

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
 Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

AMOP reference links (Updated list given on 2nd page of each class presentation)

[Web Resources - front page](#)

[UAF Physics UTube channel](#)

[Quantum Theory for the Computer Age](#)

[Principles of Symmetry, Dynamics, and Spectroscopy](#)

[Classical Mechanics with a Bang!](#)

[Modern Physics and its Classical Foundations](#)

[2014 AMOP](#)

[2017 Group Theory for QM](#)

[2018 AMOP](#)

[Frame Transformation Relations And Multipole Transitions In Symmetric Polyatomic Molecules - RMP-1978](#)

[Rotational energy surfaces and high- J eigenvalue structure of polyatomic molecules - Harter - Patterson - 1984](#)

[Galloping waves and their relativistic properties - ajp-1985-Harter](#)

[Asymptotic eigensolutions of fourth and sixth rank octahedral tensor operators - Harter-Patterson-JMP-1979](#)

[Nuclear spin weights and gas phase spectral structure of 12C60 and 13C60 buckminsterfullerene -Harter-Reimer-Cpl-1992 - \(Alt1, Alt2 Erratum\)](#)

Theory of hyperfine and superfine levels in symmetric polyatomic molecules.

I) [Trigonal and tetrahedral molecules: Elementary spin-1/2 cases in vibronic ground states - PRA-1979-Harter-Patterson \(Alt scan\)](#)

II) [Elementary cases in octahedral hexafluoride molecules - Harter-PRA-1981 \(Alt scan\)](#)

[Rotation-vibration scalar coupling zeta coefficients and spectroscopic band shapes of buckminsterfullerene - Weeks-Harter-CPL-1991 \(Alt scan\)](#)

[Fullerene symmetry reduction and rotational level fine structure/ the Buckyball isotopomer 12C 13C59 - jcp-Reimer-Harter-1997 \(HiRez\)](#)

[Molecular Eigensolution Symmetry Analysis and Fine Structure - IJMS-harter-mitchell-2013](#)

Rotation–vibration spectra of icosahedral molecules.

I) [Icosahedral symmetry analysis and fine structure - harter-weeks-jcp-1989](#)

II) [Icosahedral symmetry, vibrational eigenfrequencies, and normal modes of buckminsterfullerene - weeks-harter-jcp-1989](#)

III) [Half-integral angular momentum - harter-reimer-jcp-1991](#)

[QTCA Unit 10 Ch 30 - 2013](#)

[AMOP Ch 32 Molecular Symmetry and Dynamics - 2019](#)

[AMOP Ch 0 Space-Time Symmetry - 2019](#)

RESONANCE AND REVIVALS

I) [QUANTUM ROTOR AND INFINITE-WELL DYNAMICS - ISMSLi2012 \(Talk\) OSU knowledge Bank](#)

II) [Comparing Half-integer Spin and Integer Spin - Alva-ISMS-Ohio2013-R777 \(Talks\)](#)

III) [Quantum Resonant Beats and Revivals in the Morse Oscillators and Rotors - \(2013-Li-Diss\)](#)

[Rovibrational Spectral Fine Structure Of Icosahedral Molecules - Cpl 1986 \(Alt Scan\)](#)

[Gas Phase Level Structure of C60 Buckyball and Derivatives Exhibiting Broken Icosahedral Symmetry - reimer-diss-1996](#)

[Resonance and Revivals in Quantum Rotors - Comparing Half-integer Spin and Integer Spin - Alva-ISMS-Ohio2013-R777 \(Talk\)](#)

[Quantum Revivals of Morse Oscillators and Farey-Ford Geometry - Li-Harter-cpl-2013](#)

[Wave Node Dynamics and Revival Symmetry in Quantum Rotors - harter - jms - 2001](#)

**In development - a web based A.M.O.P. oriented reference page, with thumbnail/previews, greater control over the information display, and eventually full on Apache-SOLR Index and search for nuanced, whole-site content/metadata level searching. This bad boy will be a sure force multiplier.*

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

➔ Review: H -matrix Global vs Local symmetry

Molecular vibration K -matrix symmetry analogous to quantum H -matrix

Molecular K -matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K -matrix eigensolutions

D_3 -direct-connection K -matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K -matrix "Coriolis" eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

D_3 Hamiltonian *local*- \mathbf{H} matrices in $|\mathbf{P}^{(\mu)}\rangle$ -basis

\mathbf{H} matrix in $|\mathbf{g}\rangle$ -basis:

$$(\mathbf{H})_G = \sum_{g=1}^{\circ G} r_g \bar{\mathbf{g}} =$$

$$\begin{pmatrix} r_0 & r_2 & r_1 & i_1 & i_2 & i_3 \\ r_1 & r_0 & r_1 & i_3 & i_1 & i_2 \\ r_2 & r_1 & r_0 & i_2 & i_3 & i_1 \\ i_1 & i_3 & i_2 & r_0 & r_1 & r_2 \\ i_2 & i_1 & i_3 & r_2 & r_0 & r_1 \\ i_3 & i_2 & i_1 & r_1 & r_2 & r_0 \end{pmatrix}$$

\mathbf{H} matrix in $|\mathbf{P}^{(\mu)}\rangle$ -basis:

$$(\mathbf{H})_P = \bar{T} (\mathbf{H})_G \bar{T}^\dagger =$$

$$\begin{matrix} |\mathbf{P}_{xx}^{A_1}\rangle & |\mathbf{P}_{yy}^{A_2}\rangle & |\mathbf{P}_{xx}^{E_1}\rangle & |\mathbf{P}_{xy}^{E_1}\rangle & |\mathbf{P}_{yx}^{E_1}\rangle & |\mathbf{P}_{yy}^{E_1}\rangle \end{matrix}$$

$$\begin{pmatrix} H^{A_1} & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & H^{A_2} & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & H_{xx}^{E_1} & H_{xy}^{E_1} & \cdot & \cdot \\ \cdot & \cdot & H_{yx}^{E_1} & H_{yy}^{E_1} & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & H_{xx}^{E_1} & H_{xy}^{E_1} \\ \cdot & \cdot & \cdot & \cdot & H_{yx}^{E_1} & H_{yy}^{E_1} \end{pmatrix}$$

$$H_{ab}^\alpha = \langle \mathbf{P}_{ma}^\mu | \mathbf{H} | \mathbf{P}_{nb}^\mu \rangle = \frac{\langle \mathbf{1} | \mathbf{P}_{am}^\mu \mathbf{H} \mathbf{P}_{nb}^\mu | \mathbf{1} \rangle}{(norm)^2} = \langle \mathbf{1} | \mathbf{H} \mathbf{P}_{am}^\mu \mathbf{P}_{nb}^\mu | \mathbf{1} \rangle = \delta_{mn} \langle \mathbf{1} | \mathbf{H} \mathbf{P}_{ab}^\mu | \mathbf{1} \rangle = \sum_{g=1}^{\circ G} \langle \mathbf{1} | \mathbf{H} | \mathbf{g} \rangle D_{ab}^{\alpha*}(g) = \sum_{g=1}^{\circ G} r_g D_{ab}^{\alpha*}(g)$$

$$H^{A_1} = r_0 D^{A_1*}(1) + r_1 D^{A_1*}(r^1) + r_1^* D^{A_1*}(r^2) + i_1 D^{A_1*}(i_1) + i_2 D^{A_1*}(i_2) + i_3 D^{A_1*}(i_3) = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$= r_0 + 2r_1 + 2i_{12} + i_3$$

$$H^{A_2} = r_0 D^{A_2*}(1) + r_1 D^{A_2*}(r^1) + r_1^* D^{A_2*}(r^2) + i_1 D^{A_2*}(i_1) + i_2 D^{A_2*}(i_2) + i_3 D^{A_2*}(i_3) = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$= r_0 + 2r_1 - 2i_{12} - i_3$$

$$H_{xx}^{E_1} = r_0 D_{xx}^{E_1*}(1) + r_1 D_{xx}^{E_1*}(r^1) + r_1^* D_{xx}^{E_1*}(r^2) + i_1 D_{xx}^{E_1*}(i_1) + i_2 D_{xx}^{E_1*}(i_2) + i_3 D_{xx}^{E_1*}(i_3) = (2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3)/2$$

$$= r_0 - r_1 - i_{12} + i_3$$

$$H_{xy}^{E_1} = r_0 D_{xy}^{E_1*}(1) + r_1 D_{xy}^{E_1*}(r^1) + r_1^* D_{xy}^{E_1*}(r^2) + i_1 D_{xy}^{E_1*}(i_1) + i_2 D_{xy}^{E_1*}(i_2) + i_3 D_{xy}^{E_1*}(i_3) = \sqrt{3}(-r_1 + r_1^* - i_1 + i_2)/2 = H_{yx}^{E_1*} = 0$$

$$= 0$$

$$H_{yy}^{E_1} = r_0 D_{yy}^{E_1*}(1) + r_1 D_{yy}^{E_1*}(r^1) + r_1^* D_{yy}^{E_1*}(r^2) + i_1 D_{yy}^{E_1*}(i_1) + i_2 D_{yy}^{E_1*}(i_2) + i_3 D_{yy}^{E_1*}(i_3) = (2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3)/2$$

$$= r_0 - r_1 + i_{12} - i_3$$

$$C_2 = \{\mathbf{1}, \mathbf{i}_3\}$$

Local symmetry determines all levels and eigenvectors with just 4 real parameters

$$\begin{pmatrix} H_{xx}^{E_1} & H_{xy}^{E_1} \\ H_{yx}^{E_1} & H_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

$$= \begin{pmatrix} r_0 - r_1 - i_{12} + i_3 & 0 \\ 0 & r_0 - r_1 - i_{12} - i_3 \end{pmatrix}$$

Choosing local $C_2 = \{\mathbf{1}, \mathbf{i}_3\}$ symmetry with local constraints $r_1 = r_1^ = r_2$ and $i_1 = i_2$*

For: $r_1 = r_1^$ and $i_1 = i_2$*

Global (LAB) symmetry

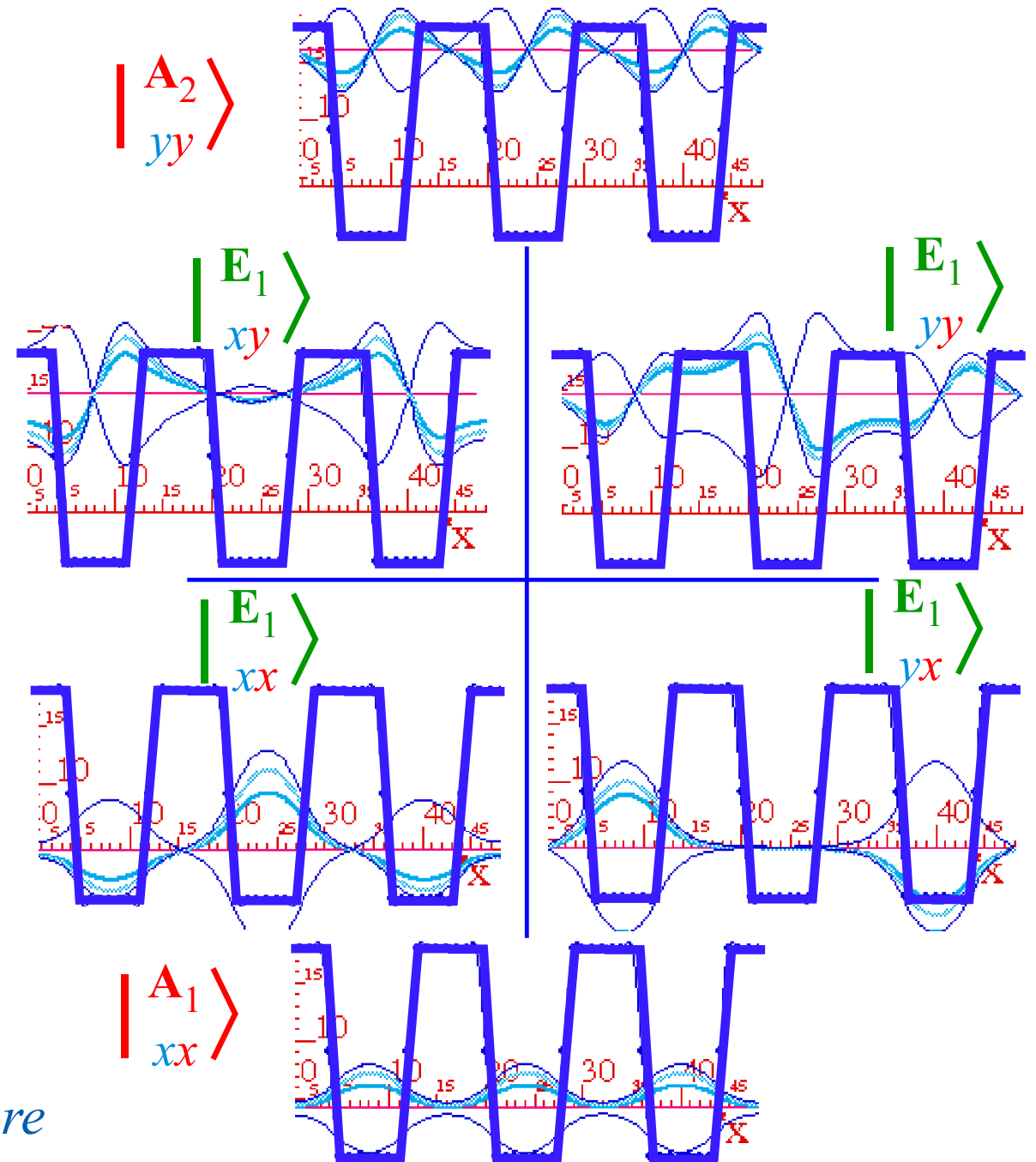
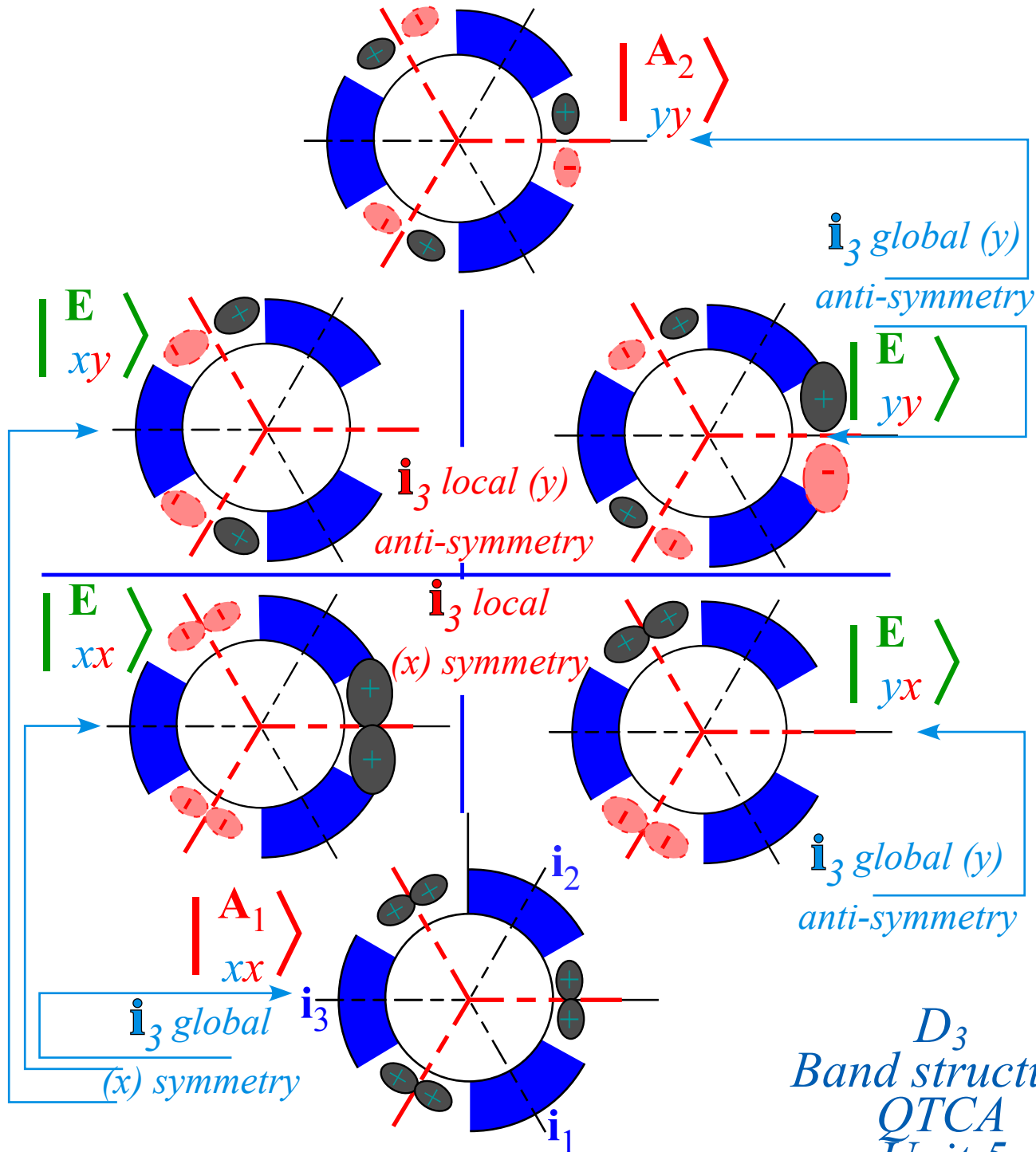
$D_3 > C_2 i_3$ projector states

