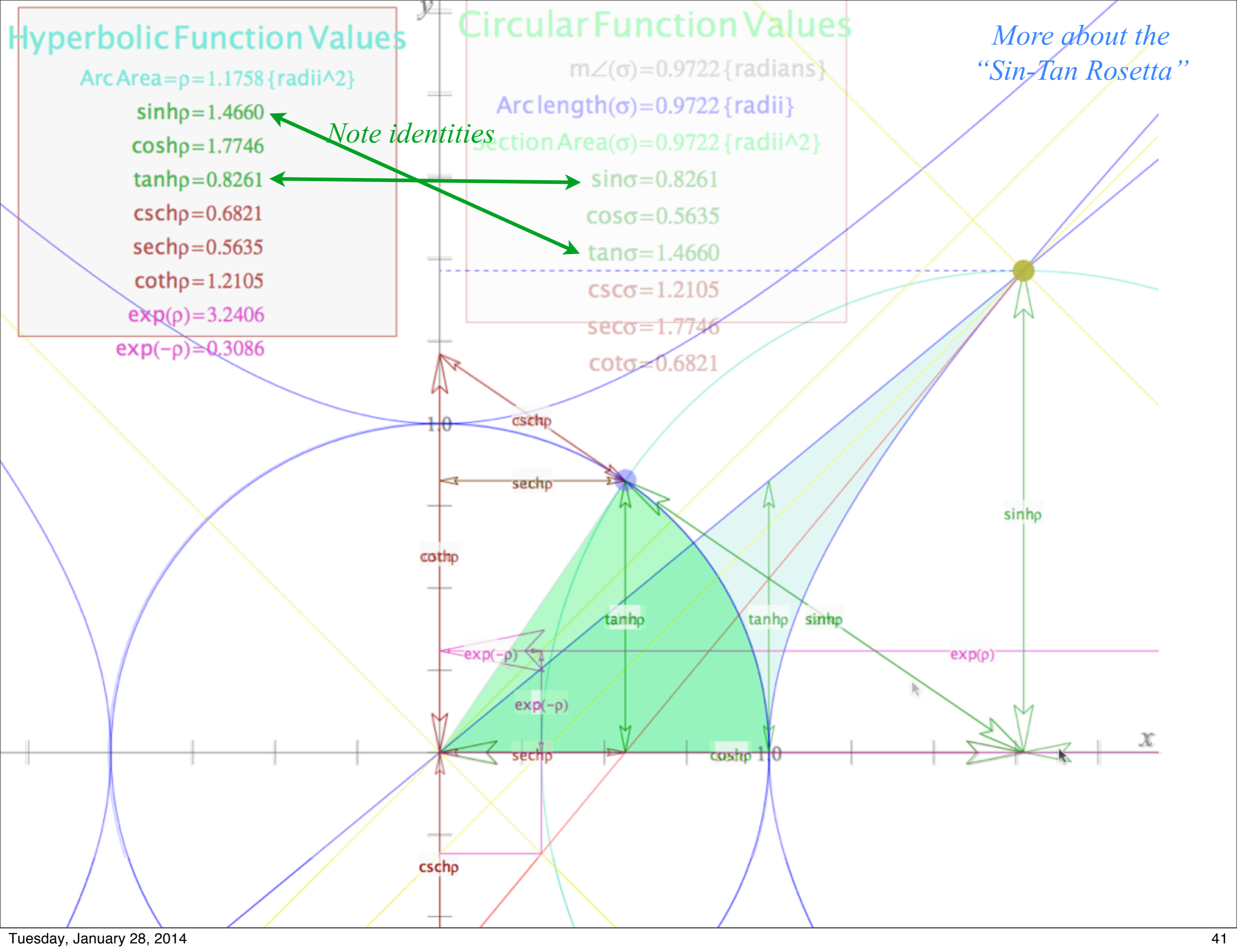
$\tan \sigma = 1.4660$

$\operatorname{csc} \sigma = 1.2105$

$\operatorname{sec} \sigma = 1.7746$

$\cot \sigma = 0.6821$

*More about the
"Sin-Tan Rosetta"*



Hyperbolic Function Values

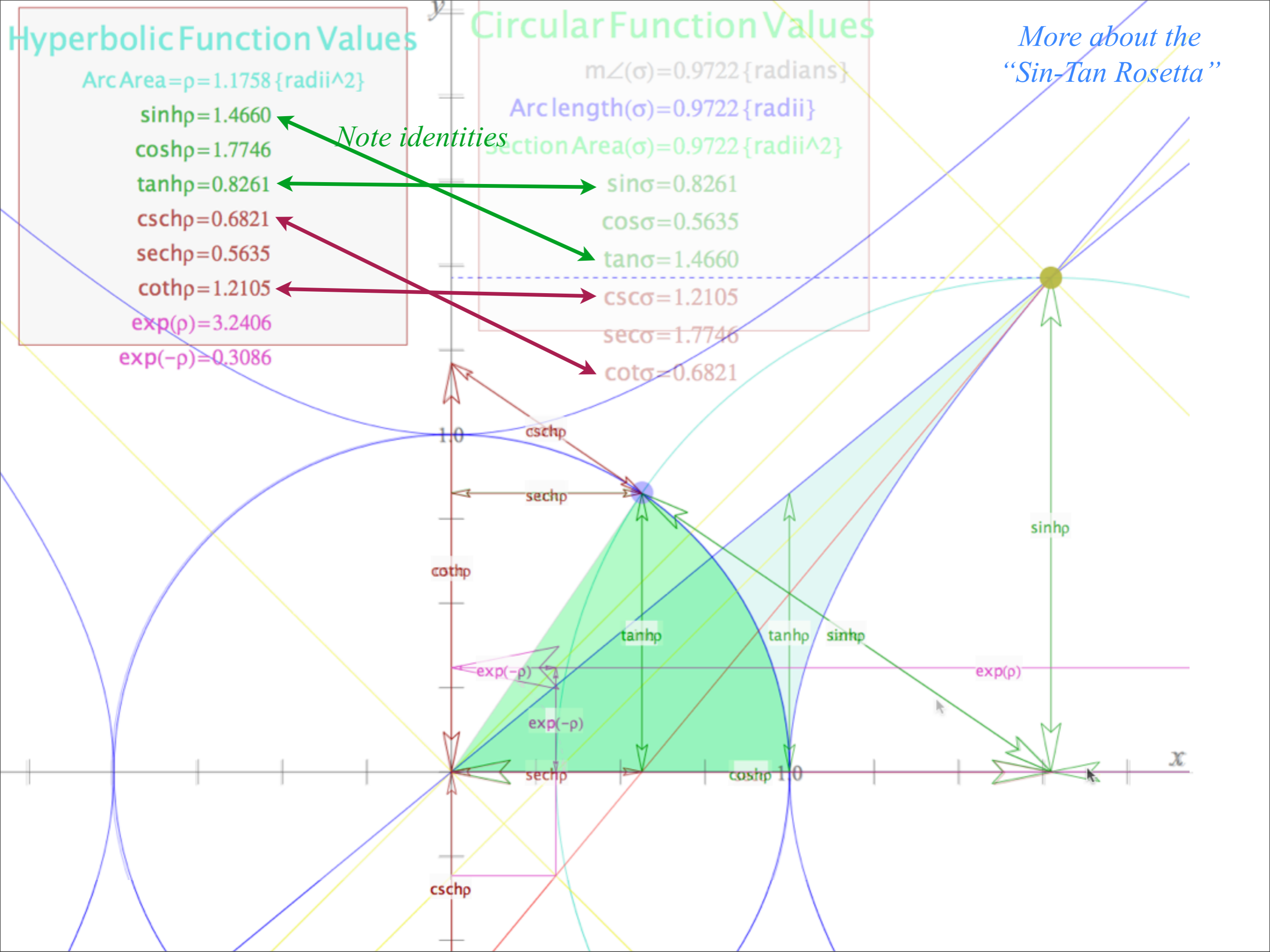
Circular Function Values

More about the "Sin-Tan Rosetta"

Arc Area = $\rho = 1.1758 \{ \text{radii}^2 \}$
 $\sinh \rho = 1.4660$
 $\cosh \rho = 1.7746$
 $\tanh \rho = 0.8261$
 $\operatorname{csch} \rho = 0.6821$
 $\operatorname{sech} \rho = 0.5635$
 $\operatorname{coth} \rho = 1.2105$
 $\exp(\rho) = 3.2406$
 $\exp(-\rho) = 0.3086$

