

Lecture 22 C_N Wave Modes

Thursday 3.31.2016

C_N -Symmetric Wave Modes and 2-CW Algebra and Geometry

(Ch. 5 of Unit 4 3.31.16)

Wave resonance in cyclic C_n symmetry (REVIEW)

C_6 symmetric mode model: Distant neighbor coupling

C_6 moving waves and degenerate standing waves

C_6 dispersion functions for 1st, 2nd, and 3rd-neighbor coupling

*C_6 dispersion functions split by **C-type** symmetry (complex, chiral, ...)*

C_{12} and higher symmetry mode models: Archetypes of dispersion functions and 1-CW phase velocity

$\frac{1}{2}$ -Sum- $\frac{1}{2}$ -Diff-theory of 2-CW group and phase velocity

Given two 1-CW phases: Find 2-CW phase velocity $V_{\text{phase}}^{(2\text{-CW})}$ and group velocity $V_{\text{group}}^{(2\text{-CW})}$

Example: Bohr Dispersion 2-CW made of 1-CW($m=-1$) + 1-CW($m=2$)

Find 2-CW space-time (x,t) lattice from per-space-time (κ,v) by matrix-algebra/geometry

Same 1-CW($m=-1$) + 1-CW($m=2$) Example

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Easy to resolve spectral projectors $\mathbf{P}^{(m)}$ and eigen-bra-vectors $\langle (m) |$

$$\mathbf{P}^{(0)} = \frac{1}{3}(\mathbf{r}^0 + \mathbf{r}^1 + \mathbf{r}^2) = \frac{1}{3}(1 + \mathbf{r}^1 + \mathbf{r}^2)$$

$$\mathbf{P}^{(1)} = \frac{1}{3}(\mathbf{r}^0 + \rho_1^* \mathbf{r}^1 + \rho_2^* \mathbf{r}^2) = \frac{1}{3}(1 + e^{-i2\pi/3} \mathbf{r}^1 + e^{+i2\pi/3} \mathbf{r}^2)$$

$$\mathbf{P}^{(2)} = \frac{1}{3}(\mathbf{r}^0 + \rho_2^* \mathbf{r}^1 + \rho_1^* \mathbf{r}^2) = \frac{1}{3}(1 + e^{+i2\pi/3} \mathbf{r}^1 + e^{-i2\pi/3} \mathbf{r}^2)$$

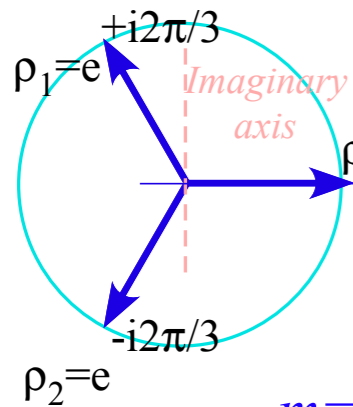
$$\langle (0_3) | = \langle 0 | \mathbf{P}^{(0)} \sqrt{3} = \sqrt{\frac{1}{3}} (1 \quad 1 \quad 1)$$

$$\langle (1_3) | = \langle 0 | \mathbf{P}^{(1)} \sqrt{3} = \sqrt{\frac{1}{3}} (1 \quad e^{-i2\pi/3} \quad e^{+i2\pi/3})$$

$$\langle (2_3) | = \langle 0 | \mathbf{P}^{(2)} \sqrt{3} = \sqrt{\frac{1}{3}} (1 \quad e^{+i2\pi/3} \quad e^{-i2\pi/3})$$

Basic "trinary" $\rho_{mp} =$
 wavefunction: $\psi^{k_m}(x_p) = e^{ik_m x_p} = e^{i \frac{2\pi m p}{3}}$

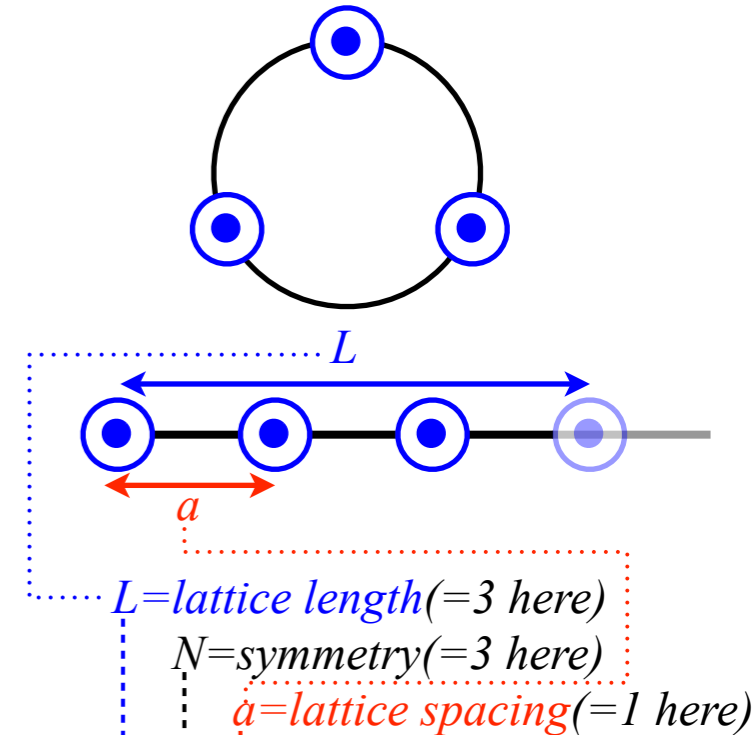
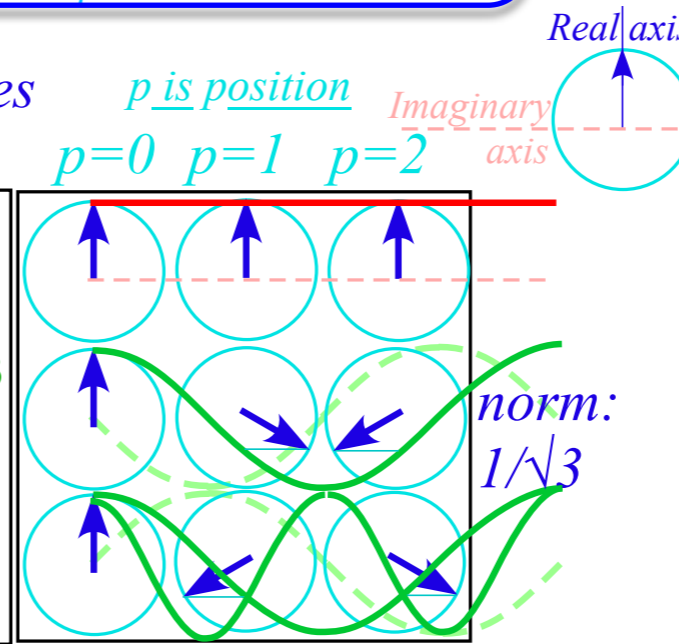
(m_3) means: m -modulo-3 (Details follow)



C_3 mode phase character tables

wave-number
 $m =$
 "momentum"

	$p=0$	$p=1$	$p=2$
$m=0_3$	$\rho_{00}^* = 1$	$\rho_{01}^* = 1$	$\rho_{02}^* = 1$
$m=1_3$	$\rho_{10}^* = 1$	$\rho_{11}^* = e^{-i2\pi/3}$	$\rho_{12}^* = e^{i2\pi/3}$
$m=2_3$	$\rho_{20}^* = 1$	$\rho_{21}^* = e^{i2\pi/3}$	$\rho_{22}^* = e^{-i2\pi/3}$



Two distinct types of "quantum" numbers.

$p=0,1,$ or 2 is *power* p of operator \mathbf{r}^p and defines each oscillator's *position point* p .

$m=0,1,$ or 2 is *mode momentum* m of the waves or wavevector $k_m = 2\pi/\lambda_m = 2\pi m/L$. ($L = Na = 3$)
 wavelength $\lambda_m = 2\pi/k_m = L/m$

Each quantum number follows *modular arithmetic*: sums or products are an *integer-modulo-3*, that is, always $0,1,$ or 2 , or else $-1,0,$ or 1 , or else $-2,-1,$ or 0 , etc., depending on choice of origin.

For example, for $m=2$ and $p=2$ the number $(\rho_m)^p = (e^{im2\pi/3})^p$ is $e^{imp \cdot 2\pi/3} = e^{i4 \cdot 2\pi/3} = e^{i1 \cdot 2\pi/3} e^{i2\pi} = e^{i2\pi/3} = \rho_1$.
 That is, $(2\text{-times-}2) \bmod 3$ is not 4 but 1 ($4 \bmod 3 = 1$, the remainder of 4 divided by 3 .)

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Same 1-CW($m=-1$) + 1-CW($m=2$) Example

C₆ Symmetric Mode Model: 1st neighbor coupling

We usually assume Real $r = \bar{r}$
 Stability only requires $(r)^* = \bar{r}$

(a) 1st Neighbor C₆

$$\mathbf{H}^{\text{B1}(6)} = \begin{pmatrix} H_1 & -r & \cdot & \cdot & \cdot & -\bar{r} \\ -\bar{r} & H_1 & -r & \cdot & \cdot & \cdot \\ \cdot & -\bar{r} & H_1 & -r & \cdot & \cdot \\ \cdot & \cdot & -\bar{r} & H_1 & -r & \cdot \\ \cdot & \cdot & \cdot & -\bar{r} & H_1 & -r \\ -r & \cdot & \cdot & \cdot & -\bar{r} & H_1 \end{pmatrix} \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix}$$

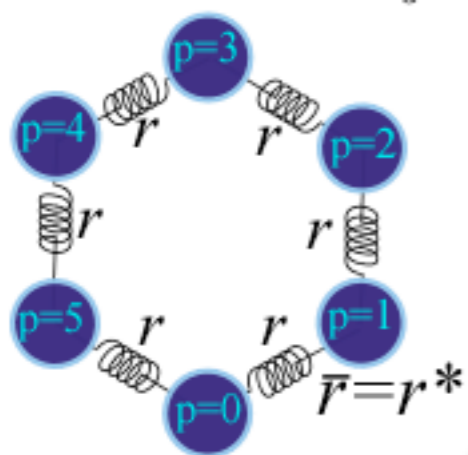
$$= H_1 \mathbf{1} - r \mathbf{r} - \bar{r} \mathbf{r}^{-1}$$


Fig. 12 *International Journal of Molecular Science* 14, 749 (2013)

C₆ Symmetric Mode Model: 1st and 2nd neighbor coupling

We usually assume Real $r = \bar{r}$
 Stability only requires $(r)^* = \bar{r}$

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$$= H_1 \mathbf{1} - r\mathbf{r} - \bar{r}\mathbf{r}^{-1}$$

(b) 2nd Neighbor C₆

...same with s

$$\mathbf{H}^{B2(6)} = \begin{pmatrix} H_2 & \cdot & -s & \cdot & -\bar{s} & \cdot \\ \cdot & H_2 & \cdot & -s & \cdot & -\bar{s} \\ -\bar{s} & \cdot & H_2 & \cdot & -s & \cdot \\ \cdot & -\bar{s} & \cdot & H_2 & \cdot & -s \\ -s & \cdot & -\bar{s} & \cdot & H_2 & \cdot \\ \cdot & -s & \cdot & -\bar{s} & \cdot & H_2 \end{pmatrix} \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix}$$

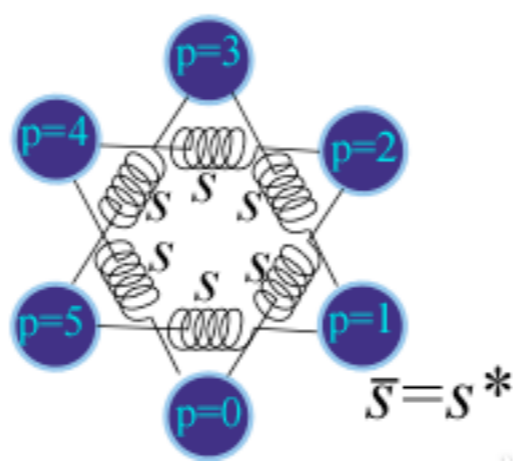
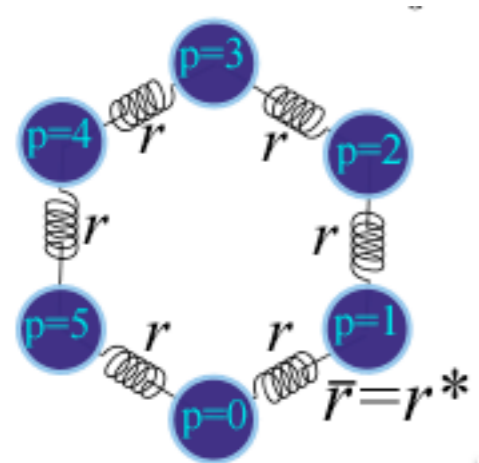
$$= H_2 \mathbf{1} - s\mathbf{r}^2 - \bar{s}\mathbf{r}^{-2}$$


Fig. 12 International Journal of Molecular Science 14, 749 (2013)

C₆ Symmetric Mode Model: 1st, 2nd and 3rd neighbor coupling

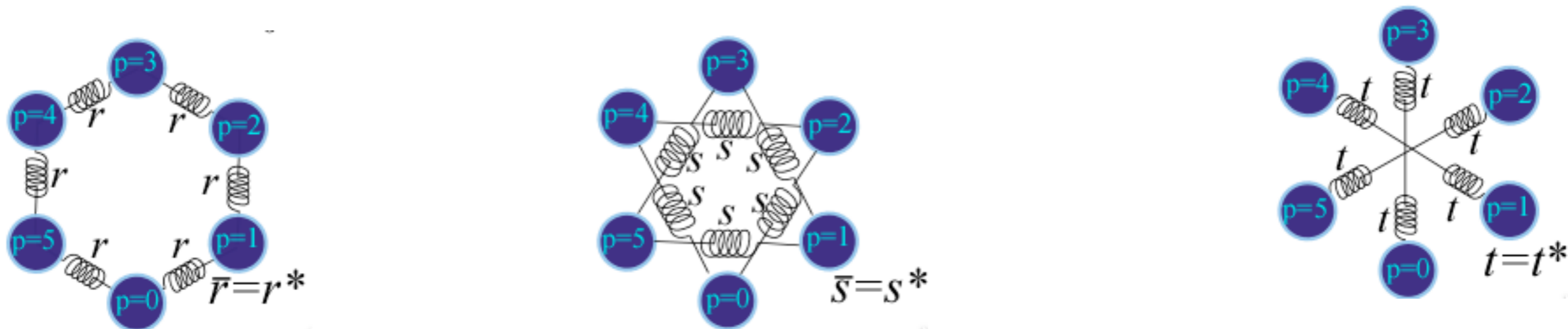
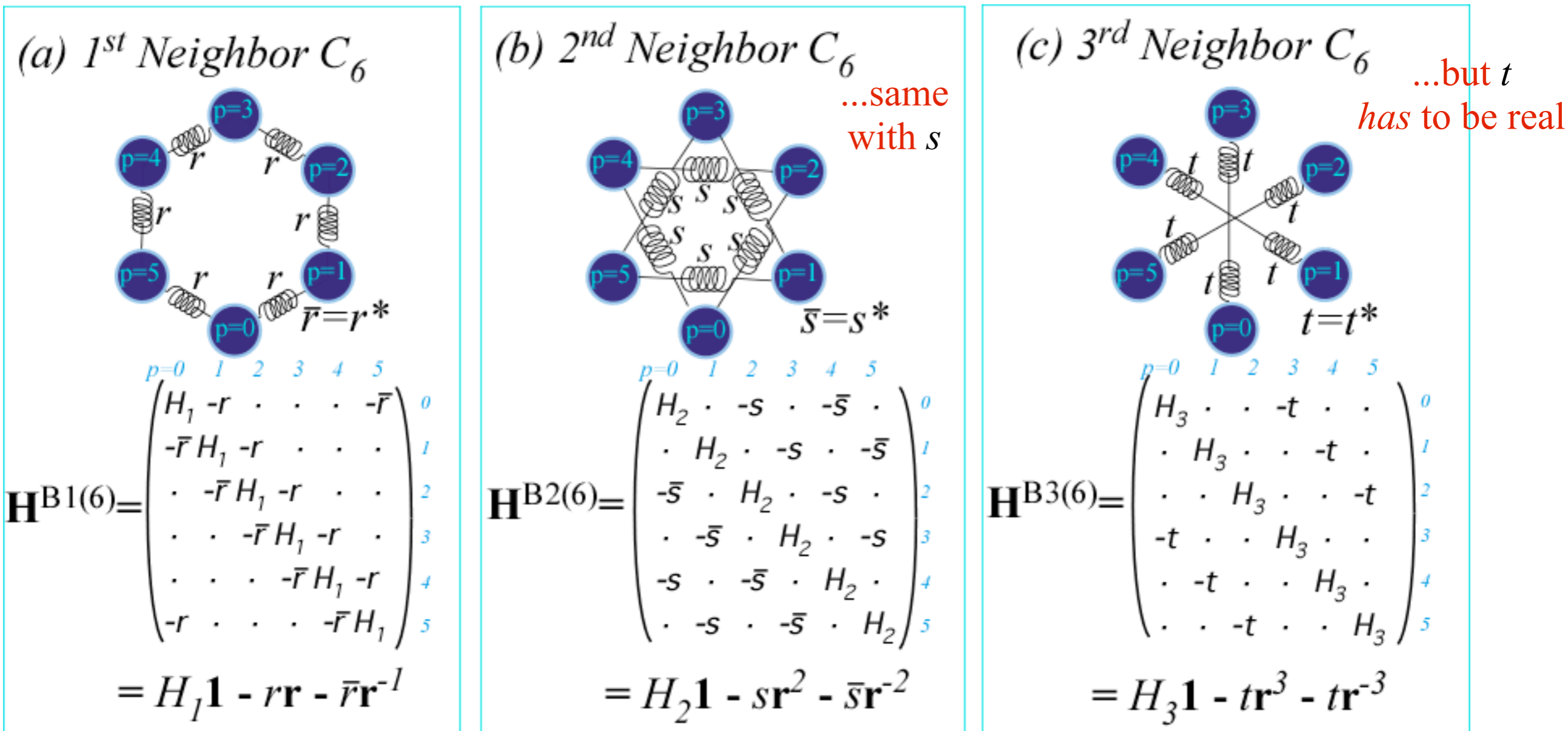


Fig. 12 International Journal of Molecular Science 14, 749 (2013)

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Example: Bohr Dispersion 2-CW made of 1-CW($m=-1$) + 1-CW($m=2$)

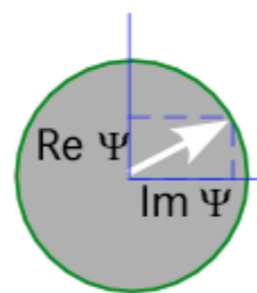
Find 2-CW space-time (x,t) lattice from per-space-time (κ,ν) by matrix-algebra/geometry

Same 1-CW($m=-1$) + 1-CW($m=2$) Example

C₆ Spectral resolution: 6th roots of unity

$\chi_p^{m*} (C_6)$	$r^{p=0}$	r^1	r^2	r^3	r^4	r^5
$m=0_6$	1	1	1	1	1	1
1_6	1	ϵ^*	ϵ^{2*}	-1	ϵ^2	ϵ
2_6	1	ϵ^{2*}	ϵ^2	1	ϵ^{2*}	ϵ^2
$3_6 = -3_6$	1	-1	1	-1	1	-1
$4_6 = -2_6$	1	ϵ^2	ϵ^{2*}	1	ϵ^2	ϵ^{2*}
$5_6 = -1_6$	1	ϵ	ϵ^2	-1	ϵ^{2*}	ϵ^*

Wavefunction: $\Psi^m(x_p) = \chi_p^{m*} = D^{m*}(r^p)$



$m_n = 0_6$

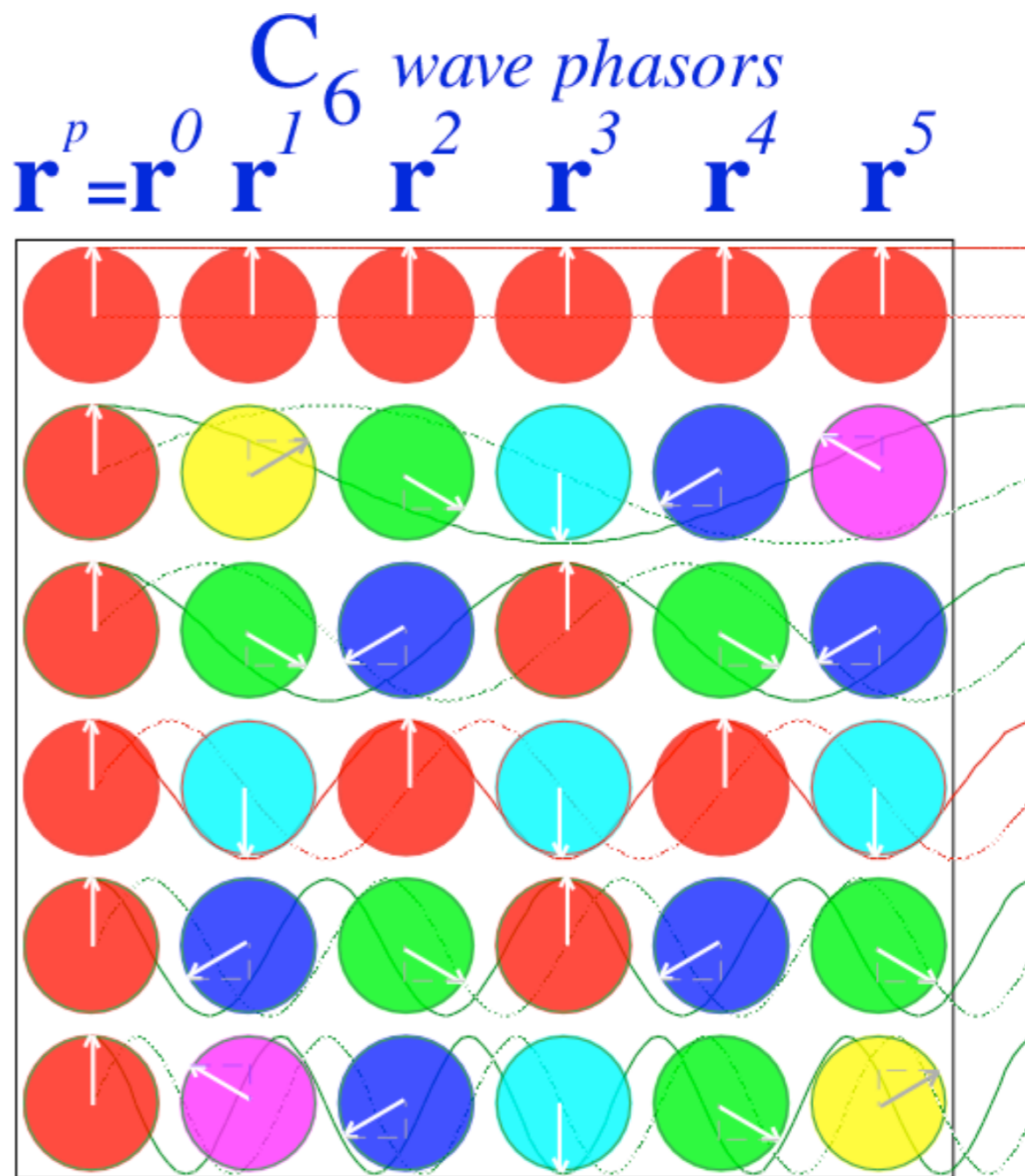
1_6

2_6

$3_6 = -3_6$

$4_6 = -2_6$

$5_6 = -1_6$



$$\chi_p^m = e^{ik_m r^p} = e^{\frac{2\pi i m p}{6}}$$

[WaveIt C₆ Character Phasors Web Simulation](#)

Fig. 13 *International Journal of Molecular Science* 14, 752 (2013)

C₆ Spectral resolution: 6th roots of unity

$\chi_p^{m*}(C_6)$	$r^{p=0}$	r^1	r^2	r^3	r^4	r^5
$m=0_6$	1	1	1	1	1	1
1_6	1	ϵ^*	ϵ^{2*}	-1	ϵ^2	ϵ
2_6	1	ϵ^{2*}	ϵ^2	1	ϵ^{2*}	ϵ^2
$3_6 = -3_6$	1	-1	1	-1	1	-1
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Wavefunction: $\Psi^m(x_p) = \chi_p^{m*} = D^{m*}(r^p)$

WaveIt

Local Controls

Number of x-Grid Points =

Number of Oscillators C(n) =

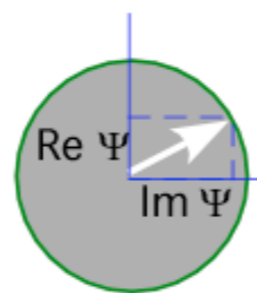
Upper Brillouin Zone order =

Lower Brillouin Zone order =

Dispersion Dependence

WaveIt Scenarios

[WaveIt C₆ Character Phasors Web Simulation](#)



$m_n = 0_6$

1_6

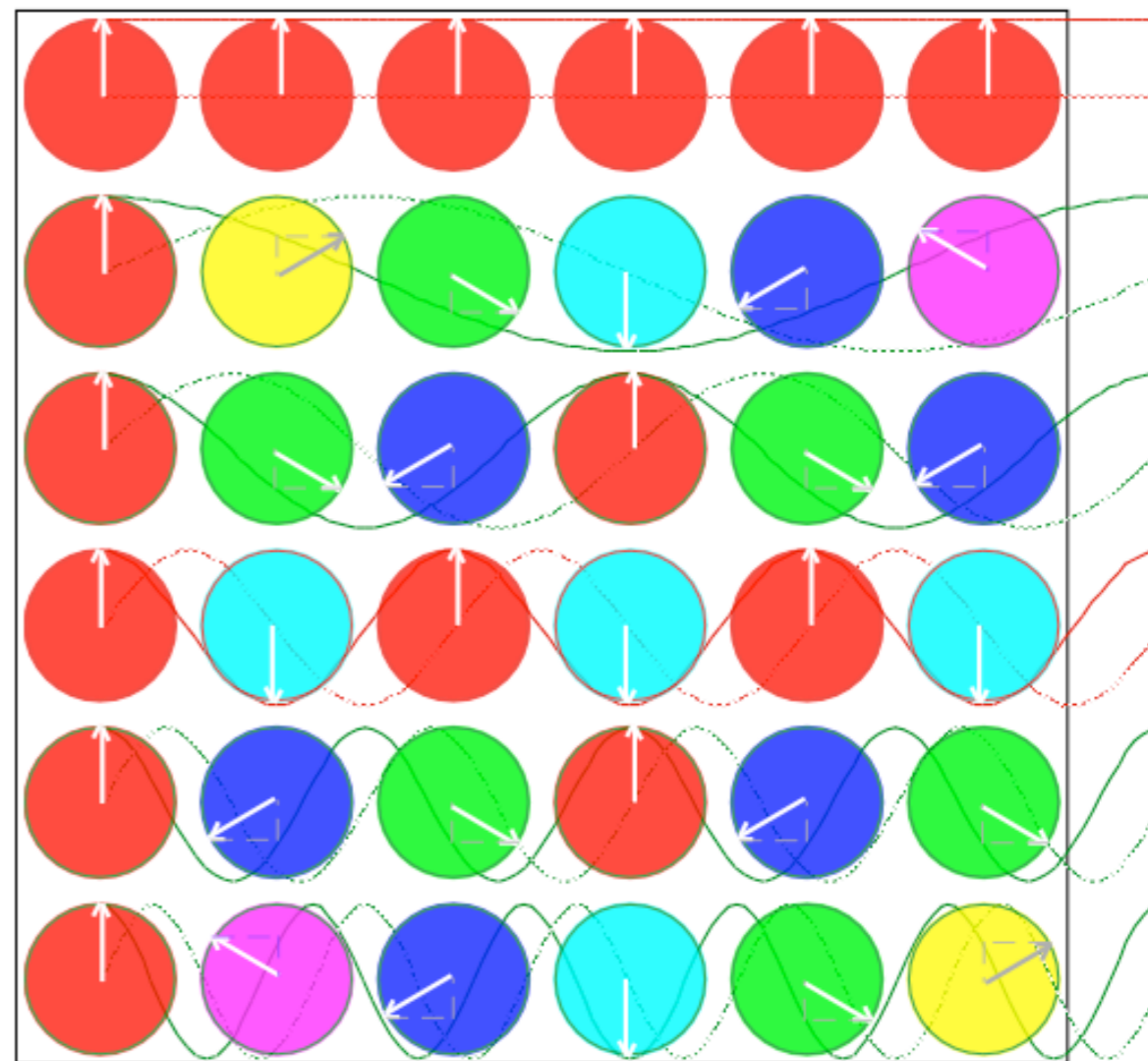
2_6

$3_6 = -3_6$

$4_6 = -2_6$

$5_6 = -1_6$

C₆ wave phasors
 $r^p = r^0 \quad r^1 \quad r^2 \quad r^3 \quad r^4 \quad r^5$



$$\chi_p^m = e^{ik_m r^p} = e^{\frac{2\pi i m p}{6}}$$

Fig. 13 International Journal of Molecular Science 14, 752 (2013)

