## Tue. 12.10.2014

## Geometry and Symmetry of Coulomb Orbital Dynamics I. (Ch. 2-4 of Unit 5 12.11.14)

Rutherford scattering and differential scattering cross-sections Parabolic "kite" and envelope geometry Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry Review and connection to standard development  $\varepsilon$ -vector and Coulomb  $\mathbf{p}=m\mathbf{v}$  geometry  $\varepsilon$ -vector and Coulomb  $\mathbf{p}=m\mathbf{v}$  algebra Example with elliptical orbit Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry Connection formulas for (a,b) and  $(\varepsilon,\lambda)$  with  $(\gamma,\mathbf{R})$ 



- *Review and added: Rutherford scattering and differential scattering cross-sections* Parabolic "kite" and envelope geometry





Rutherford scattering of  $\alpha^{+2}$ particles from  $Au^{+79}$  nucleus at O Assume "Dead-On" closest approach 2a. (E=k/2a)  $a\sim 10^{-11}m >>7.3\cdot 10^{-15}m$ 

Pick an "impact parameter" line y = b. Draw circle of radius a around center point C=(-a,b) tangent to y-axis. Draw "focus-locus" line OCF.



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Copy angle  $\angle$ BCF (equal to  $\Theta/2$ ) to make angle  $\angle$ FCB' (also equal to  $\Theta/2$ ) Resulting line CB' is outgoing asymptote at scattering angle  $\Theta$ .



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*Review: Coulomb scattering geometry* 

Review and added: Rutherford scattering and differential scattering cross-sections Parabolic "kite" and envelope geometry

## Rutherford scattering geometry











Wednesday, December 24, 2014













Fig. 5.3.2 Family of iso-energetic Rutherford scattering orbits with varying impact parameter.

Incremental window  $d\sigma = b \cdot db$  normal to beam axis at  $x = -\infty$  scatters to area  $dA = R^2 \sin \Theta d\Theta d\phi = R^2 d\Omega$ onto a sphere at  $R = +\infty$  where is called the *incremental solid angled*  $\Omega = \sin \Theta d\Theta d\phi$ 

Ratio 
$$\frac{d\sigma}{d\Omega} = \frac{b \, db \, d\varphi}{\sin \Theta d\Theta d\varphi} = \frac{b}{\sin \Theta} \frac{db}{d\Theta}$$
 is called the *differential scattering crossection (DSC)*  
Geometry  $b = a \, \cot \frac{\Theta}{2} = \frac{k}{2E} \cot \frac{\Theta}{2}$  gives the *Rutherford DSC*.  $\frac{d\sigma}{d\Omega} = \frac{k^4}{16E^2} \sin^{-4} \frac{\Theta}{2}$ 

Agrees exactly with 1<sup>st</sup> Born approximation to *quantum* Coulomb DSC!



Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry Review and connection to standard development  $\varepsilon$ -vector and Coulomb **p**=m**v** geometry  $\varepsilon$ -vector and Coulomb **p**=m**v** algebra Example with elliptical orbit Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry Connection formulas for (a,b) and ( $\varepsilon, \lambda$ ) with ( $\gamma, \mathbf{R}$ ) *Eccentricity vector*  $\varepsilon$  *and* ( $\varepsilon$ , $\lambda$ ) *geometry of orbital mechanics* 

Isotropic field V = V(r) guarantees conservation *angular momentum vector* **L** 

 $\mathbf{L} = \mathbf{r} \times \mathbf{p} = m \, \mathbf{r} \times \dot{\mathbf{r}}$ 

*Eccentricity vector*  $\varepsilon$  *and* ( $\varepsilon$ , $\lambda$ ) *geometry of orbital mechanics* 

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Coulomb V = -k/r also conserves *eccentricity vector*  $\varepsilon$ 

 $\mathbf{\varepsilon} = \hat{\mathbf{r}} - \frac{\mathbf{p} \times \mathbf{L}}{km} = \frac{\mathbf{r}}{r} - \frac{\mathbf{p} \times (\mathbf{r} \times \mathbf{p})}{km}$ 