$m\angle(\sigma) = 0.9722 \{ \text{radians} \}$
 Arc length $(\sigma) = 0.9722 \{ \text{radii} \}$
 Section Area $(\sigma) = 0.9722 \{ \text{radii}^2 \}$
 $\sin \sigma = 0.8261$
 $\cos \sigma = 0.5635$
 $\tan \sigma = 1.4660$
 $\operatorname{csc} \sigma = 1.2105$
 $\operatorname{sec} \sigma = 1.7746$
 $\operatorname{cot} \sigma = 0.6821$

Note identities



Hyperbolic Function Values

Circular Function Values

*More about the
"Sin-Tan Rosetta"*

Arc Area = $\rho = 1.1758 \text{ {radii}^2}$

$m\angle(\sigma) = 0.9722 \text{ {radians}}$

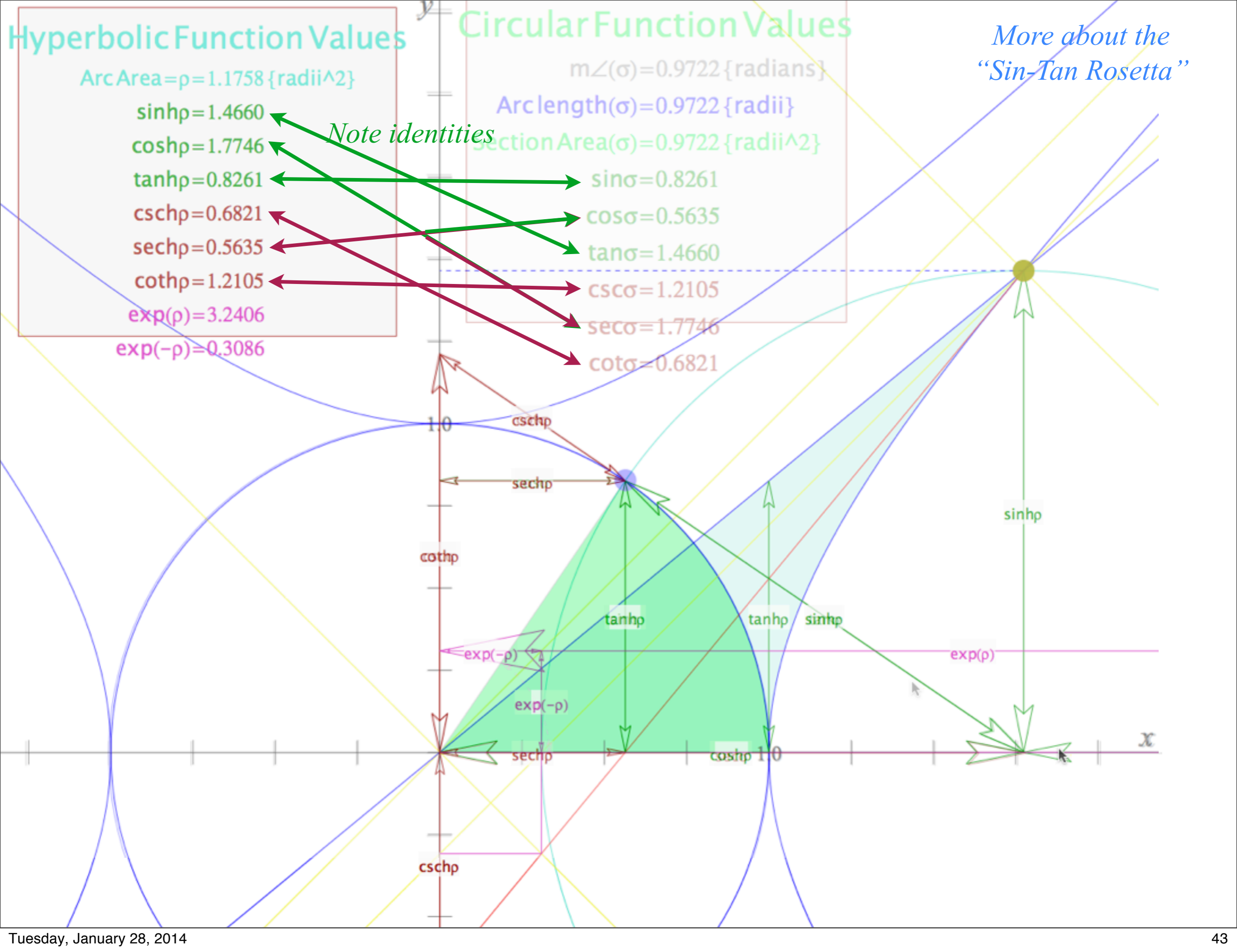
Arc length(σ) = $0.9722 \text{ {radii}}$