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C₆ Spectral resolution of nth Neighbor H: Same modes but different dispersion

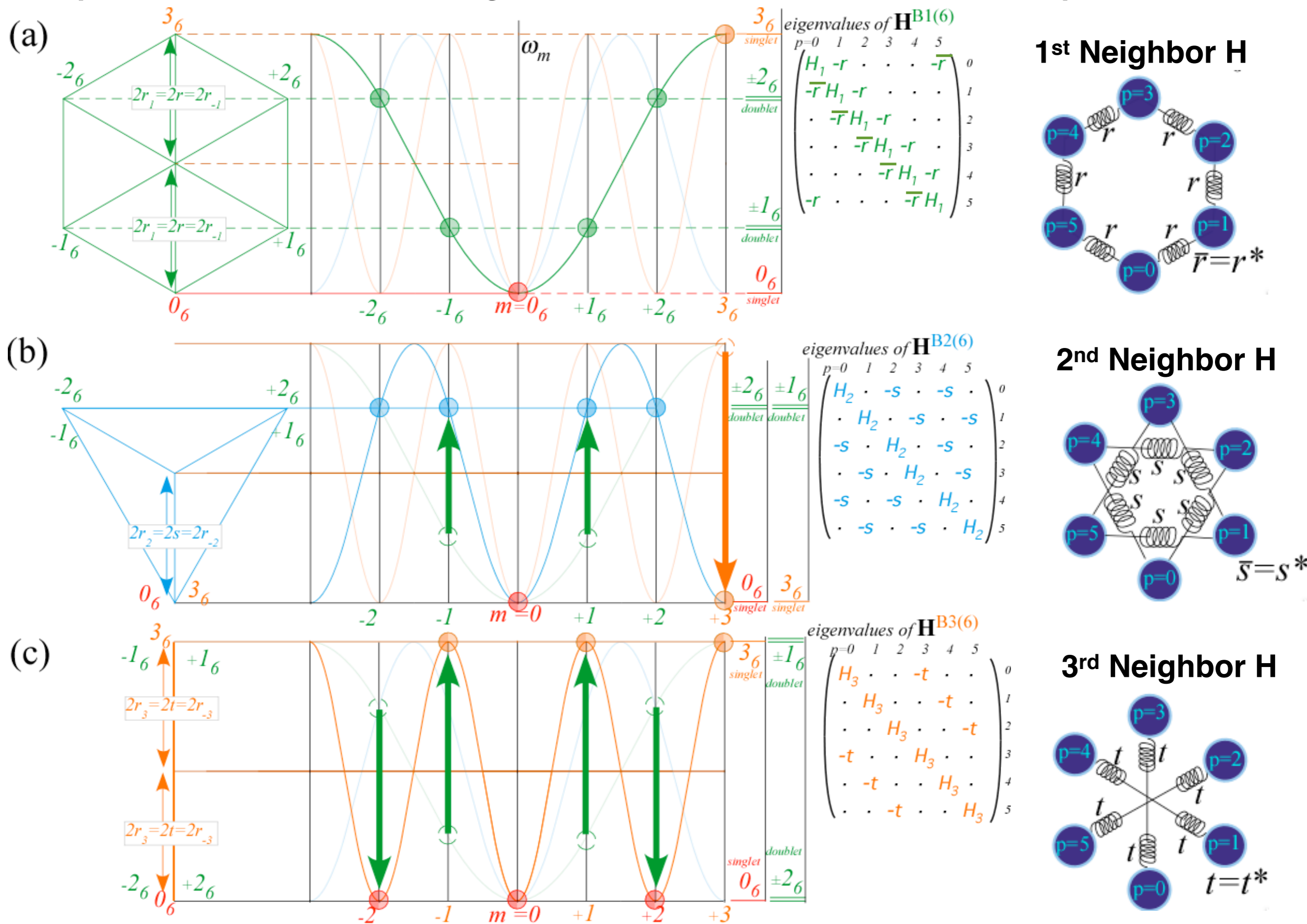


Fig. 14 International Journal of Molecular Science 14, 754 (2013)

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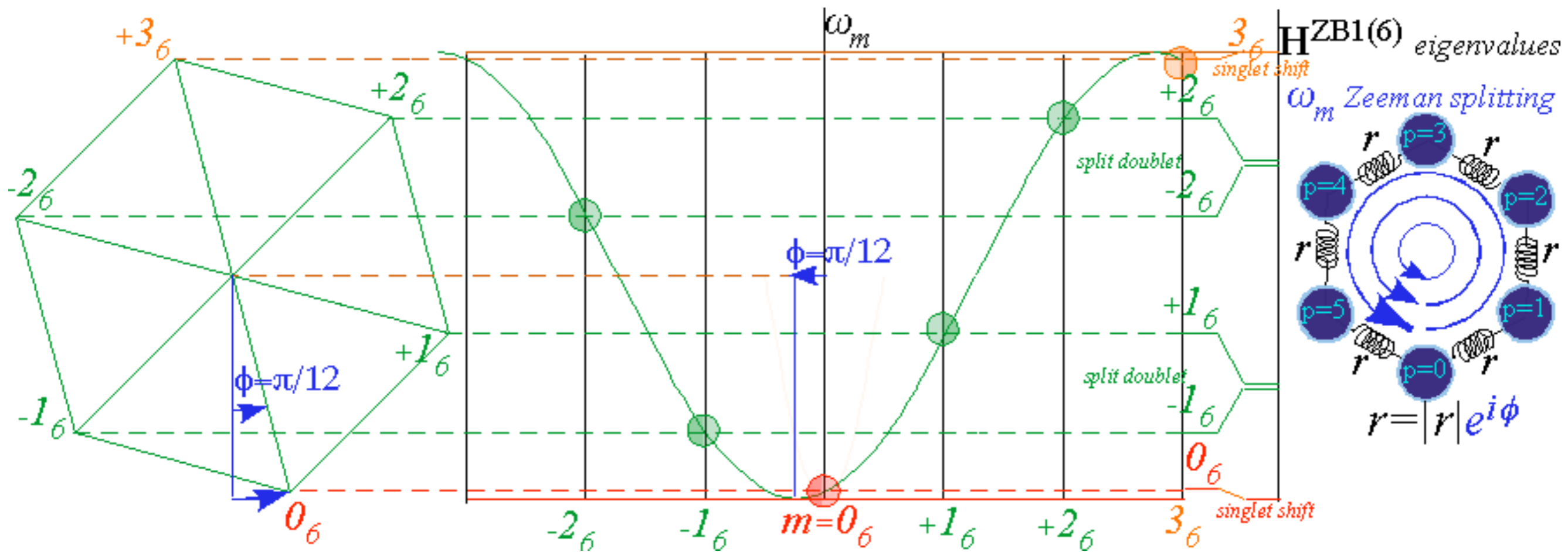
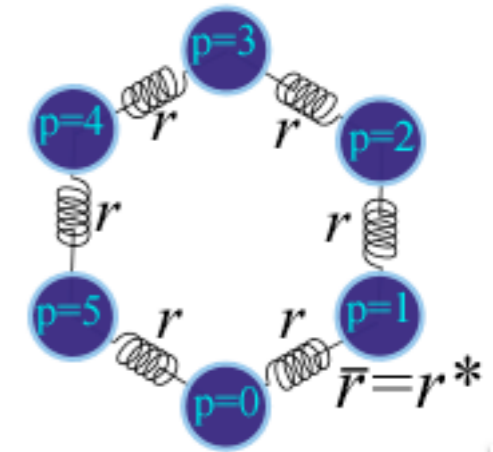
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Same 1-CW($m=-1$) + 1-CW($m=2$) Example

C₆ Spectra of 1st neighbor gauge splitting by C-type (Chiral, Coriolis,...,

1st Neighbor H



Standing wave combinations like $\cos kx = (e^{+ikx} + e^{-ikx})/2$ are not eigenmodes unless $\phi=0$.

Fig. 15 International Journal of Molecular Science 14, 755 (2013)

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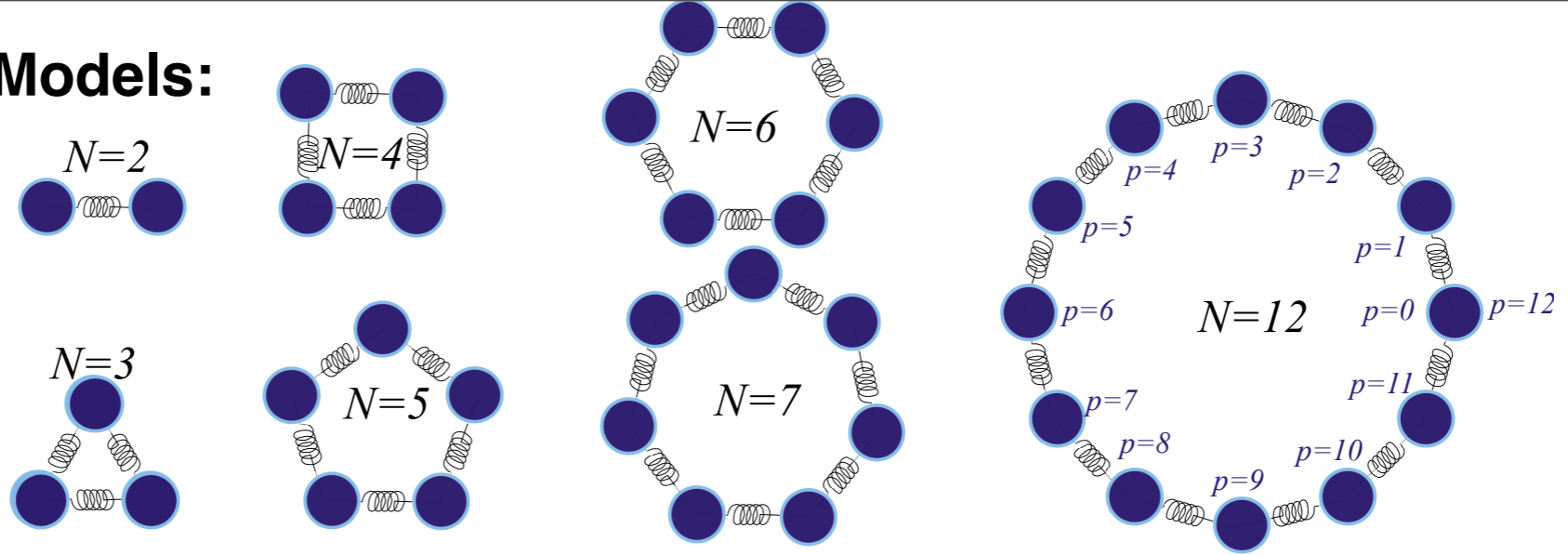
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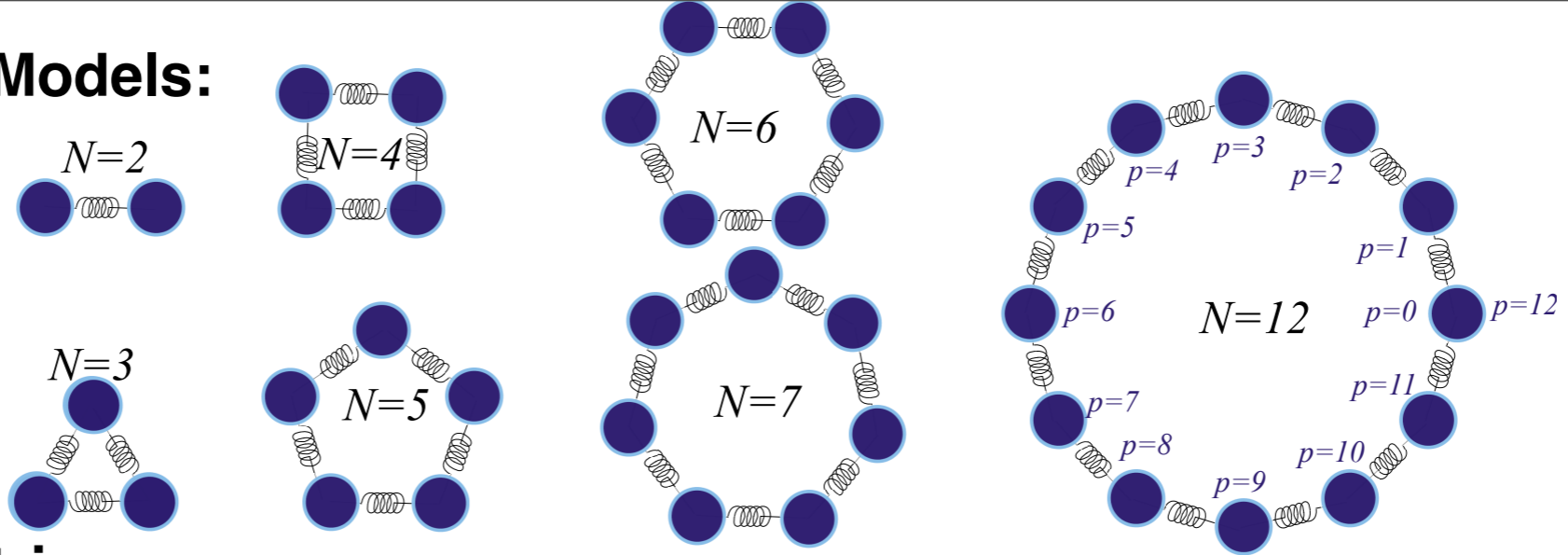
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C_N Symmetric Mode Models:



*Fig. 4.8.4
Unit 4
CMwBang*

C_N Symmetric Mode Models:



1st Neighbor K-matrix

$$- \begin{pmatrix} F_0 \\ F_1 \\ F_2 \\ F_3 \\ F_4 \\ \vdots \\ F_{N-1} \end{pmatrix} = \begin{pmatrix} K & -k_{12} & \cdot & \cdot & \cdot & \cdots & -k_{12} \\ -k_{12} & K & -k_{12} & \cdot & \cdot & \cdots & \cdot \\ \cdot & -k_{12} & K & -k_{12} & \cdot & \cdots & \cdot \\ \cdot & \cdot & -k_{12} & K & -k_{12} & \cdots & \cdot \\ \cdot & \cdot & \cdot & -k_{12} & K & \cdots & \cdot \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & -k_{12} \\ -k_{12} & \cdot & \cdot & \cdot & \cdot & -k_{12} & K \end{pmatrix} \bullet \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ \vdots \\ x_{N-1} \end{pmatrix}$$

where:

$$K = k + 2k_{12}$$

$$k = \frac{Mg}{\ell}$$

$$(\cdot) = 0$$

Fig. 4.8.4
Unit 4
CMwBang

C_N Symmetric Mode Models:

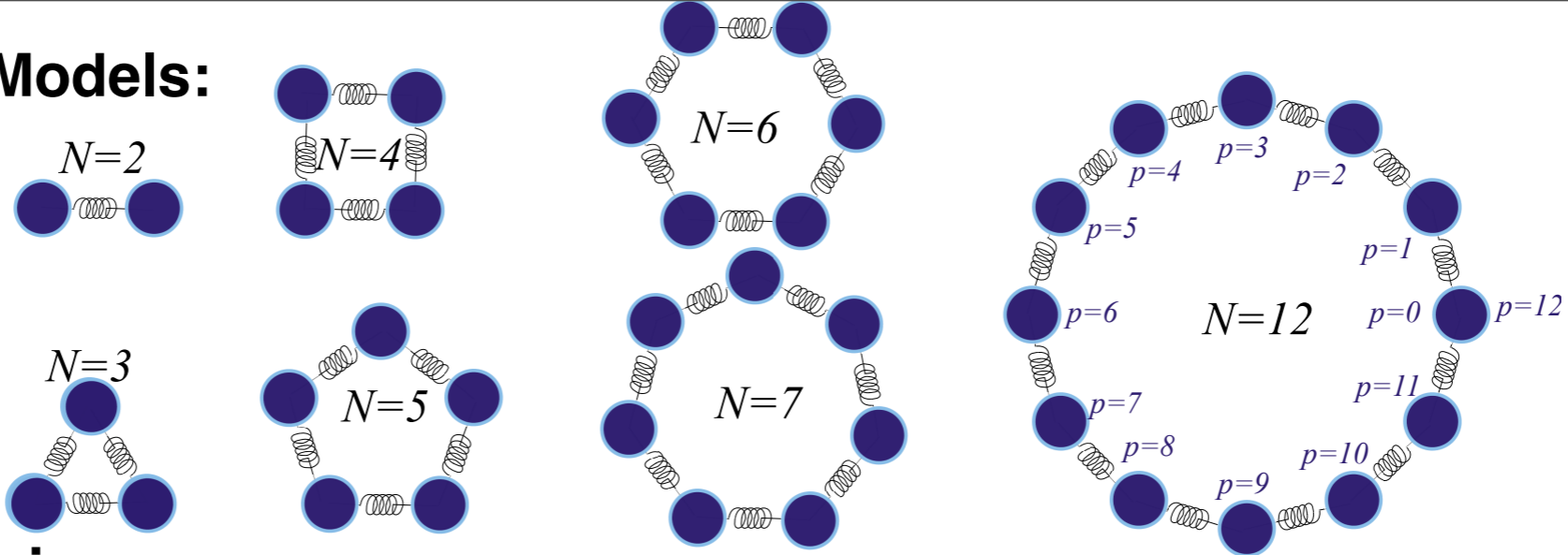


Fig. 4.8.4
Unit 4
CMwBang

1st Neighbor K-matrix

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where: $K = k + 2k_{12}$
 $k = \frac{Mg}{\ell}$
 $(\cdot) = 0$

Nth roots of 1 $e^{i m \cdot p 2\pi/N} = \langle m | \mathbf{r}^p | m \rangle$ serving as *e-values*, *eigenfunctions*, *transformation matrices*, *dispersion relations*, *Group reps.* etc.

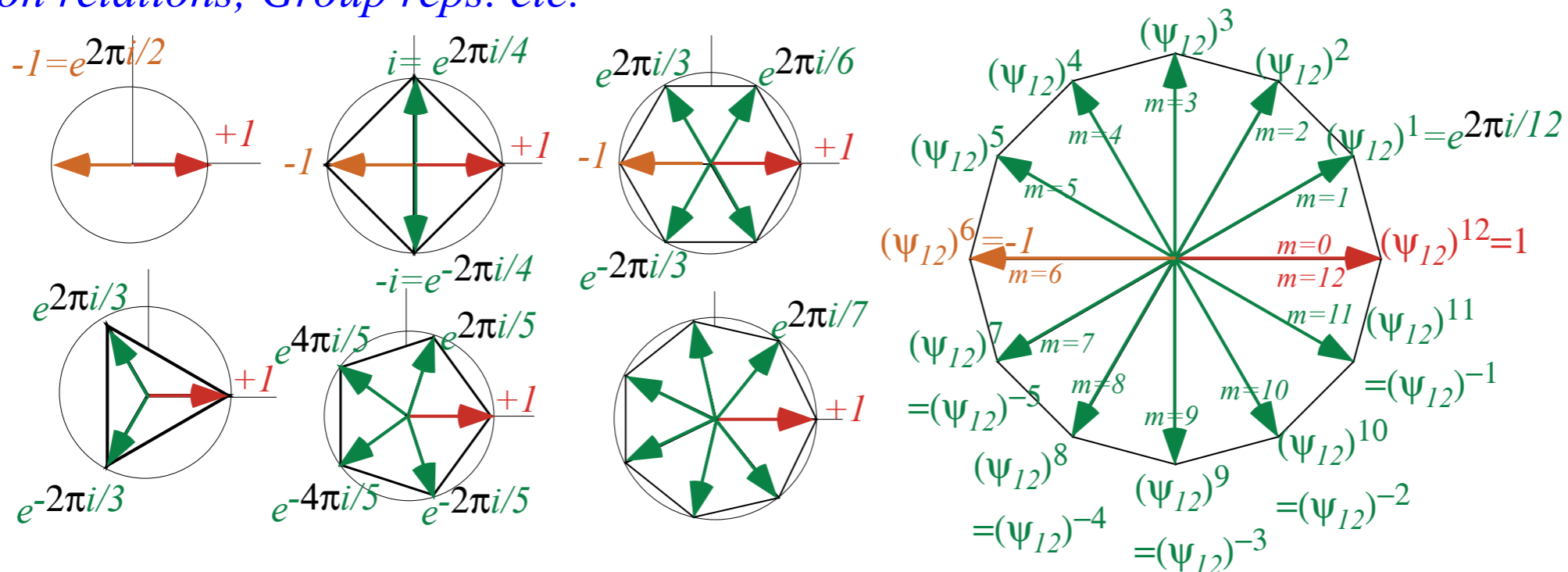
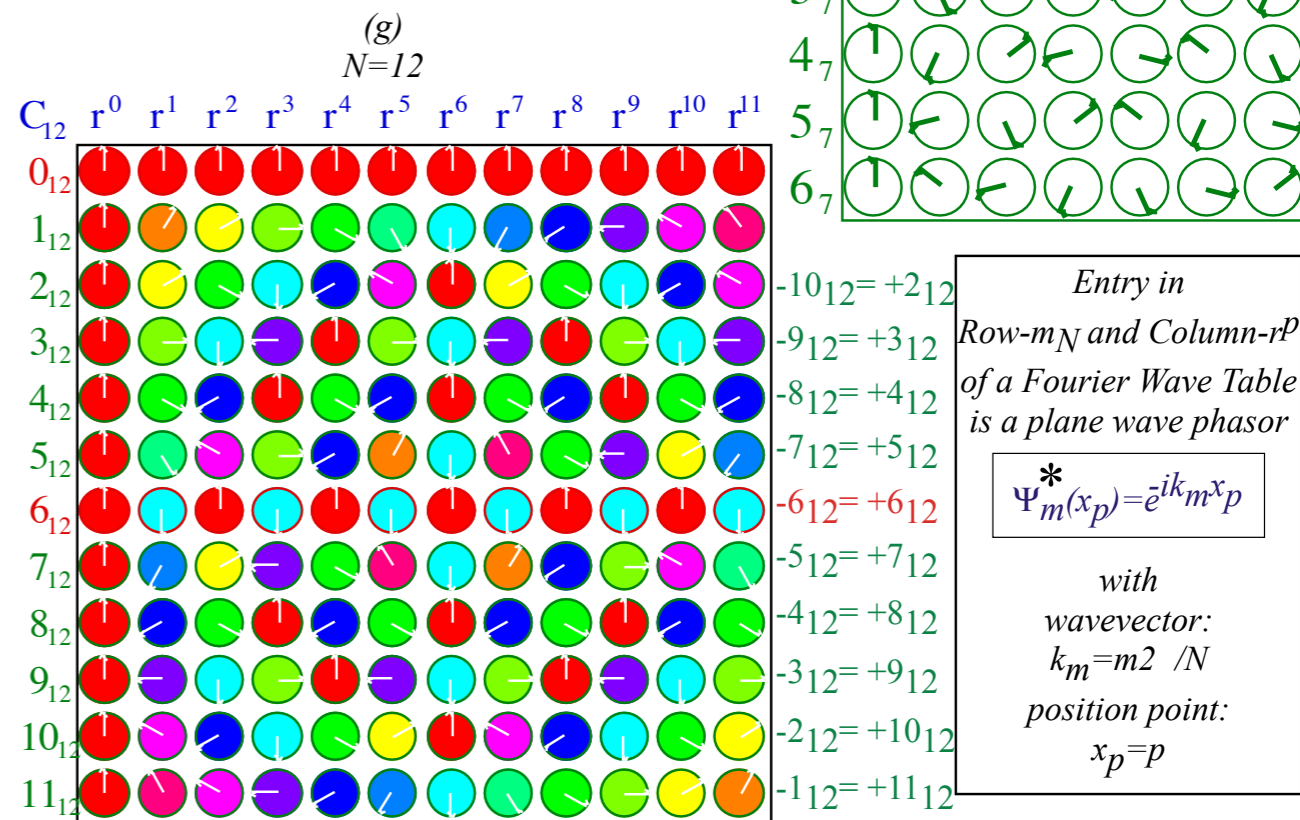
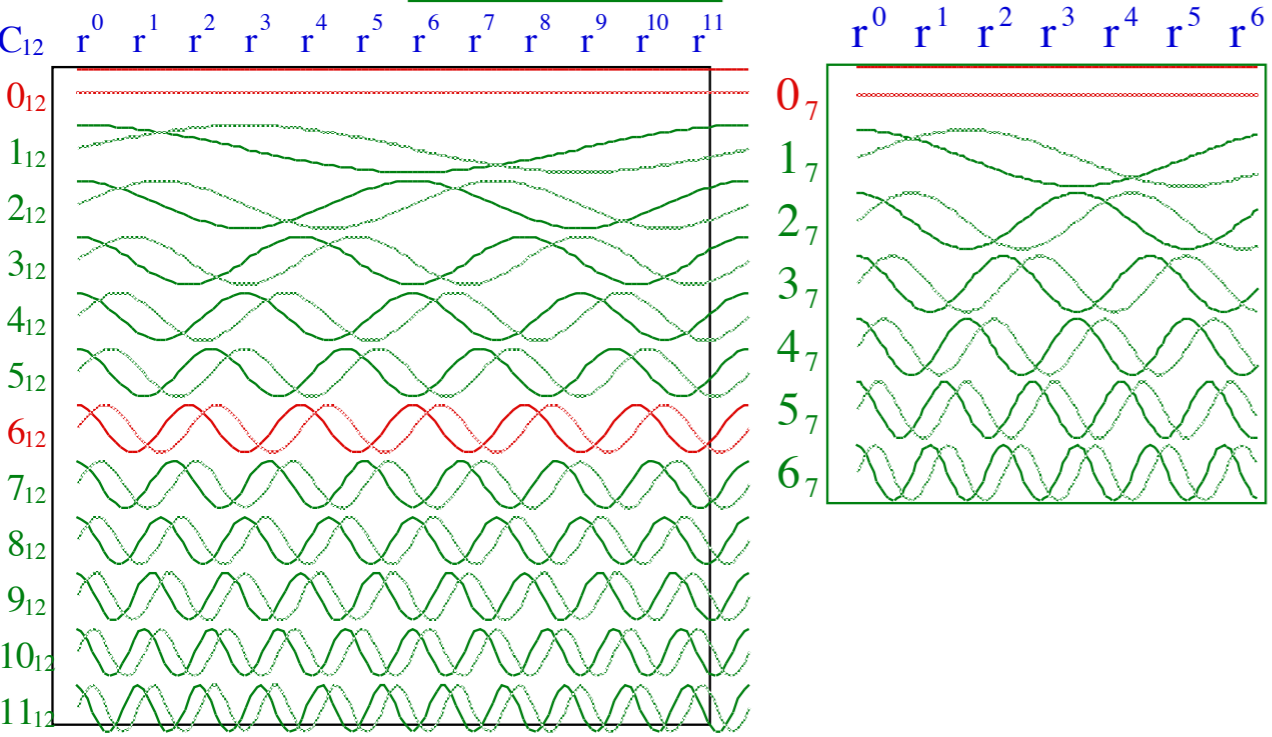
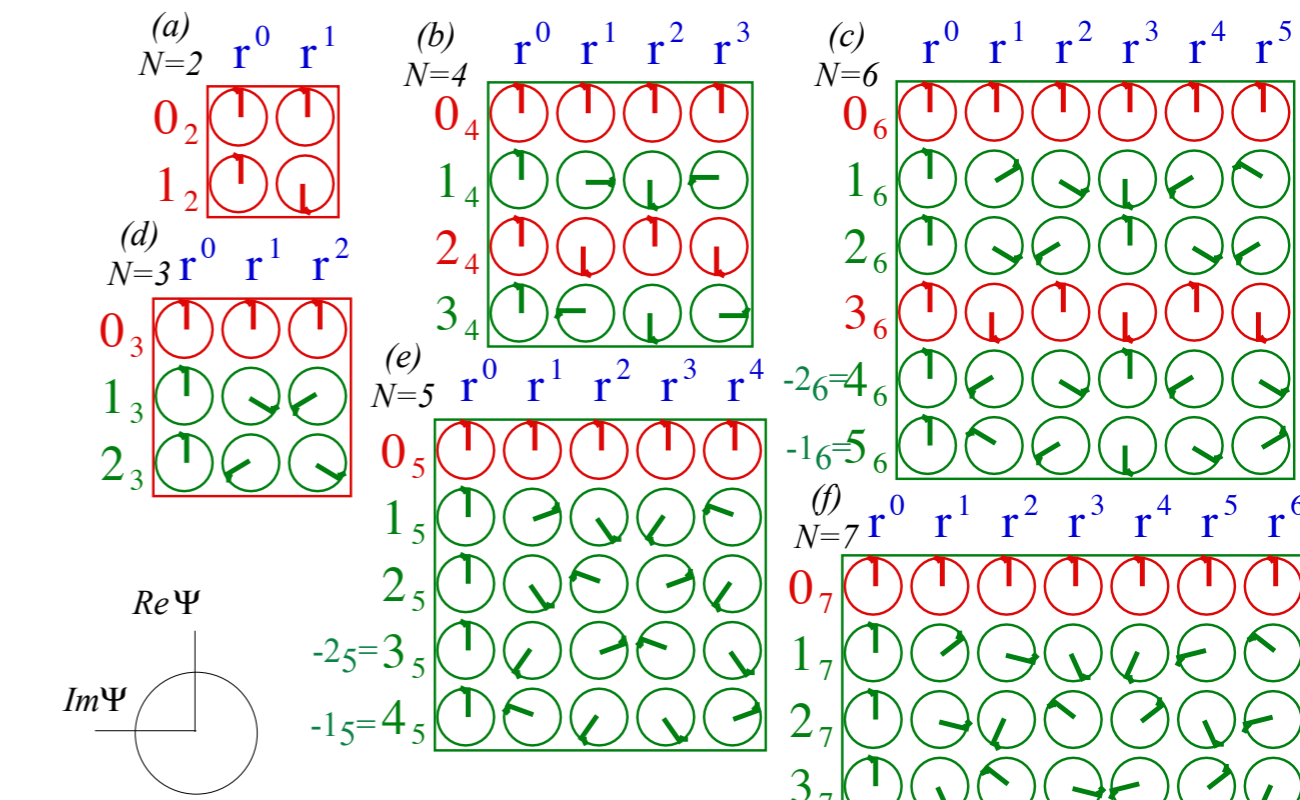
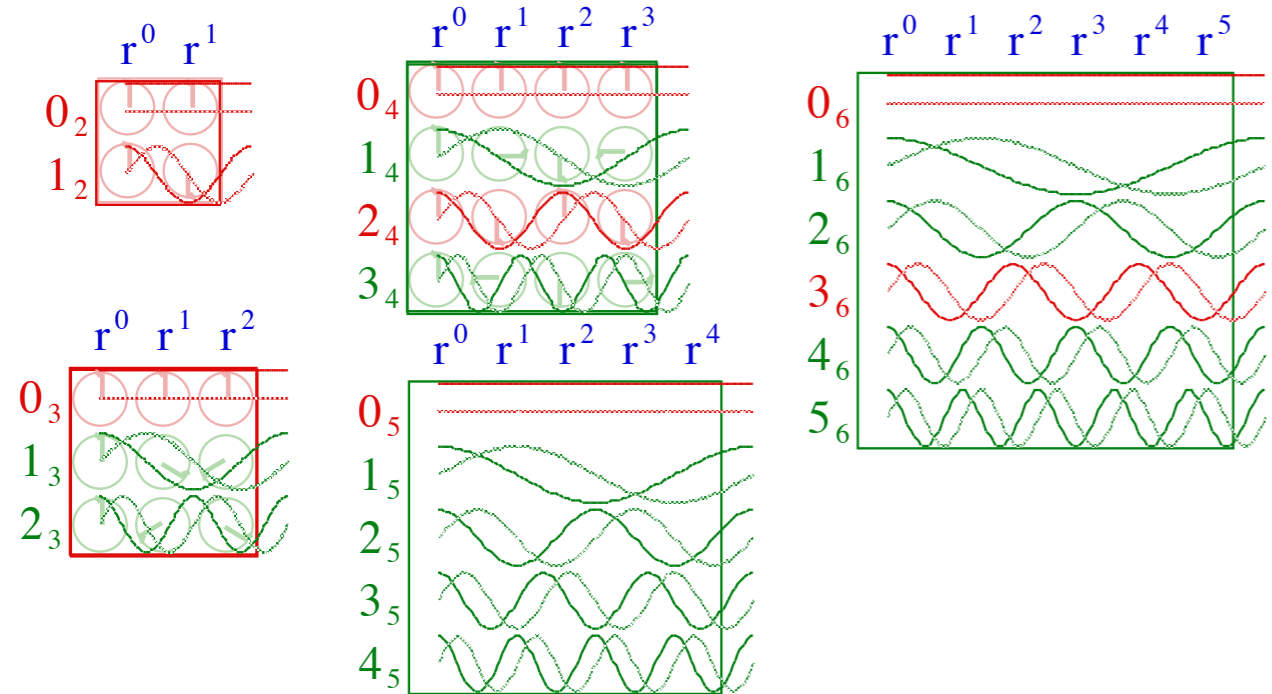