Local (BOD) symmetry

$$\mathbf{i}_3 |_{eb}^{(m)} \rangle = \mathbf{i}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = (-1)^e |^{(m)} \rangle$$

$$|_{eb}^{(m)} \rangle = \mathbf{P}_{eb}^{(m)} |1\rangle$$

$$\bar{\mathbf{i}}_3 |_{eb}^{(m)} \rangle = \bar{\mathbf{i}}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = \mathbf{P}_{eb}^{(m)} \bar{\mathbf{i}}_3 |1\rangle = \mathbf{P}_{eb}^{(m)} \mathbf{i}_3^\dagger |1\rangle = (-1)^b |^{(m)} \rangle$$



2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: H -matrix Global vs Local symmetry

 Molecular vibration K -matrix symmetry analogous to quantum H -matrix

Molecular K -matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K -matrix eigensolutions

D_3 -direct-connection K -matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K -matrix "Coriolis" eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Molecular vibration K-matrix analogy with quantum H-matrix

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ [Int. Journal of Molec. Sci. \(2013\) page 798-804 pdf page85](#)

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

Squared time generator $(i\hbar\partial_t=\mathbf{H})^2$ has classical form with $K=H^2$ and $M=\hbar^2$.

$$-\hbar^2\partial_t^2\psi^a = \sum_b K_{ab}\psi^b \text{ where: } K = H^2$$

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ [Int. Journal of Molec. Sci. \(2013\) page 798-804 pdf page86](#)

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

Squared time generator $(i\hbar\partial_t=\mathbf{H})^2$ has classical form with $K=H^2$ and $M=\hbar^2$.

$$-\hbar^2\partial_t^2\psi^a = \sum_b K_{ab}\psi^b \text{ where: } K = H^2$$

(\mathbf{H}/\hbar) -eigenvalues are quantum angular frequencies $\epsilon_m/\hbar=\omega_m$. (Like Planck axiom: $\epsilon=\hbar\omega$.)

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ [Int. Journal of Molec. Sci. \(2013\) page 798-804 pdf page86](#)

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

Squared time generator $(i\hbar\partial_t=\mathbf{H})^2$ has classical form with $K=H^2$ and $M=\hbar^2$.

$$-\hbar^2\partial_t^2\psi^a = \sum_b K_{ab}\psi^b \text{ where: } K = H^2$$

(\mathbf{H}/\hbar) -eigenvalues are quantum angular frequencies $\epsilon_m/\hbar=\omega_m$. (Like Planck axiom: $\epsilon=\hbar\omega$.)

(\mathbf{K}/M) -eigenvalues are classical *squared* frequencies $k_m/M=\omega_m^2$. (Like Hooke's law: $k/M=\omega^2$.)

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ Int. Journal of Molec. Sci. (2013) page 798-804 [pdf page86](#)

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

Squared time generator $(i\hbar\partial_t=\mathbf{H})^2$ has classical form with $K=H^2$ and $M=\hbar^2$.

$$-\hbar^2\partial_t^2\psi^a = \sum_b K_{ab}\psi^b \text{ where: } K = H^2$$

(\mathbf{H}/\hbar) -eigenvalues are quantum angular frequencies $\epsilon_m/\hbar=\omega_m$. (Like Planck axiom: $\epsilon=\hbar\omega$.)
 (\mathbf{K}/M) -eigenvalues are classical *squared* frequencies $k_m/M=\omega_m^2$. (Like Hooke's law: $k/M=\omega^2$.)

Apart from normalization, *eigenvectors* of \mathbf{H} and \mathbf{K} are the same.

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ Int. Journal of Molec. Sci. (2013) page 798-804 [pdf page86](#)

Molecular vibrational modes vs. Hamiltonian eigenmodes

Classical equations of coupled harmonic motion are Newtonian $\mathbf{F}=\mathbf{M}\cdot\mathbf{a}$ relations of n -dimensional force vector \mathbf{F} , acceleration vector \mathbf{a} , and mass operator $\mathbf{M}=M\cdot\mathbf{1}$ for D_3 -symmetry. Force \mathbf{F} is a (-)derivative of potential $V(x)$ that becomes a $\mathbf{F}=-\mathbf{K}\cdot\mathbf{x}$ matrix expression.

$$-M\partial_t^2 x^a = \frac{\partial V}{\partial x^a} = \sum_b K_{ab}x^b$$

Compare classical equation to Schrodinger's equation for quantum motion. † ‡

$$i\hbar\partial_t\psi^a = \sum_b H_{ab}\psi^b$$

Squared time generator $(i\hbar\partial_t=\mathbf{H})^2$ has classical form with $K=H^2$ and $M=\hbar^2$.

$$-\hbar^2\partial_t^2\psi^a = \sum_b K_{ab}\psi^b \text{ where: } K = H^2$$

(\mathbf{H}/\hbar) -eigenvalues are quantum angular frequencies $\epsilon_m/\hbar=\omega_m$. (Like Planck axiom: $\epsilon=\hbar\omega$.)

(\mathbf{K}/M) -eigenvalues are classical *squared* frequencies $k_m/M=\omega_m^2$. (Like Hooke's law: $k/M=\omega^2$.)

Apart from normalization, *eigenvectors* of \mathbf{H} and \mathbf{K} are the same.

And, each *eigenvalue* set corresponds to its respective energy spectrum.

† Recall $U(2)$ vs $R(3)$ Schrodinger vs Classical analogs in Lect. 4 p14

‡ Int. Journal of Molec. Sci. (2013) page 798-804 [pdf page86](#)

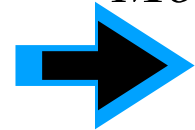
3.02.18 class 14.0: *Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics*

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix



Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

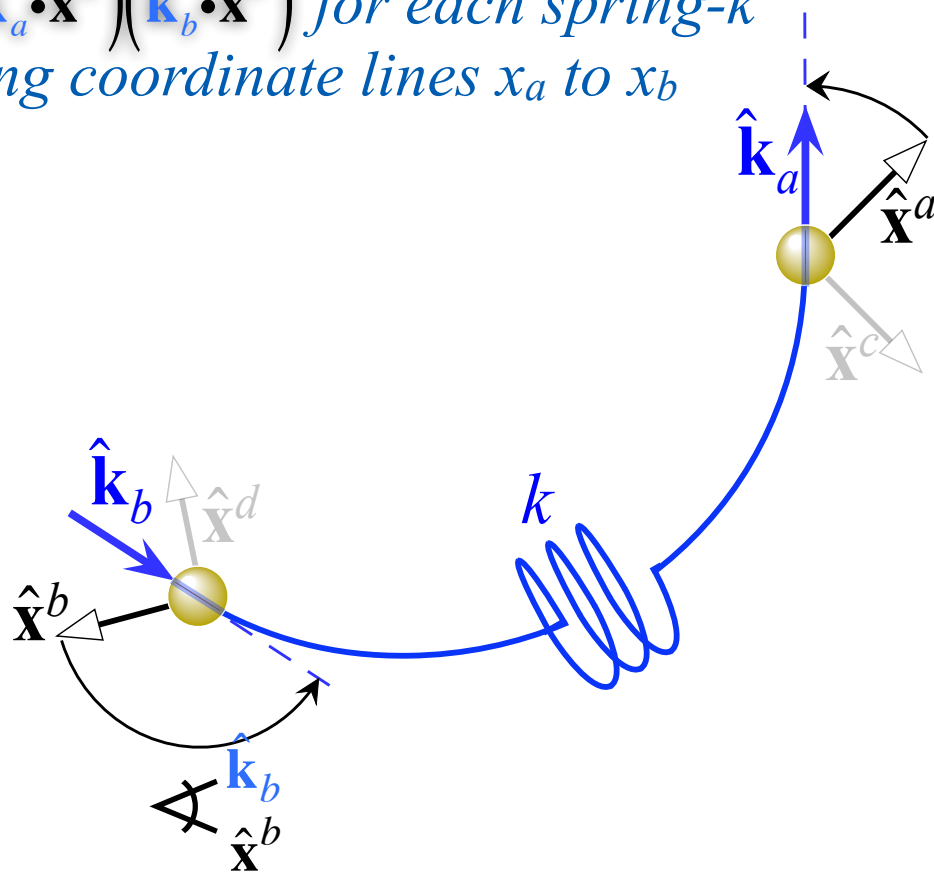
Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

Coupling $K_{ab} = \langle a | \mathbf{K} | b \rangle$

Sum $k \cdot (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a) (\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for each spring- k connecting coordinate lines x_a to x_b



Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

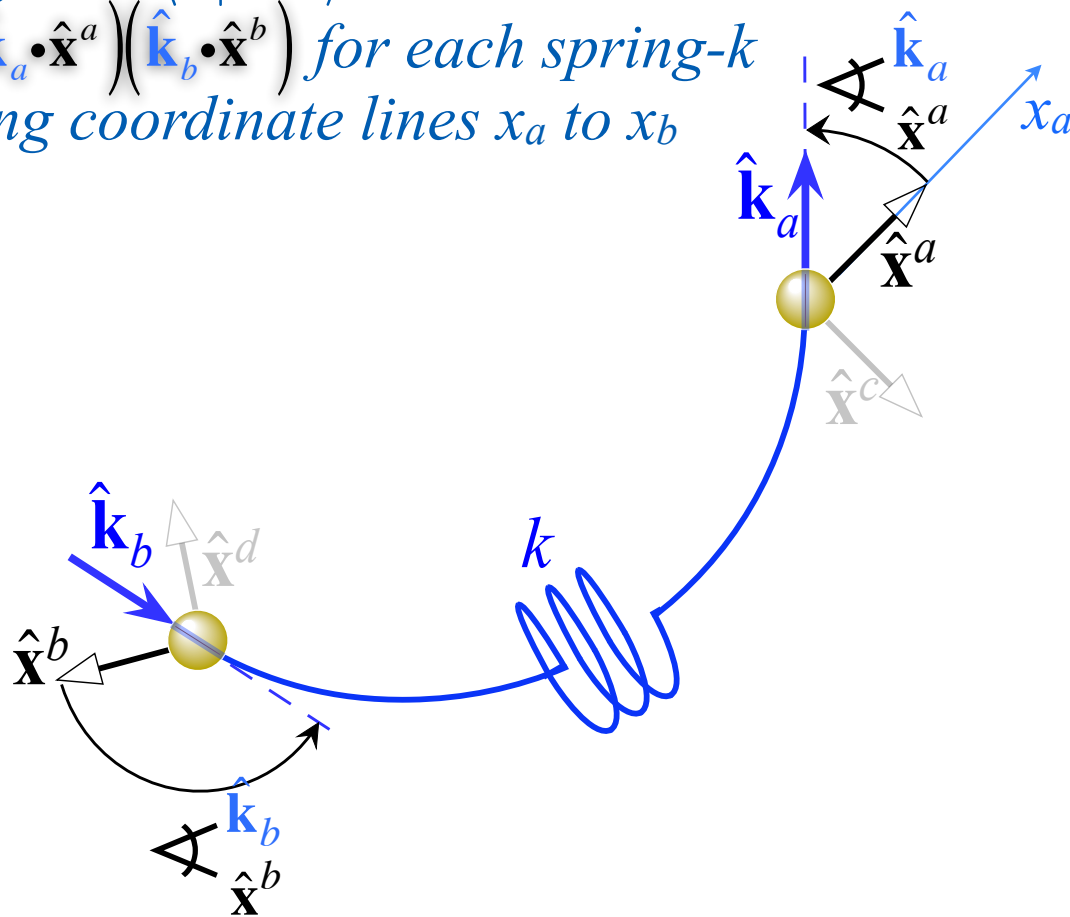
Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

Coupling $K_{ab} = \langle a | \mathbf{K} | b \rangle$

Sum $k \cdot (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for each spring- k connecting coordinate lines x_a to x_b

Diagonal $K_{aa} = \langle a | \mathbf{K} | a \rangle$

Sum $-\frac{1}{2}k \cdot (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)^2$ for each spring- k connected to coordinate line x_a



Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

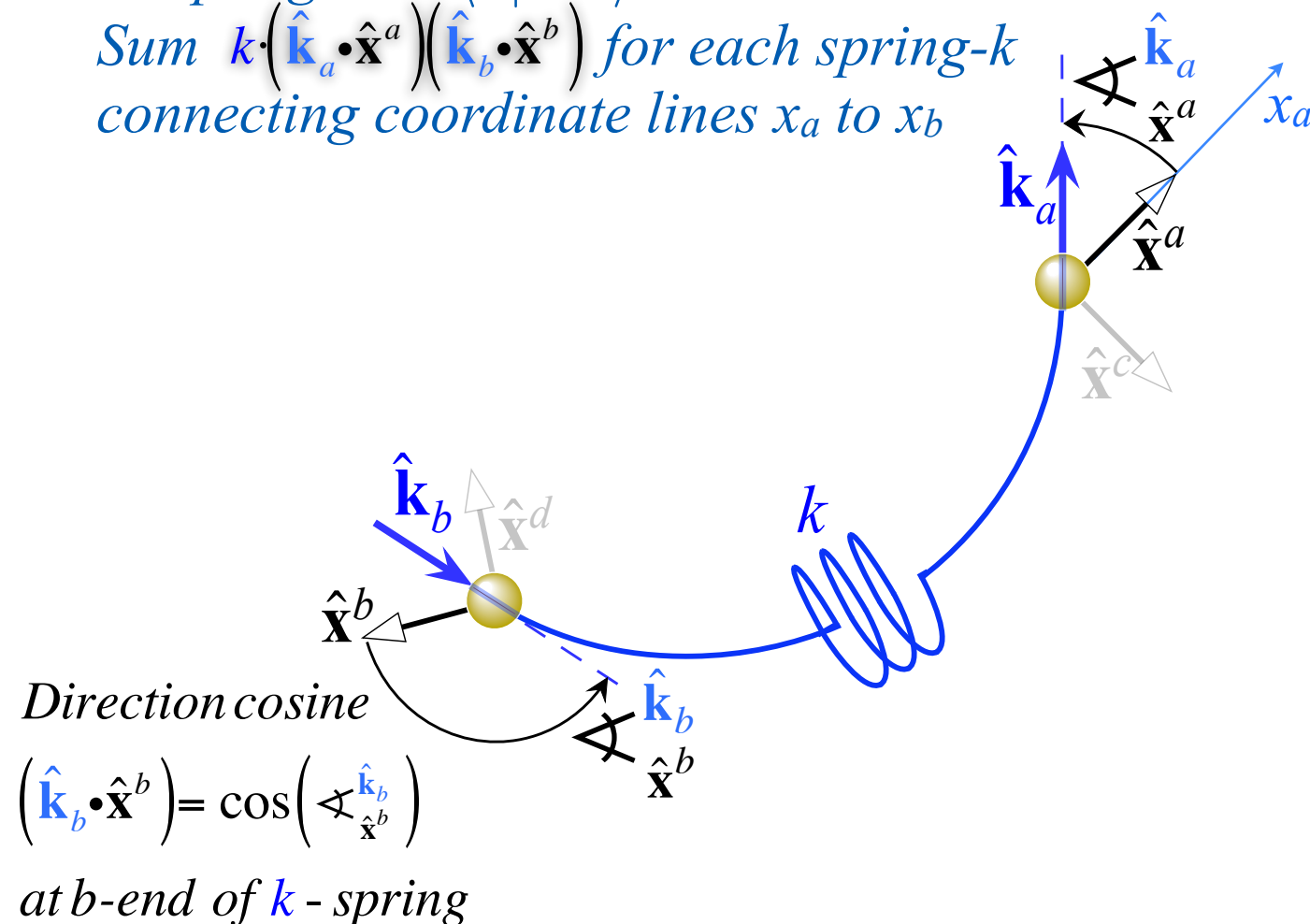
Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

Coupling $K_{ab} = \langle a | \mathbf{K} | b \rangle$

Sum $k \cdot (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for each spring- k connecting coordinate lines x_a to x_b

Diagonal $K_{aa} = \langle a | \mathbf{K} | a \rangle$

Sum $-\frac{1}{2}k \cdot (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)^2$ for each spring- k connected to coordinate line x_a



Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

$$V(x) = \frac{1}{2} \sum_{a,b} K_{ab} x_a x_b \quad \text{where: } K_{ab} = \begin{cases} \sum_{(k)} \frac{k}{2} (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)^2 & \text{if } : a = b \\ - \sum_{(k)} k (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b) & \text{if } : a \neq b \end{cases}$$

Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

$$V(x) = \frac{1}{2} \sum_{a,b} K_{ab} x_a x_b \quad \text{where: } K_{ab} = \begin{cases} \sum_{(k)} \frac{k}{2} (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)^2 & \text{if } : a = b \\ - \sum_{(k)} k (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b) & \text{if } : a \neq b \end{cases}$$

$$\begin{aligned} V(x) &= \sum_{(k)} \frac{k}{2} (\Delta \ell_k)^2 = \sum_{(k)} \frac{k}{2} \sum_{a,b} (\hat{\mathbf{k}}_a \bullet \mathbf{x}^a - \hat{\mathbf{k}}_b \bullet \mathbf{x}^b)^2 \\ &= \sum_{(k)} \frac{k}{2} \sum_a (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)^2 x_a^2 - \sum_{(k)} k \sum_{a \neq b} (\hat{\mathbf{k}}_a \bullet \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \bullet \hat{\mathbf{x}}^b) x_a x_b \end{aligned}$$

Molecular K -matrix construction

Classical modes are eigenvectors of force-field matrix K or operator \mathbf{K} .

Harmonic potential $V(\mathbf{x})$ is a quadratic K -form of coordinates x_a based on six D_3 -labeled axes $\hat{\mathbf{x}}^a$ or $|a\rangle$.

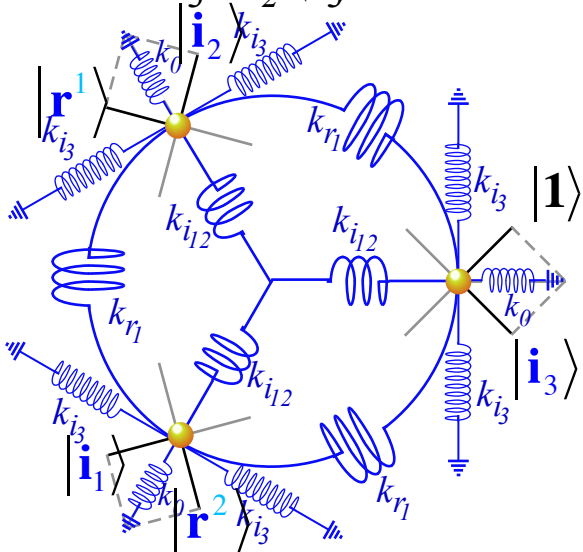
$$V(x) = \sum_{(k)} \frac{1}{2} \langle x | \mathbf{K} | x \rangle \quad \text{where: } |x\rangle = \sum_a x_a |a\rangle, \quad (a, b) = (1, r^1, r^2, i_1, i_2, i_3)$$

Each \mathbf{K} component $K_{ab} = \langle a | \mathbf{K} | b \rangle$ is a sum over spring k -constants that connect axis- \mathbf{x}^a to axis- \mathbf{x}^b multiplied by factor $(\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b)$ for projecting spring- k 's end vectors $\hat{\mathbf{k}}_a$ and $\hat{\mathbf{k}}_b$ onto $\hat{\mathbf{x}}^a$ and $\hat{\mathbf{x}}^b$ at respective connections.

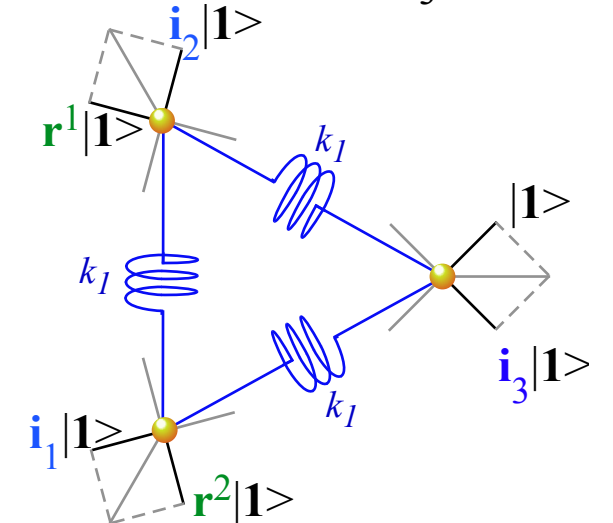
$$V(x) = \frac{1}{2} \sum_{a,b} K_{ab} x_a x_b \quad \text{where: } K_{ab} = \begin{cases} \sum_{(k)} \frac{k}{2} (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)^2 & \text{if } : a = b \\ - \sum_{(k)} k (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b) & \text{if } : a \neq b \end{cases}$$

$$\begin{aligned} V(x) &= \sum_{(k)} \frac{k}{2} (\Delta \ell_k)^2 = \sum_{(k)} \frac{k}{2} \sum_{a,b} (\hat{\mathbf{k}}_a \cdot \mathbf{x}^a - \hat{\mathbf{k}}_b \cdot \mathbf{x}^b)^2 \\ &= \sum_{(k)} \frac{k}{2} \sum_a (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)^2 x_a^2 - \sum_{(k)} k \sum_{a \neq b} (\hat{\mathbf{k}}_a \cdot \hat{\mathbf{x}}^a)(\hat{\mathbf{k}}_b \cdot \hat{\mathbf{x}}^b) x_a x_b \end{aligned}$$

Local D_3 $C_{2v}(i_3)$ model



Direct connection D_3 model



2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: H -matrix Global vs Local symmetry

Molecular vibration K -matrix symmetry analogous to quantum H -matrix

Molecular K -matrix construction

➔ $D_3 \supset C_2(i_3)$ local-symmetry K -matrix eigensolutions

D_3 -direct-connection K -matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K -matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix eigensolutions *Local $D_3 \supset C_2(i_3)$ model*

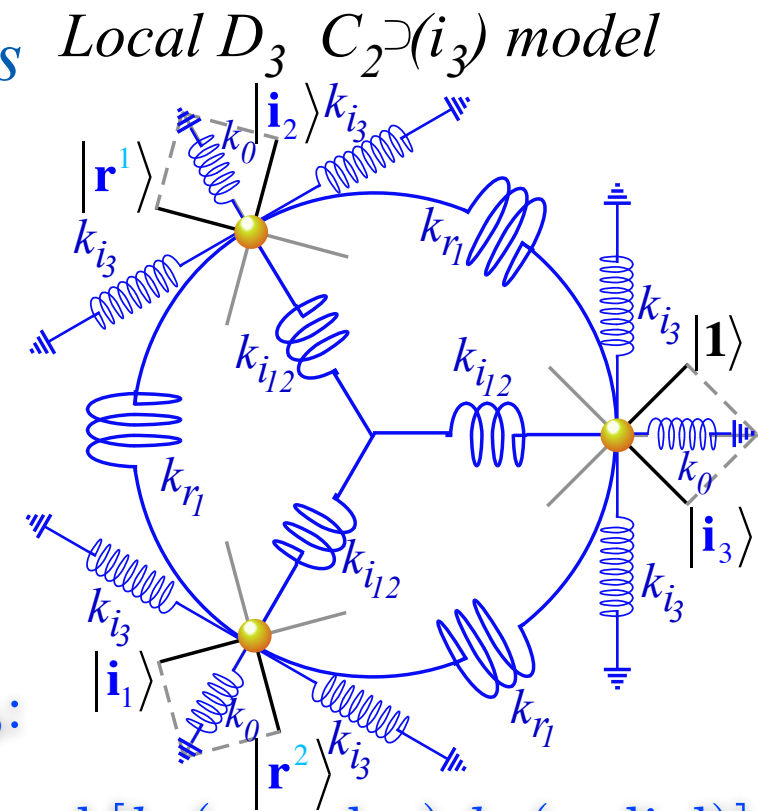
Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix

1st-row parameters $g_b = \langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = K_{1b}$ of the force matrix K_{ab} :

$D_3 \supset C_2(i_3)$ model has internal [k_r (angular), k_i (radial)] and external [k_3 (angular), k_0 (radial)] constants between masses and lab frame.

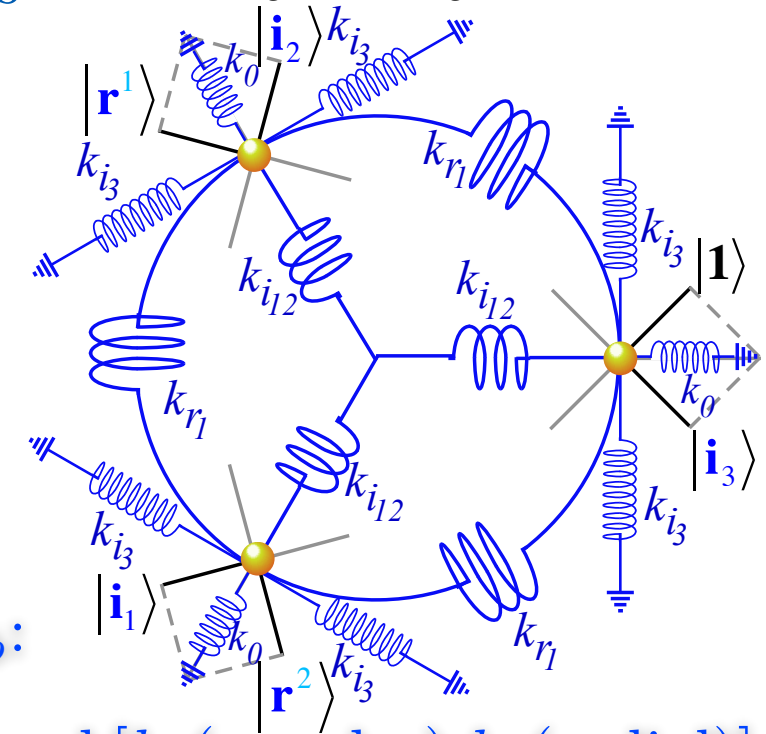


$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix eigensolutions

Local $D_3 \supset C_2(i_3)$ model

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$



$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix

1st-row parameters $g_b = \langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = K_{1b}$ of the force matrix K_{ab} :

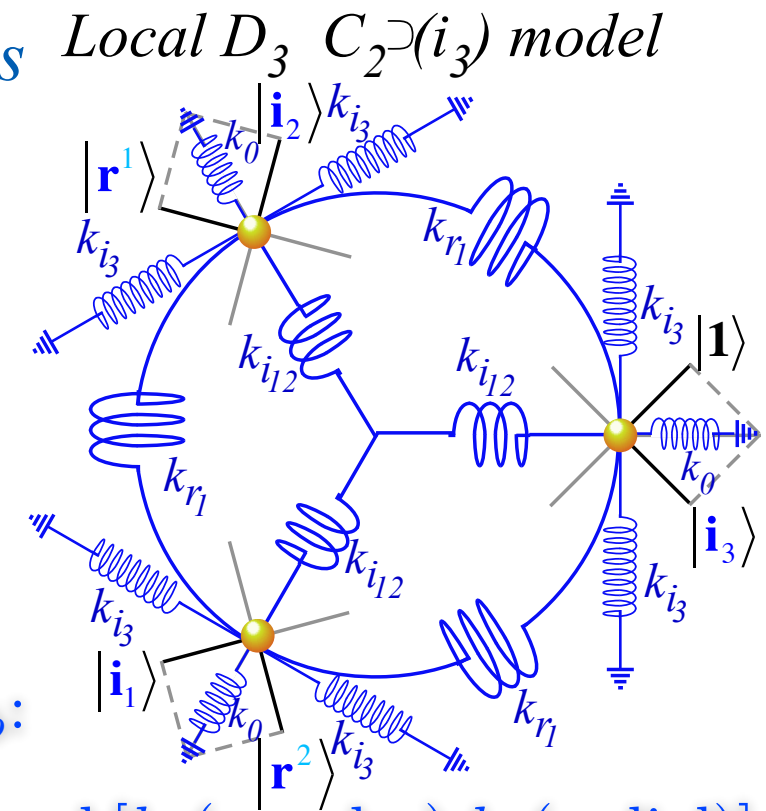
$D_3 \supset C_2(i_3)$ model has internal [k_r (angular), k_i (radial)] and external [k_3 (angular), k_0 (radial)] constants between masses and lab frame.