Section Area(σ) = $0.9722 \text{ {radii}^2}$

- sinh $\rho = 1.4660$
- cosh $\rho = 1.7746$
- tanh $\rho = 0.8261$
- csch $\rho = 0.6821$
- sech $\rho = 0.5635$
- coth $\rho = 1.2105$
- exp(ρ) = 3.2406
- exp(- ρ) = 0.3086

- sin $\sigma = 0.8261$
- cos $\sigma = 0.5635$
- tan $\sigma = 1.4660$
- csc $\sigma = 1.2105$
- sec $\sigma = 1.7746$
- cot $\sigma = 0.6821$

Note identities



5. That “old-time” relativity (Circa 600BCE- 1905CE)

(“Bouncing-photons” in smoke & mirrors and Thales, again)

The Ship and Lighthouse saga


Light-conic-sections make invariants

A politically incorrect analogy of rotational transformation and Lorentz transformation

The straight scoop on “angle” and “rapidity” (They’re area!)

*Galilean velocity addition becomes **rapidity** addition*

Introducing the “Sin-Tan Rosetta Stone” (Thanks, Thales!)

 *Introducing the **stellar aberration angle** σ vs. **rapidity** ρ*

How Minkowski’s space-time graphs help visualize relativity

Group vs. phase velocity and tangent contacts

Introducing the stellar aberration angle σ vs. rapidity ρ

Together, rapidity $\rho = \ln b$ and stellar aberration angle σ are parameters of relative velocity

The rapidity $\rho = \ln b$ is based on longitudinal wave Doppler shift $b = e^\rho$ defined by $u/c = \tanh(\rho)$.

At low speed: $u/c \sim \rho$.

The stellar aberration angle σ is based on the transverse wave rotation $R = e^{i\sigma}$ defined by $u/c = \sin(\sigma)$.

At low speed: $u/c \sim \sigma$.

(a) Fixed Observer

(b) Moving Observer

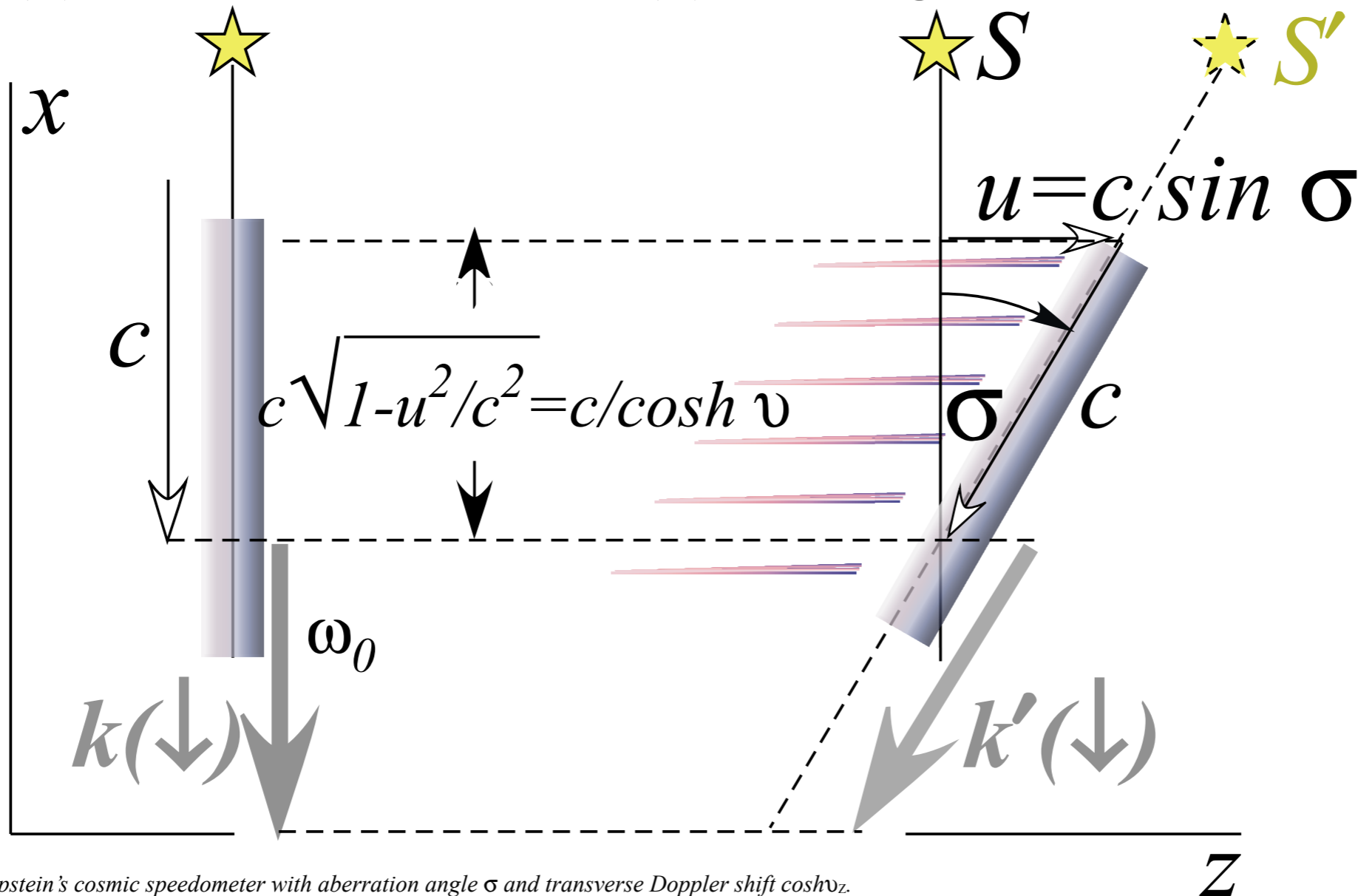


Fig. 5.6 Epstein's cosmic speedometer with aberration angle σ and transverse Doppler shift $\cosh v_z$.