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$$\mathbf{L} = \mathbf{r} \times \mathbf{p} = m\mathbf{r} \times \dot{\mathbf{r}}$$
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HO  $V = (k/2)r^2$  also conserves Stokes vector S  
 $S_A = \frac{1}{2}(x_1^2 + p_1^2 - x_2^2 - p_2^2)$   
 $S_B = x_1p_1 + x_2p_2$   
 $S_C = x_1p_2 - x_2p_1$ 
A = km  $\varepsilon$  is known as the Laplace-Hamilton-Gibbs-Runge-Lenz vector. Generate symmetry groups:  $U(2) \subset U(2)$   
or:  $R(3) \subset R(3) \times R(3) \subset O(4)$ 

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 $\mathbf{L} = \mathbf{r} \times \mathbf{p} = m \mathbf{r} \times \dot{\mathbf{r}}$ Coulomb V=-k/r also conserves eccentricity vector  $\boldsymbol{\varepsilon}$   $\varepsilon = \hat{\mathbf{r}} - \frac{\mathbf{p} \times \mathbf{L}}{km} = \frac{\mathbf{r}}{r} - \frac{\mathbf{p} \times (\mathbf{r} \times \mathbf{p})}{km}$ (...for sake of comparison...)
IHO V=(k/2)r^2 also conserves Stokes vector S  $S_A = \frac{1}{2}(x_1^2 + p_1^2 - x_2^2 - p_2^2)$   $S_B = x_1 p_1 + x_2 p_2$   $S_C = x_1 p_2 - x_2 p_1$ 

 $\mathbf{A} = km \cdot \varepsilon \text{ is known as the Laplace-Hamilton-Gibbs-Runge-Lenz vector.} \overset{\text{Generate symmetry groups:}}{\to} U(2) \subset U(2) \xrightarrow{} U(2) \subset U(2) \xrightarrow{} U(3) \subset R(3) \subset R(3) \subset R(3) \subset Q(4)$ 

Consider dot product of  $\varepsilon$  with a radial vector **r**:

$$\mathbf{\varepsilon} \bullet \mathbf{r} = \frac{\mathbf{r} \bullet \mathbf{r}}{r} - \frac{\mathbf{r} \bullet \mathbf{p} \times \mathbf{L}}{km} = r - \frac{\mathbf{r} \times \mathbf{p} \bullet \mathbf{L}}{km} = r - \frac{\mathbf{L} \bullet \mathbf{L}}{km}$$

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 $\mathbf{L} = \mathbf{r} \times \mathbf{p} = m\mathbf{r} \times \dot{\mathbf{r}}$ Coulomb *V*=-*k/r* also conserves *eccentricity vector*  $\varepsilon$   $\varepsilon = \dot{\mathbf{r}} - \frac{\mathbf{p} \times \mathbf{L}}{km} = \frac{\mathbf{r}}{r} - \frac{\mathbf{p} \times (\mathbf{r} \times \mathbf{p})}{km}$ HO *V*=(*k*/2)*r*<sup>2</sup> also conserves *Stokes vector S*  $S_A = \frac{1}{2}(x_1^2 + p_1^2 - x_2^2 - p_2^2)$   $S_B = x_1 p_1 + x_2 p_2$   $S_C = x_1 p_2 - x_2 p_1$ A = *km*  $\varepsilon$  is known as the *Laplace-Hamilton-Gibbs-Runge-Lenz vector*. Generate symmetry groups: *U*(2)  $\subset$ *U*(2) or: *R*(3)  $\subset$ *R*(3)  $\subset$ *R*(3)  $\subset$ *O*(4)
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Wednesday, December 24, 2014
Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry  $\checkmark$  Review and connection to standard development  $\varepsilon$ -vector and Coulomb **p**=m**v** geometry  $\varepsilon$ -vector and Coulomb **p**=m**v** algebra Example with elliptical orbit Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry Connection formulas for (a,b) and ( $\varepsilon, \lambda$ ) with ( $\gamma, \mathbf{R}$ )



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Eccentricity vector ε and (ε,λ)-geometry of orbital mechanics
ε-vector and Coulomb r-orbit geometry
Review and connection to standard development
ε-vector and Coulomb p=mv geometry
ε-vector and Coulomb p=mv algebra
Example with elliptical orbit
Analytic geometry derivation of ε-construction
Algebra of ε-construction geometry
Connection formulas for (a,b) and (ε,λ) with (γ, R)

Radius r:  

$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$$

*Polar angle* 
$$\phi$$
 *using:*  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$ 

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

Radius r:

adius r:  

$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$$
Polar angle  $\phi$  using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$   
 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2}$ 