$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_i/2$	$k_i/2$	$k_i/2$	$k_i/2$	$k_i/2$	$k_i/2$
	$+k_r$	$-k_r/2$	$-k_r/2$	$+k_r/2$	$+k_r/2$	$-k_r$
	$+k_3$	$+0$	$+0$	$+0$	$+0$	$-k_3$
	$+k_0/2$	$+0$	$+0$	$+0$	$+0$	$+k_0/2$

$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix eigensolutions Local $D_3 \supset C_2(i_3)$ model

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$



$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix

1st-row parameters $g_b = \langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = K_{1b}$ of the force matrix K_{ab} :

$D_3 \supset C_2(i_3)$ model has internal [k_r (angular), k_i (radial)] and external [k_3 (angular), k_0 (radial)] constants between masses and lab frame.

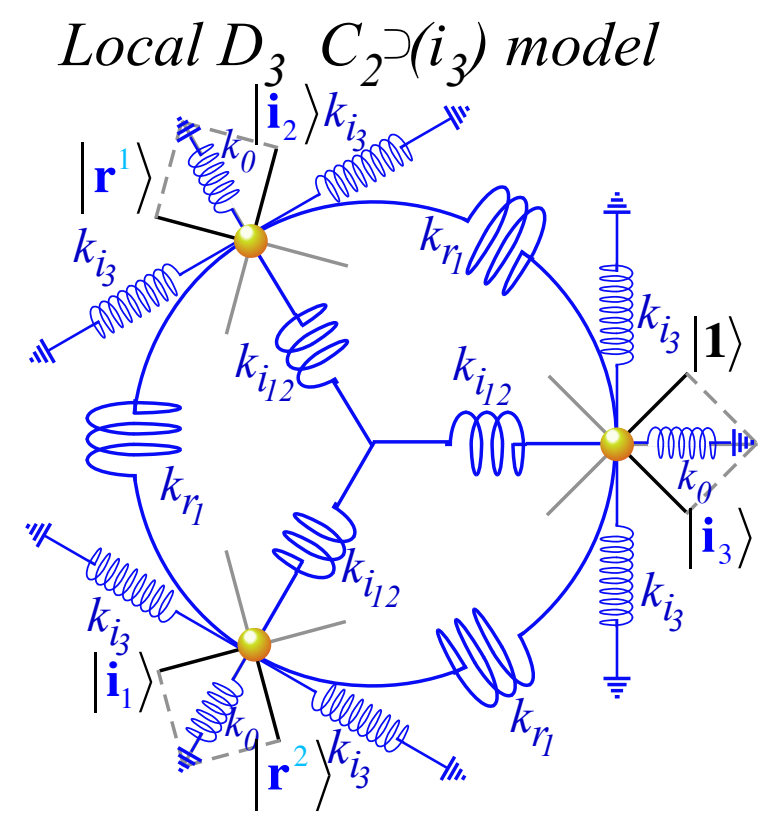
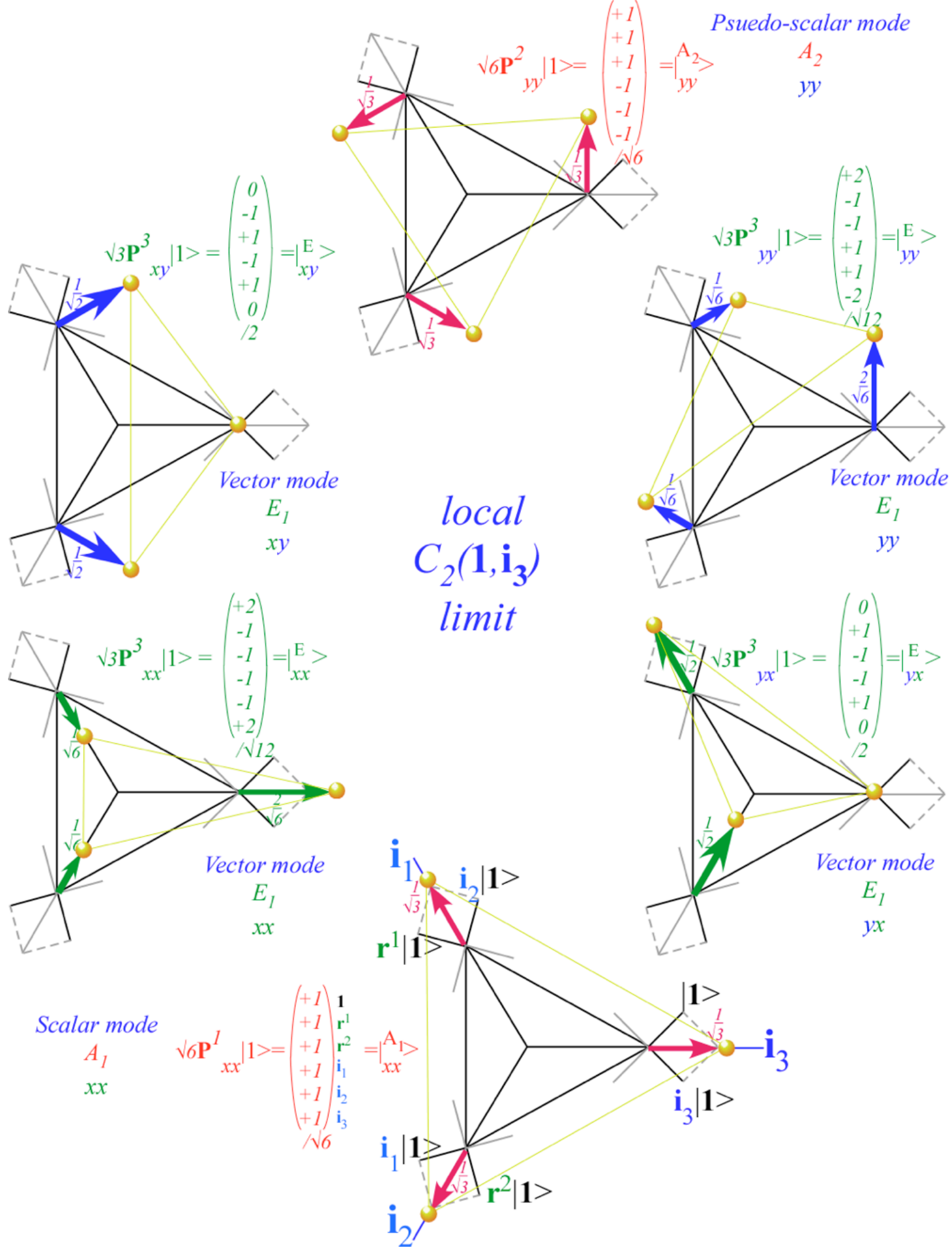
$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_i/2$ $+k_r$ $+k_3$ $+k_0/2$	$k_i/2$ $-k_r/2$ $+0$ $+0$	$k_i/2$ $-k_r/2$ $+0$ $+0$	$k_i/2$ $+k_r/2$ $+0$ $+0$	$k_i/2$ $+k_r/2$ $+0$ $+0$	$k_i/2$ $-k_r$ $-k_3$ $+k_0/2$

$D_3 \supset C_2(i_3)$ local-symmetry vibrational K -matrix eigenvalues $K_m/M = \omega_m^2$

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3 = k_0 + 3k_i$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3 = 3k_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix} = \begin{pmatrix} k_0 & 0 \\ 0 & k_3 + 2k_r \end{pmatrix}$$



*Classical D_3 K-eigen-modes
 analogous to
 Quantum H-eigenwaves on
 following page*

K-matrix symmetry analogous to quantum H-matrix

Global (LAB) symmetry

$D_3 > C_2$ i_3 projector states

Local (BOD) symmetry

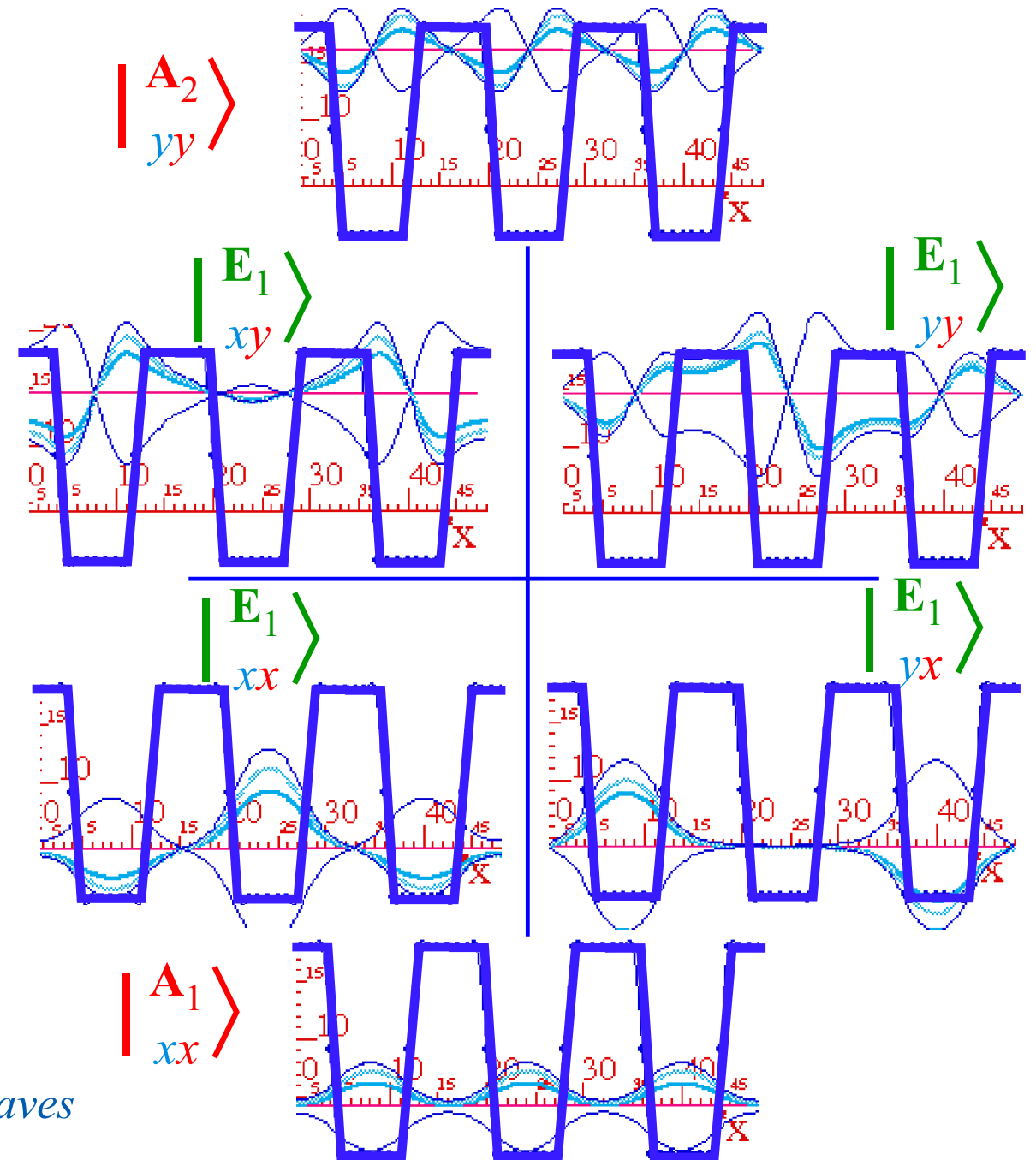
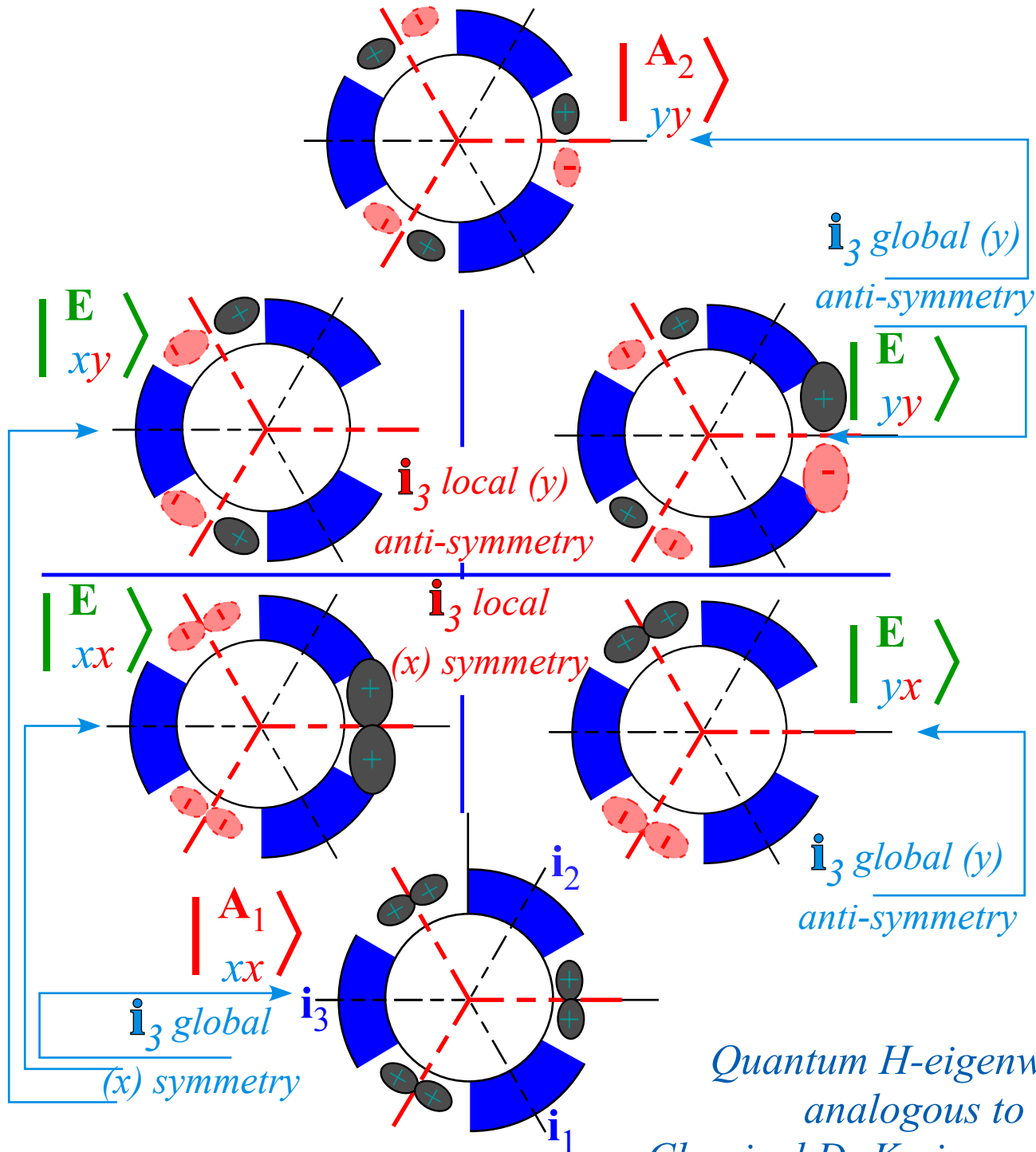
$$\mathbf{i}_3 |_{eb}^{(m)} \rangle = \mathbf{i}_3 \mathbf{P}_{eb}^{(m)} |1\rangle$$

$$= (-1)^e |^{(m)} \rangle$$

$$|_{eb}^{(m)} \rangle = \mathbf{P}_{eb}^{(m)} |1\rangle$$

$$\bar{\mathbf{i}}_3 |_{eb}^{(m)} \rangle = \bar{\mathbf{i}}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = \mathbf{P}_{eb}^{(m)} \bar{\mathbf{i}}_3 |1\rangle$$

$$= \mathbf{P}_{eb}^{(m)} \mathbf{i}_3^\dagger |1\rangle = (-1)^b |^{(m)} \rangle$$