Z

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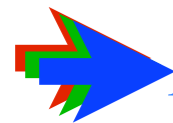
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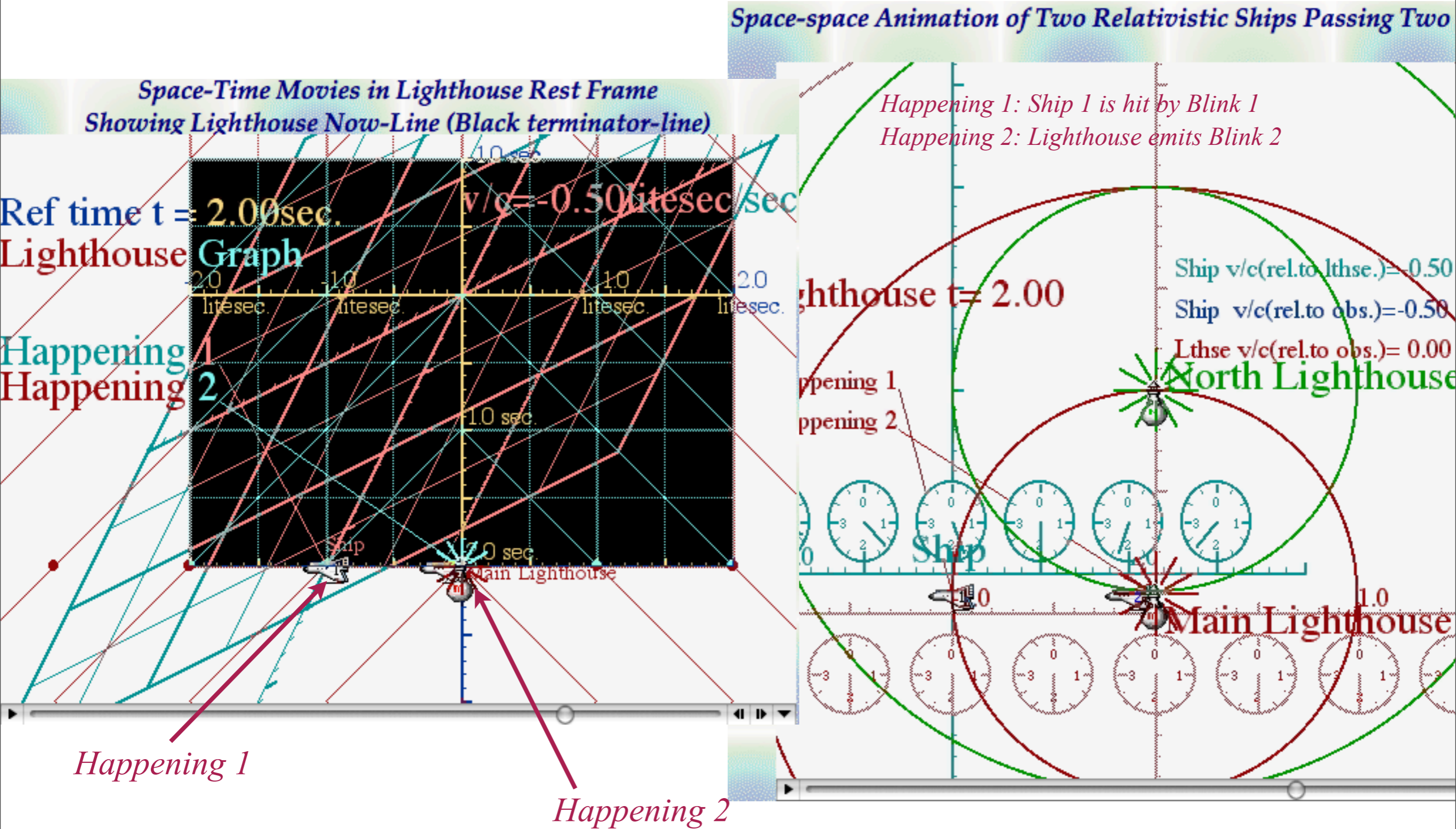


How Minkowski’s space-time graphs help visualize relativity

Group vs. phase velocity and tangent contacts

How Minkowski's space-time graphs help visualize relativity

Note that in Lighthouse frame Happening 1 is simultaneous with Happening 2 at $t=2.00\text{sec}$.