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

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 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$ 

using: 
$$\frac{1}{r^2} = \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos\phi)^2$$

1 1

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

Radius r:

$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$$
$$\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2}$$

Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$   
 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$ 

using: 
$$\frac{1}{r^2} = \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos\phi)^2$$

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

Radius r:  $r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$   $\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2}$ 

Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$   
 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \epsilon \cos \phi)^2$   
 $r\dot{\phi} = \frac{L}{mr}$ 

using:  $\frac{1}{r^2} = \left(\frac{\kappa m}{L^2}\right) (1 - \varepsilon \cos \phi)^2$ 

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

Radius r:

$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$$
$$\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2}$$

Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$   
 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$   
 $r\dot{\phi} = \frac{L}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right) (1 - \varepsilon \cos \phi) = \frac{k}{L} (1 - \varepsilon \cos \phi)$   
 $using: \frac{1}{r} = \left(\frac{km}{L^2}\right) (1 - \varepsilon \cos \phi)$ 

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

Radius r:

$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi}$$
$$\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2}$$
$$\dot{r} = \frac{L^2}{km} \frac{-\varepsilon \sin \phi \dot{\phi}}{(1 - \varepsilon \cos \phi)^2}$$

Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$   
 $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$   
 $r\dot{\phi} = \frac{L}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right) (1 - \varepsilon \cos \phi) = \frac{k}{L} (1 - \varepsilon \cos \phi)$   
 $using: \frac{1}{r^2} = \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$ 

Radius r:Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$  $r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2/km}{1 - \varepsilon \cos \phi}$  $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)^2}{(1 - \varepsilon \cos \phi)^2}$  $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{L^2}{km} \frac{-\varepsilon \sin \phi \dot{\phi}}{(1 - \varepsilon \cos \phi)^2}$  $using: \frac{1}{r^2} = \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = -\frac{L^2}{km} \left(\frac{km}{L^2}\right)^2 r^2 \dot{\phi} \varepsilon \sin \phi$  $using: \frac{1}{(1 - \varepsilon \cos \phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2$ 

$$\begin{aligned} \text{Radius r:} \\ r &= \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi} \\ \dot{r} &= \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{L^2}{km} \frac{-\varepsilon \sin \phi \dot{\phi}}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= -\frac{L^2}{km} \left(\frac{km}{L^2}\right)^2 r^2 \dot{\phi} \varepsilon \sin \phi \\ \dot{r} &= -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin \phi = -\frac{k}{L} \varepsilon \sin \phi \end{aligned}$$

Radius r:  
$$r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2/km}{1 - \varepsilon \cos \phi}$$
Polar angle  $\phi$  using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$  $\dot{r} = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2/km}{1 - \varepsilon \cos \phi}$  $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)^2}{(1 - \varepsilon \cos \phi)^2}$  $r\dot{\phi} = \frac{L}{mr} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi) = \frac{k}{L} (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{L^2}{km} \frac{-\varepsilon \sin \phi \dot{\phi}}{(1 - \varepsilon \cos \phi)^2}$  $using: \frac{1}{mr} = \frac{L}{m} \frac{1}{r^2} = \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = -\frac{L^2}{km} \frac{km}{L^2}^2 r^2 \dot{\phi} \varepsilon \sin \phi$  $using: \frac{1}{(1 - \varepsilon \cos \phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2$  $\dot{r} = -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin \phi = -\frac{k}{L} \varepsilon \sin \phi$  $using: \frac{1}{(1 - \varepsilon \cos \phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2$  $\dot{r} = -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin \phi = -\frac{k}{L} \varepsilon \sin \phi$  $using: \frac{1}{(1 - \varepsilon \cos \phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2$  $\dot{r} = -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin \phi = -\frac{k}{L} \varepsilon \sin \phi$  $using: L = mr^2 \dot{\phi}$ Cartesian  $x = r \cos \phi:$  $\dot{y} = \frac{dy}{dt} = r \sin \phi:$  $\dot{y} = \frac{dy}{dt} = r \sin \phi + \cos \phi r \dot{\phi}$ 