Quantum H-eigenwaves
analogous to
Classical D_3 K-eigen-modes on
preceding page

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

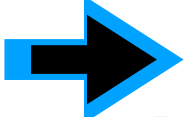
Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

 *D_3 -direct-connection K-matrix eigenstates mix local symmetry*

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

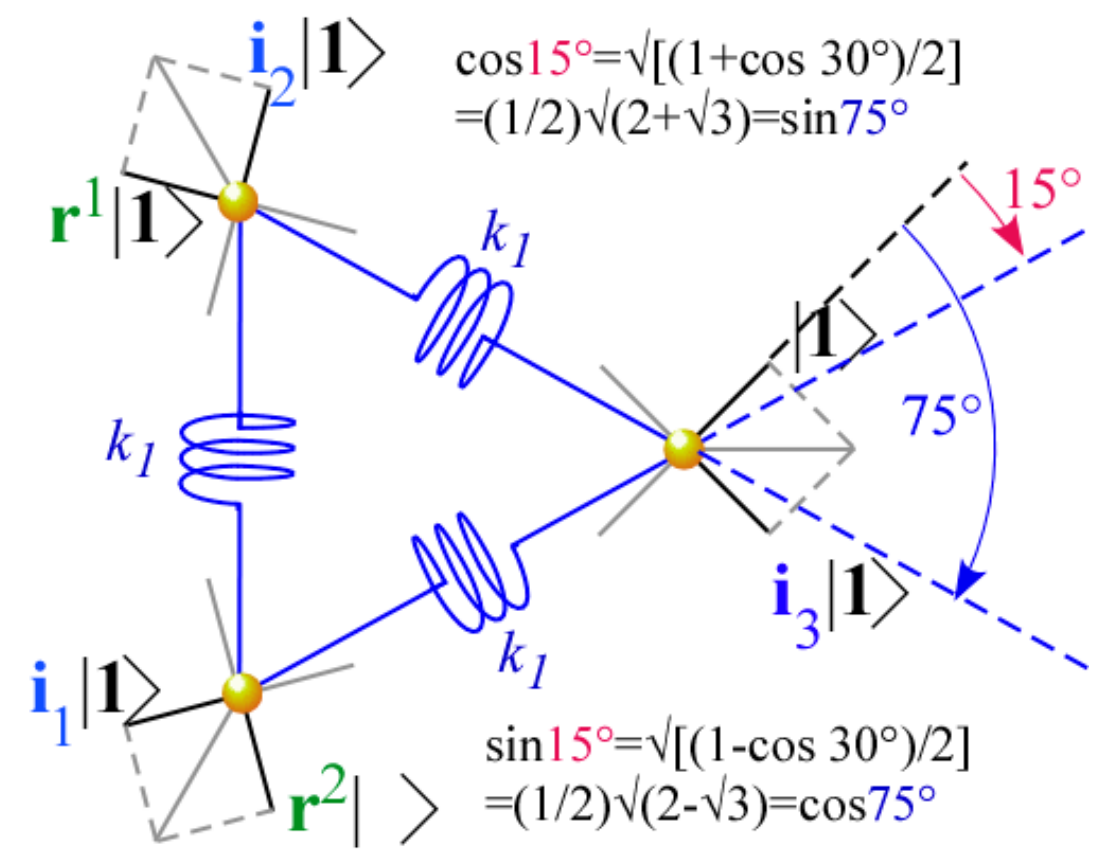
$U(12)$ -Supersymmetry

D_3 -direct-connection K -matrix eigensolutions

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

D_3 -direct-connection vibrational K -matrix



D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

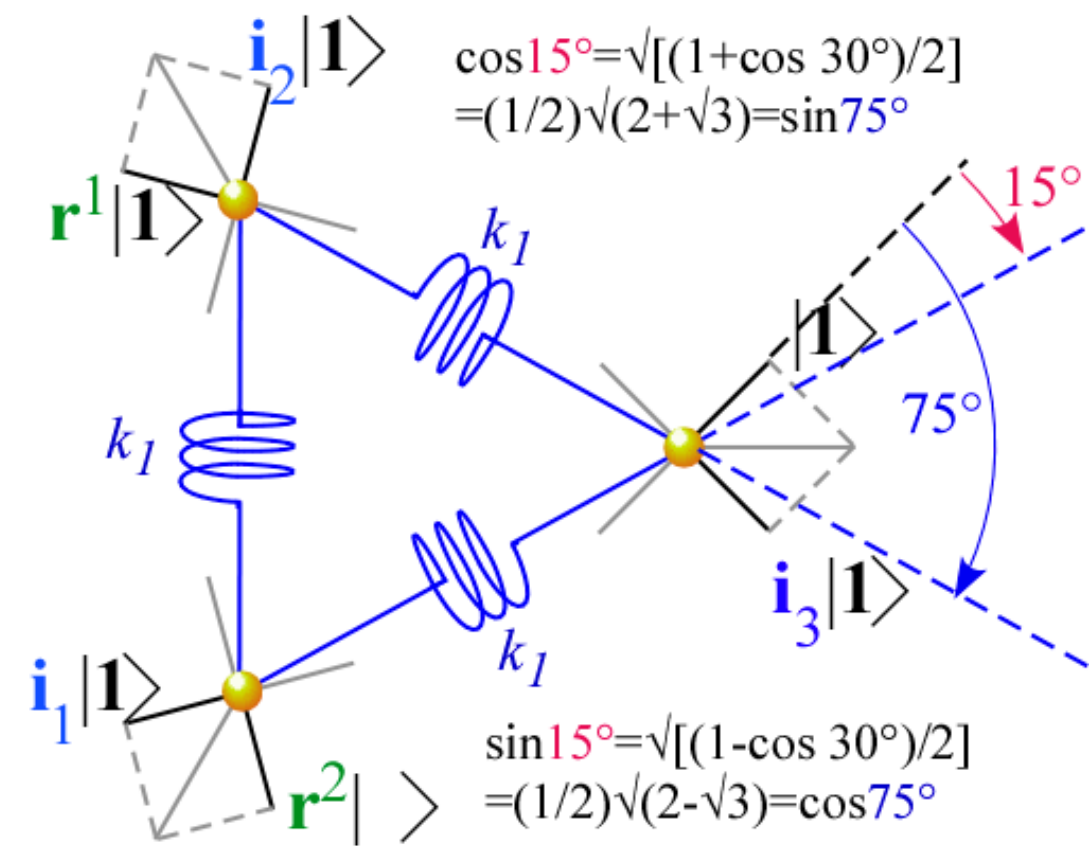
Generic K -matrix D_3 projections

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix



D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

Generic K -matrix D_3 projections

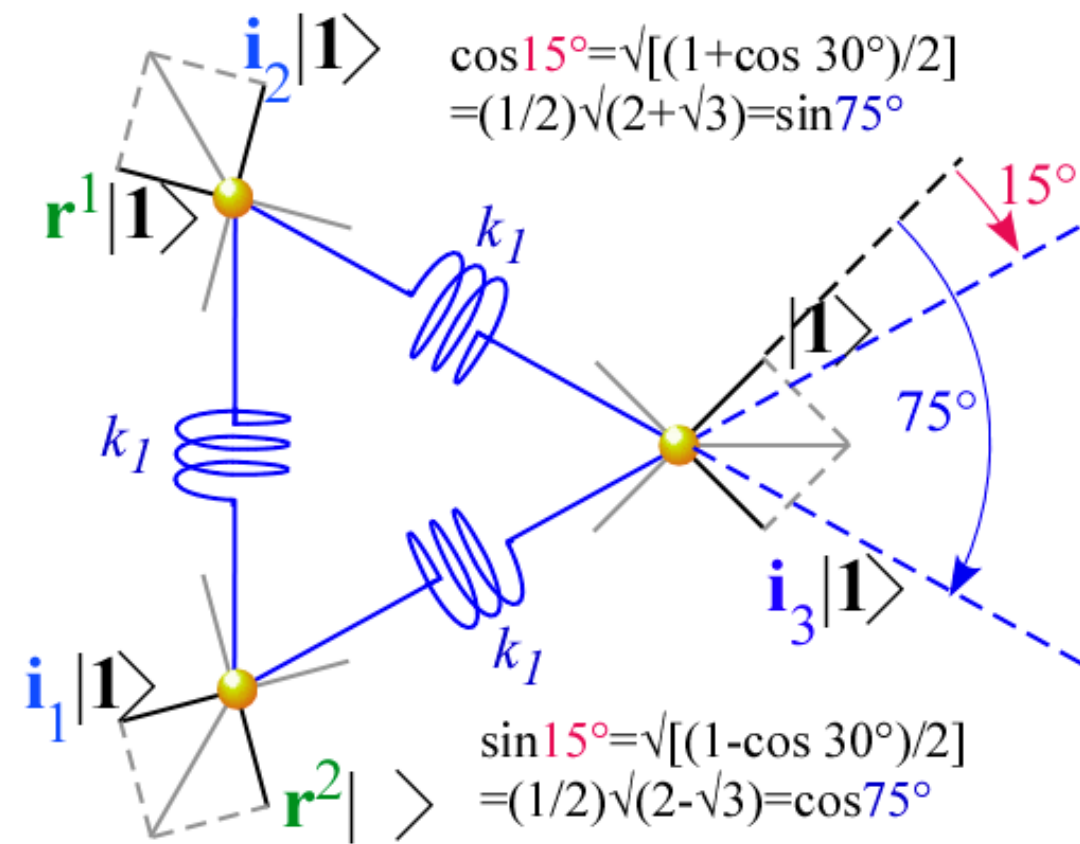
$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix

$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_1(\cos^2 75^\circ + \cos^2 15^\circ) = k_1$	$k_1 \cos 75^\circ \cdot \cos 15^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 75^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 15^\circ = \frac{k_1(2 - \sqrt{3})}{4}$	$k_1 \cos 75^\circ \cdot \cos 75^\circ = \frac{k_1(2 + \sqrt{3})}{4}$	$k_1(\cos^2 75^\circ - \cos^2 15^\circ) = \frac{k_1}{2}$



D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

Generic K -matrix D_3 projections

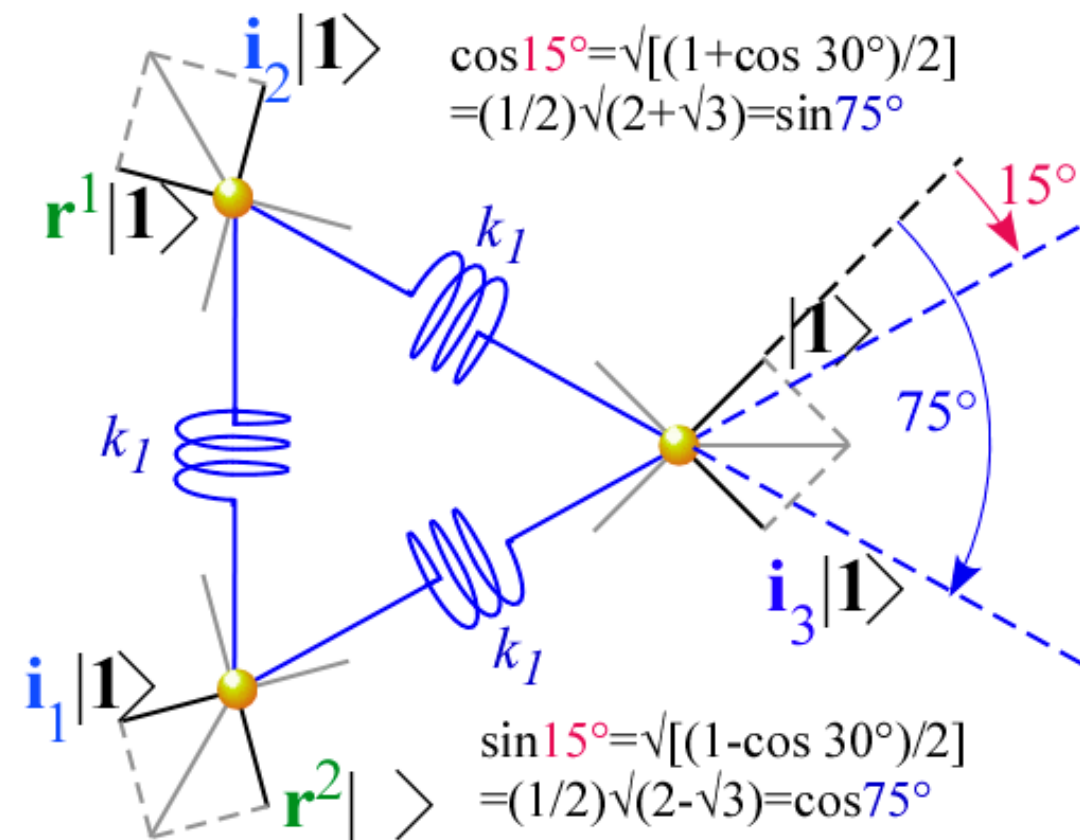
$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix

$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_1(\cos^2 75^\circ + \cos^2 15^\circ) = k_1$	$k_1 \cos 75^\circ \cdot \cos 15^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 75^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 15^\circ = \frac{k_1(2 - \sqrt{3})}{4}$	$k_1 \cos 75^\circ \cdot \cos 75^\circ = \frac{k_1(2 + \sqrt{3})}{4}$	$k_1(\cos^2 75^\circ - \cos^2 15^\circ) = \frac{k_1}{2}$



$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3 = k_1 + \frac{k_1}{4} + \frac{k_1}{4} + \frac{k_1}{2} + \frac{k_1}{2} + \frac{k_1}{2} = \frac{3k_1}{2} + \frac{3k_1}{2} = 3k_1$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3 = k_1 + \frac{k_1}{4} + \frac{k_1}{4} - \frac{k_1}{2} - \frac{k_1}{2} - \frac{k_1}{2} = \frac{3k_1}{2} - \frac{3k_1}{2} = 0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