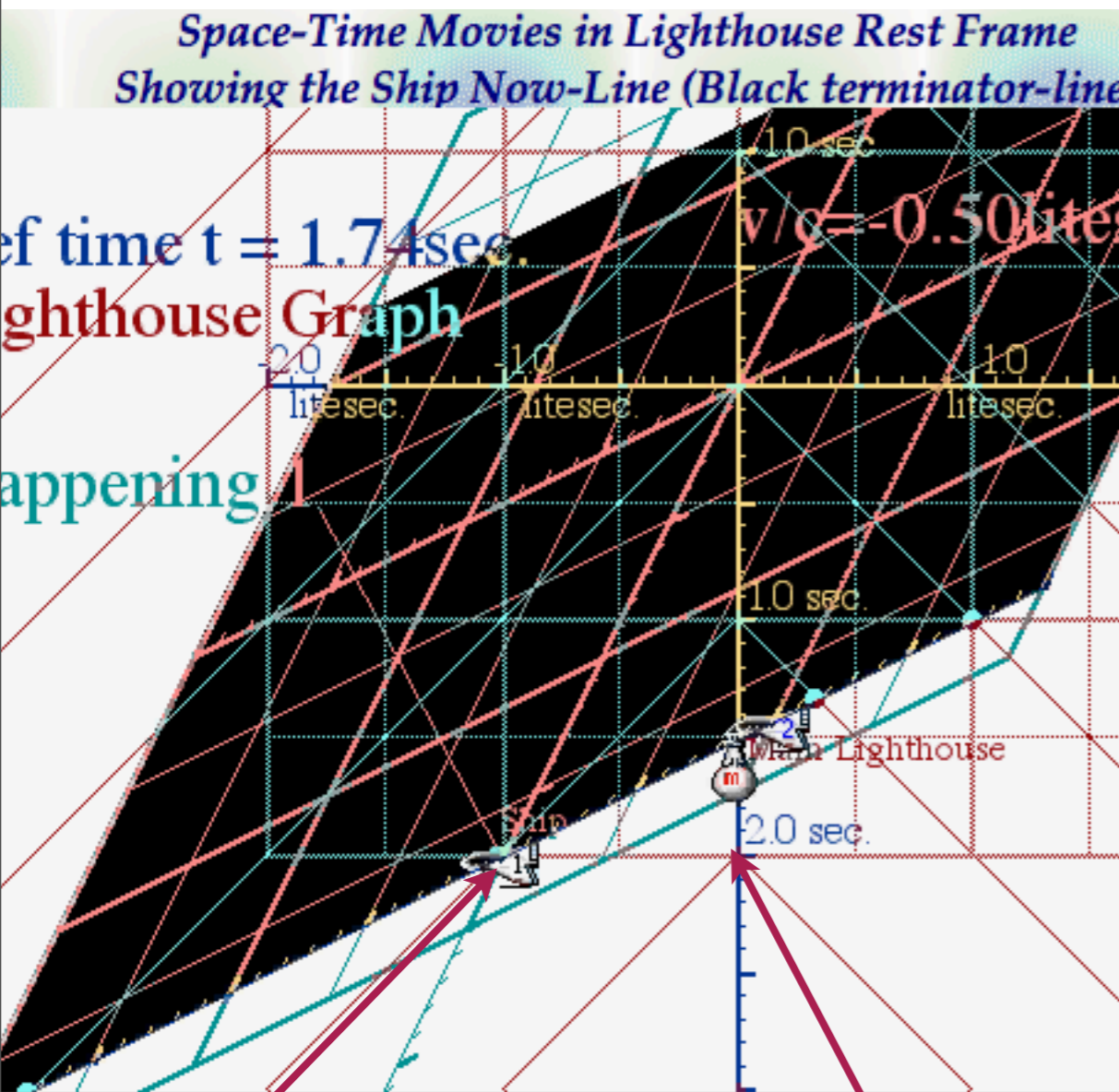


www.uark.edu/ua/pirelli/php/lighthouse_scenarios.php

How Minkowski's space-time graphs help visualize relativity (Here: $r = \text{atanh}(1/2) = 0.549$,

Note that in Lighthouse frame Happening 1 is simultaneous with Happening 2 at $t = 2.00 \text{ sec}$.

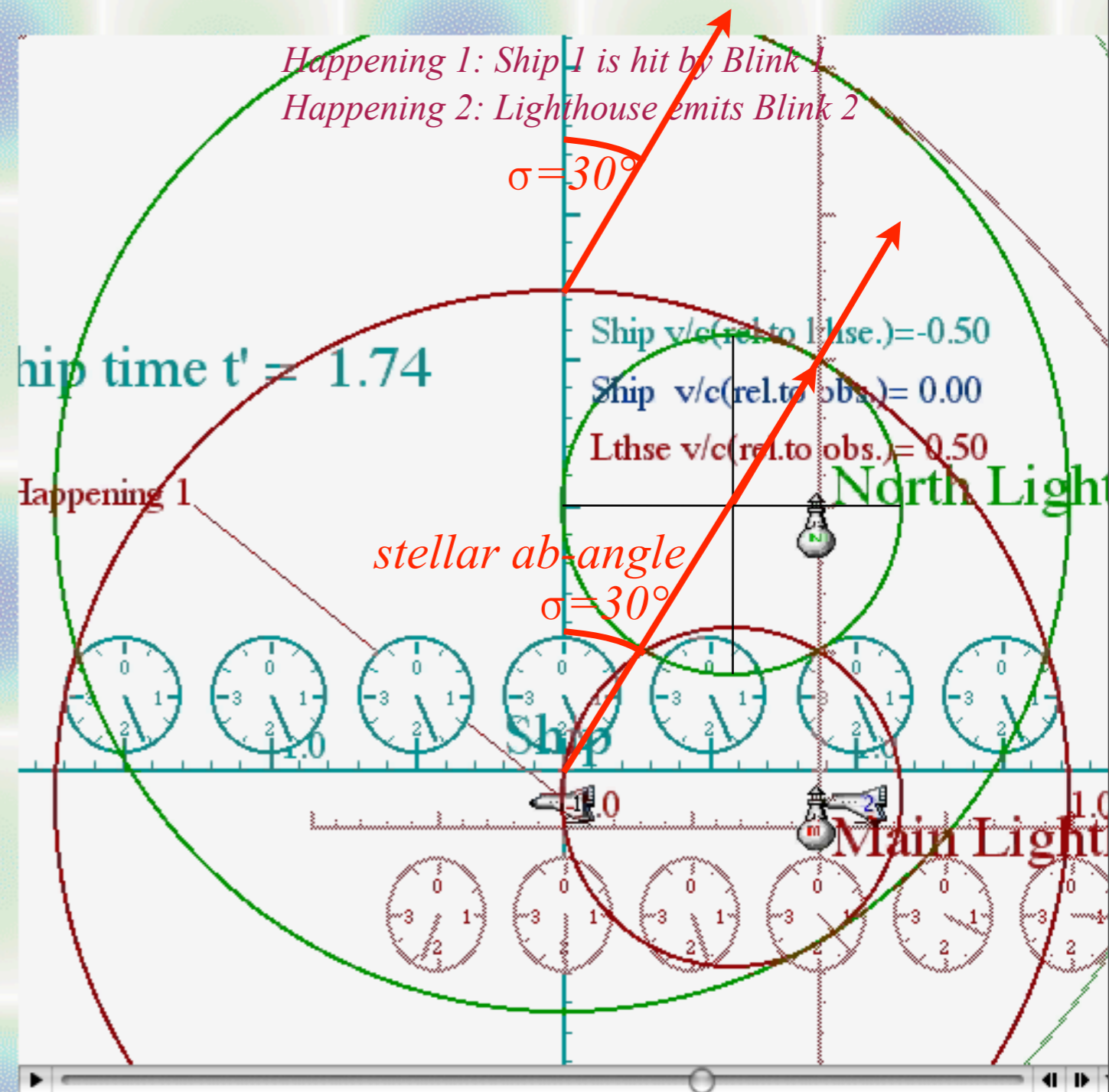
...but, in Ship frame Happening 1 is at $t' = 1.74$ and Happening 2 is at $t' = 2.30 \text{ sec}$.