$$\begin{aligned} \text{Radius } r: \\ r &= \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2 / km}{1 - \varepsilon \cos \phi} \\ \dot{r} &= \frac{dr}{dt} = \frac{L^2}{km} - \frac{d}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{dr}{dt} = \frac{L^2}{km} - \frac{d}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{dr}{dt} = \frac{L^2}{km} - \frac{d}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{L^2}{km} - \frac{1}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= \frac{L^2}{km} - \frac{1}{(1 - \varepsilon \cos \phi)^2} \\ \dot{r} &= -\frac{L^2}{km} - \frac{k}{L^2} - \frac{k}{2} \sin \phi \\ \dot{r} &= -\frac{k}{L^2} - \frac{k}{2} \sin \phi = -\frac{k}{L} \varepsilon \sin \phi \\ \dot{r} &= -\frac{k}{L^2} \sin \phi \cos \phi - \sin \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \cos \phi - \sin \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \cos \phi - \sin \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \cos \phi - \sin \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi) \\ \dot{r} &= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi$$

Radius r:Polar angle 
$$\phi$$
 using:  $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi}$  $r = \frac{\lambda}{1 - \varepsilon \cos \phi} = \frac{L^2/km}{1 - \varepsilon \cos \phi}$  $\dot{\phi} = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos \phi)}{(1 - \varepsilon \cos \phi)^2}$  $r\dot{\phi} = \frac{L}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi)^2$  $\dot{r} = \frac{L^2}{km} \frac{-\varepsilon \sin \phi \dot{\phi}}{(1 - \varepsilon \cos \phi)^2}$  $using: \frac{1}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos \phi) = \frac{k}{L} (1 - \varepsilon \cos \phi)^2$  $\dot{r} = -\frac{L^2}{km} \left(\frac{km}{L^2}\right)^2 r^2 \dot{\phi} \varepsilon \sin \phi$  $using: \frac{1}{(1 - \varepsilon \cos \phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2$  $\dot{r} = -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin \phi = -\frac{k}{L} \varepsilon \sin \phi$  $again using: L = mr^2 \dot{\phi}$ Cartesian  $x = r \cos \phi$ : $Cartesian y = r \sin \phi$ : $\dot{x} = \frac{dx}{dt} = -r \cos \phi - \sin \phi r \dot{\phi}$  $\dot{y} = \frac{dy}{dt} = -r \sin \phi + \cos \phi r \dot{\phi}$  $= -\frac{k}{L} \varepsilon \sin \phi \cos \phi - \sin \phi \frac{k}{L} (1 - \varepsilon \cos \phi)$  $= -\frac{k}{L} \varepsilon \sin \phi \sin \phi + \cos \phi \frac{k}{L} (1 - \varepsilon \cos \phi)$  $= -\frac{k}{L} \sin \phi$  $= -\frac{k}{L} \cos \phi - \varepsilon$ 

Finding time derivatives of orbital coordinates r,  $\phi$ , x, y, and eventually velocity **v** or momentum **p**=m**v** 

$$\begin{aligned} \text{Radius } r: & \text{Polar angle $\phi$ using: $L = mr^2 \frac{d\phi}{dt} = mr^2 \dot{\phi} \\ r = \frac{\lambda}{1 - \varepsilon \cos\phi} = \frac{L^2/km}{1 - \varepsilon \cos\phi} & \phi = \frac{L}{mr^2} = \frac{L}{m} \frac{1}{r^2} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos\phi)^2 \\ \dot{r} = \frac{dr}{dt} = \frac{L^2}{km} \frac{-\frac{d}{dt}(-\varepsilon \cos\phi)}{(1 - \varepsilon \cos\phi)^2} & r\phi = \frac{L}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos\phi)^2 \\ r\dot{r} = \frac{L^2}{km} \frac{-\varepsilon \sin\phi \dot{\phi}}{(1 - \varepsilon \cos\phi)^2} & using: \frac{1}{mr} = \frac{L}{m} \frac{1}{r} = \frac{L}{m} \left(\frac{km}{L^2}\right)^2 (1 - \varepsilon \cos\phi) = \frac{k}{L} (1 - \varepsilon \cos\phi)^2 \\ \dot{r} = -\frac{L^2}{km} \left(\frac{km}{L^2}\right)^2 r^2 \dot{\phi} \varepsilon \sin\phi & using: \frac{1}{(1 - \varepsilon \cos\phi)^2} = \left(\frac{km}{L^2}\right)^2 r^2 \\ \dot{r} = -\frac{k}{L^2} mr^2 \dot{\phi} \varepsilon \sin\phi = -\frac{k}{L} \varepsilon \sin\phi & again using: L = mr^2 \dot{\phi} \\ \end{aligned}$$