Fig. 4.8.5
Unit 4
CMwBang

C_N Symmetric Mode Models:

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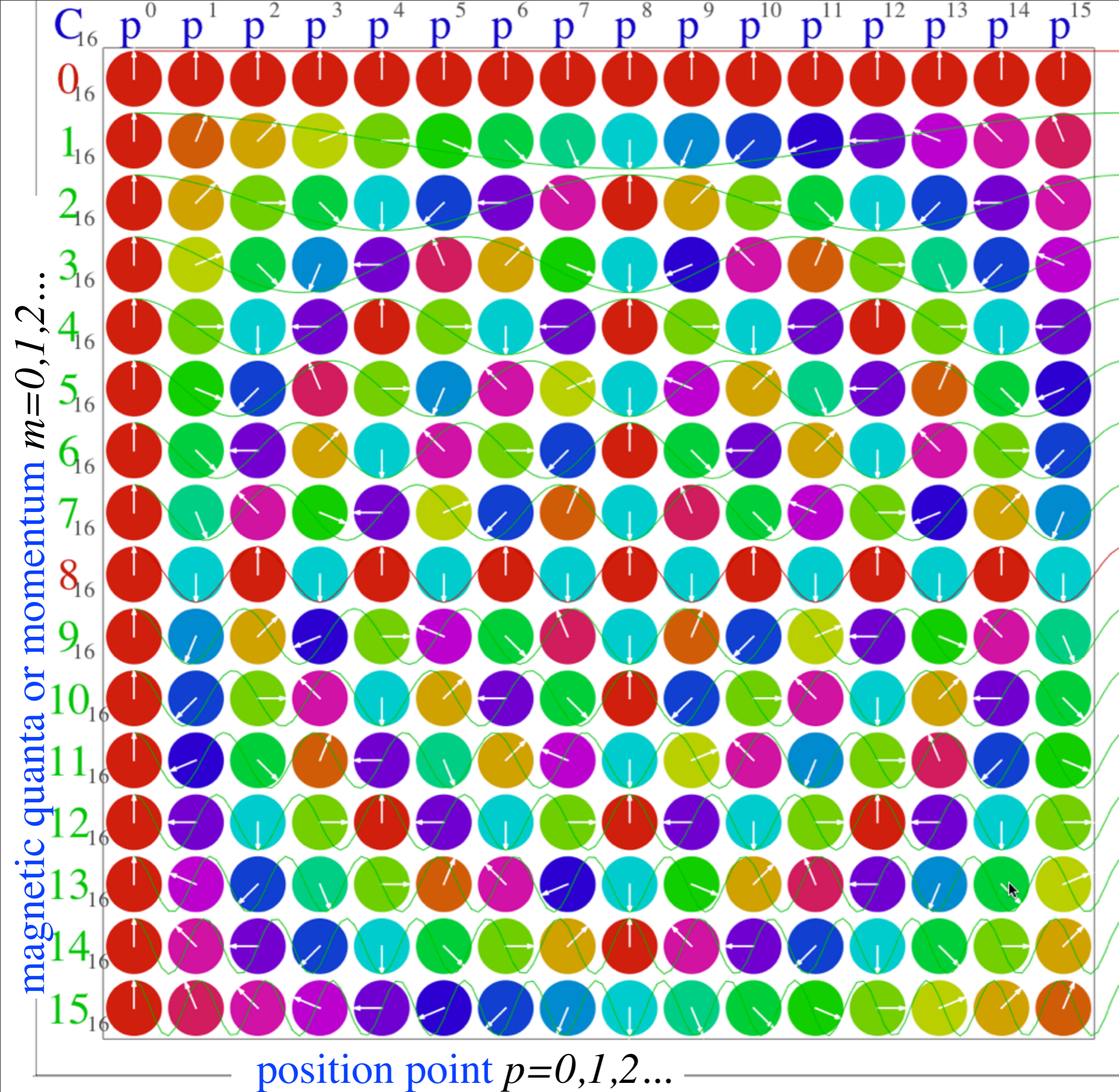


WaveIt C₁₂ Web Simulation

WaveIt C₁₂ Character Phasors Web Simulation

Orig. Fig. 4.8.6-7
Unit 4
CMwBang

Fourier
transformation matrices



C_{16}

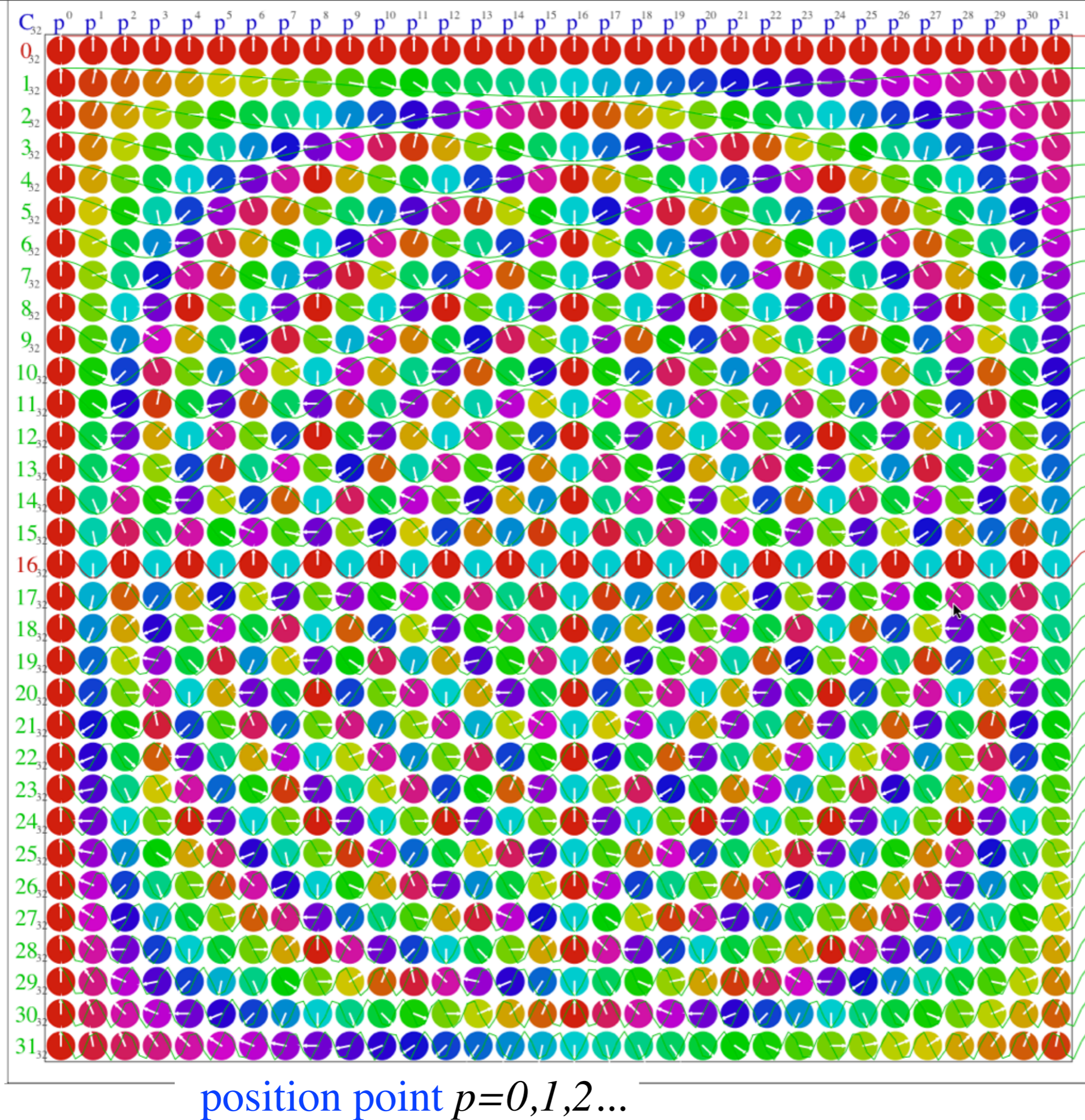
phasor
character
table

$$\chi_p^m = e^{ik_m r^p}$$

$$= e^{\frac{2\pi i m p}{16}}$$

[WaveIt C₁₆ Character Phasors Web Simulation](#)

magnetic quanta or momentum $m=0,1,2,\dots$



C_{32}

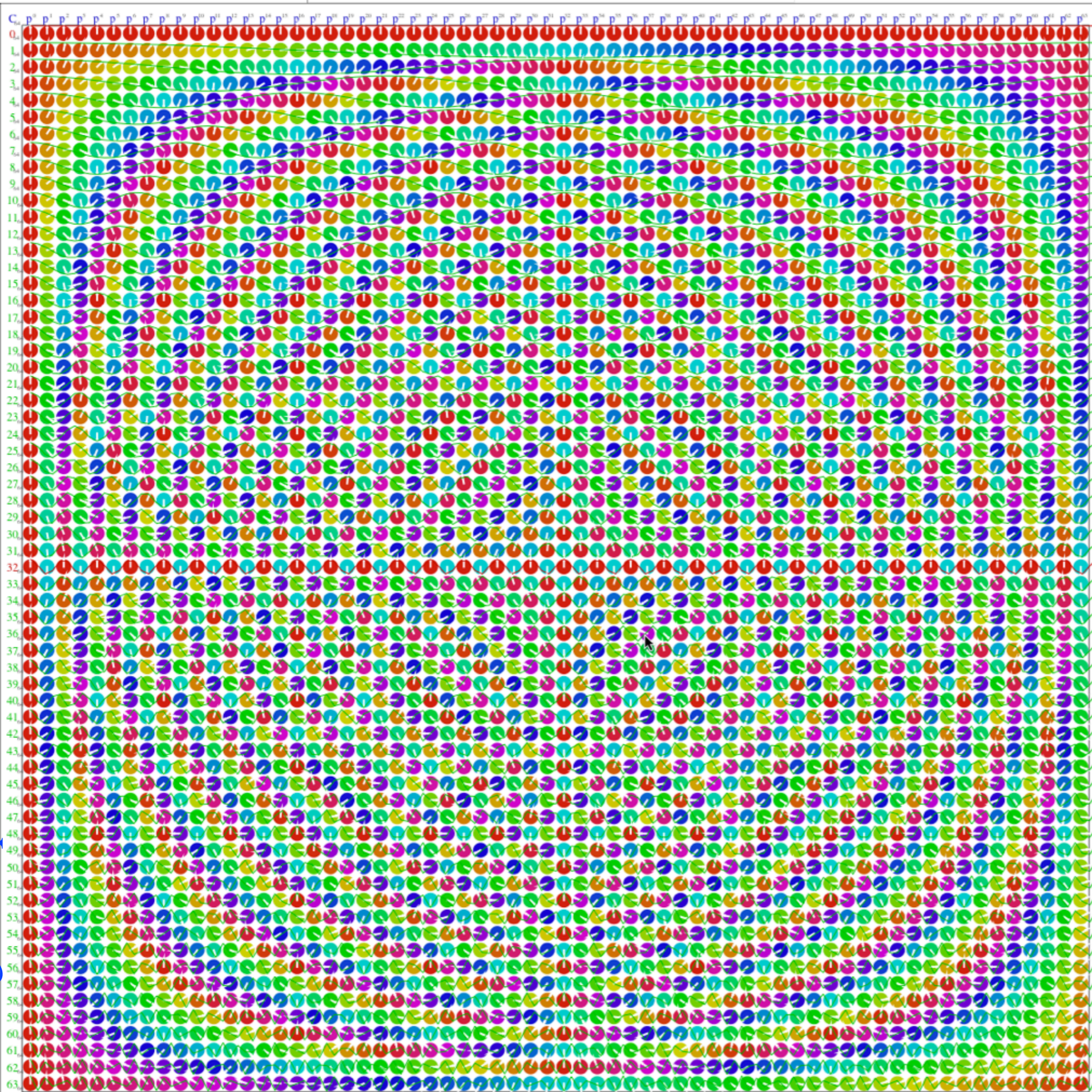
phasor
character
table

$$\chi_p^m = e^{ik_m r^p}$$

$$= e^{\frac{2\pi i m p}{32}}$$

[WaveIt C₃₂ Character Phasors Web Simulation](#)

magnetic quanta or momentum $m=0,1,2,\dots$



position point $p=0,1,2,\dots$

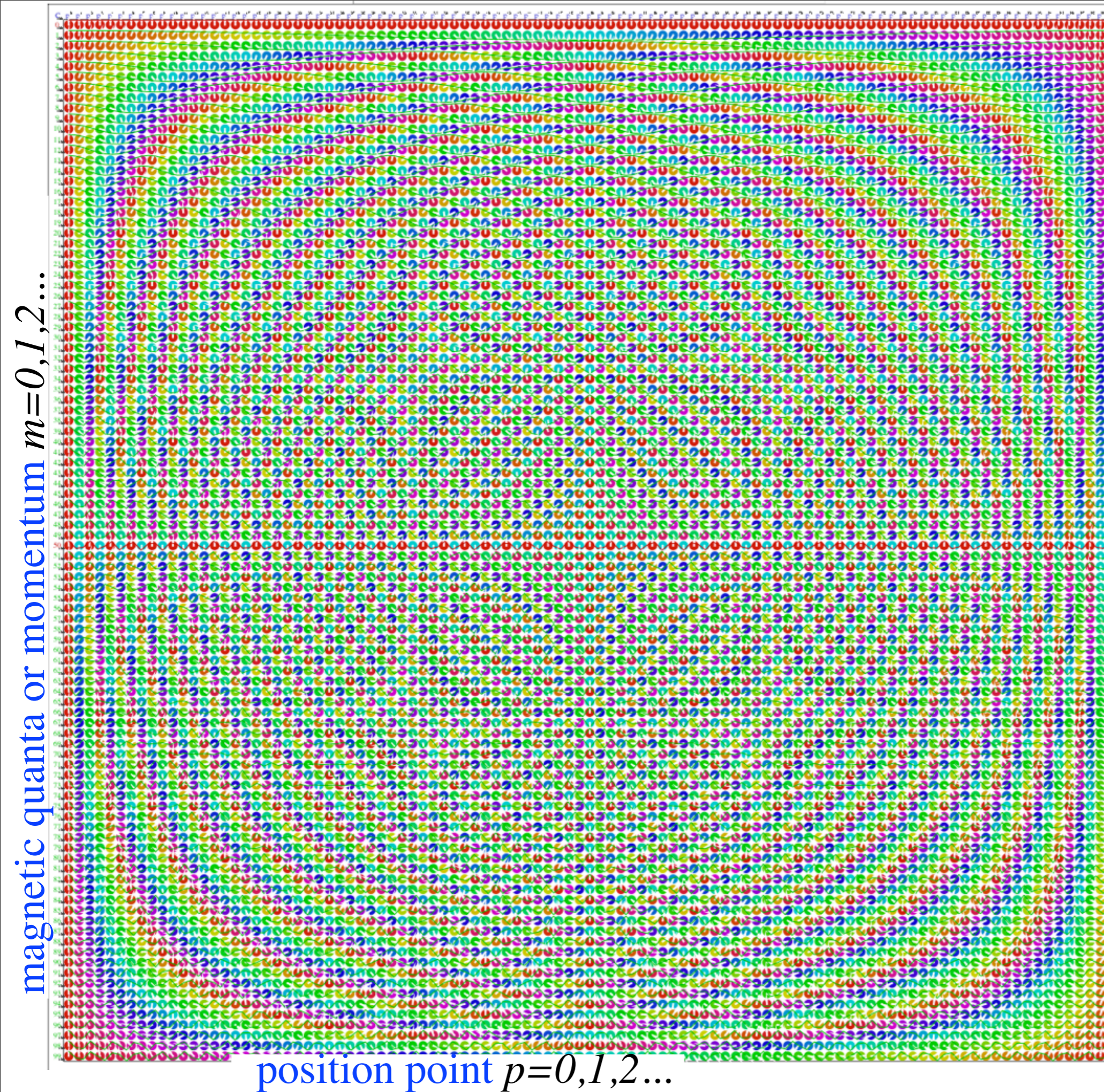
C_{64}

phasor
character
table

$$\chi_p^m = e^{ik_m r^p}$$

$$= e^{\frac{2\pi i m p}{64}}$$

Invariant phase
“Uncertainty”
hyperbolas:
 $m \cdot p = \text{const.}$



C_{100}

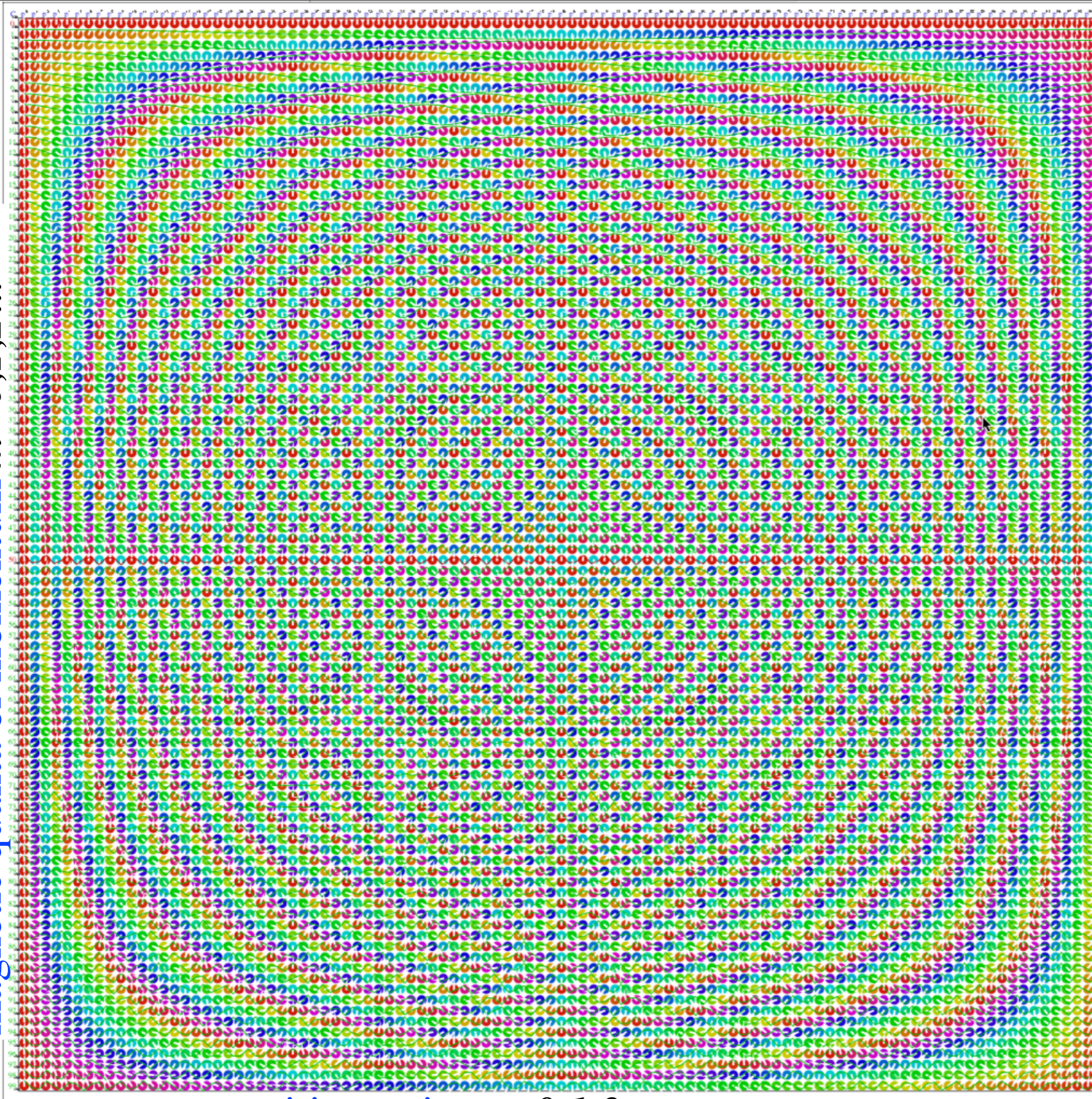
phasor
character
table

$$\chi_p^m = e^{ik_m r^p}$$

$$= e^{\frac{2\pi i m p}{100}}$$

Invariant phase
“Uncertainty”
hyperbolas:
 $m \cdot p = \text{const.}$

magnetic quanta or momentum $n=0,1,2,\dots$



position point $p=0,1,2,\dots$

C_{256}

phasor
character
table

$$\chi_p^m = e^{ik_m r^p} \\ = e^{\frac{2\pi i m p}{256}}$$

Invariant phase
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[WaveIt C₂₅₆ Character Phasors
Web Simulation](#)