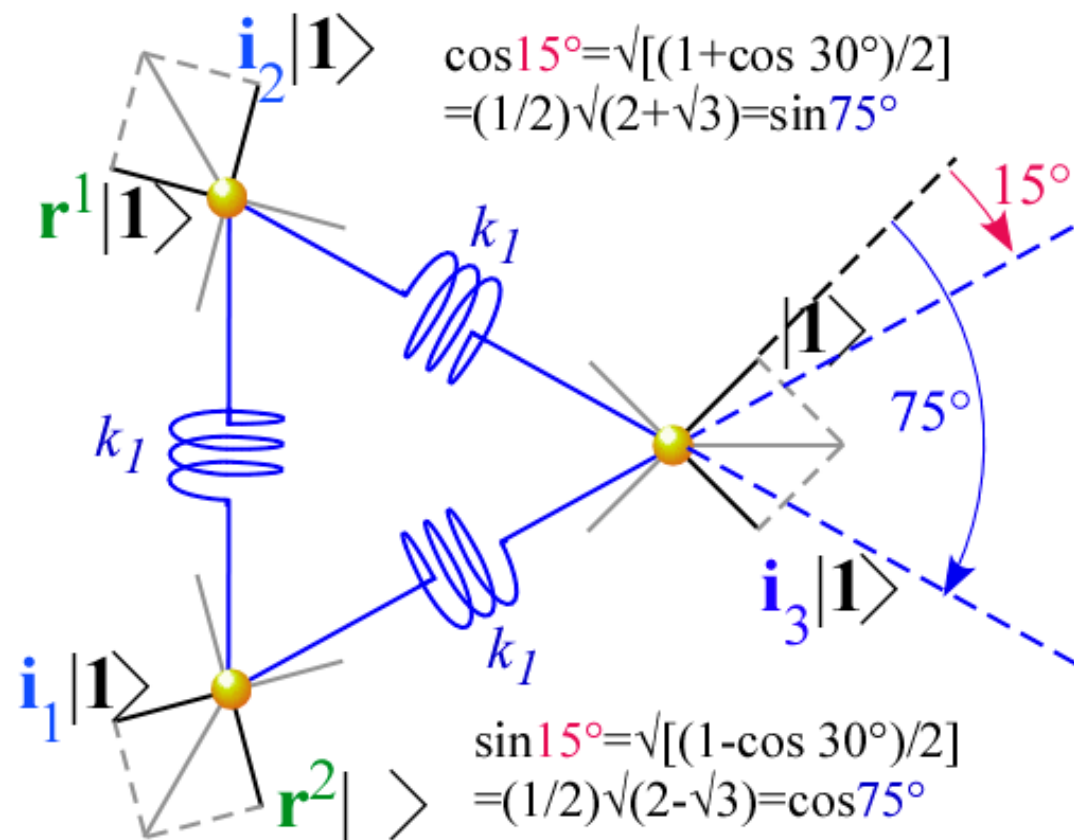
Generic K -matrix D_3 projections

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix



$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_1 (\cos^2 75^\circ + \cos^2 15^\circ) = k_1$	$k_1 \cos 75^\circ \cdot \cos 15^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 75^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 15^\circ = \frac{k_1(2 - \sqrt{3})}{4}$	$k_1 \cos 75^\circ \cdot \cos 75^\circ = \frac{k_1(2 + \sqrt{3})}{4}$	$k_1 (\cos^2 75^\circ - \cos^2 15^\circ) = \frac{k_1}{2}$

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$= k_1 + \frac{k_1}{4} + \frac{k_1}{4} + \frac{k_1}{2} + \frac{k_1}{2} + \frac{k_1}{2} = \frac{3k_1}{2} + \frac{3k_1}{2} = 3k_1$$

$$= k_1 + \frac{k_1}{4} + \frac{k_1}{4} - \frac{k_1}{2} - \frac{k_1}{2} - \frac{k_1}{2} = \frac{3k_1}{2} - \frac{3k_1}{2} = 0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

$$\left(\begin{array}{l} \frac{1}{2} \left(2k_1 - \frac{k_1}{4} - \frac{k_1}{4} - \frac{k_1}{2} - \frac{k_1}{2} + 2 \frac{k_1}{2} \right) = \frac{1}{2} \left(2k_1 - \frac{k_1}{2} - k_1 + k_1 \right) = \frac{3k_1}{4} \\ \frac{\sqrt{3}}{2} \left(-\frac{k_1}{4} + \frac{k_1}{4} + \frac{k_1 \sqrt{3}}{4} + \frac{k_1 \sqrt{3}}{4} \right) = \frac{k_1 3}{4} \\ \frac{1}{2} \left(2k_1 - \frac{k_1}{4} - \frac{k_1}{4} + \frac{k_1}{2} + \frac{k_1}{2} - 2 \frac{k_1}{2} \right) = \frac{3k_1}{4} \end{array} \right) \text{ (symmetric)}$$

D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

Generic K -matrix D_3 projections

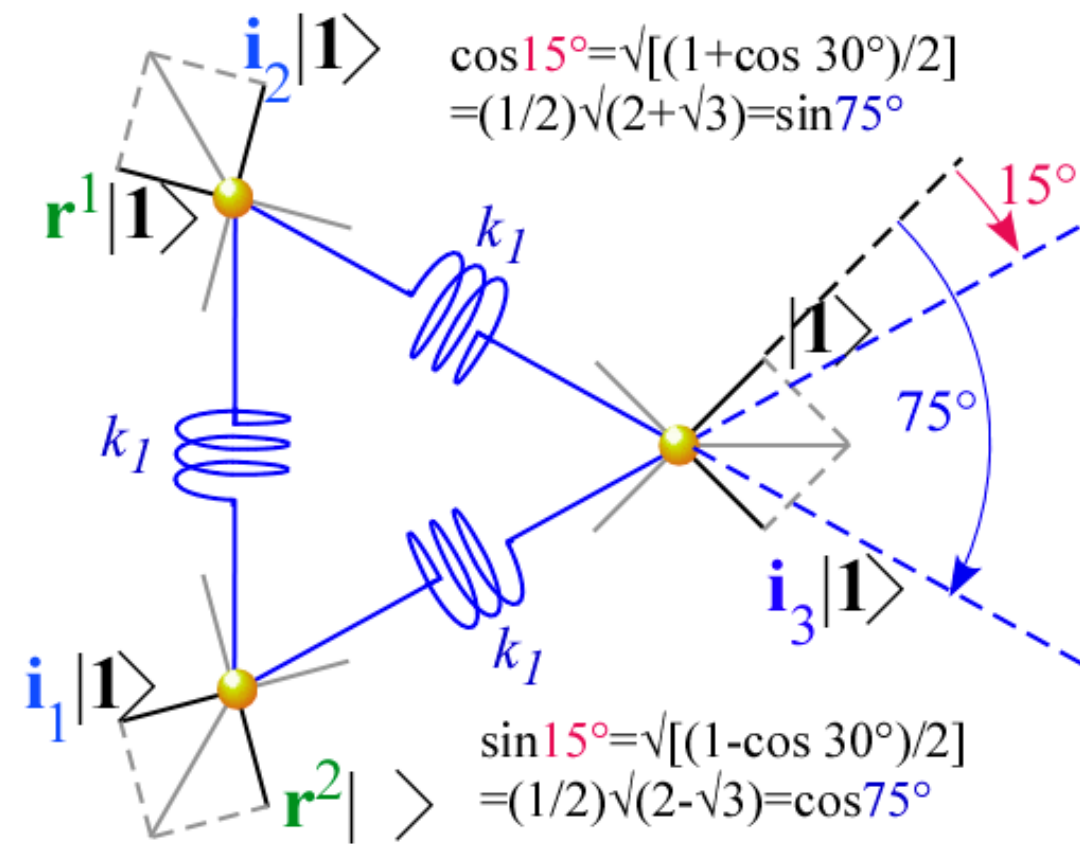
$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix

$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_1(\cos^2 75^\circ + \cos^2 15^\circ) = k_1$	$k_1 \cos 75^\circ \cdot \cos 15^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 75^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 15^\circ = \frac{k_1(2 - \sqrt{3})}{4}$	$k_1 \cos 75^\circ \cdot \cos 75^\circ = \frac{k_1(2 + \sqrt{3})}{4}$	$k_1(\cos^2 75^\circ - \cos^2 15^\circ) = \frac{k_1}{2}$



D_3 -direct-connection vibrational K -matrix eigenvalues $K_m/M = \omega_m^2$

$$K_{xx}^{A_1} = 3k_1$$

$$K_{yy}^{A_2} = 0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} \frac{3k_1}{4} & \frac{3k_1}{4} \\ \frac{3k_1}{4} & \frac{3k_1}{4} \end{pmatrix}$$

D_3 -direct-connection K -matrix eigensolutions

Generic K -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

Generic K -matrix D_3 projections

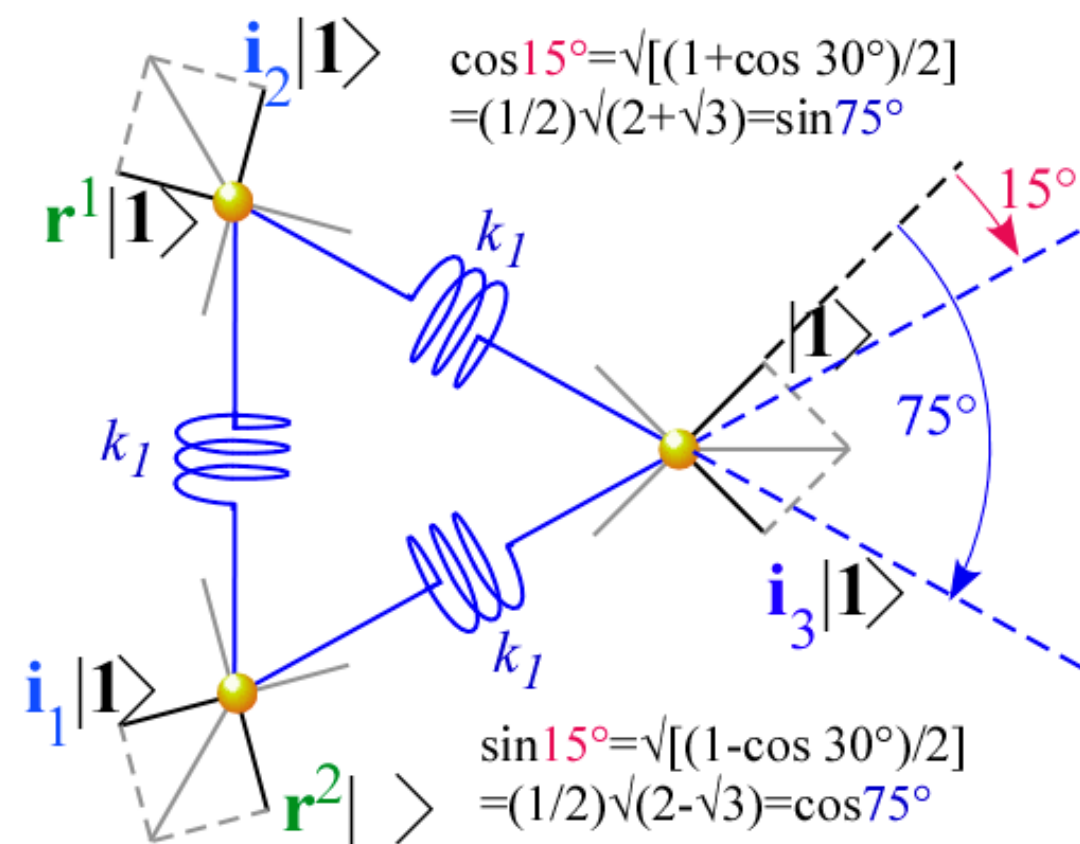
$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix}$$

D_3 -direct-connection vibrational K -matrix

$ g_b\rangle$	$ \mathbf{1}\rangle$	$ \mathbf{r}^1\rangle$	$ \mathbf{r}^2\rangle$	$ \mathbf{i}_1\rangle$	$ \mathbf{i}_2\rangle$	$ \mathbf{i}_3\rangle$
$\langle \mathbf{1} \mathbf{K} g_b \rangle =$	$k_1(\cos^2 75^\circ + \cos^2 15^\circ) = k_1$	$k_1 \cos 75^\circ \cdot \cos 15^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 75^\circ = \frac{k_1}{4}$	$k_1 \cos 15^\circ \cdot \cos 15^\circ = \frac{k_1(2 - \sqrt{3})}{4}$	$k_1 \cos 75^\circ \cdot \cos 75^\circ = \frac{k_1(2 + \sqrt{3})}{4}$	$k_1(\cos^2 75^\circ - \cos^2 15^\circ) = \frac{k_1}{2}$



D_3 -direct-connection vibrational K -matrix eigenvalues $K_m/M = \omega_m^2$

$$K_{xx}^{A_1} = 3k_1$$

$$K_{yy}^{A_2} = 0$$

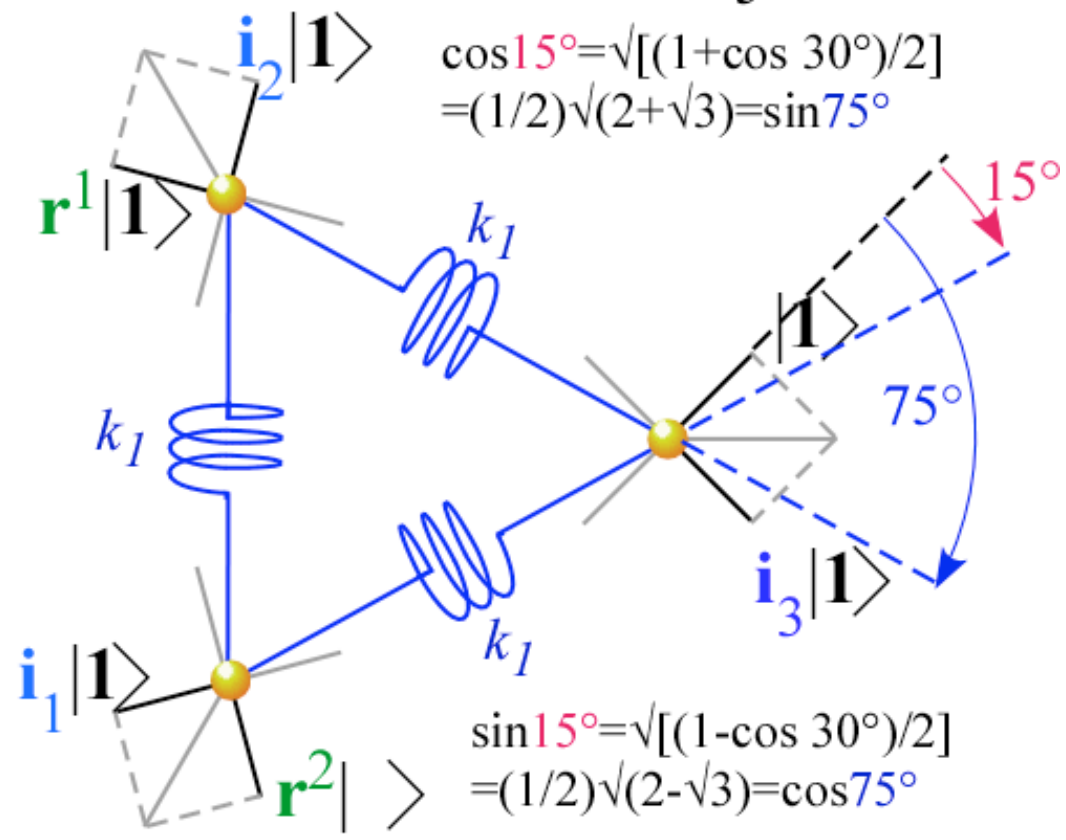
E_1 Eigenvectors in terms of $D_3 \supset C_2(i_3)$ E_1 -vectors