$$\begin{aligned} \text{Cartesian $x = r \cos\phi$:} & \text{Cartesian $y = r \sin\phi$:} \\ \dot{x} = \frac{dx}{dt} = -r \cos\phi - \sin\phi r \phi & y = \frac{dy}{dt} = -r \sin\phi + \cos\phi r \phi \\ &= -\frac{k}{L} \sin\phi & \text{(Velocity:} & = \frac{k}{L} (\cos\phi - \varepsilon) \\ \hline p_x = m\dot{x} = -\frac{mk}{L} \sin\phi & \text{(Momentum)} \\ \hline p_y = m\dot{y} = \frac{mk}{L} (\cos\phi - \varepsilon) \end{aligned}$$

Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry Review and connection to standard development  $\varepsilon$ -vector and Coulomb **p**=m**v** geometry  $\varepsilon$ -vector and Coulomb **p**=m**v** algebra  $\blacktriangleright$  Example with elliptical orbit Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry Connection formulas for (a,b) and ( $\varepsilon, \lambda$ ) with ( $\gamma, \mathbf{R}$ )






















Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry Review and connection to standard development  $\varepsilon$ -vector and Coulomb **p**=m**v** geometry  $\varepsilon$ -vector and Coulomb **p**=m**v** algebra Example with elliptical orbit  $\bullet$  Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry Connection formulas for (a,b) and ( $\varepsilon, \lambda$ ) with ( $\gamma, \mathbf{R}$ )



Next several pages give *step-by-step constructions* of  $\varepsilon$ -vector and Coulomb orbit and trajectory physics

## $\varepsilon$ -vector and Coulomb orbit construction steps

Pick launch point P (radius vector  $\mathbf{r}$ ) and elevation angle  $\gamma$  from radius (momentum initial  $\mathbf{p}$  direction)



Next several pages give step-by-step constructions of  $\varepsilon$ -vector and Coulomb orbit and trajectory physics

## $\varepsilon$ -vector and Coulomb orbit construction steps

Copy F-center circle around launch point P Pick launch point P *Copy elevation angle*  $\gamma$  ( $\angle$ FPP') *onto*  $\angle$ P'PQ (radius vector **r**) and elevation angle  $\gamma$  from radius Extend resulting line QPQ' to make focus locus (momentum initial **p** direction ) inital momentum *wpied* elevation angle  $\gamma$ D inital momentum elevation angle  $\gamma$ Reason for focus loc Line **r** from 1<sup>st</sup> focus **F**/"reflects line **p** (or **P'P**) toward 2<sup>nd</sup> focus **F** somewhere so incident-angle  $\gamma$  equals reflected-angle  $\gamma$ 

Next several pages give step-by-step constructions of  $\varepsilon$ -vector and Coulomb orbit and trajectory physics









Eccentricity vector ε and (ε,λ)-geometry of orbital mechanics
ε-vector and Coulomb r-orbit geometry
Review and connection to standard development
ε-vector and Coulomb p=mv geometry
ε-vector and Coulomb p=mv algebra
Example with elliptical orbit
Analytic geometry derivation of ε-construction
Algebra of ε-construction geometry
Connection formulas for (a,b) and (ε,λ) with (γ, R)











Eccentricity vector  $\varepsilon$  and  $(\varepsilon, \lambda)$ -geometry of orbital mechanics  $\varepsilon$ -vector and Coulomb **r**-orbit geometry Review and connection to standard development  $\varepsilon$ -vector and Coulomb **p**=m**v** geometry  $\varepsilon$ -vector and Coulomb **p**=m**v** algebra Example with elliptical orbit Analytic geometry derivation of  $\varepsilon$ -construction Algebra of  $\varepsilon$ -construction geometry  $\checkmark$  Connection formulas for (a,b) and ( $\varepsilon, \lambda$ ) with ( $\gamma, \mathbf{R}$ ) Algebra of  $\varepsilon$ -construction geometry The eccentricty parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$ 

$$\varepsilon^{2} = 1 + 4R(R+1)\sin^{2}\gamma$$
$$= 1 - \frac{b^{2}}{a^{2}} \quad \text{for ellipse} \quad (\varepsilon < 1)$$
$$= 1 + \frac{b^{2}}{a^{2}} \quad \text{for hyperbola} \ (\varepsilon > 1)$$