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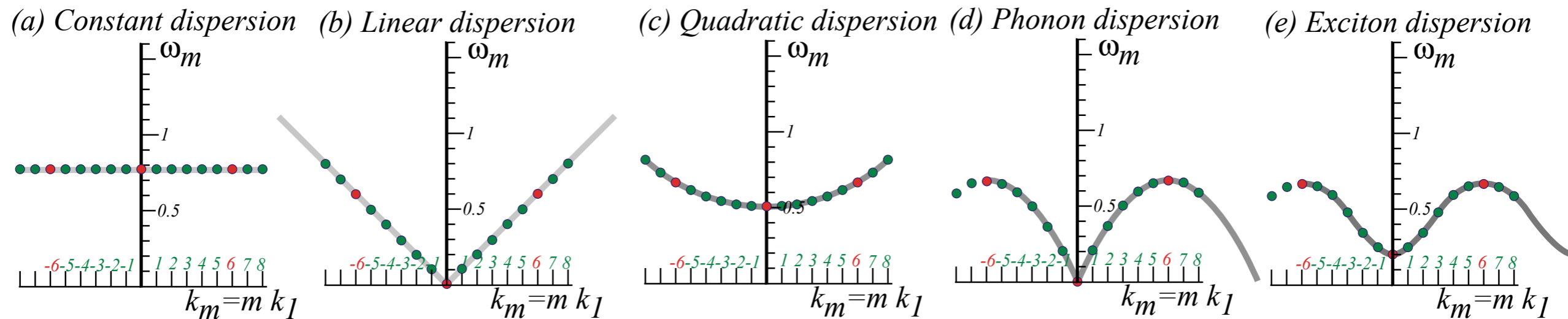
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Archetypical Examples of C_{12} Dispersion Functions



Applications:

Uncoupled pendulums

Weakly coupled pendulums (No gravity)

Weakly coupled pendulums (With gravity)

Strongly coupled pendulums (No gravity)

Strongly coupled pendulums (With gravity)

Movie marquis
Xmas lights

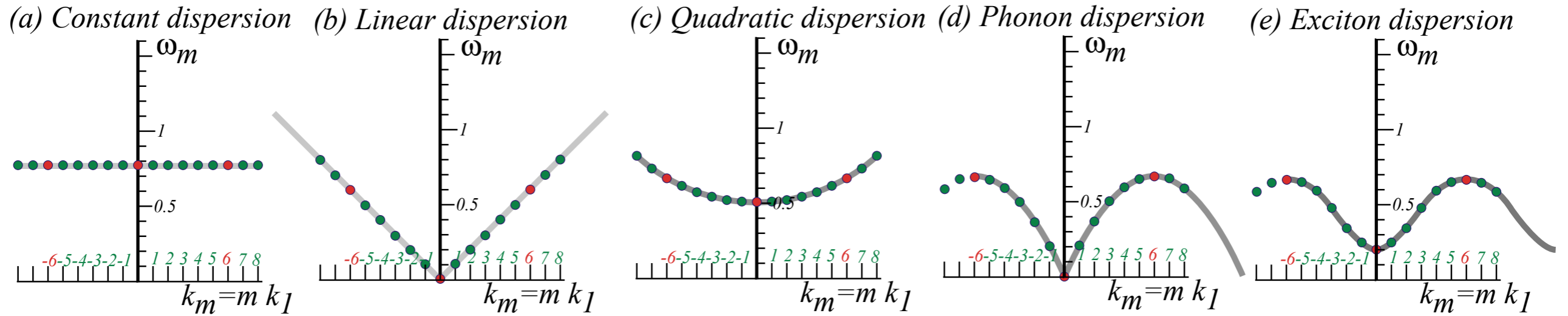
Light in vacuum (Exactly)
Sound (Approximately)

Light in fiber (Approx)
Non-relativistic
Schrodinger matter wave

Acoustic mode in solids

Optical mode in solids
Relativistic matter
(If exact hyperbola)

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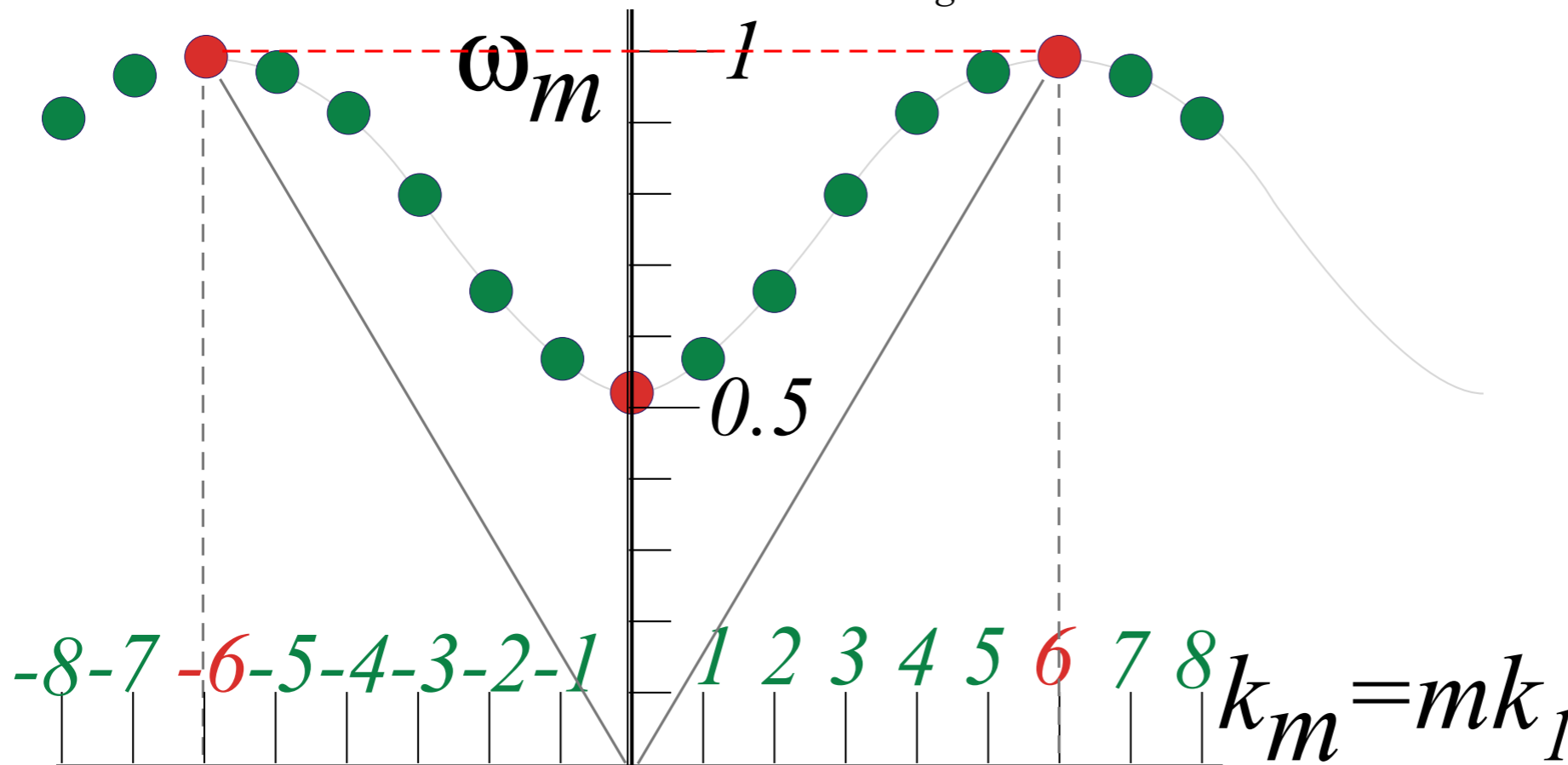
Movie marquis
Xmas lights

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Sound (Approximately)

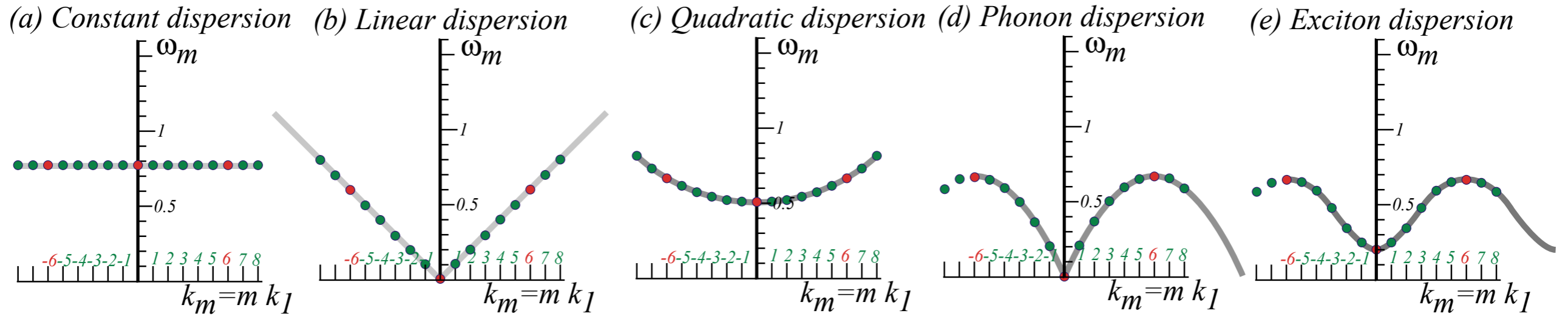
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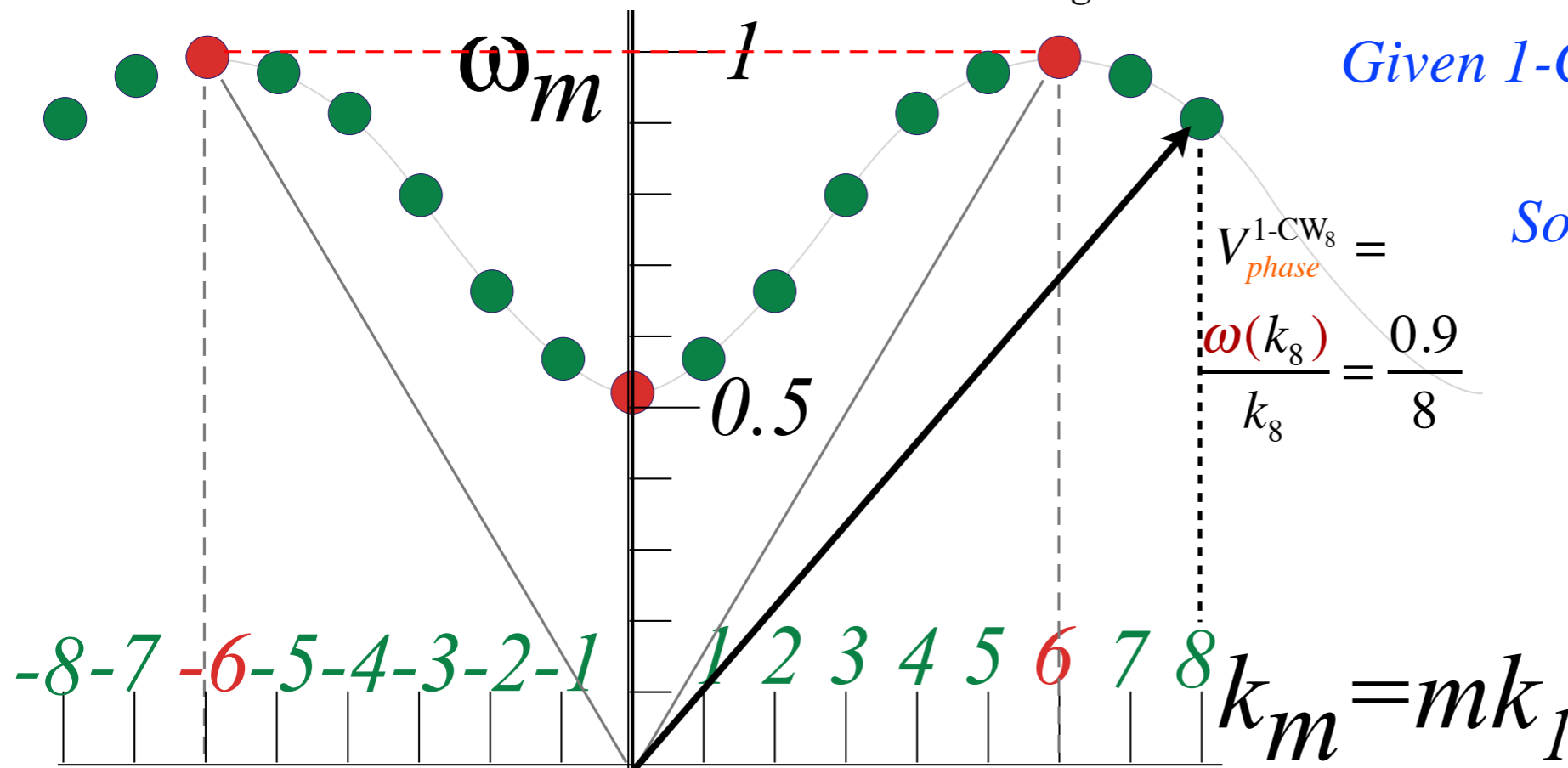


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Applications:

Uncoupled pendulums	Weakly coupled pendulums (No gravity)	Weakly coupled pendulums (With gravity)	Strongly coupled pendulums (No gravity)	Strongly coupled pendulums (With gravity)
Movie marquis Xmas lights	Light in vacuum (<u>Exactly</u>) Sound (Approximately)	Light in fiber (Approx) Non-relativistic Schrodinger matter wave	Acoustic mode in solids	Optical mode in solids Relativistic matter (If exact hyperbola)



Given 1-CW phase of wave $e^{i(kx - \omega t)}$:

$$a = \underbrace{k \cdot x - \omega \cdot t}$$

Solve for 1-CW phase velocity

$$x = \frac{\omega}{k} \cdot t + \frac{a}{k}$$

$$V_{\text{phase}}^{1\text{-CW}_8} = \frac{\omega(k_8)}{k_8} = \frac{0.9}{8}$$

Wave velocities depend on **Dispersion function**
 $\omega = \omega(k)$

(a) 1-CW **phase** velocity:

$$V_{\text{phase}}^{1\text{-CW}} = \frac{\omega(k)}{k}$$

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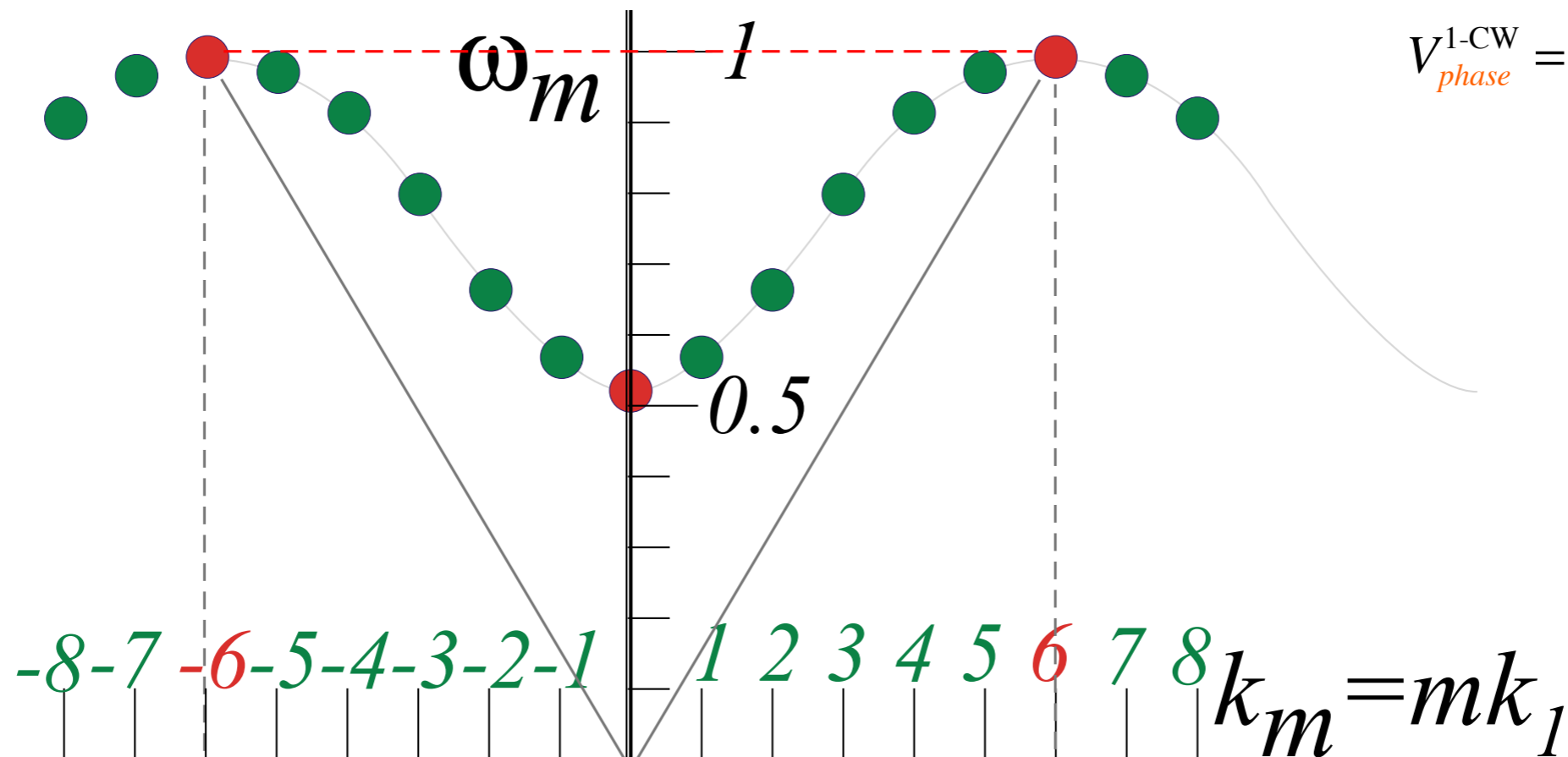
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The $\frac{1}{2}$ -Sum- $\frac{1}{2}$ -Diff-Identity and 2-CW phase and group velocity

Given 2-CW phases:

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...find 2-CW phase velocity $V_{\text{phase}}^{2\text{-CW}}$ and group velocity $V_{\text{group}}^{2\text{-CW}}$



Velocities depend upon
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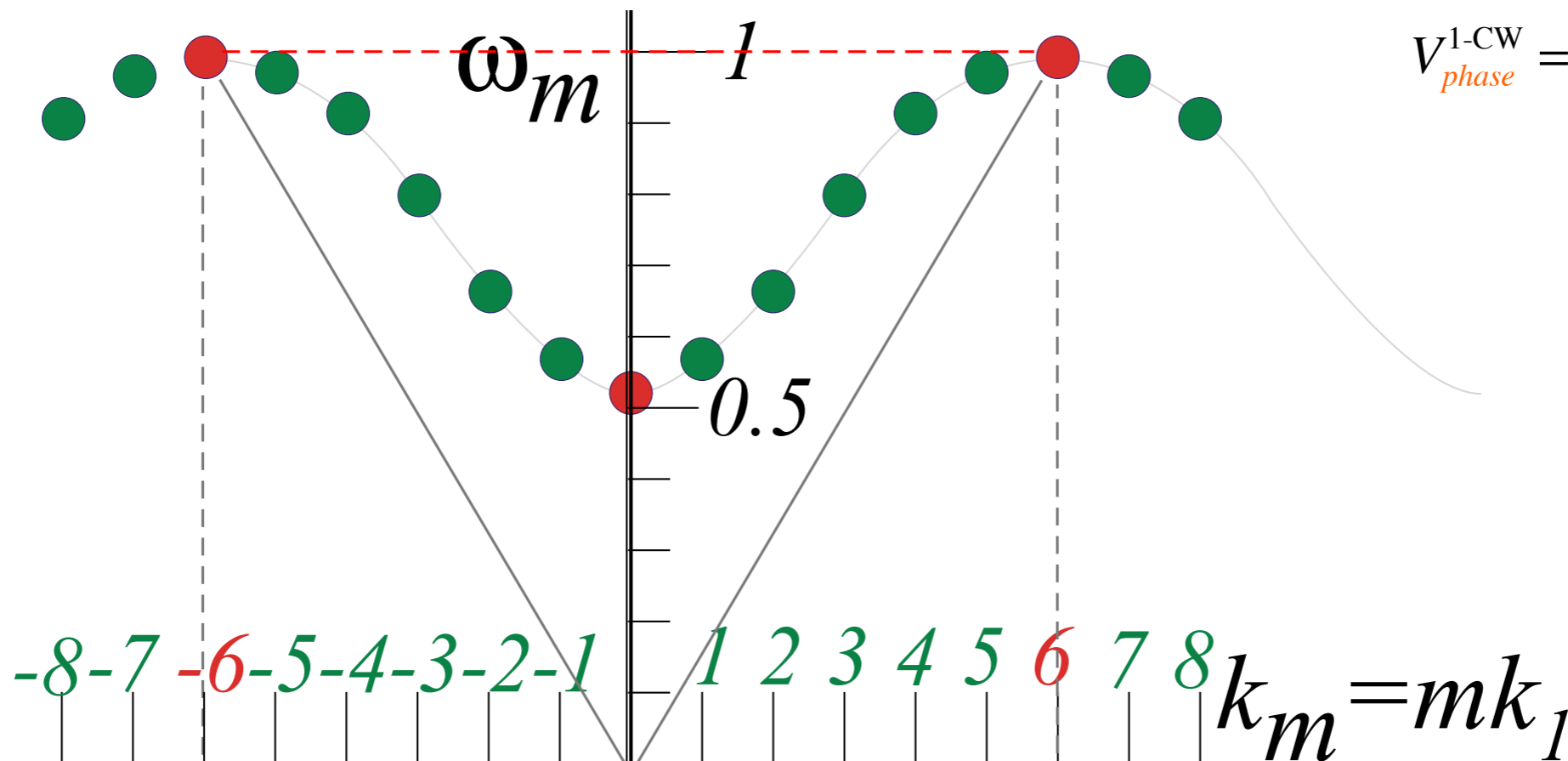
$$a = k_a \cdot x - \omega_a \cdot t \quad \text{and} \quad b = k_b \cdot x - \omega_b \cdot t$$

$$\frac{e^{ia} + e^{ib}}{2} = e^{i\frac{a+b}{2}} \left(\frac{e^{i\frac{a-b}{2}} + e^{-i\frac{a-b}{2}}}{2} \right) = e^{i\frac{a+b}{2}} \cos\left(\frac{a-b}{2}\right)$$