Happening 1

Happening 2
won't happen
'til $t = 2.00$

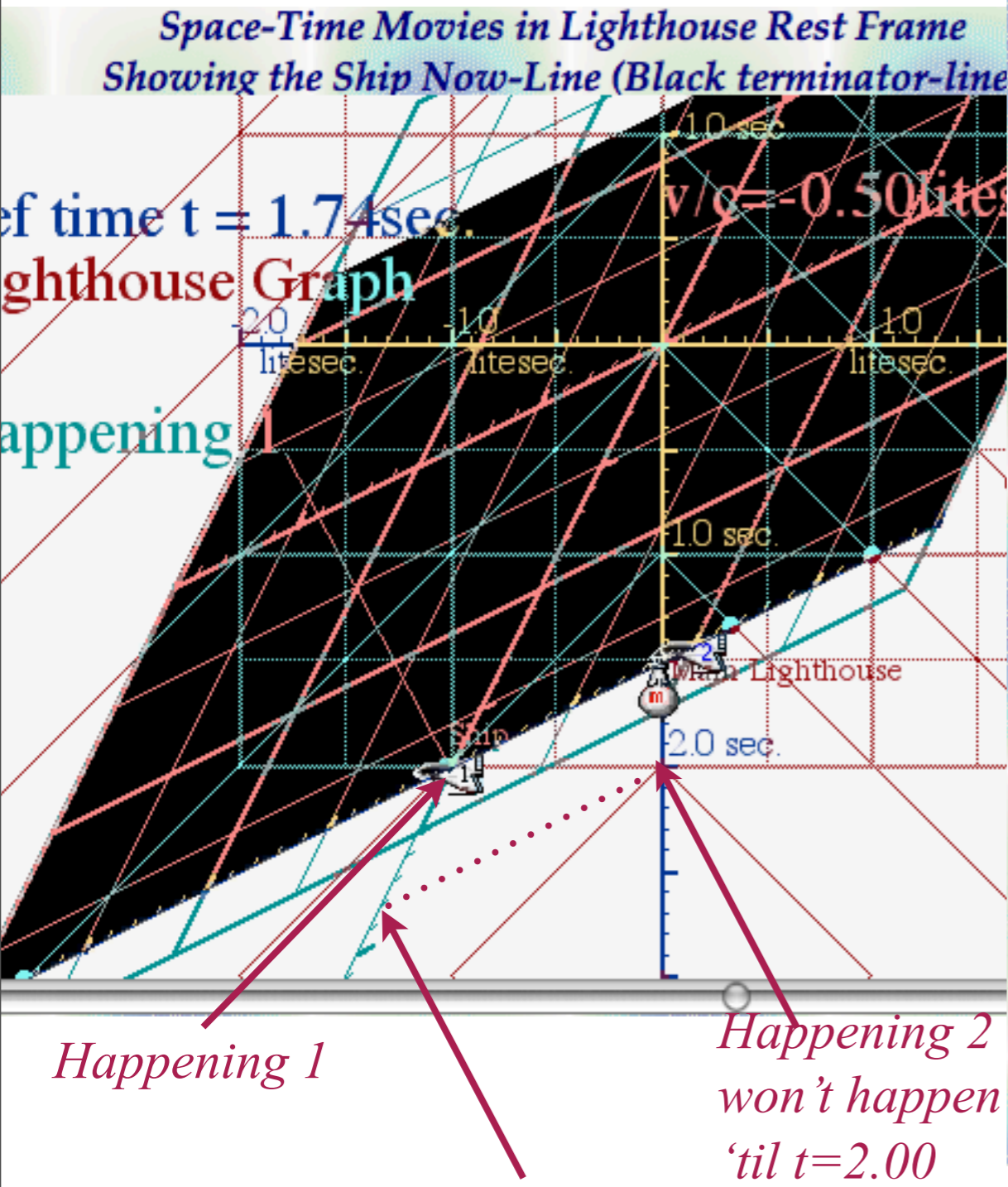
Space-space Animation of Two Relativistic Lighthouses Passing Two



(Here: $\rho = A \text{atanh}(1/2) = 0.55$,
and: $\sigma = A \text{sin}(1/2) = 0.52 \text{ or } 30^\circ$)