Three pairs of parameters for Coulomb orbits: 1.Cartesian (a,b), 2.Physics (E,L), 3.Polar  $(\varepsilon, \lambda)$ Now we relate a 4th pair: 4.Initial  $(\gamma, \mathbf{R})$  Algebra of  $\varepsilon$ -construction geometry The eccentricty parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$ 

$$\varepsilon^{2} = 1 + 4R(R+1)\sin^{2}\gamma$$

$$= 1 - \frac{b^{2}}{a^{2}} \quad \text{for ellipse} \quad (\varepsilon < 1) \quad \text{where:} \quad 4R(R+1)\sin^{2}\gamma = -\frac{b^{2}}{a^{2}} = \varepsilon^{2} - 1$$

$$= 1 + \frac{b^{2}}{a^{2}} \quad \text{for hyperbola} \ (\varepsilon > 1) \quad \text{where:} \quad 4R(R+1)\sin^{2}\gamma = +\frac{b^{2}}{a^{2}} = \varepsilon^{2} - 1$$

Three pairs of parameters for Coulomb orbits: 1.Cartesian (a,b), 2.Physics (E,L), 3.Polar  $(\varepsilon, \lambda)$ Now we relate a 4th pair: 4.Initial  $(\gamma, \mathbf{R})$  Algebra of  $\varepsilon$ -construction geometry The eccentricty parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$  Three pairs of parameters for Coulomb orbits: 1.Cartesian (a,b), 2.Physics (E,L), 3.Polar ( $\varepsilon$ , $\lambda$ ) Now we relate a 4th pair: 4.Initial ( $\gamma$ ,**R**)

$$\varepsilon^{2} = 1 + 4R(R+1)\sin^{2}\gamma$$

$$= 1 - \frac{b^{2}}{a^{2}} \text{ for ellipse } (\varepsilon < 1) \text{ where: } 4R(R+1)\sin^{2}\gamma = -\frac{b^{2}}{a^{2}} = \varepsilon^{2} - 1 \text{ implying: } R(R+1) < 0$$

$$= 1 + \frac{b^{2}}{a^{2}} \text{ for hyperbola } (\varepsilon > 1) \text{ where: } 4R(R+1)\sin^{2}\gamma = +\frac{b^{2}}{a^{2}} = \varepsilon^{2} - 1 \text{ implying: } R(R+1) > 0$$

Algebra of  $\varepsilon$ -construction geometryThree pairs of parameters for Coulomb orbits:<br/>1. Cartesian (a,b), 2. Physics (E,L), 3. Polar ( $\varepsilon$ ,  $\lambda$ )<br/>Now we relate a 4th pair: 4. Initial ( $\gamma$ , R)The eccentricty parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$ Three pairs of parameters for Coulomb orbits:<br/>1. Cartesian (a,b), 2. Physics (E,L), 3. Polar ( $\varepsilon$ ,  $\lambda$ )<br/>Now we relate a 4th pair: 4. Initial ( $\gamma$ , R) $\varepsilon^2 = 1+4R(R+1)\sin^2\gamma$ <br/> $= 1-\frac{b^2}{a^2}$  for ellipse ( $\varepsilon < 1$ ) where:  $4R(R+1)\sin^2\gamma = -\frac{b^2}{a^2} = \varepsilon^2 - 1$  implying: R(R+1) < 0 (or:  $-R^2 > R$ )<br/>(or: 0 > R > -1)<br/> $= 1+\frac{b^2}{a^2}$  for hyperbola ( $\varepsilon > 1$ ) where:  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2} = \varepsilon^2 - 1$  implying: R(R+1) > 0 (or:  $-R^2 < R$ )<br/>(or: 0 < R < -1)