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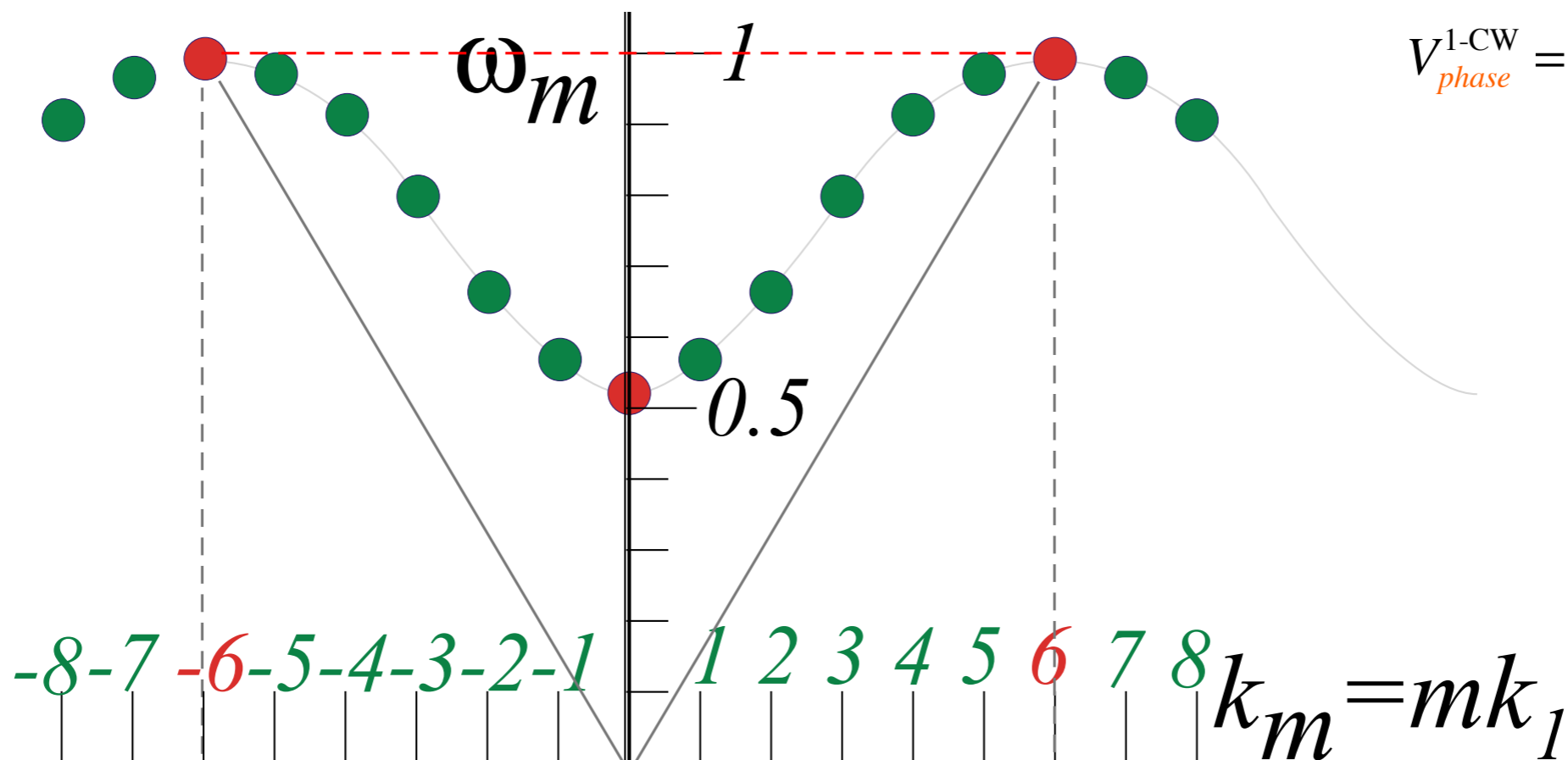
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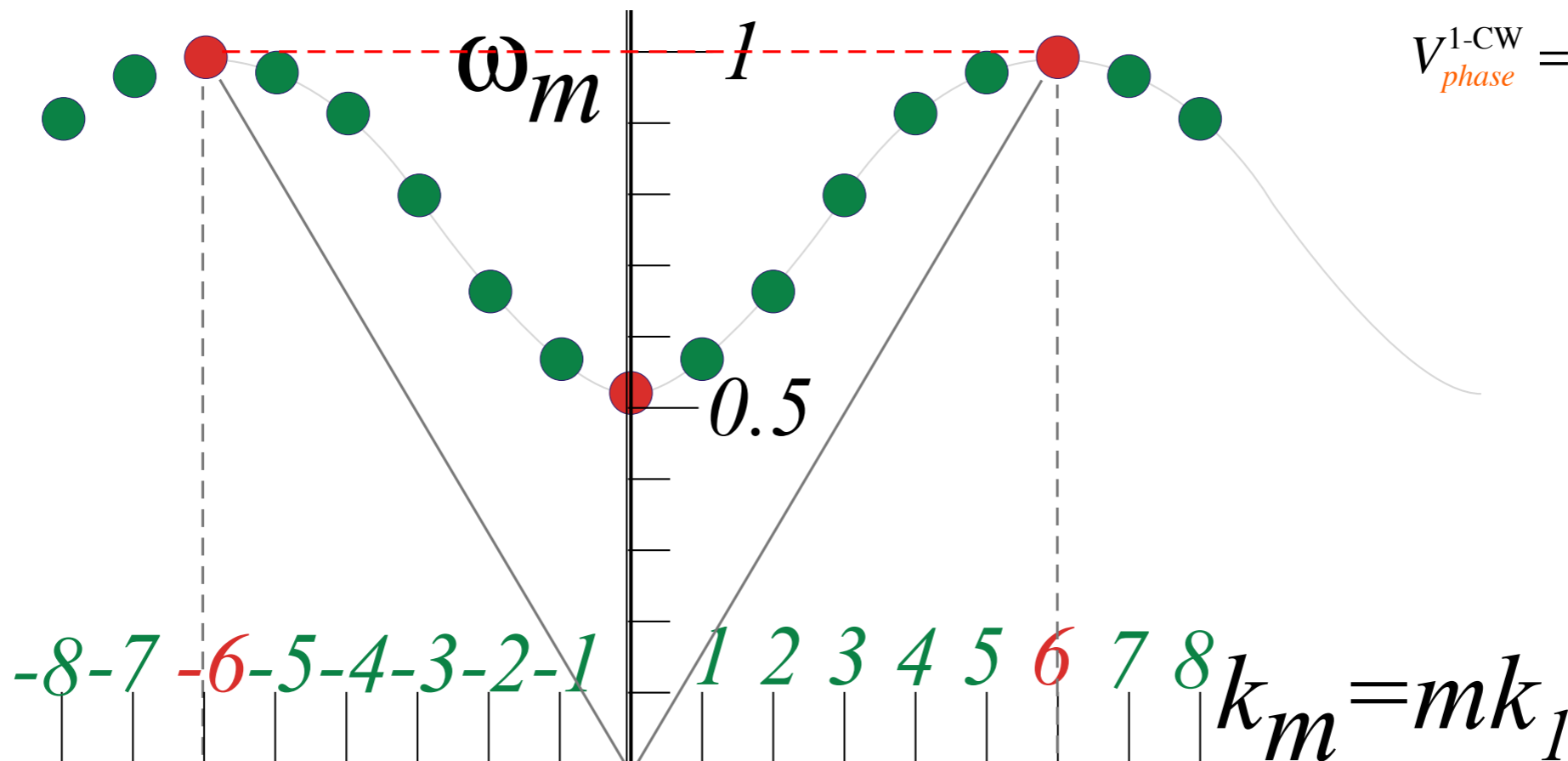
$$V_{phase}^{2-CW} = \frac{(\omega_a + \omega_b)}{(k_a + k_b)}$$

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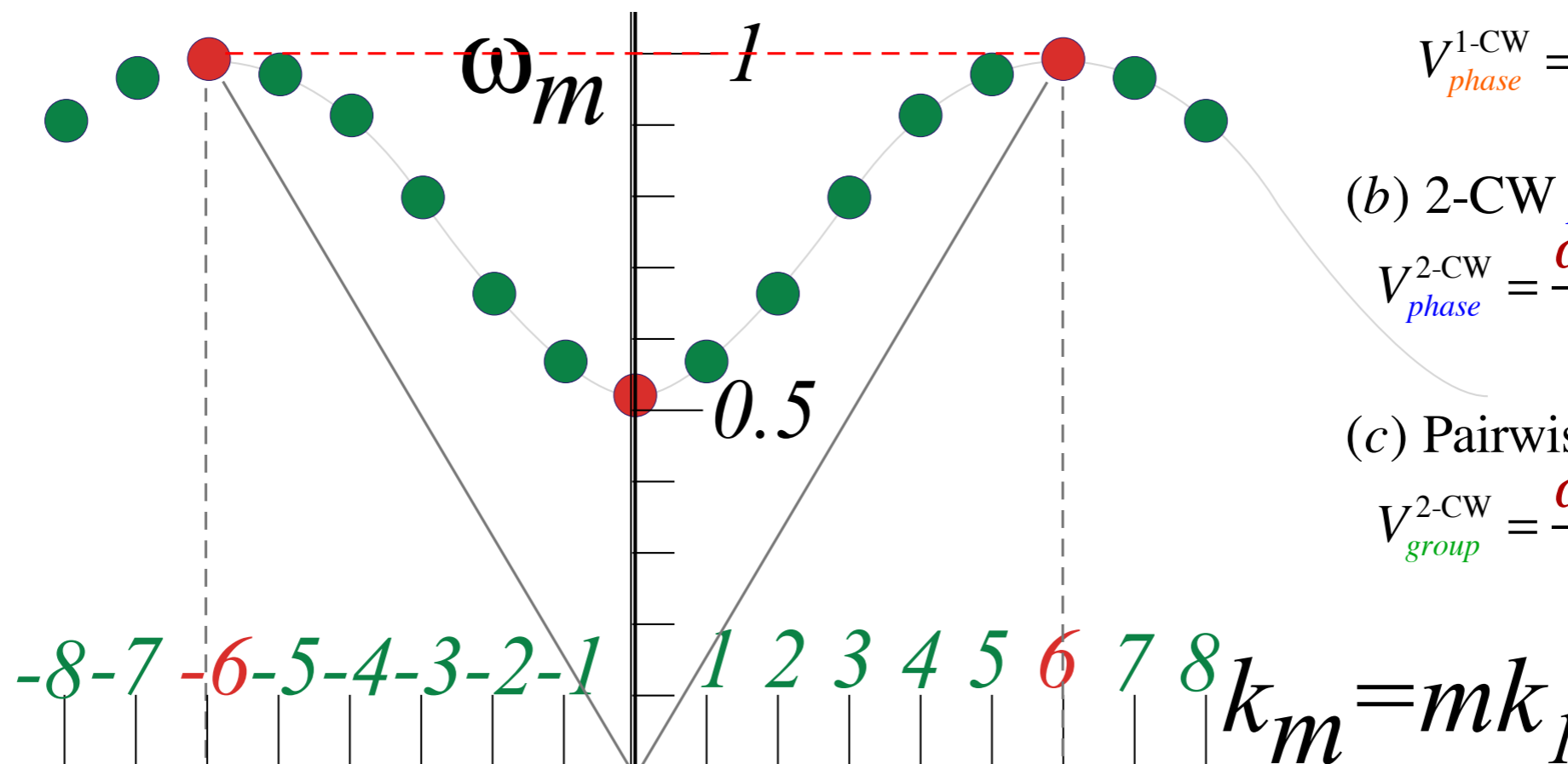
$$V_{phase}^{1-CW} = \frac{\omega(k)}{k}$$

(b) 2-CW *phase* velocity:

$$V_{phase}^{2-CW} = \frac{\omega(k_1) + \omega(k_2)}{k_1 + k_2}$$

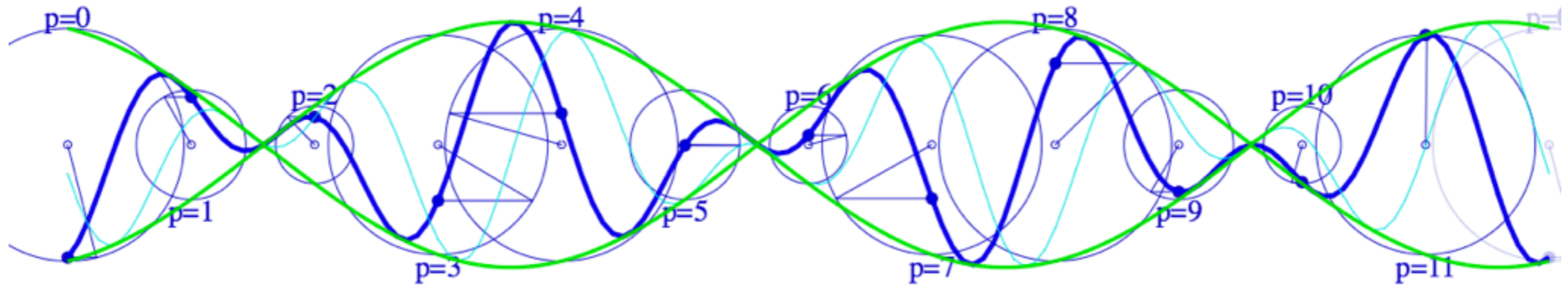
(c) Pairwise *group* velocity:

$$V_{group}^{2-CW} = \frac{\omega(k_1) - \omega(k_2)}{k_1 - k_2}$$



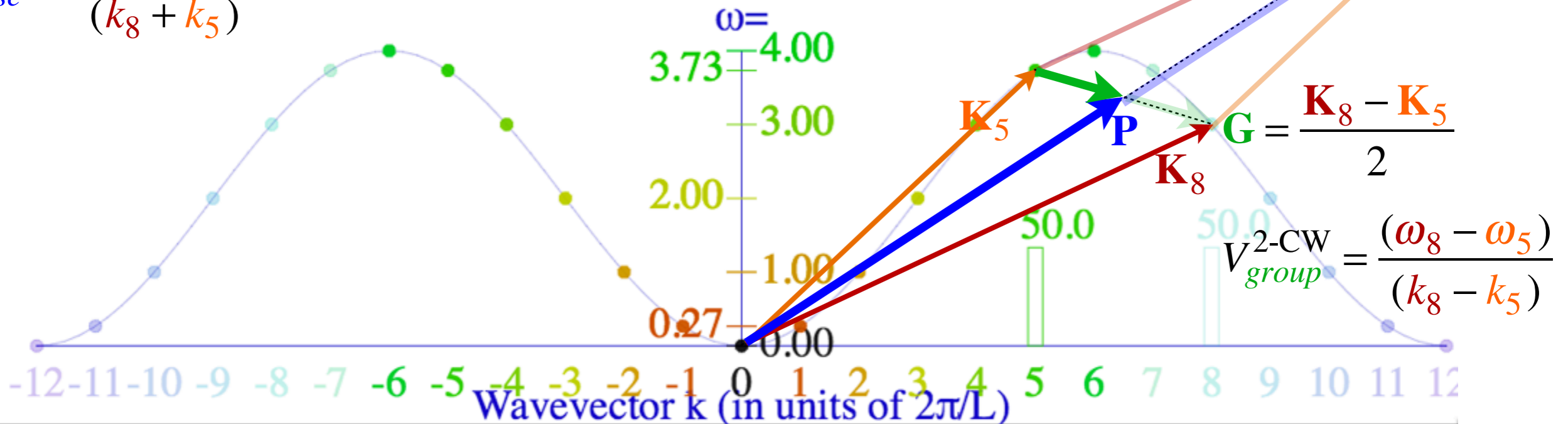
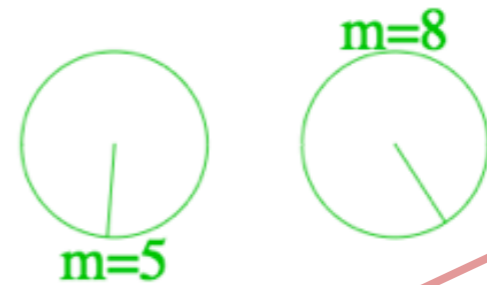
Position p (in units of L/12)

Fourier Control On



$$\mathbf{P} = \frac{\mathbf{K}_8 + \mathbf{K}_5}{2} = \frac{1}{2} \begin{pmatrix} k_8 \\ \omega_8 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} k_5 \\ \omega_5 \end{pmatrix}$$

$$V_{phase}^{2-CW} = \frac{(\omega_8 + \omega_5)}{(k_8 + k_5)}$$



WaveIt Web Simulation - Wave Mixing (N=12; k=5, 8)

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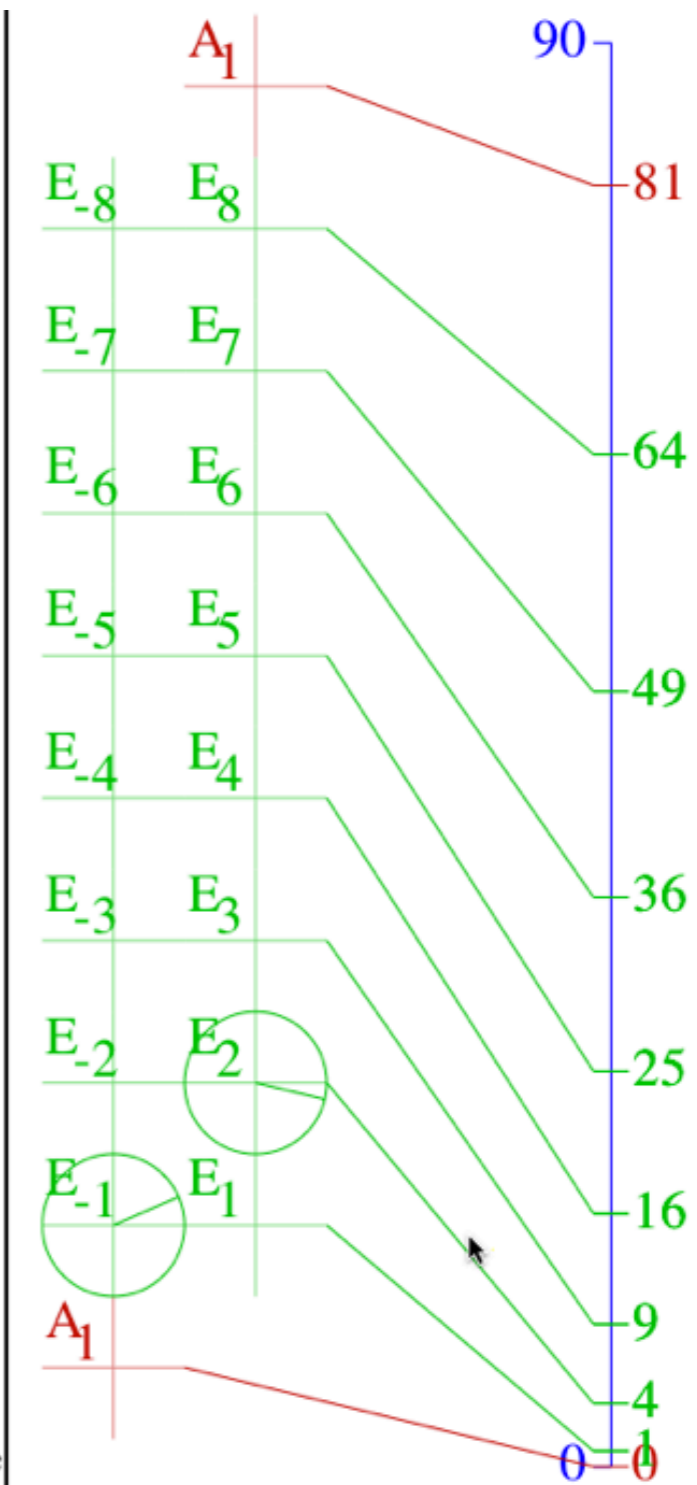
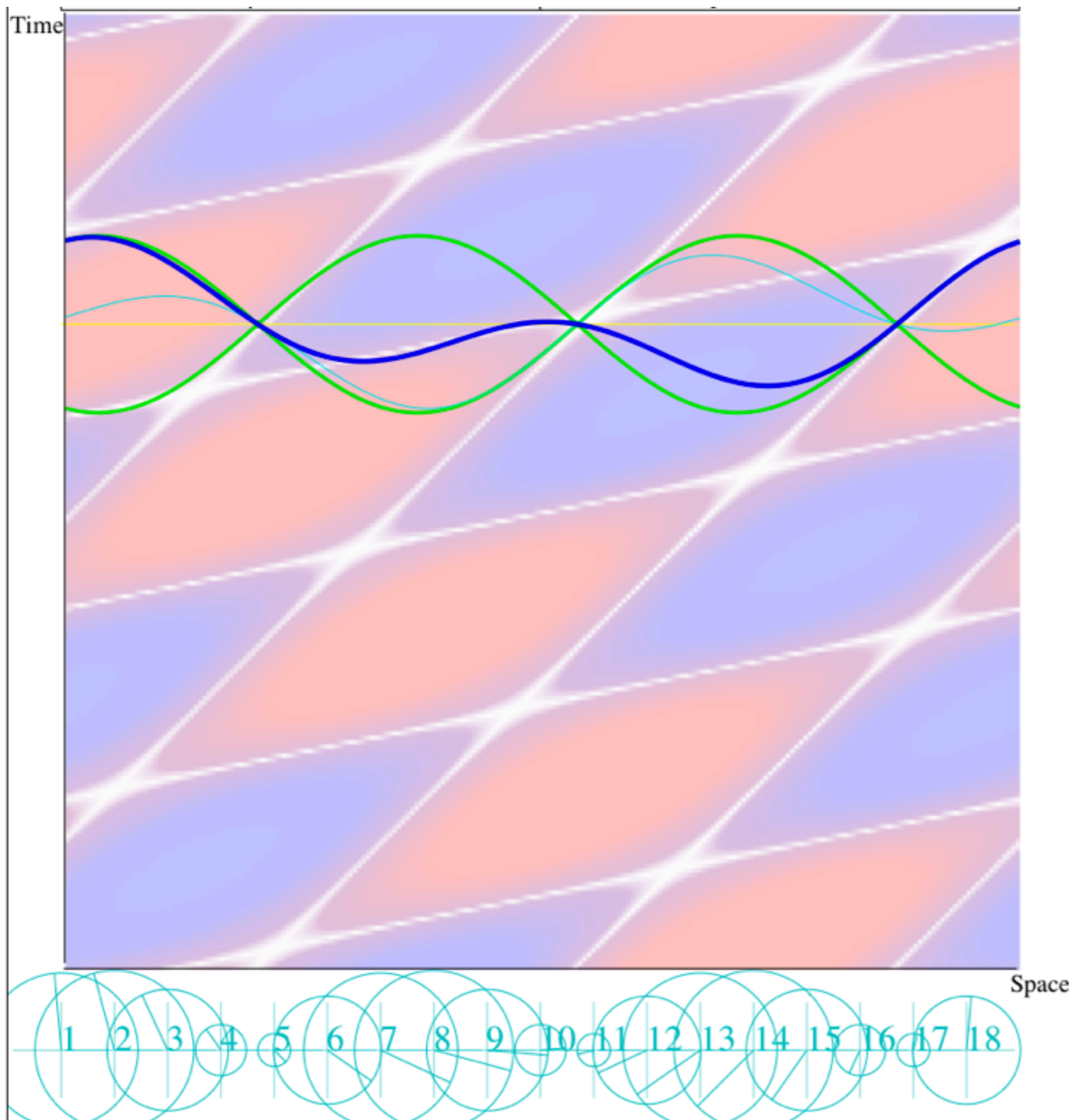


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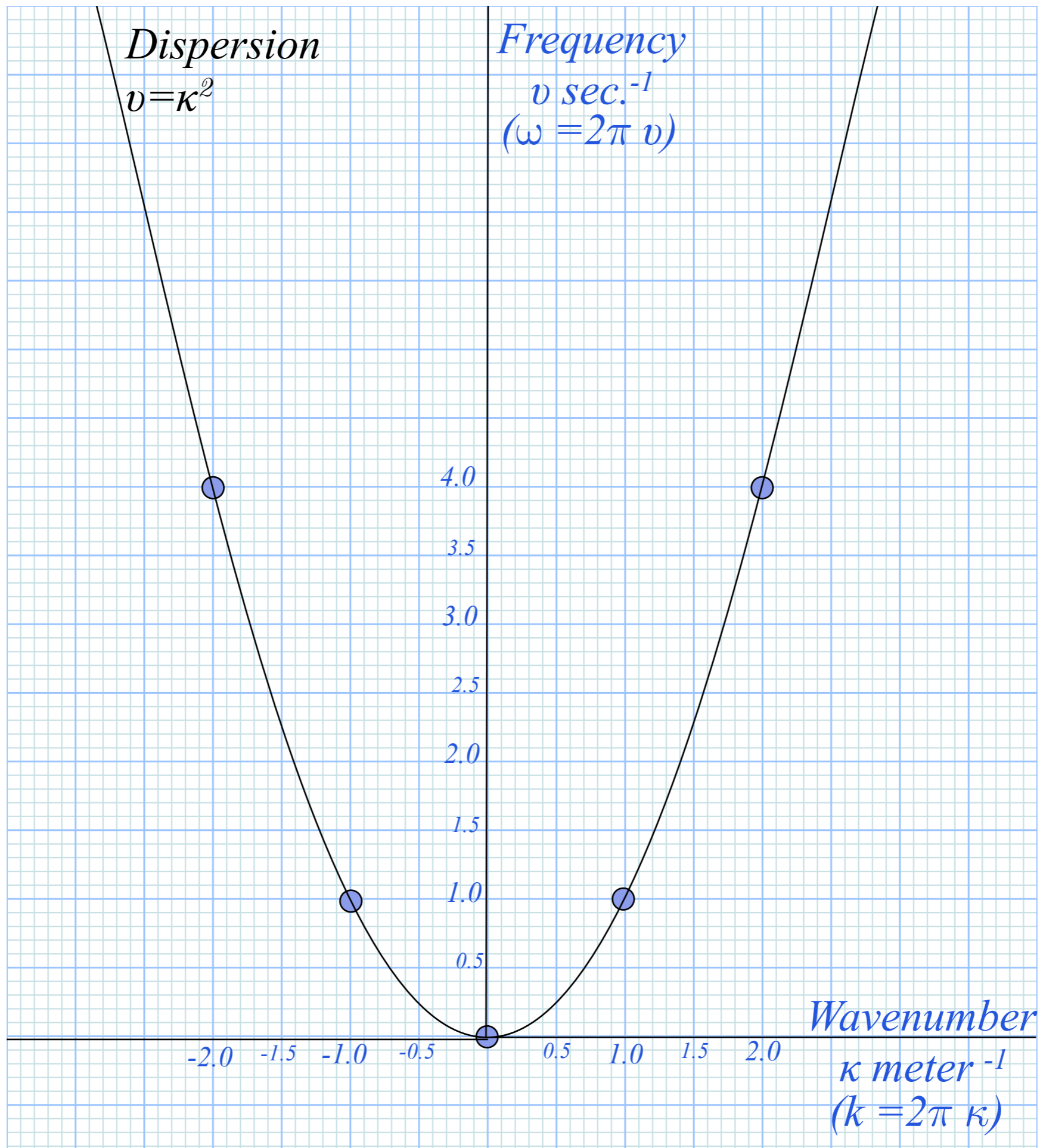