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} \frac{3k_1}{4} & \frac{3k_1}{4} \\ \frac{3k_1}{4} & \frac{3k_1}{4} \end{pmatrix}$$

$$\mathbf{K} \begin{bmatrix} E_1 \\ g(+) \end{bmatrix} = \mathbf{K} \left(\begin{bmatrix} E_1 \\ gx \end{bmatrix} + \begin{bmatrix} E_1 \\ gy \end{bmatrix} \right) \frac{1}{\sqrt{2}} = \frac{3k_1}{2} \begin{bmatrix} E_1 \\ g(+) \end{bmatrix}$$

$$\mathbf{K} \begin{bmatrix} E_1 \\ g(-) \end{bmatrix} = \mathbf{K} \left(\begin{bmatrix} E_1 \\ gx \end{bmatrix} - \begin{bmatrix} E_1 \\ gy \end{bmatrix} \right) \frac{1}{\sqrt{2}} = 0 \begin{bmatrix} E_1 \\ g(-) \end{bmatrix}, \quad g = (x \text{ or } y).$$

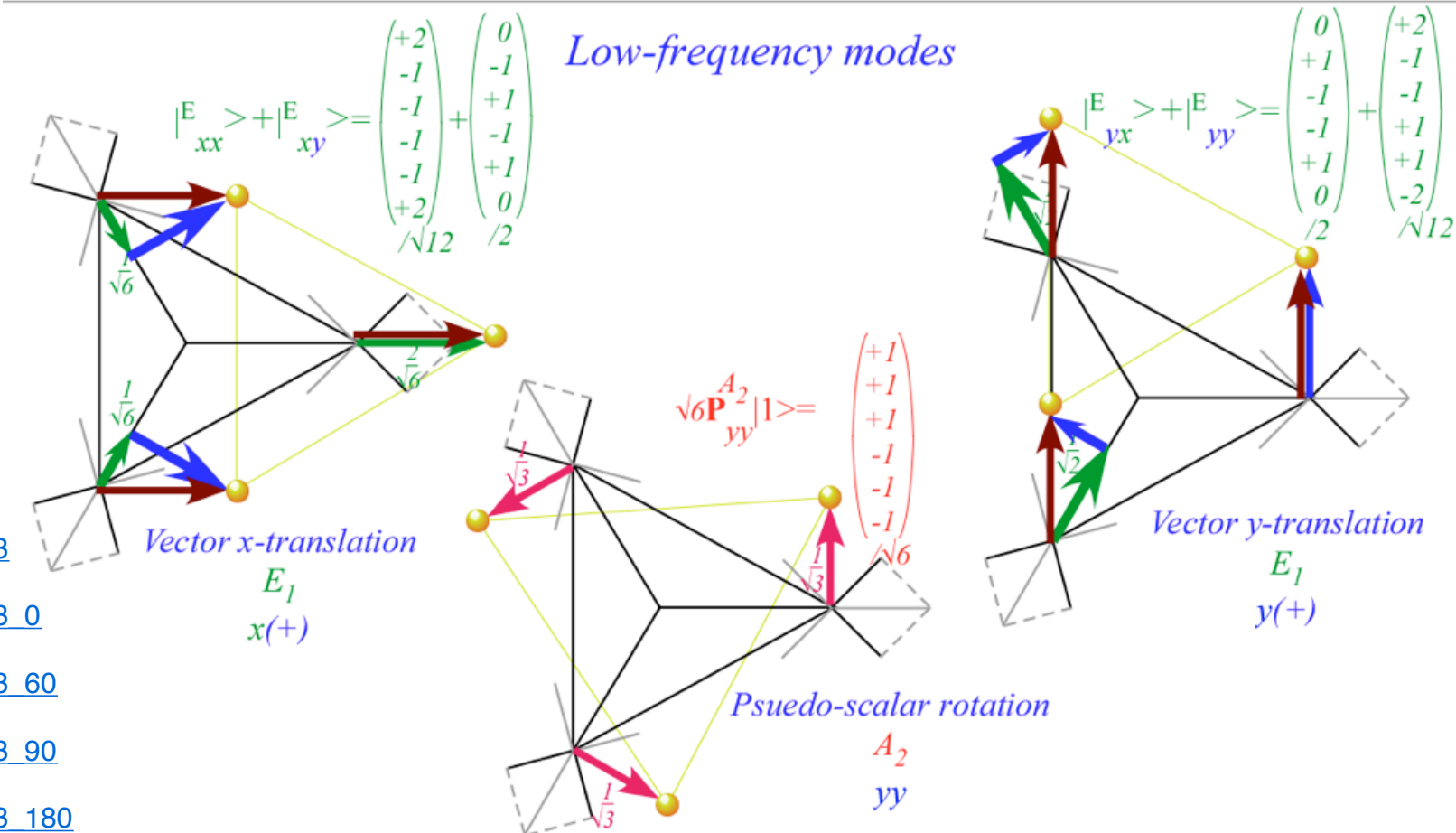
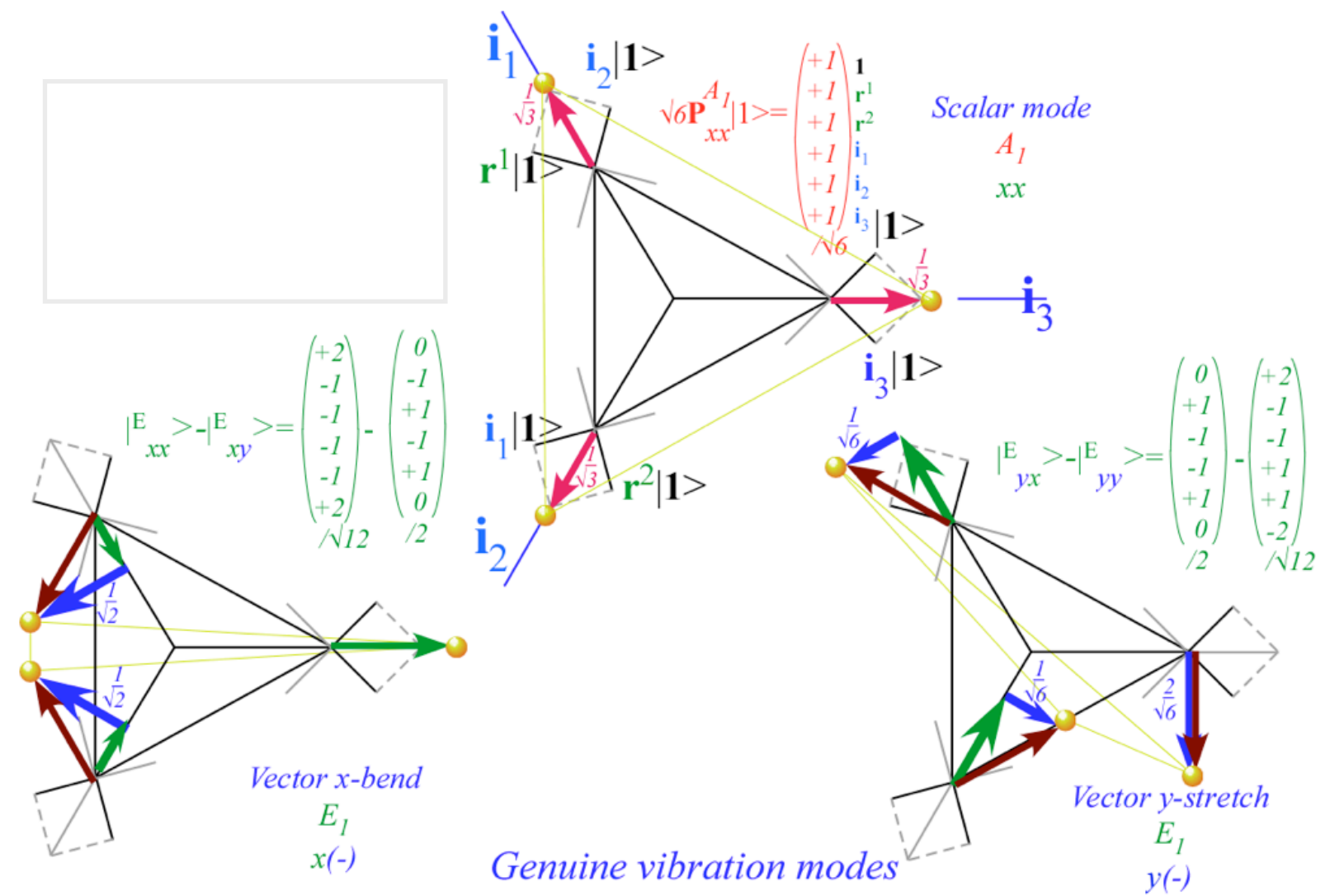
Mixed local symmetry D_3 model



$$K_{xx}^{A_1} = 3k_1$$

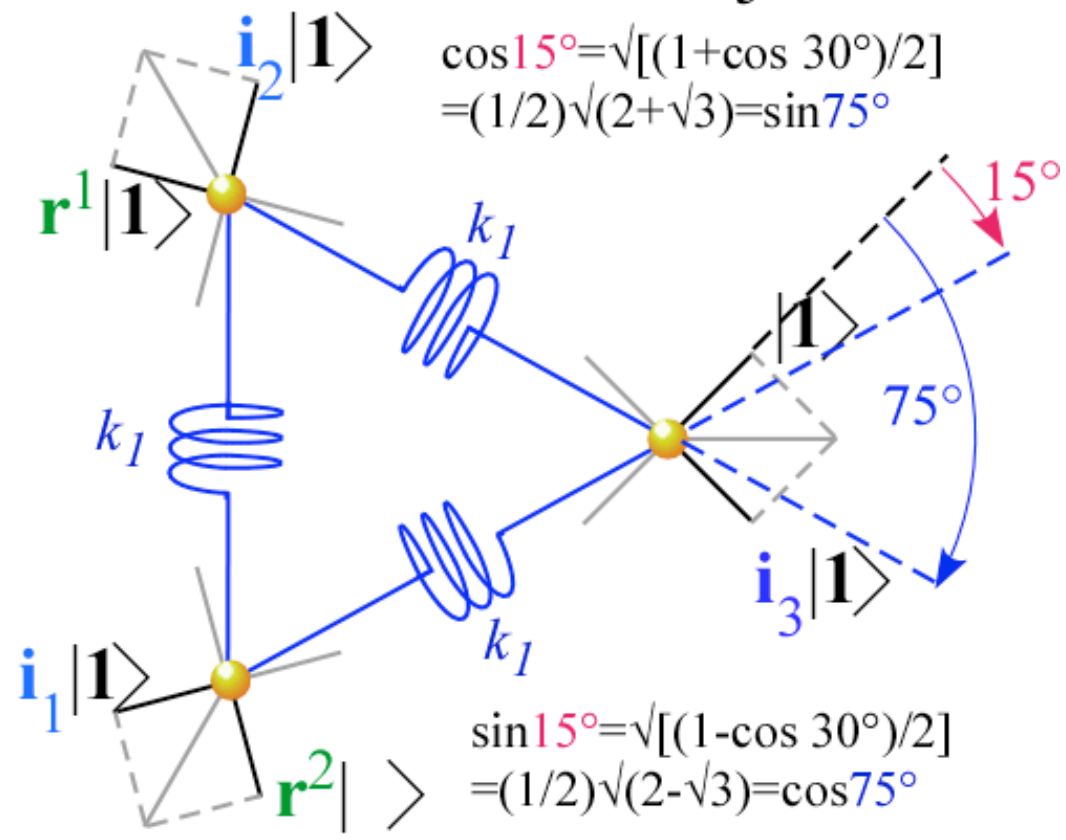
$$K_{yy}^{A_2} = 0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} \frac{3k_1}{4} & \frac{3k_1}{4} \\ \frac{3k_1}{4} & \frac{3k_1}{4} \end{pmatrix}$$



- <https://modphys.hosted.uark.edu/markup/MoIVibesWeb.html?scenario=C3vN3>
- https://modphys.hosted.uark.edu/markup/MoIVibesWeb.html?scenario=C3vN3_0
- https://modphys.hosted.uark.edu/markup/MoIVibesWeb.html?scenario=C3vN3_60
- https://modphys.hosted.uark.edu/markup/MoIVibesWeb.html?scenario=C3vN3_90
- https://modphys.hosted.uark.edu/markup/MoIVibesWeb.html?scenario=C3vN3_180