How Minkowski's space-time graphs help visualize relativity

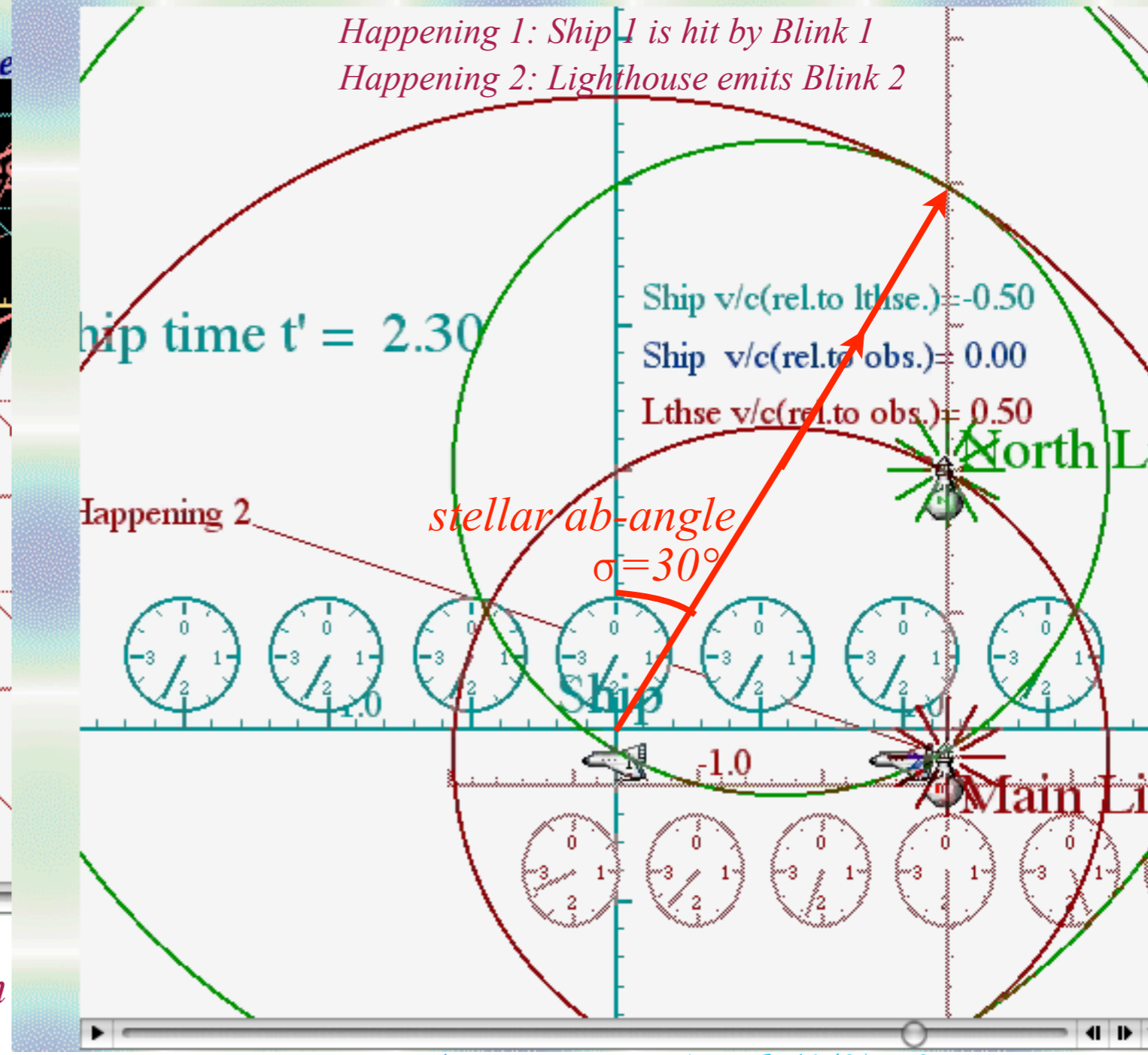
Note that in Lighthouse frame Happening 1 is simultaneous with Happening 2 at $t=2.00\text{sec}$.
 ...but, in Ship frame Happening 1 is at $t'=1.74$ and Happening 2 is at $t'=2.30\text{sec}$.



That is $t'=2.30$ ship time

www.uark.edu/ua/pirelli/php/lighthouse_scenarios.php

Space-space Animation of Two Relativistic Lighthouses Passing Two



(Here: $\rho = A \tanh(1/2) = 0.55$,
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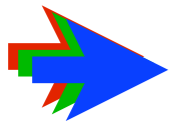
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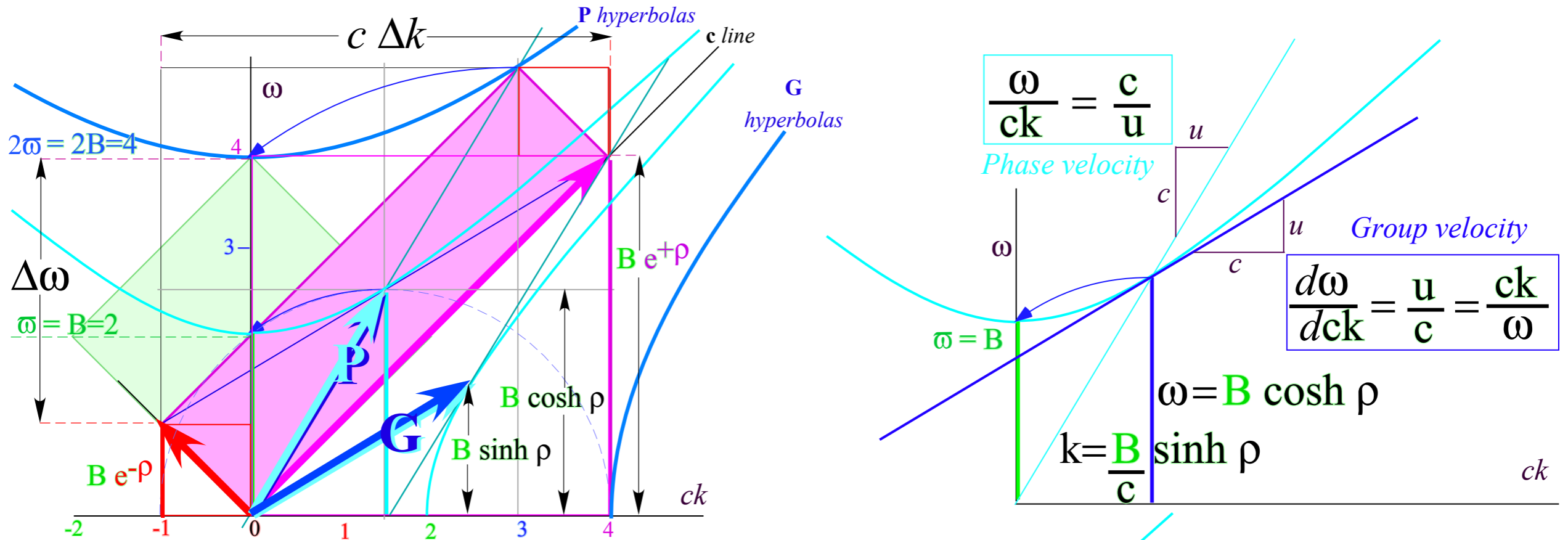
How Minkowski’s space-time graphs help visualize relativity

Group vs. phase velocity and tangent contacts



Group velocity u and phase velocity c^2/u are hyperbolic tangent slopes

(From Fig. 2.3.4)