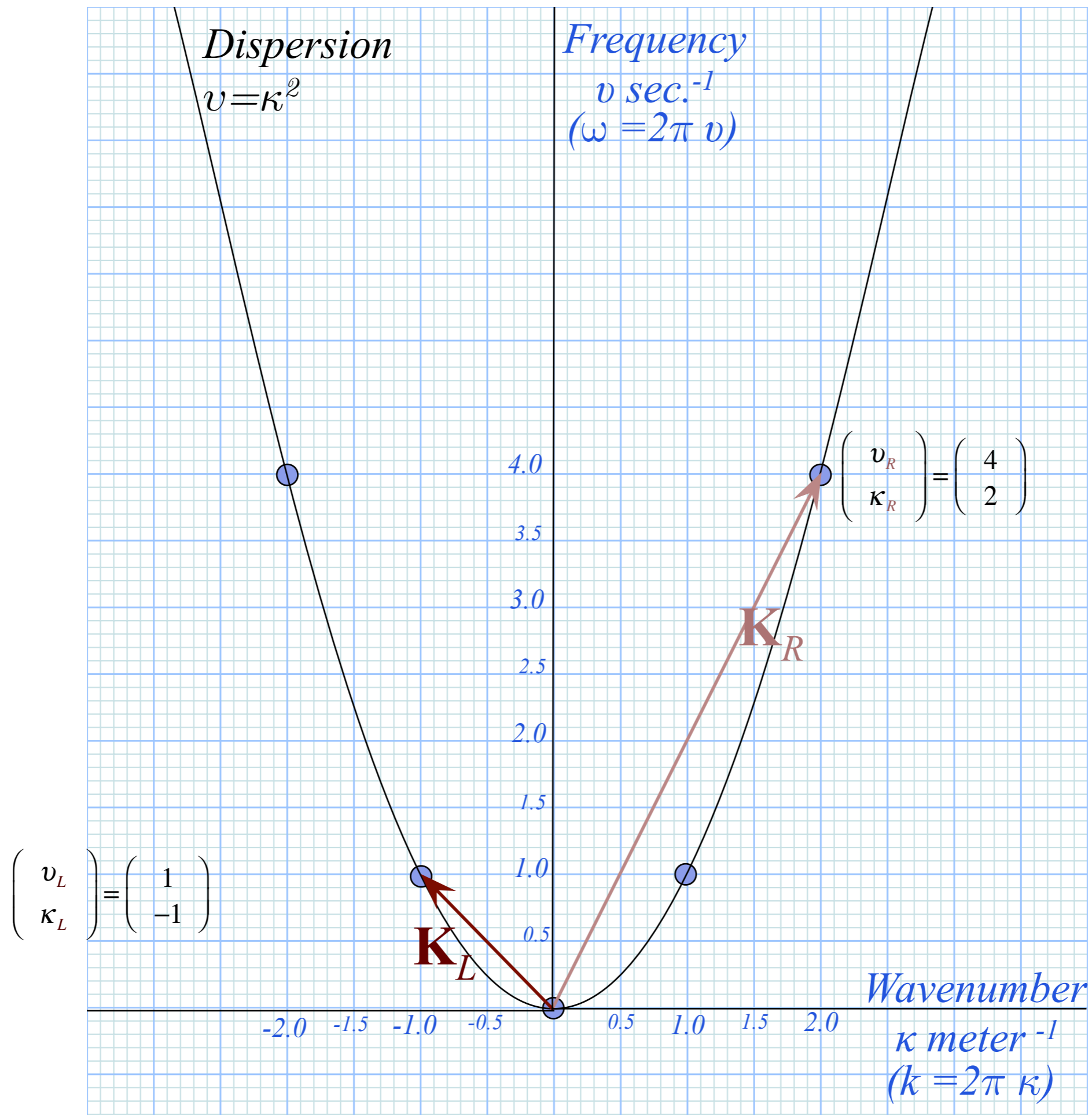
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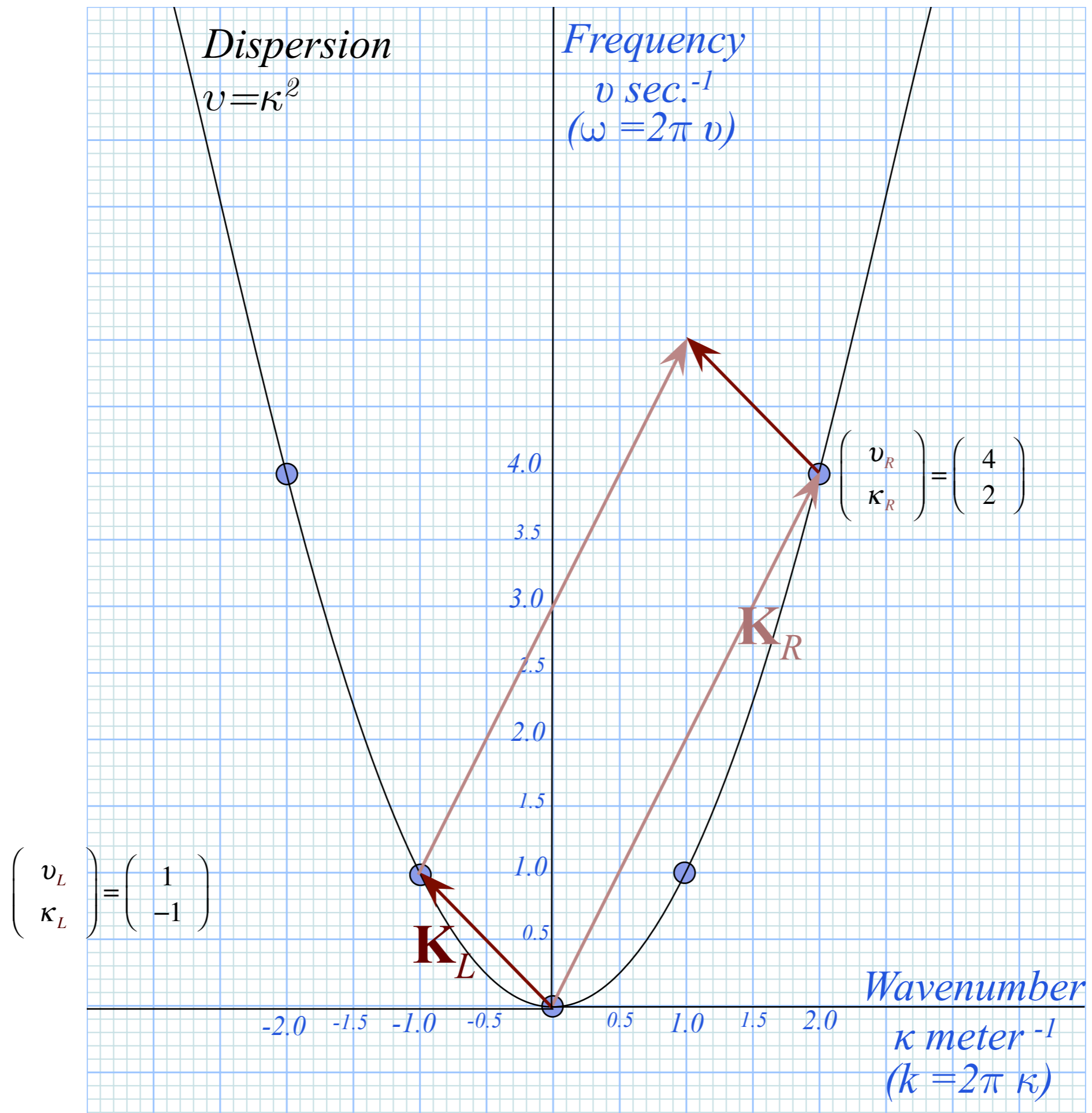
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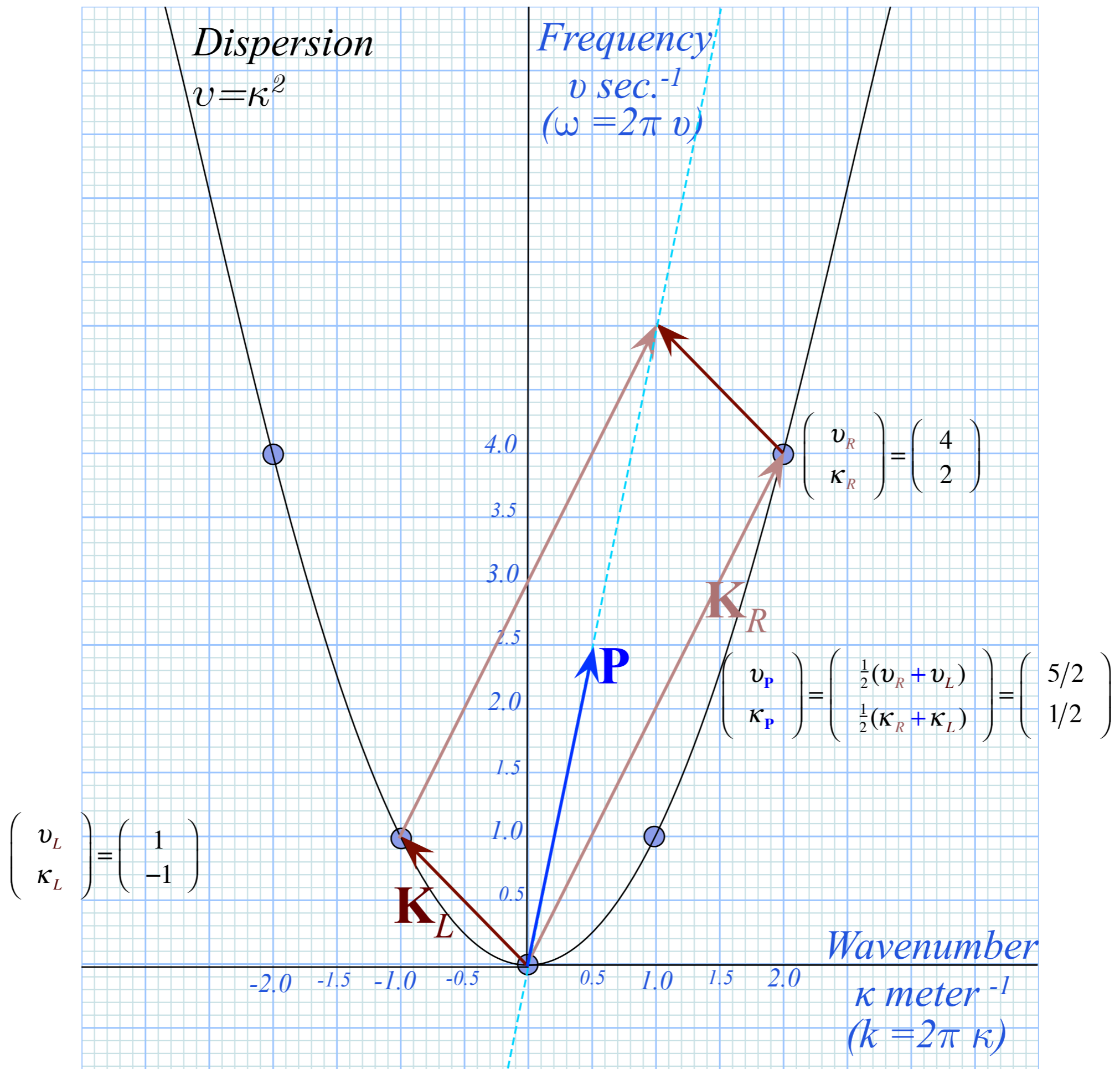


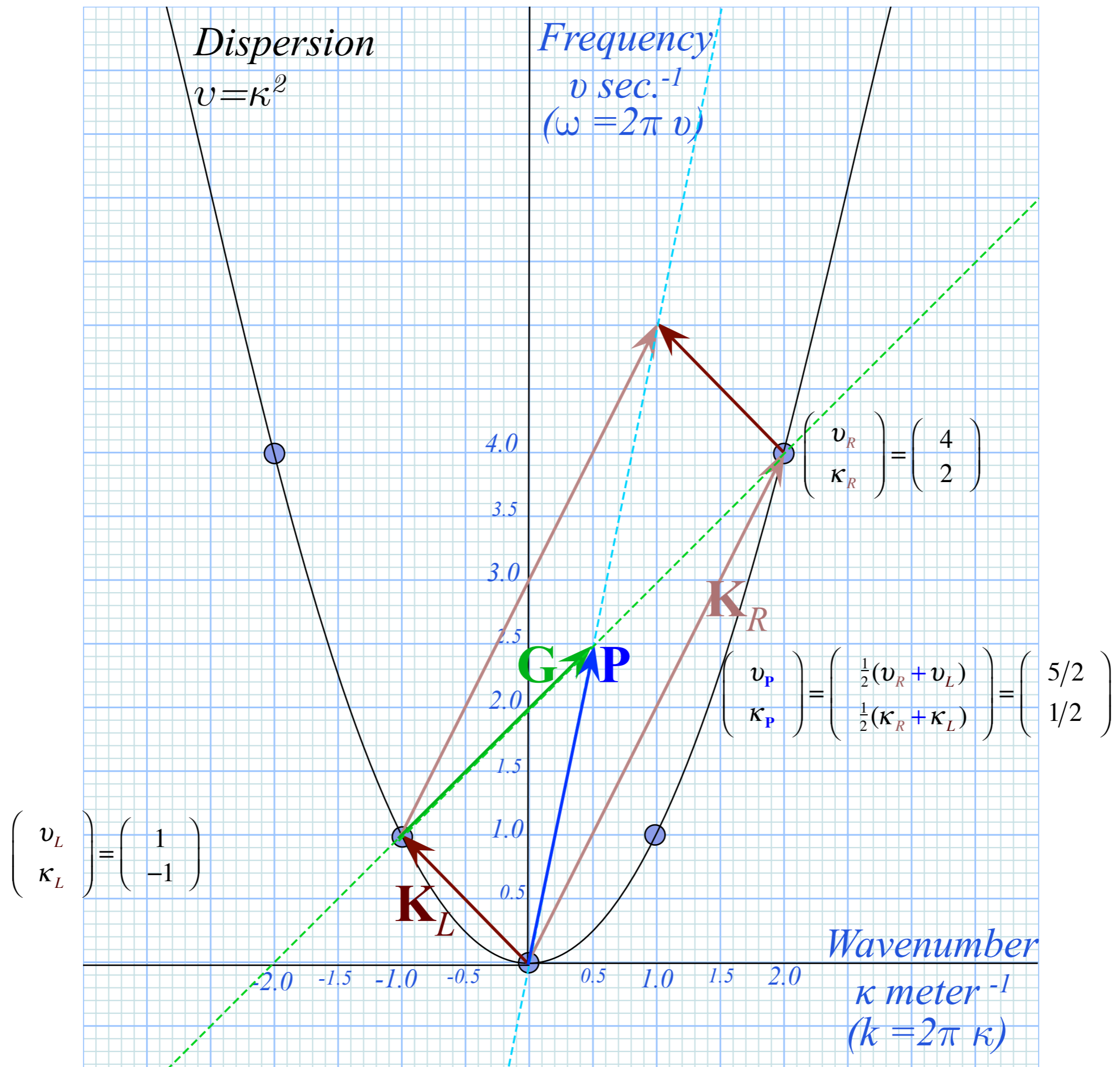
[BohrIt Web Simulation](#)
Bohr-Schrödinger {Quadratic dispersion} Wave Mixing









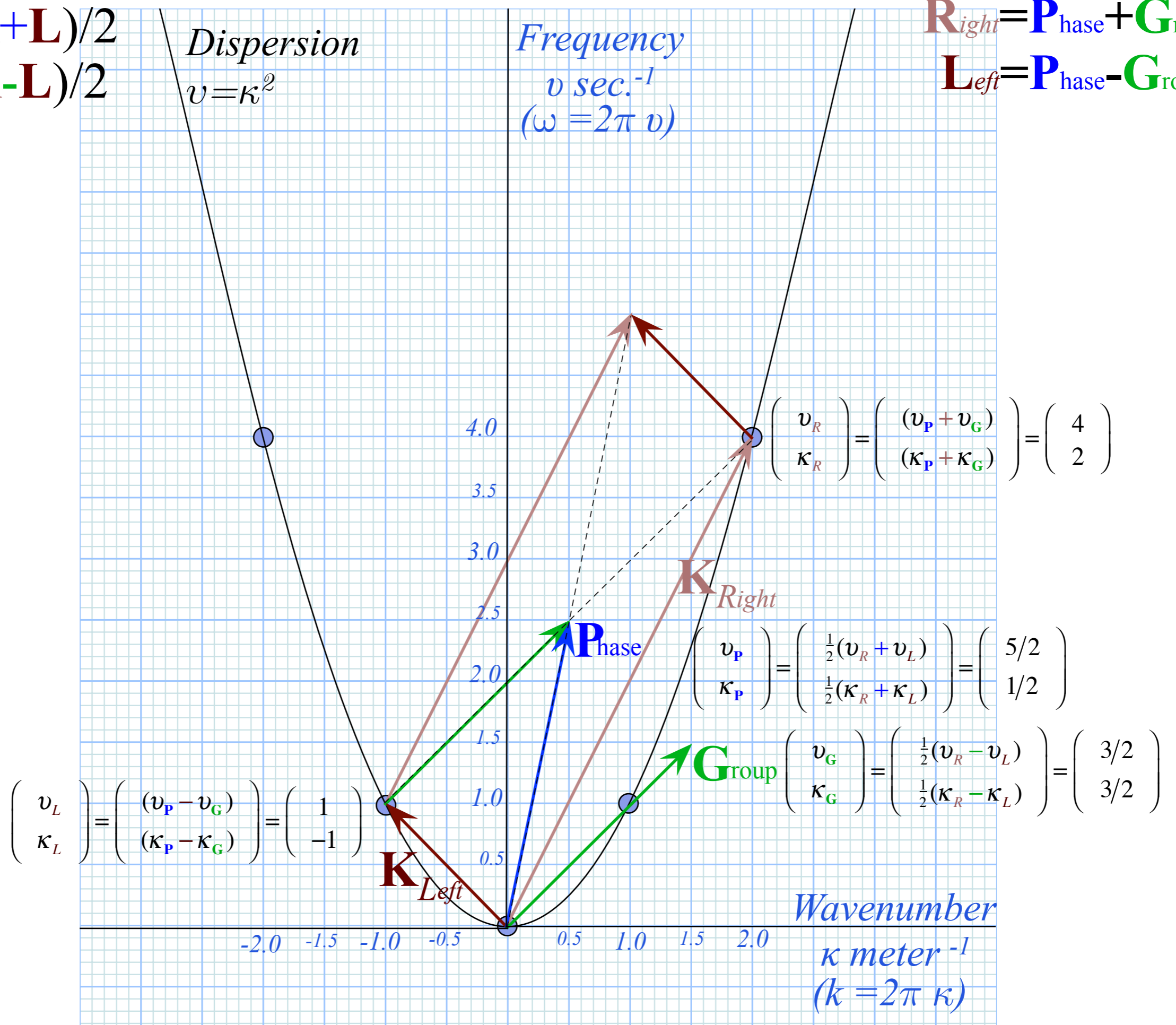


$$\mathbf{P}_{\text{hase}} = (\mathbf{R} + \mathbf{L}) / 2$$

$$\mathbf{G}_{\text{roup}} = (\mathbf{R} - \mathbf{L}) / 2$$

$$\mathbf{R}_{\text{ight}} = \mathbf{P}_{\text{hase}} + \mathbf{G}_{\text{roup}}$$

$$\mathbf{L}_{\text{eft}} = \mathbf{P}_{\text{hase}} - \mathbf{G}_{\text{roup}}$$



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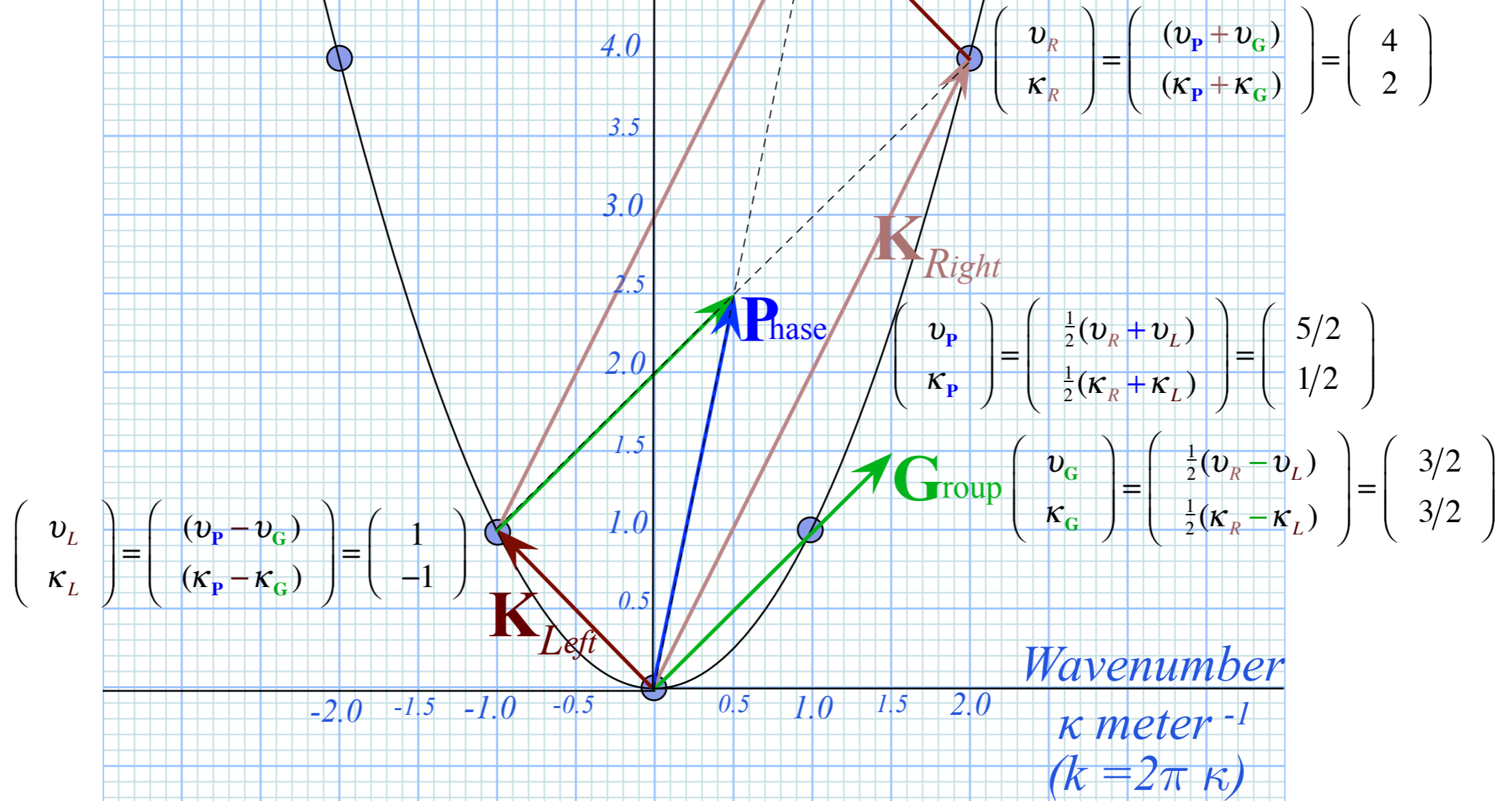
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 $v = \kappa^2$

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Frequency
 $v \text{ sec.}^{-1}$
 $(\omega = 2\pi v)$

	Group	Phase	Phase	Group	
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per-space	$\frac{1}{V_G} = \frac{1}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	space
= velocity	$V_G = 1$	$V_P = 5$	$V_P = 5$	$V_G = 1$	velocity ⁻¹



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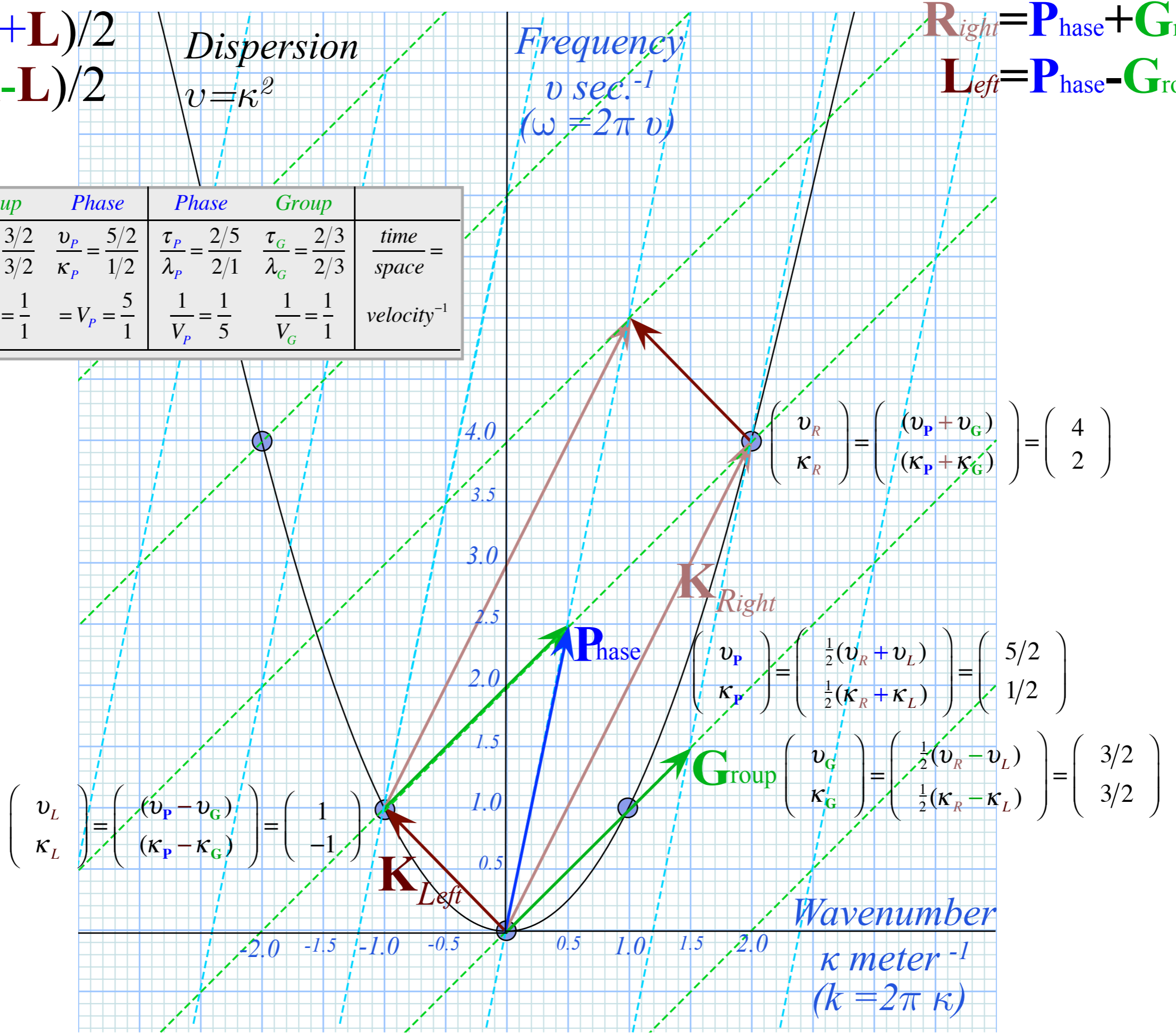
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2-CW space-time (x,t) lattice from per-space-time (κ,ν) by algebra

Real wave-zeros ($\cos\phi=0$) need $\phi=kx-\omega t=N\pi/2$ for odd N .

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...becomes
matrix equation:
$$\begin{pmatrix} k_P & -\omega_P \\ k_G & -\omega_G \end{pmatrix} \begin{pmatrix} x \\ t \end{pmatrix} = \begin{pmatrix} N_P \\ N_G \end{pmatrix} \frac{\pi}{2}$$

2-CW space-time (x,t) lattice from per-space-time (κ,ν) by algebra

Real wave-zeros ($\cos\phi=0$) need $\phi=kx-\omega t=N\pi/2$ for odd N .