Algebra of  $\varepsilon$ -construction geometry The eccentricity parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$ Three pairs of parameters for Coulomb orbits: 1. Cartesian (a,b), 2. Physics (E,L), 3. Polar  $(\varepsilon,\lambda)$ Now we relate a 4th pair: 4. Initial  $(\gamma, R)$   $\varepsilon^2 = 1+4R(R+1)\sin^2\gamma$   $= 1 - \frac{b^2}{a^2}$ for ellipse  $(\varepsilon < 1)$  where:  $4R(R+1)\sin^2\gamma = -\frac{b^2}{a^2} = \varepsilon^2 - 1$  implying: R(R+1) < 0 (or:  $-R^2 > R$ ) (or: 0 > R > -1)  $= 1 + \frac{b^2}{a^2}$ for hyperbola  $(\varepsilon > 1)$  where:  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2} = \varepsilon^2 - 1$  implying: R(R+1) > 0 (or:  $-R^2 < R$ ) (or: 0 < R < -1)Total  $\frac{-k}{2a} = \varepsilon = energy = KE + PE$  relates ratio  $R = \frac{KE}{PE}$  to individual radii  $a, b, \text{ and } \lambda$ .  $\frac{-k}{2a} = E = KE + PE = R \cdot PE + PE = (R+1)PE = (R+1)\frac{-k}{r}$  or:  $\frac{1}{2a} = (R+1)\frac{1}{r} = (R+1)$ 

*Three pairs of parameters for Coulomb orbits:* Algebra of  $\varepsilon$ -construction geometry 1. Cartesian (a,b), 2. Physics (E,L), 3. Polar ( $\varepsilon$ ,  $\lambda$ ) The *eccentricty* parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$ Now we relate a 4th pair: 4. Initial  $(\gamma, \mathbf{R})$  $\varepsilon^2 = 1 + 4R(R+1)\sin^2\gamma$  $=1-\frac{b^2}{a^2} \quad \text{for ellipse} \quad (\varepsilon < 1) \text{ where: } 4R(R+1)\sin^2\gamma = -\frac{b^2}{a^2} = \varepsilon^2 - 1 \text{ implying: } R(R+1) < 0 \quad (\text{or: } -R^2 > R) \\ (\text{or: } 0 > R > -1) \quad (\text{or: } 0 > R > =1+\frac{b^2}{a^2} \text{ for hyperbola } (\varepsilon > 1) \text{ where: } 4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2} = \varepsilon^2 - 1 \text{ implying: } R(R+1) > 0 \quad (\text{or: } -R^2 < R) \text{ (or: } 0 < R < -1)$ Total  $\frac{-k}{2a} = E = energy = KE + PE$  relates ratio  $R = \frac{KE}{PE}$  to individual radii a, b, and  $\lambda$ .  $\frac{-k}{2a} = E = KE + PE = \mathbf{R} \cdot PE + PE = (\mathbf{R}+1)PE = (\mathbf{R}+1)\frac{-k}{r} \text{ or: } \frac{1}{2a} = (\mathbf{R}+1)\frac{1}{r} = (\mathbf{R}+1)$  $a = \frac{r}{2(\mathbf{R}+1)} = \left(\frac{1}{2(\mathbf{R}+1)} \text{ assuming unit initial radius } (r \equiv 1).\right)$ 

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Latus radius is similarly related:

$$\lambda = \frac{b^2}{a} = \mp 2r R \sin^2 \gamma$$

Algebra of 
$$\varepsilon$$
-construction geometry  
The eccentricity parameter relates ratios  $R = \frac{KE}{PE}$  and  $\frac{b^2}{a^2}$   
 $\varepsilon^2 = 1+4R(R+1)\sin^2\gamma$   
 $= 1 - \frac{b^2}{a^2}$  ellipse( $\varepsilon < 1$ )  $4R(R+1)\sin^2\gamma = -\frac{b^2}{a^2}$   
 $= 1 + \frac{b^2}{a^2}$  hyperbola ( $\varepsilon > 1$ )  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2}$   
 $= 1 + \frac{b^2}{a^2}$  hyperbola ( $\varepsilon > 1$ )  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2}$   
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 $= 1 + \frac{b^2}{a^2}$  hyperbola ( $\varepsilon > 1$ )  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2}$   
 $= 1 + \frac{b^2}{a^2} + \frac{b^2}{a^2}$  hyperbola ( $\varepsilon > 1$ )  $4R(R+1)\sin^2\gamma = +\frac{b^2}{a^2}$   
 $= 1 + \frac{b^2}{a^2} + \frac{b^2}{a^2} + \frac{b^2}{a^2}$   
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From  $\varepsilon^2$  result (at top):  
 $\frac{b}{a} = 2\sqrt{+R(R+1)}\sin\gamma = \sqrt{\pm(1-\varepsilon^2)}$ 

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