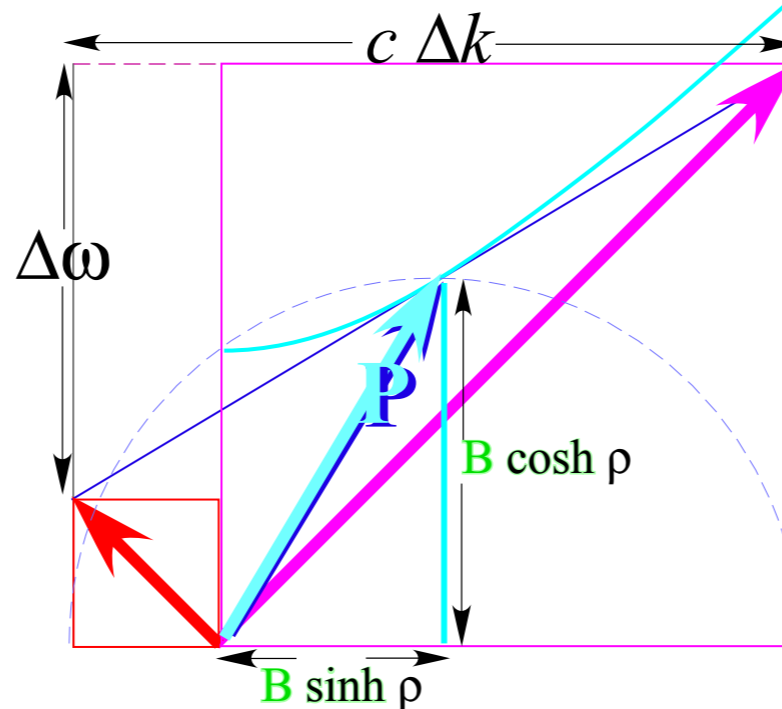


Rare but important case where

$$\frac{d\omega}{dk} = \frac{\Delta\omega}{\Delta k}$$

with **LARGE** Δk
(not infinitesimal)

Relativistic
group wave
speed $u = c \tanh \rho$



Newtonian speed $u \sim c\rho$
Low speed approximation
Rapidity ρ approaches u/c

Lecture 25 ended here

Group vs. phase velocity and tangent contacts

Phase velocity

$$\frac{c^2}{u} = u_{phase} = \frac{\omega}{k} = \frac{c^2 \Delta k}{\Delta \omega} = c \coth \rho$$

Phase-line slope

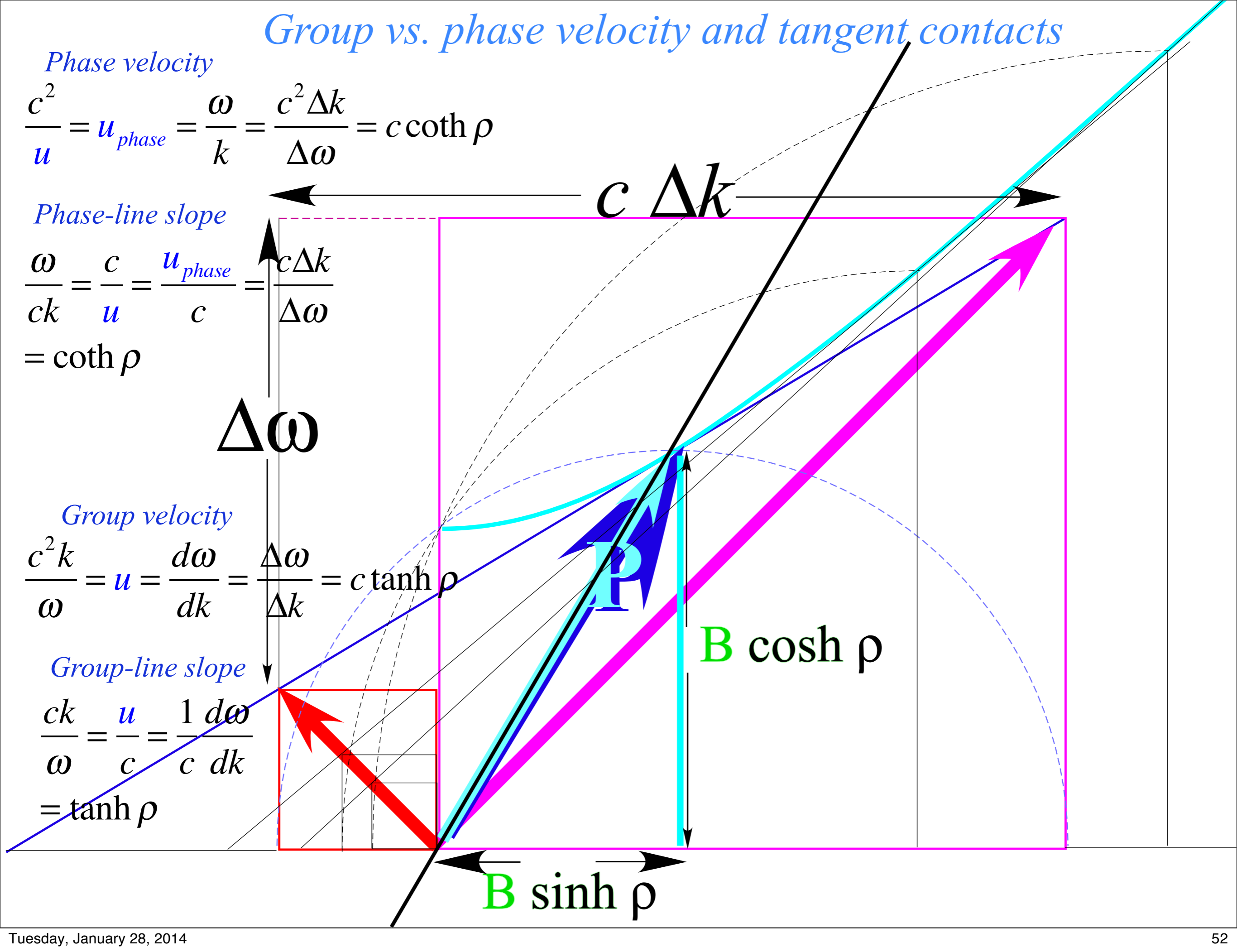
$$\frac{\omega}{ck} = \frac{c}{u} = \frac{u_{phase}}{c} = \frac{c \Delta k}{\Delta \omega} = \coth \rho$$

Group velocity

$$\frac{c^2 k}{\omega} = u = \frac{d\omega}{dk} = \frac{\Delta \omega}{\Delta k} = c \tanh \rho$$

Group-line slope

$$\frac{ck}{\omega} = \frac{u}{c} = \frac{1}{c} \frac{d\omega}{dk} = \tanh \rho$$



Group vs. phase velocity and tangent contacts