Real ψ_{phase} -zeros ($\cos\phi_P=0$) need $\phi_P=k_Px-\omega_Pt=N_P\pi/2$ for odd $N_P=\dots\pm3, \pm1, \pm3, \pm5,\dots$

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...becomes matrix equation:
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...with inverted matrix solution:
$$\begin{pmatrix} x \\ t \end{pmatrix} = \begin{pmatrix} k_P & -\omega_P \\ k_G & -\omega_G \end{pmatrix}^{-1} \begin{pmatrix} N_P \\ N_G \end{pmatrix} \frac{\pi}{2}$$

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	Group	Phase	Phase	Group
per-time	$v_G = 3/2$	$v_P = 5/2$	$\tau_P = 2/5$	$\tau_G = 2/3$
per-space	$\kappa_G = 3/2$	$\kappa_P = 1/2$	$\lambda_P = 2/1$	$\lambda_G = 2/3$
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$

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Wave resonance in cyclic C_n symmetry (REVIEW)

C_6 symmetric mode model: Distant neighbor coupling

C_6 moving waves and degenerate standing waves

C_6 dispersion functions for 1st, 2nd, and 3rd-neighbor coupling

*C_6 dispersion functions split by **C-type** symmetry (complex, chiral, ...)*

C_{12} and higher symmetry mode models: Archetypes of dispersion functions and 1-CW phase velocity

$\frac{1}{2}$ -Sum- $\frac{1}{2}$ -Diff-theory of 2-CW group and phase velocity

Given two 1-CW phases: Find 2-CW phase velocity $V_{\text{phase}}^{(2\text{-CW})}$ and group velocity $V_{\text{group}}^{(2\text{-CW})}$

Example: Bohr Dispersion 2-CW made of 1-CW($m=-1$) + 1-CW($m=2$)

Find 2-CW space-time (x,t) lattice from per-space-time (κ,ν) by matrix-algebra/geometry

→ *Same 1-CW($m=-1$) + 1-CW($m=2$) Example*



(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

$N_G =$

-5 -3 -1 +1 +3 +5 +7

$N_P = -5$

-3

-5+3 +5+3

=-2 =+8

-1+3 +1+3

=+2 =+4

-5-3 +5-3

=-8 =+2

-1-3 +1-3

=-4 =-2

$\frac{1}{24}$

-1

+1

+3

+5

+7

-45 -40 -35 -30 -25 -20 -15 -10 -5

5 10 15 20 25 30 35 40 45

Space

x meters

(scale factor=24)

45

40

35

30

25

20

15

10

5

-5

-10

-15

-20

-25

(scale factor=24)

Time

t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

$N_G =$

-5 -3 -1 +1 +3 +5 +7

$N_P = -5$

$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$ $\begin{pmatrix} 10 \\ 14 \end{pmatrix}$ $\begin{pmatrix} 20 \\ 16 \end{pmatrix}$ $\begin{pmatrix} 30 \\ 18 \end{pmatrix}$

-3

$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$ $\begin{matrix} -5+9 \\ =+4 \end{matrix}$ $\begin{matrix} +5+9 \\ =+14 \end{matrix}$ $\begin{pmatrix} 24 \\ 12 \end{pmatrix}$
 $\begin{matrix} -1+9 \\ =+8 \end{matrix}$ $\begin{matrix} +1+9 \\ =+10 \end{matrix}$

$\frac{1}{24}$

-1

$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$ $\begin{matrix} -5+3 \\ =-2 \end{matrix}$ $\begin{matrix} +5+3 \\ =+8 \end{matrix}$ $\begin{pmatrix} 18 \\ +6 \end{pmatrix}$
 $\begin{matrix} -1+3 \\ =+2 \end{matrix}$ $\begin{matrix} +1+3 \\ =+4 \end{matrix}$

+1

$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$ $\begin{matrix} -5-3 \\ =-8 \end{matrix}$ $\begin{matrix} +5-3 \\ =+2 \end{matrix}$ $\begin{pmatrix} 12 \\ 0 \end{pmatrix}$
 $\begin{matrix} -1-3 \\ =-4 \end{matrix}$ $\begin{matrix} +1-3 \\ =-2 \end{matrix}$

+3

$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$ $\begin{pmatrix} -14 \\ -10 \end{pmatrix}$ $\begin{pmatrix} -4 \\ -8 \end{pmatrix}$ $\begin{pmatrix} +6 \\ -6 \end{pmatrix}$

+5

$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$ $\begin{pmatrix} -20 \\ -16 \end{pmatrix}$ $\begin{pmatrix} -10 \\ -14 \end{pmatrix}$ $\begin{pmatrix} 0 \\ -12 \end{pmatrix}$

+7

-45 -40 -35 -30 -25 -20 -15 -10 -5

5 10 15 20 25 30 35 40 45

Space

x meters

(scale factor=24)

45
40
35
30
25
20
15
10
5
-5
-10
-15
-20
-25

(scale factor=24)

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

	$N_G =$			
	-5	-3	-1	+1
$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$
-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \\ -1+9 \\ =+8 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \\ +1+9 \\ =+10 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$
$\frac{1}{24}$ -1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \\ -1+3 \\ =+2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \\ +1+3 \\ =+4 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$
+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \\ -1-3 \\ =-4 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \\ +1-3 \\ =-2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$
+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$
+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$
+7				

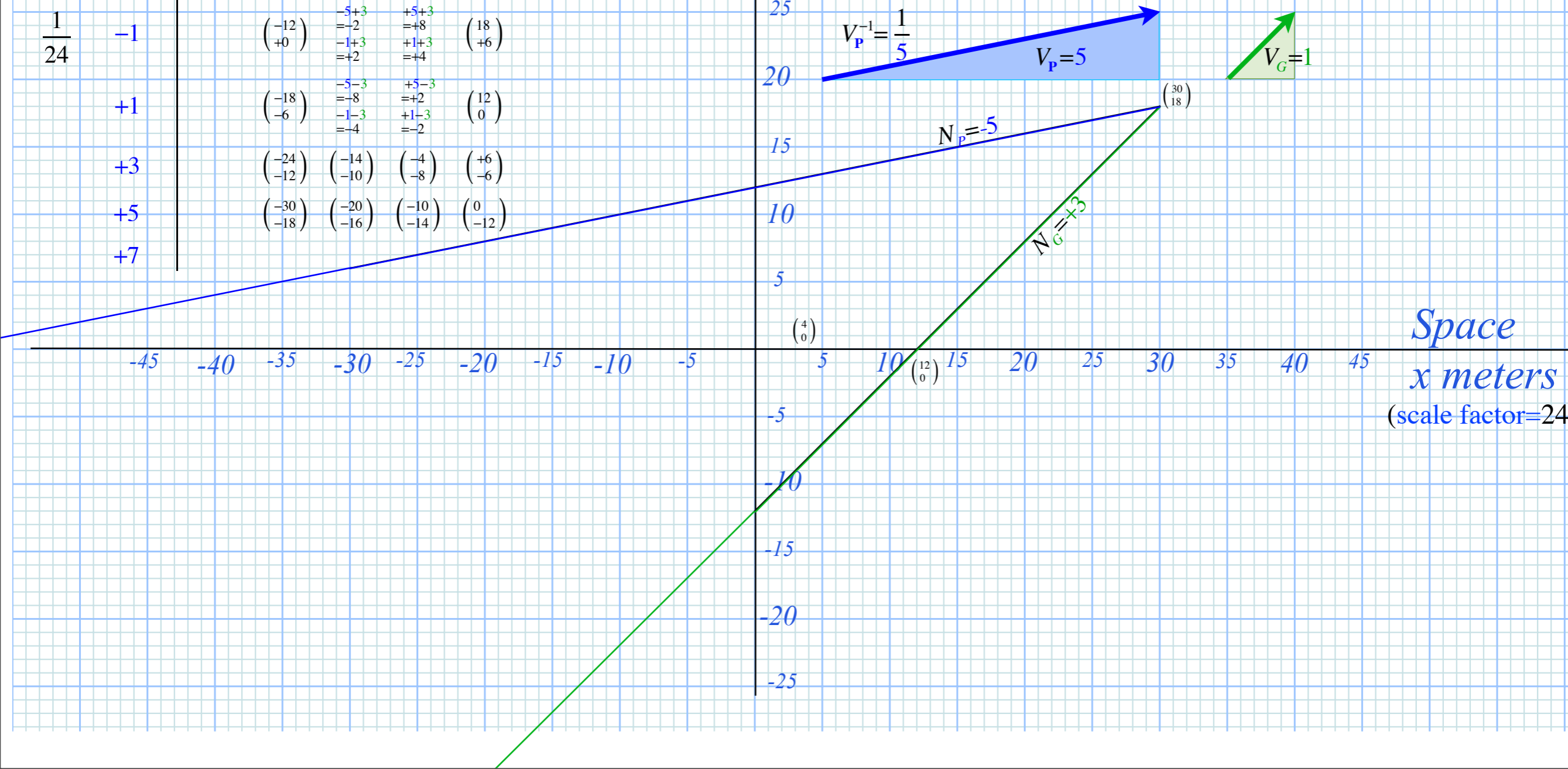
Time
 t sec.

	Group	Phase	Phase	Group	
$\frac{\text{per-time}}{\text{per-space}}$	$\frac{v_G}{\kappa_G} = \frac{3/2}{3/2}$	$\frac{v_P}{\kappa_P} = \frac{5/2}{1/2}$	$\frac{\tau_P}{\lambda_P} = \frac{2/5}{2/1}$	$\frac{\tau_G}{\lambda_G} = \frac{2/3}{2/3}$	$\frac{\text{time}}{\text{space}} =$
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	velocity ⁻¹

45
40
35
30
25
20
15
10
5
-5
-10
-15
-20
-25

Space
 x meters

(scale factor=24)



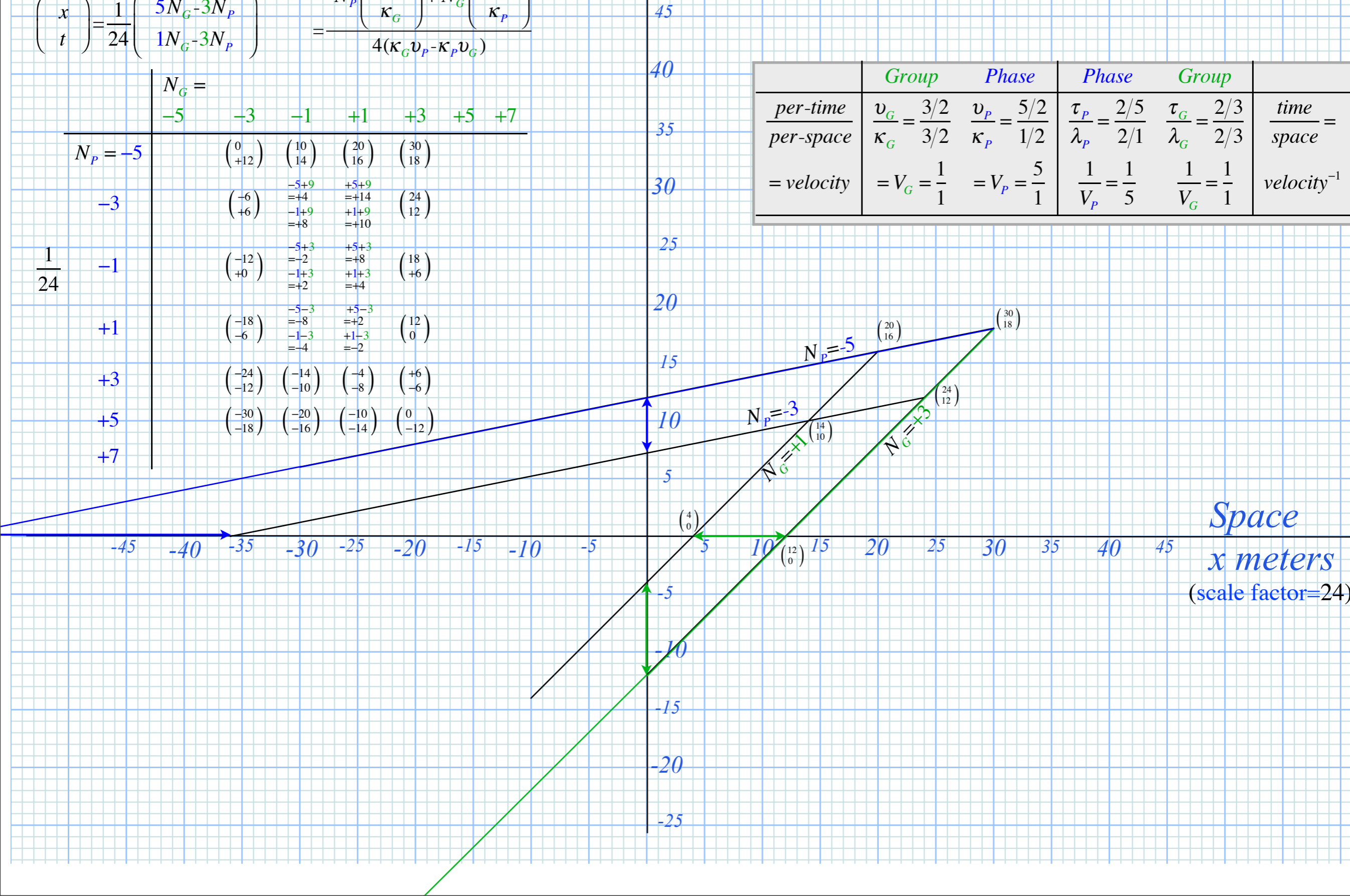
(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

	$N_G =$						
	-5	-3	-1	+1	+3	+5	+7
$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \\ -1+9 \\ =+8 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \\ +1+9 \\ =+10 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
$\frac{1}{24}$ -1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \\ -1+3 \\ =+2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \\ +1+3 \\ =+4 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \\ -1-3 \\ =-4 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \\ +1-3 \\ =-2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
+7							

	Group	Phase	Phase	Group	
$\frac{\text{per-time}}{\text{per-space}}$	$v_G = \frac{3}{2}$	$v_P = \frac{5}{2}$	$\tau_P = \frac{2}{5}$	$\tau_G = \frac{2}{3}$	$\frac{\text{time}}{\text{space}} =$
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	velocity ⁻¹



Space
x meters
(scale factor=24)

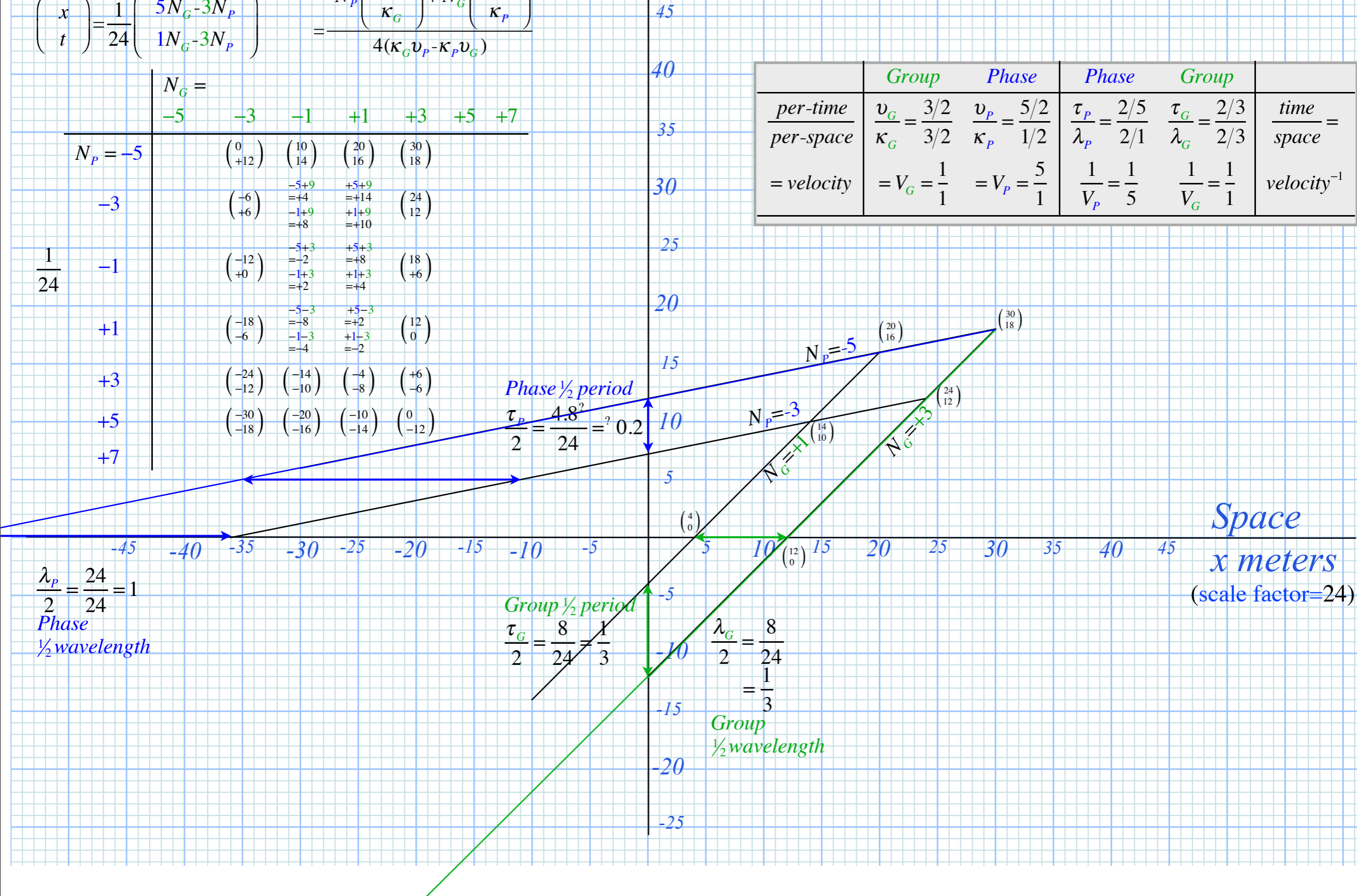
(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

	$N_G =$	-5	-3	-1	+1	+3	+5	+7
$N_P = -5$		$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
-3		$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \\ -1+9 \\ =+8 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \\ +1+9 \\ =+10 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
$\frac{1}{24}$ -1		$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \\ -1+3 \\ =+2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \\ +1+3 \\ =+4 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
+1		$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \\ -1-3 \\ =-4 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \\ +1-3 \\ =-2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
+3		$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
+5		$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
+7								

	Group	Phase	Phase	Group	
$\frac{\text{per-time}}{\text{per-space}}$	$v_G = \frac{3}{2}$	$v_P = \frac{5}{2}$	$\frac{\tau_P}{\lambda_P} = \frac{2}{5}$	$\frac{\tau_G}{\lambda_G} = \frac{2}{3}$	$\frac{\text{time}}{\text{space}} =$
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	velocity ⁻¹



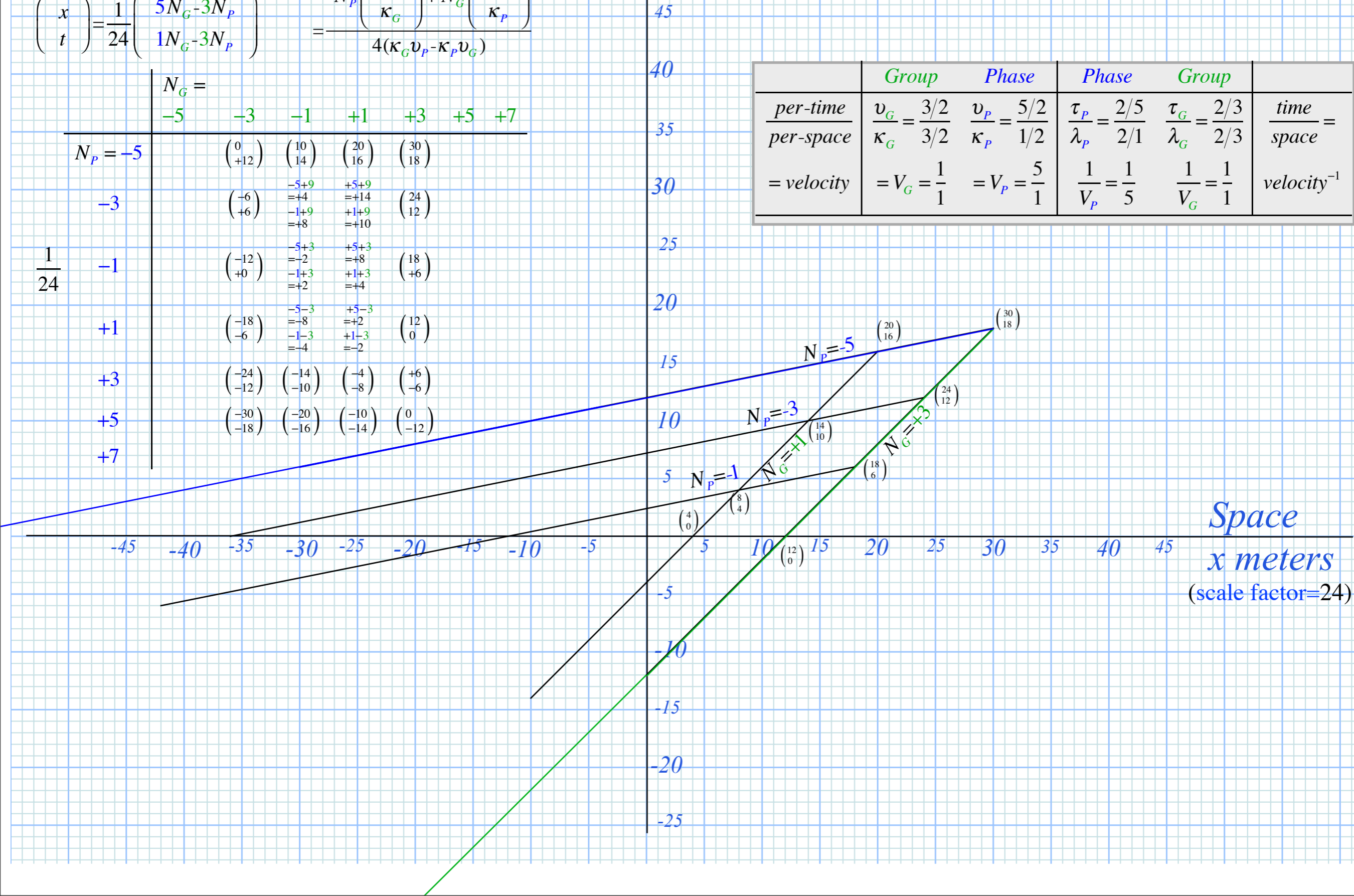
(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix} = \frac{-N_P \begin{pmatrix} v_G \\ \kappa_G \end{pmatrix} + N_G \begin{pmatrix} v_P \\ \kappa_P \end{pmatrix}}{4(\kappa_G v_P - \kappa_P v_G)}$$

	$N_G =$						
	-5	-3	-1	+1	+3	+5	+7
$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \\ -1+9 \\ =+8 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \\ +1+9 \\ =+10 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
$\frac{1}{24}$ -1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \\ -1+3 \\ =+2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \\ +1+3 \\ =+4 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \\ -1-3 \\ =-4 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \\ +1-3 \\ =-2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
+7							

	Group	Phase	Phase	Group	
<i>per-time</i>	$v_G = 3/2$	$v_P = 5/2$	$\tau_P = 2/5$	$\tau_G = 2/3$	<i>time</i>
<i>per-space</i>	$\kappa_G = 3/2$	$\kappa_P = 1/2$	$\lambda_P = 2/1$	$\lambda_G = 2/3$	<i>space</i>
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	<i>velocity</i> ⁻¹



Space
x meters
(scale factor=24)

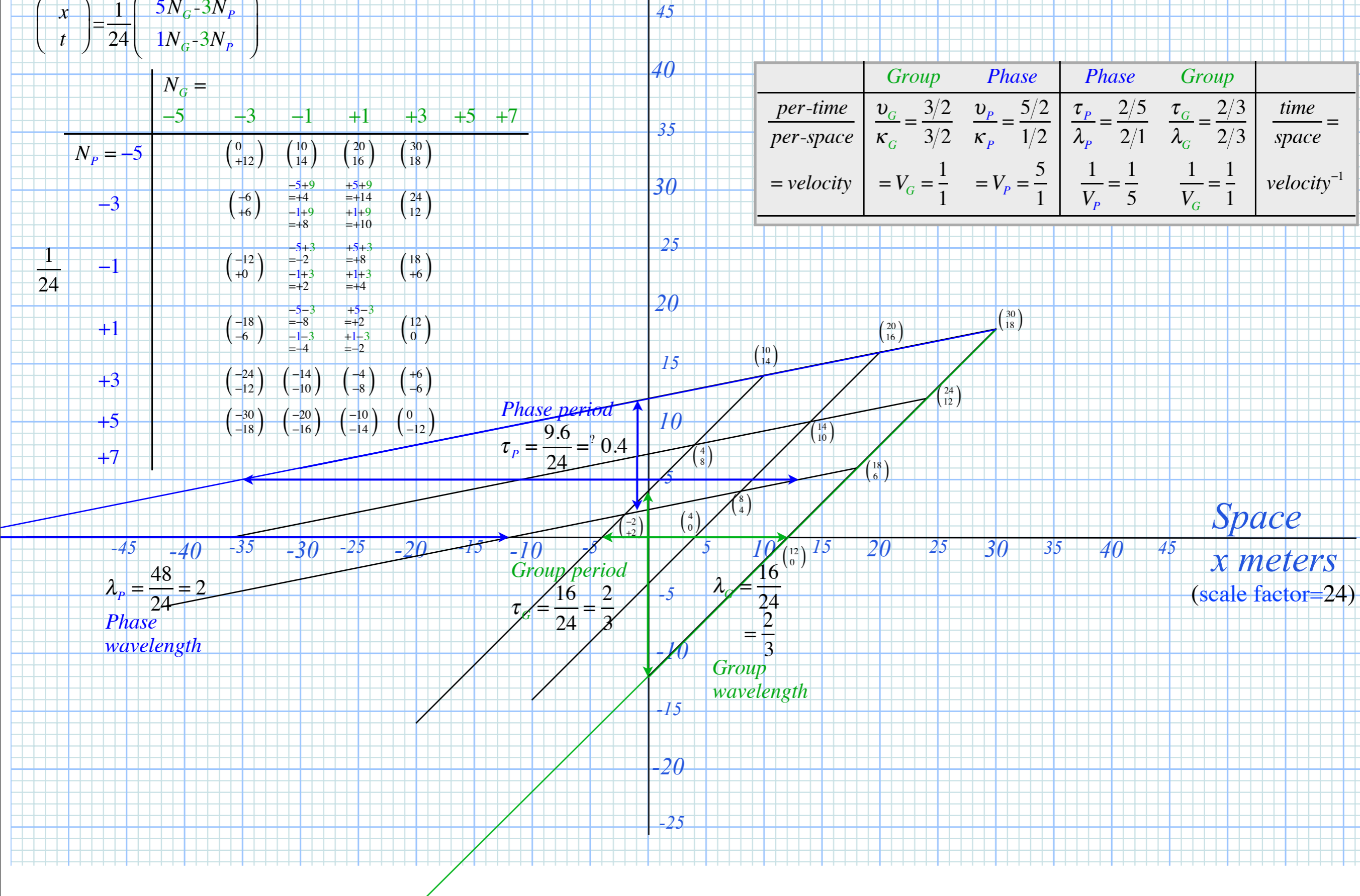
(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix}$$

	$N_G =$						
	-5	-3	-1	+1	+3	+5	+7
$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \\ -1+9 \\ =+8 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \\ +1+9 \\ =+10 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
$\frac{1}{24}$ -1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \\ -1+3 \\ =+2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \\ +1+3 \\ =+4 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \\ -1-3 \\ =-4 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \\ +1-3 \\ =-2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
+7							

	Group	Phase	Phase	Group	
$\frac{\text{per-time}}{\text{per-space}}$	$v_G = \frac{3}{2}$	$v_P = \frac{5}{2}$	$\tau_P = \frac{2}{5}$	$\tau_G = \frac{2}{3}$	$\frac{\text{time}}{\text{space}} =$
= velocity	$= V_G = \frac{1}{1}$	$= V_P = \frac{5}{1}$	$\frac{1}{V_P} = \frac{1}{5}$	$\frac{1}{V_G} = \frac{1}{1}$	velocity ⁻¹

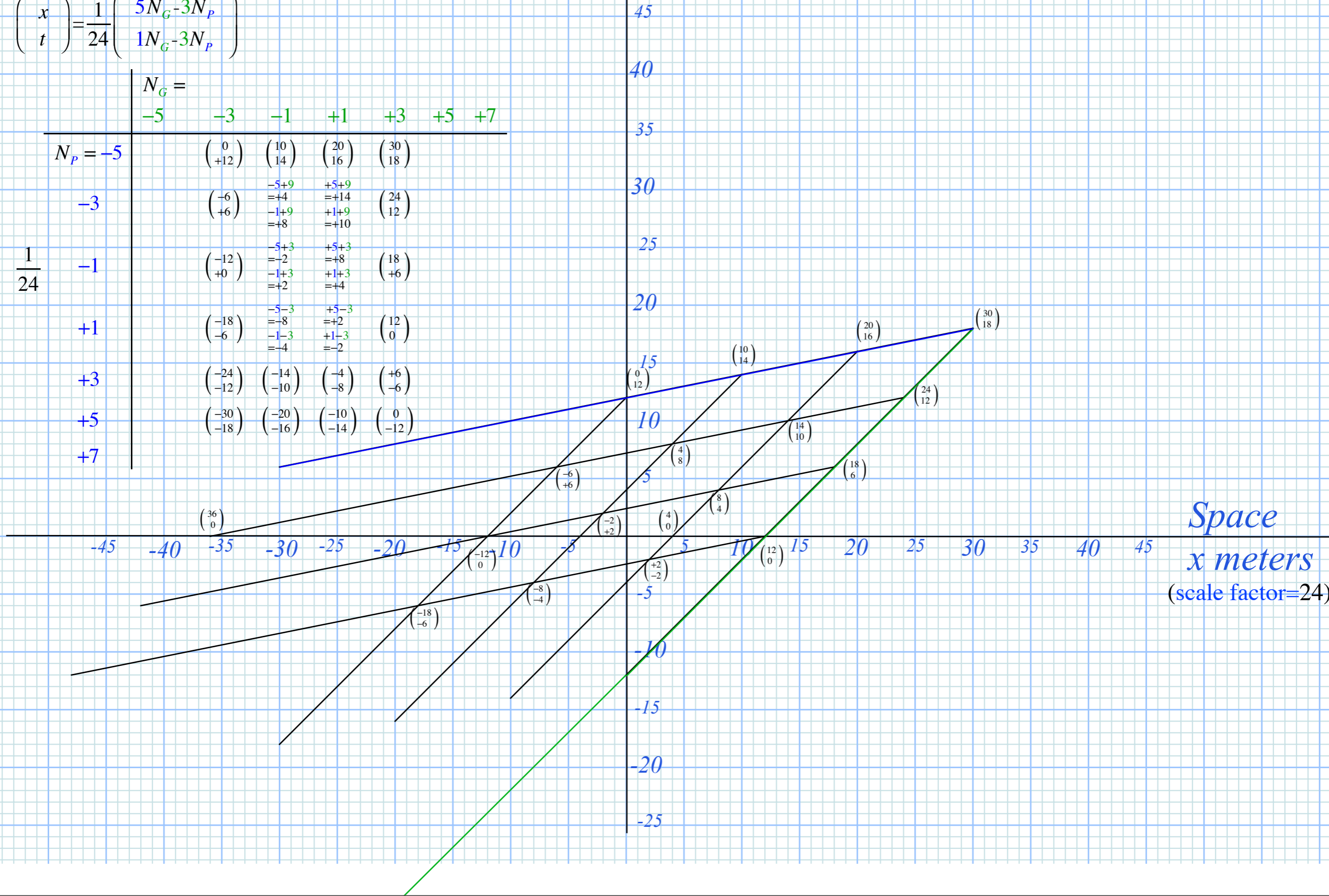


(scale factor=24)

Time
t sec.

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix}$$

		$N_G =$						
		-5	-3	-1	+1	+3	+5	+7
$\frac{1}{24}$	$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
	-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
	-1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
	+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
	+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
	+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
	+7							



Space
x meters
(scale factor=24)

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix}$$

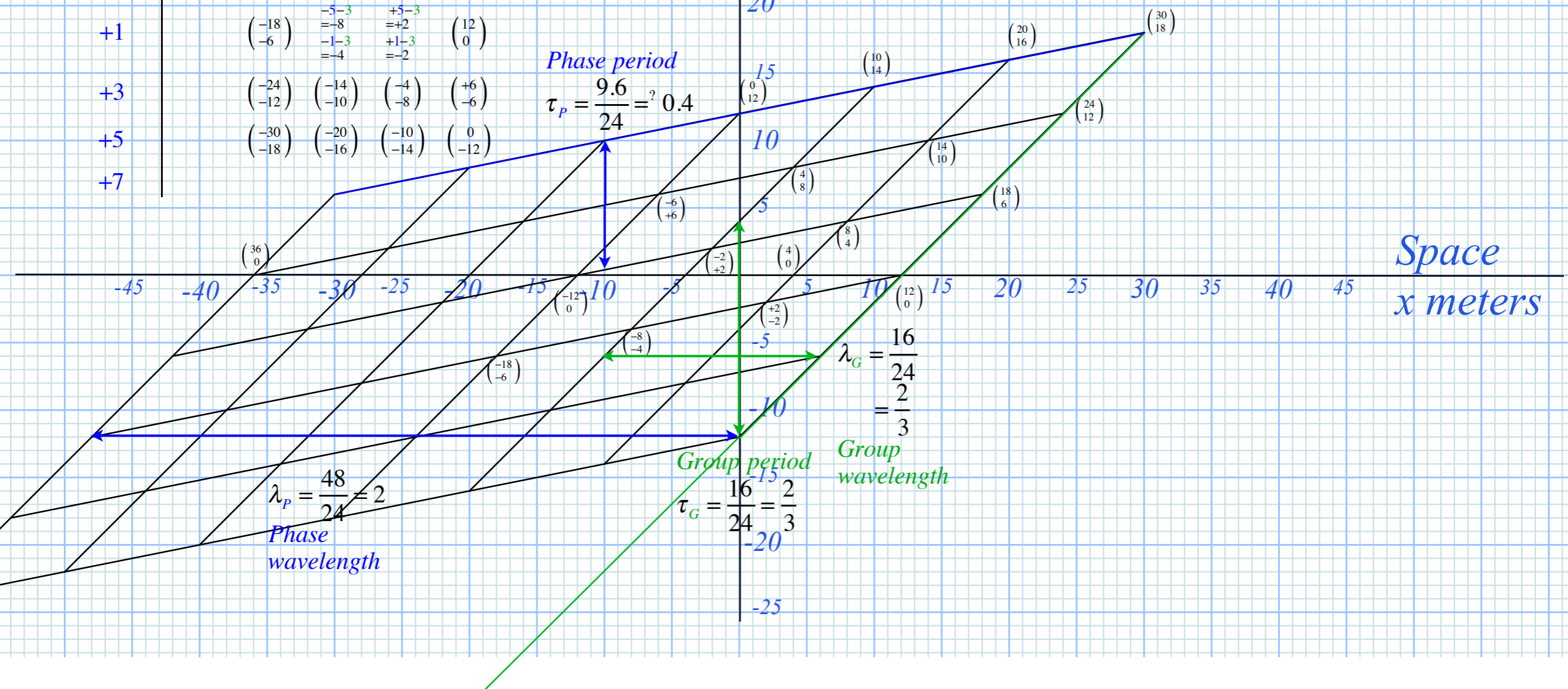
		$N_G =$						
		-5	-3	-1	+1	+3	+5	+7
$\frac{1}{24}$	$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
	-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
	-1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
	+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
	+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \end{matrix}$	$\begin{pmatrix} 6 \\ -6 \end{pmatrix}$			
	+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \end{matrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
	+7							

Time
 t sec.

45
40
35
30
25
20
15
10
5
0
-5
-10
-15
-20
-25

Space
 x meters

-45 -40 -35 -30 -25 -20 -15 -10 -5 0 5 10 15 20 25 30 35 40 45

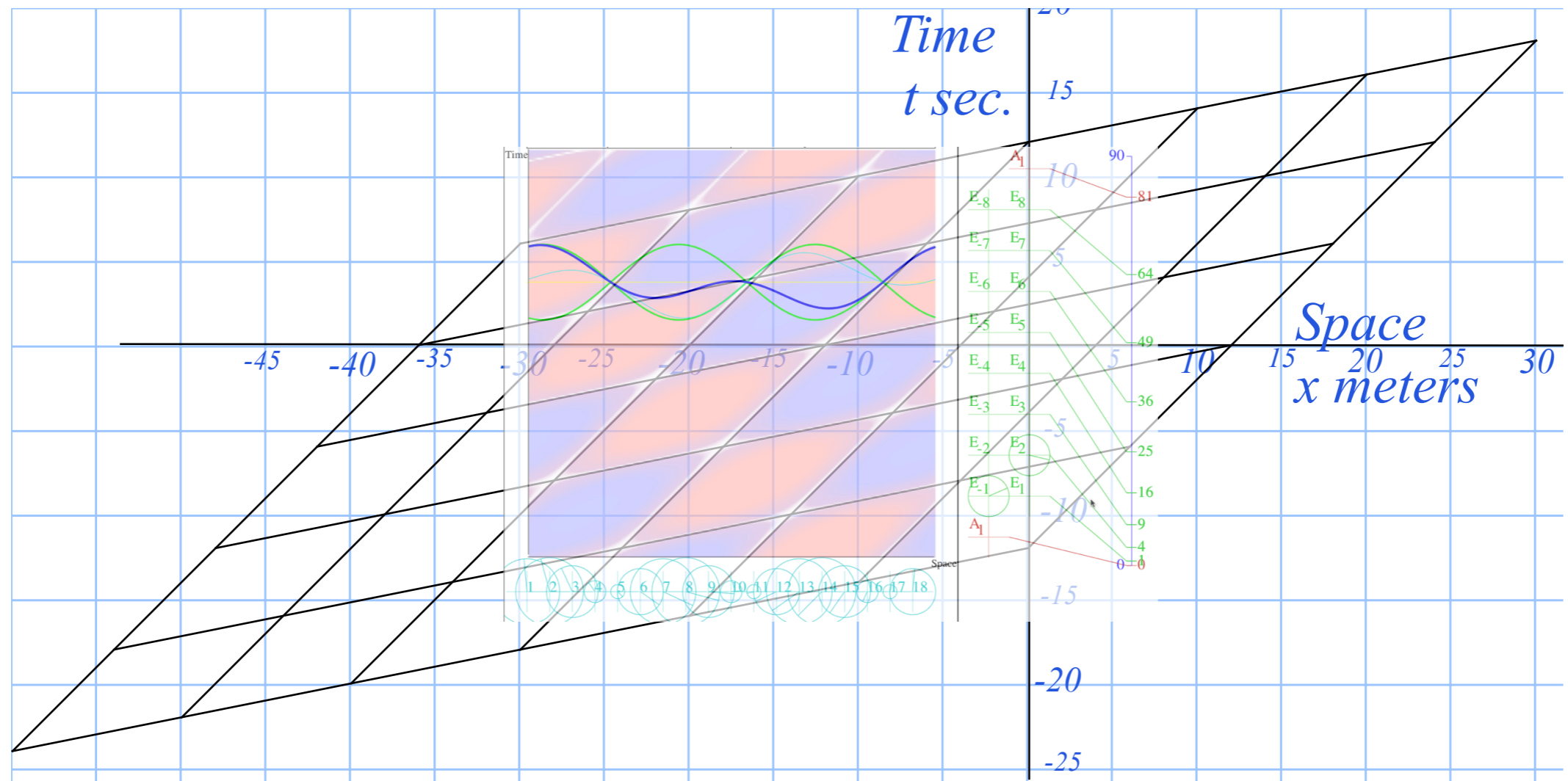


Phase period
 $\tau_P = \frac{9.6}{24} = 0.4$

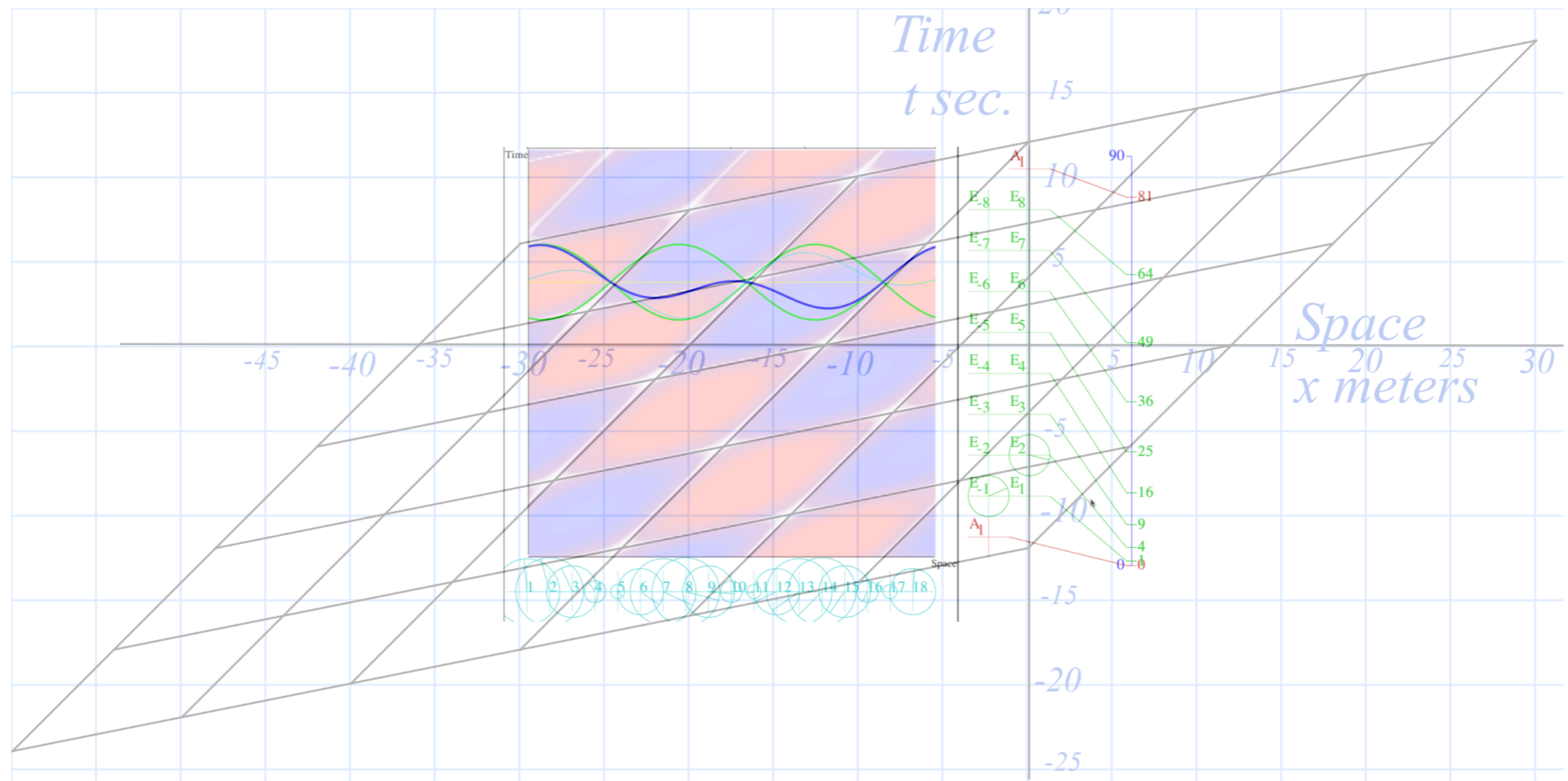
Group wavelength
 $\lambda_G = \frac{16}{24} = \frac{2}{3}$

Phase wavelength
 $\lambda_P = \frac{48}{24} = 2$

Group period
 $\tau_G = \frac{16}{24} = \frac{2}{3}$



BohrIt Web Simulation
Bohr-Schrödinger {Quadratic dispersion} Wave Mixing for $k=-1, 2$



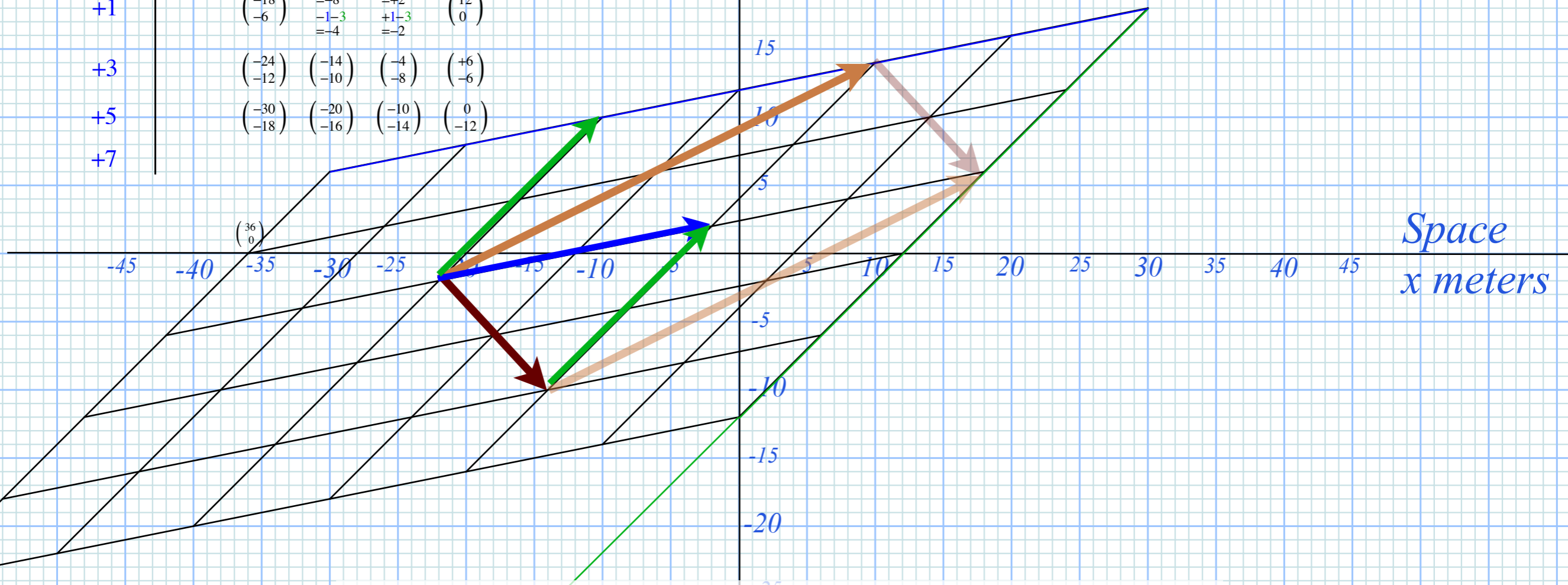
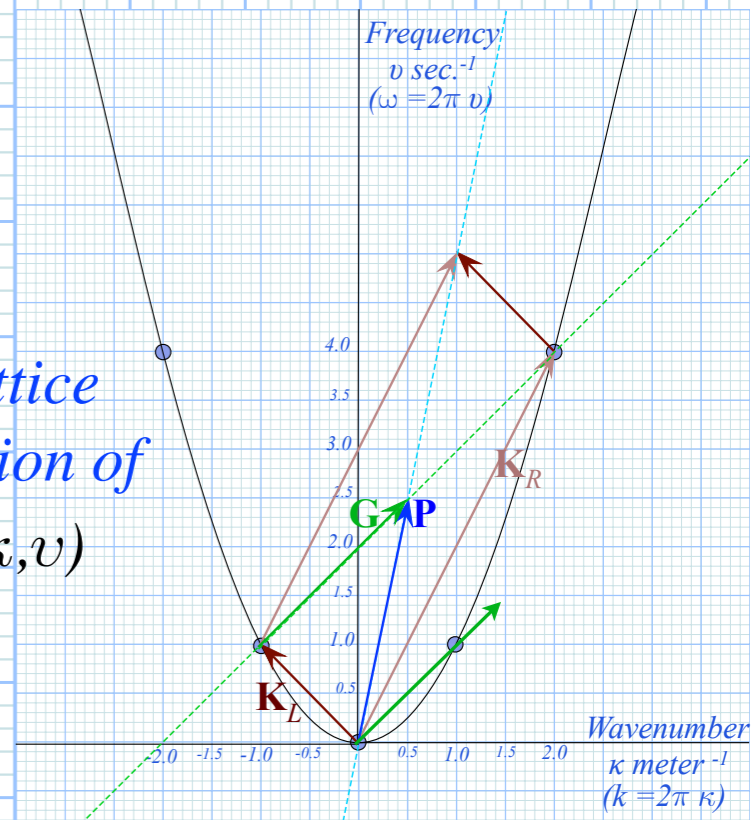
BohrIt Web Simulation
Bohr-Schrödinger {Quadratic dispersion} Wave Mixing for $k=-1, 2$

$$\begin{pmatrix} x \\ t \end{pmatrix} = \frac{1}{24} \begin{pmatrix} 5N_G - 3N_P \\ 1N_G - 3N_P \end{pmatrix}$$

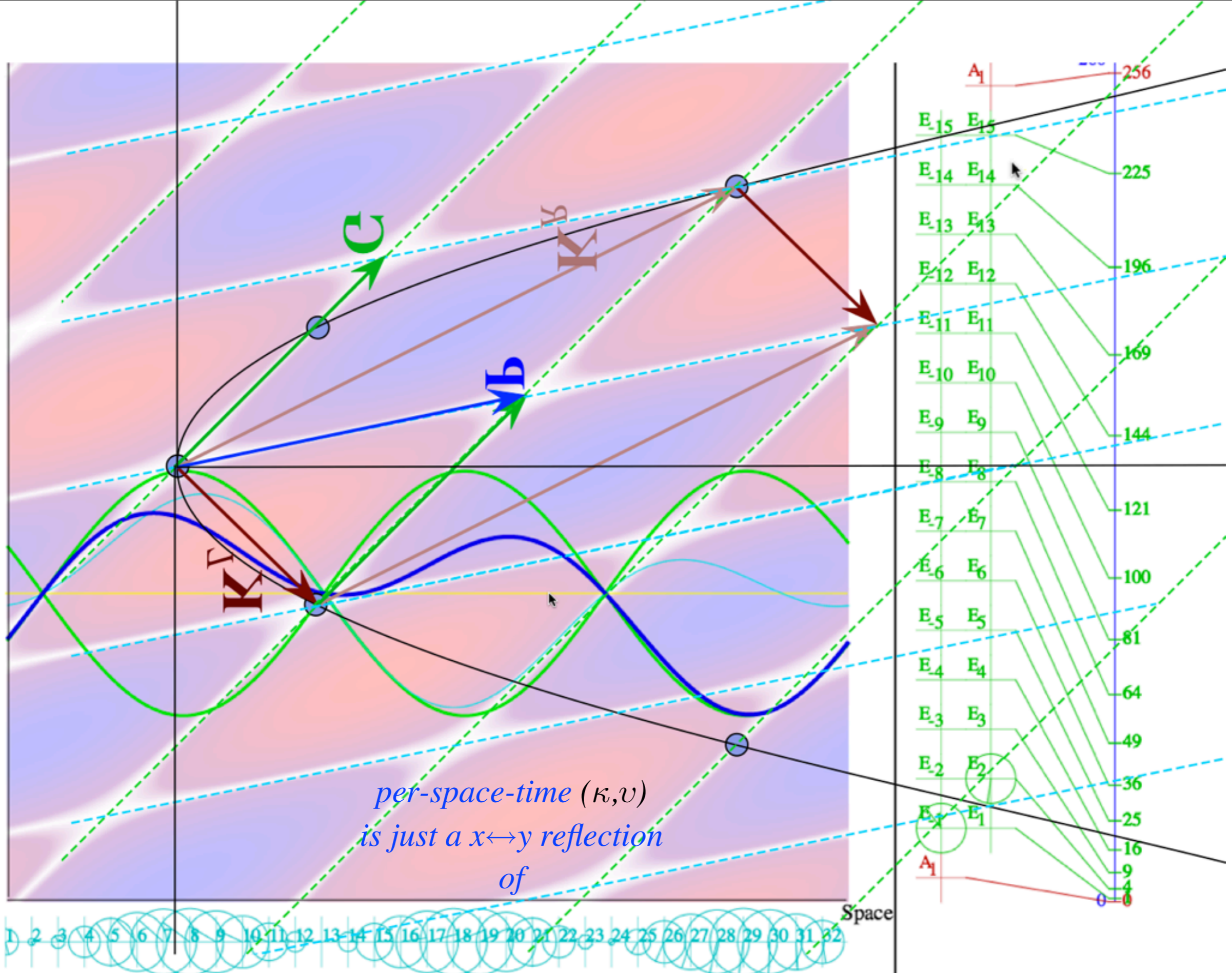
		$N_G =$						
		-5	-3	-1	+1	+3	+5	+7
$\frac{1}{24}$	$N_P = -5$	$\begin{pmatrix} 0 \\ +12 \end{pmatrix}$	$\begin{pmatrix} 10 \\ 14 \end{pmatrix}$	$\begin{pmatrix} 20 \\ 16 \end{pmatrix}$	$\begin{pmatrix} 30 \\ 18 \end{pmatrix}$			
	-3	$\begin{pmatrix} -6 \\ +6 \end{pmatrix}$	$\begin{matrix} -5+9 \\ =+4 \end{matrix}$	$\begin{matrix} +5+9 \\ =+14 \end{matrix}$	$\begin{pmatrix} 24 \\ 12 \end{pmatrix}$			
	-1	$\begin{pmatrix} -12 \\ +0 \end{pmatrix}$	$\begin{matrix} -5+3 \\ =-2 \end{matrix}$	$\begin{matrix} +5+3 \\ =+8 \end{matrix}$	$\begin{pmatrix} 18 \\ +6 \end{pmatrix}$			
	+1	$\begin{pmatrix} -18 \\ -6 \end{pmatrix}$	$\begin{matrix} -5-3 \\ =-8 \end{matrix}$	$\begin{matrix} +5-3 \\ =+2 \end{matrix}$	$\begin{pmatrix} 12 \\ 0 \end{pmatrix}$			
	+3	$\begin{pmatrix} -24 \\ -12 \end{pmatrix}$	$\begin{pmatrix} -14 \\ -10 \end{pmatrix}$	$\begin{pmatrix} -4 \\ -8 \end{pmatrix}$	$\begin{pmatrix} +6 \\ -6 \end{pmatrix}$			
	+5	$\begin{pmatrix} -30 \\ -18 \end{pmatrix}$	$\begin{pmatrix} -20 \\ -16 \end{pmatrix}$	$\begin{pmatrix} -10 \\ -14 \end{pmatrix}$	$\begin{pmatrix} 0 \\ -12 \end{pmatrix}$			
	+7							

Time
 t sec.

space-time (x,t) lattice
is just a $x \leftrightarrow y$ reflection of
per-space-time (κ, ν)



BohrIt Web Simulation
Bohr-Schrödinger {Quadratic dispersion} Wave Mixing for $k = -1, 2$



BohrIt Web Simulation

Bohr-Schrödinger {Quadratic dispersion} Wave Mixing for $k=-1, 2$

Symmetrized finite-difference operators

$$\bar{\Delta} = \frac{1}{2} \begin{pmatrix} \ddots & \vdots & & & & & \\ \dots & 0 & 1 & & & & \\ & -1 & 0 & 1 & & & \\ & & -1 & 0 & 1 & & \\ & & & -1 & 0 & 1 & \\ & & & & -1 & 0 & \\ & & & & & -1 & 0 \end{pmatrix}, \bar{\Delta}^3 = \frac{1}{2^3} \begin{pmatrix} \ddots & \vdots & 0 & -1 & & & \\ \dots & 0 & 3 & 0 & -1 & & \\ & 0 & -3 & 0 & 3 & 0 & -1 \\ & 1 & 0 & -3 & 0 & 3 & 0 \\ & & 1 & 0 & -3 & 0 & 3 \\ & & & 1 & 0 & -3 & 0 \end{pmatrix}$$

$$\bar{\Delta}^2 = \frac{1}{2^2} \begin{pmatrix} \ddots & \vdots & 1 & & & & \\ \dots & -2 & 0 & 1 & & & \\ & 1 & 0 & -2 & 0 & 1 & \\ & & 1 & 0 & -2 & 0 & 1 \\ & & & 1 & 0 & -2 & 0 \\ & & & & 1 & 0 & -2 \end{pmatrix}, \bar{\Delta}^4 = \frac{1}{2^4} \begin{pmatrix} \ddots & \vdots & -4 & 0 & 1 & & \\ \dots & 6 & 0 & -4 & 0 & 1 & \\ & -4 & 0 & 6 & 0 & -4 & 0 \\ & 0 & -4 & 0 & 6 & 0 & -4 \\ & 1 & 0 & -4 & 0 & 6 & 0 \\ & & 1 & 0 & -4 & 0 & 6 \end{pmatrix}$$