Mixed local symmetry D_3 model



$$K_{xx}^{A_1} = 3k_1$$

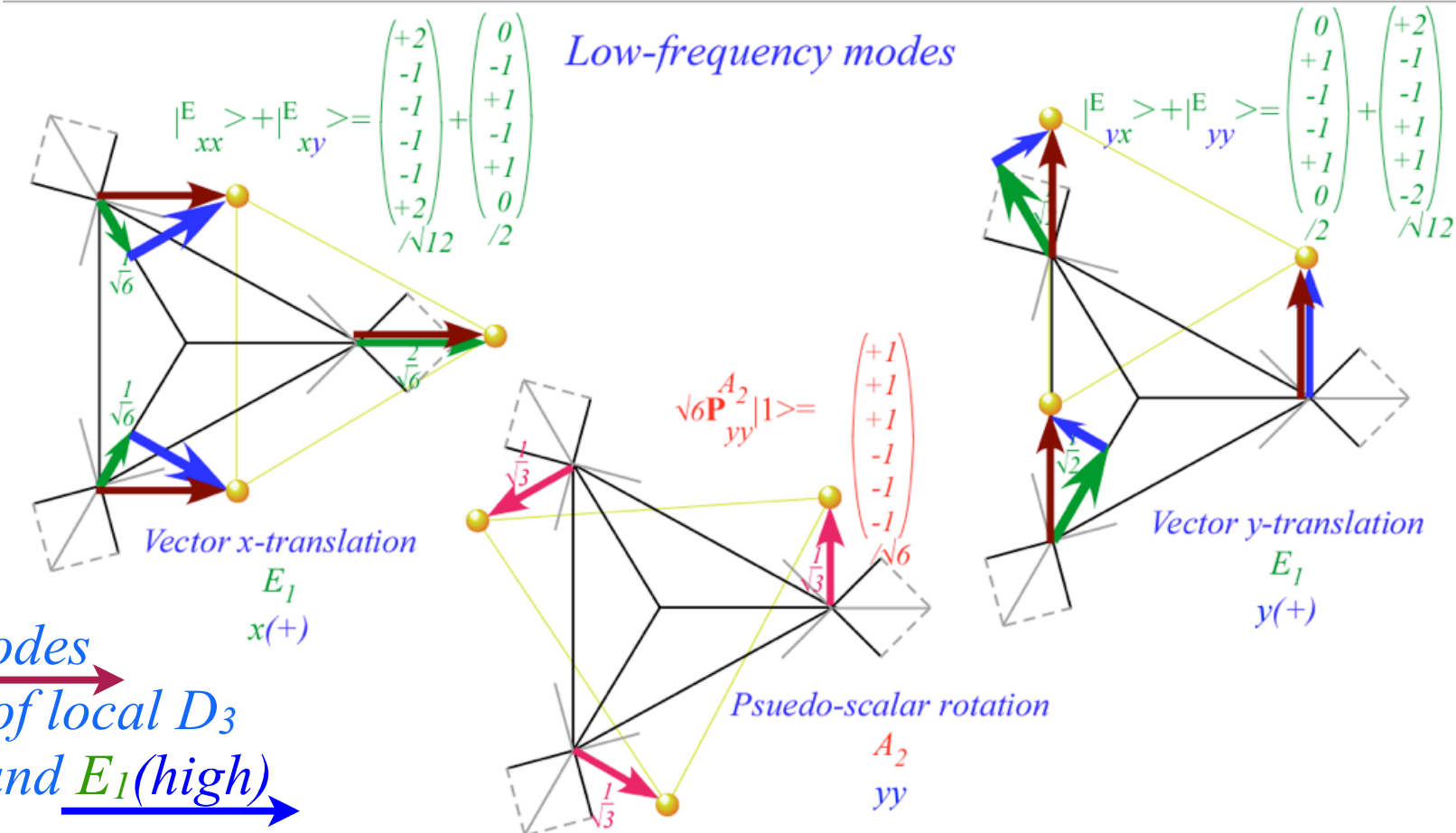
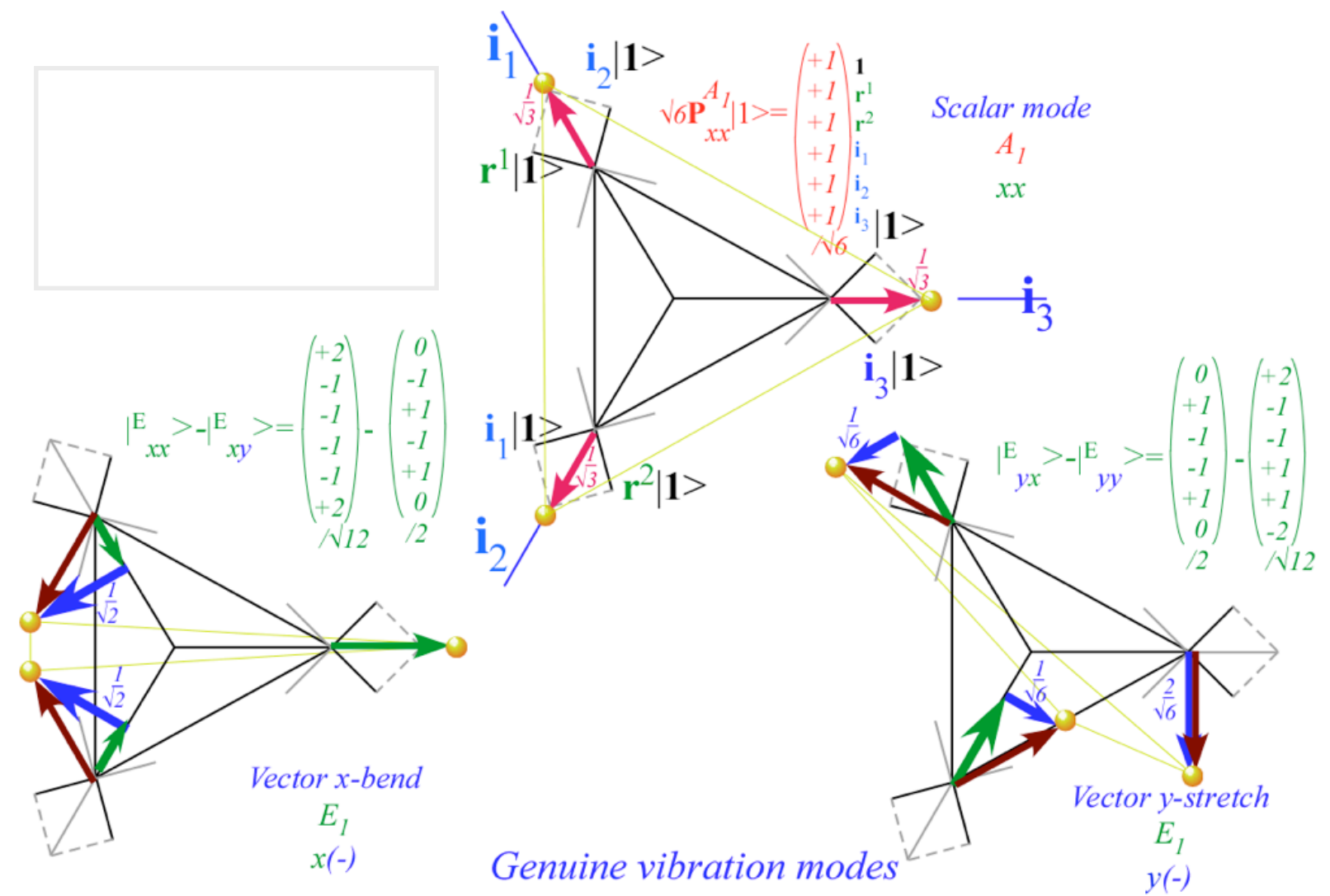
$$K_{yy}^{A_2} = 0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} \frac{3k_1}{4} & \frac{3k_1}{4} \\ \frac{3k_1}{4} & \frac{3k_1}{4} \end{pmatrix}$$

E_1 Eigenvalues: $\frac{3k_1}{2}$ 0

E_1 Eigenvectors: $\begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \\ \sqrt{2} \end{pmatrix}$ $\begin{pmatrix} 1 \\ \sqrt{2} \\ -1 \\ \sqrt{2} \end{pmatrix}$

Mixed modes
in terms of local D_3
 $E_1(\text{low})$ and $E_1(\text{high})$



2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity


Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

 *$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions*

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

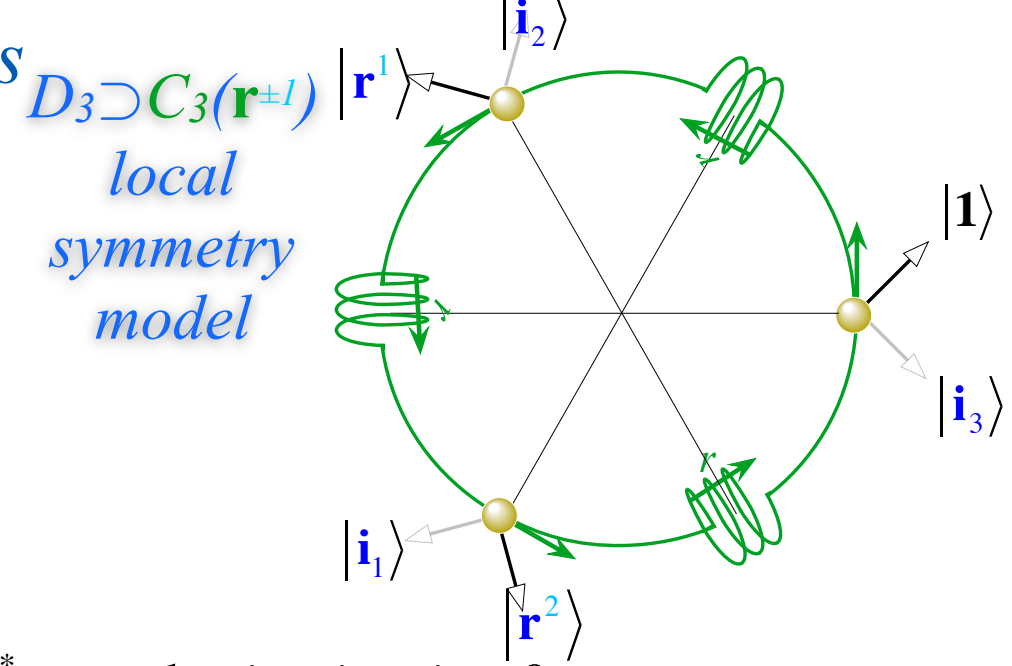
$U(12)$ -Supersymmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry K -matrix eigensolutions

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

$$\langle \mathbf{1} | \mathbf{K}_{C_3} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & ir & -ir & 0 & 0 & 0 \end{bmatrix}$$



$D_3 \supset C_3(\mathbf{r}^{\pm 1})$
local
symmetry
model

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry vibrational K -matrix Set: $r_1 = r = -r_2^*$, and: $i_1 = i_2 = i_3 = 0$

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3 = r_0$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3 = r_0$$

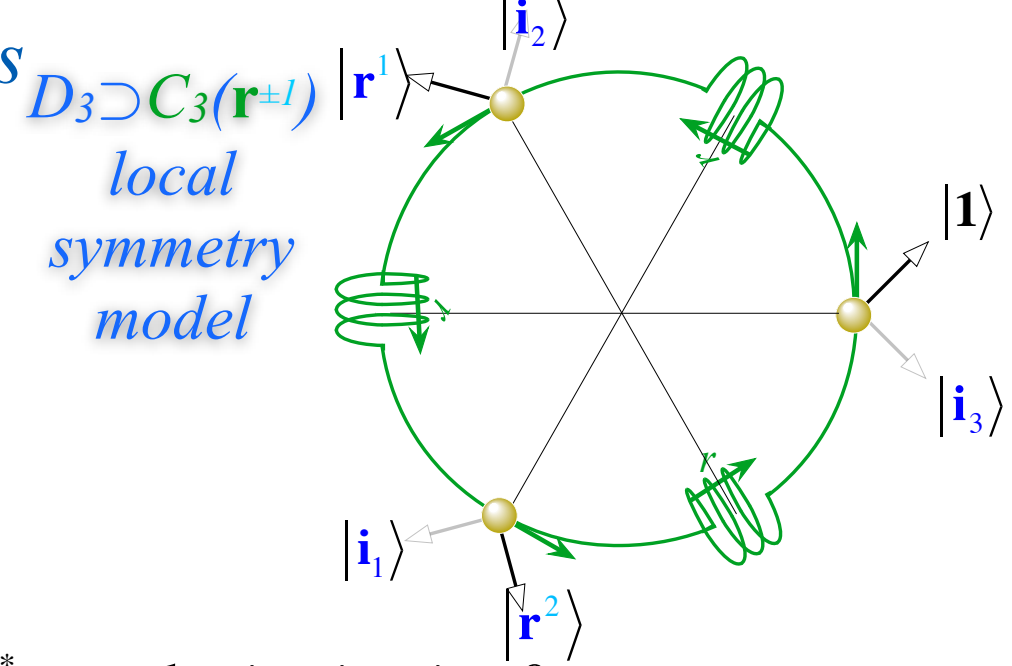
$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix} \Bigg|_{\substack{r_1=r=-r_2^* \\ i_1=i_2=i_3=0}} = \begin{pmatrix} r_0 & -ir \frac{\sqrt{3}}{2} \\ +ir \frac{\sqrt{3}}{2} & r_0 \end{pmatrix}$$

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry K -matrix eigensolutions

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

$$\langle \mathbf{1} | \mathbf{K}_{C_3} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & ir & -ir & 0 & 0 & 0 \end{bmatrix}$$



$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry vibrational K -matrix Set: $r_1 = r = -r_2^*$, and: $i_1 = i_2 = i_3 = 0$

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3 = r_0$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3 = r_0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix} \underset{i_1=i_2=i_3=0}{r_1=r=-r_2^*} = \begin{pmatrix} r_0 & -ir \frac{\sqrt{3}}{2} \\ +ir \frac{\sqrt{3}}{2} & r_0 \end{pmatrix}$$

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry vibrational K -matrix eigenvalues $K_m/M = \omega_m^2$

$$K_{xx}^{A_1} = r_0$$

$$K_{yy}^{A_2} = r_0$$

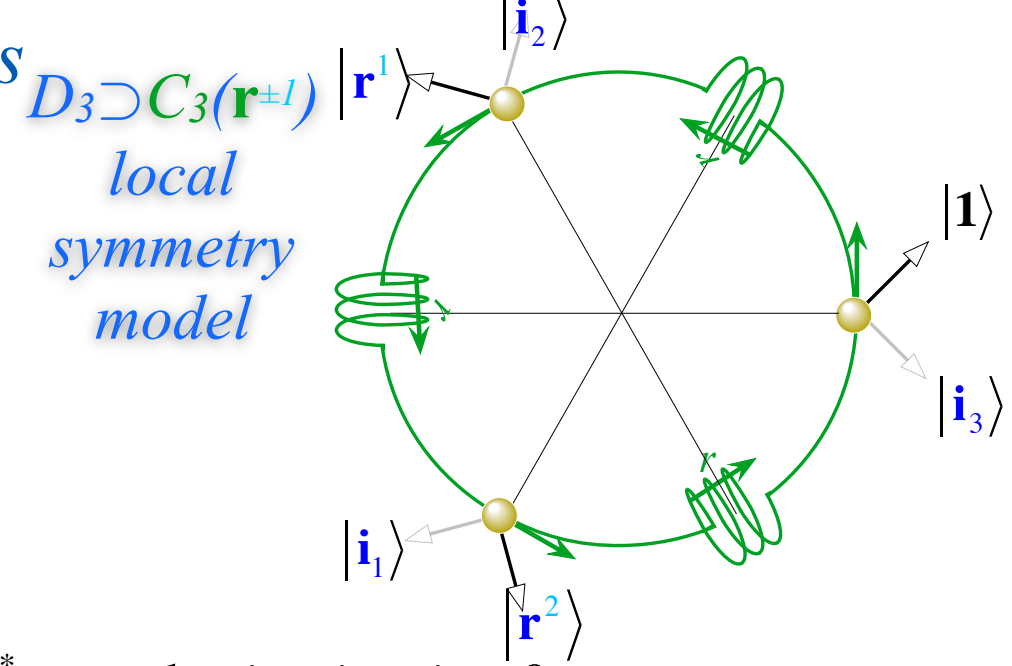
$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} r_0 & -ir \frac{\sqrt{3}}{2} \\ +ir \frac{\sqrt{3}}{2} & r_0 \end{pmatrix} \Rightarrow \begin{pmatrix} r_0 + r \frac{\sqrt{3}}{2} & 0 \\ 0 & r_0 - r \frac{\sqrt{3}}{2} \end{pmatrix}$$

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry K -matrix eigensolutions

Generic \mathbf{K} -matrix (Top row)

$$\langle \mathbf{1} | \mathbf{K} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & r_1 & r_2 & i_1 & i_2 & i_3 \end{bmatrix}$$

$$\langle \mathbf{1} | \mathbf{K}_{C_3} | \mathbf{g}_b \rangle = \begin{bmatrix} r_0 & ir & -ir & 0 & 0 & 0 \end{bmatrix}$$



$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry vibrational K -matrix Set: $r_1 = r = -r_2^*$, and: $i_1 = i_2 = i_3 = 0$

$$K_{xx}^{A_1} = r_0 + r_1 + r_1^* + i_1 + i_2 + i_3 = r_0$$

$$K_{yy}^{A_2} = r_0 + r_1 + r_1^* - i_1 - i_2 - i_3 = r_0$$

$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2r_0 - r_1 - r_1^* - i_1 - i_2 + 2i_3 & \sqrt{3}(-r_1 + r_1^* - i_1 + i_2) \\ \sqrt{3}(-r_1^* + r_1 - i_1 + i_2) & 2r_0 - r_1 - r_1^* + i_1 + i_2 - 2i_3 \end{pmatrix} \Bigg|_{\substack{r_1=r=-r_2^* \\ i_1=i_2=i_3=0}} = \begin{pmatrix} r_0 & -ir \frac{\sqrt{3}}{2} \\ +ir \frac{\sqrt{3}}{2} & r_0 \end{pmatrix}$$

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry vibrational K -matrix eigenvalues $K_m/M = \omega_m^2$

E_1 Eigenvectors in terms of $D_3 \supset C_2(i_3)$ E_1 -vectors

$$K_{xx}^{A_1} = r_0$$

$$K_{yy}^{A_2} = r_0$$

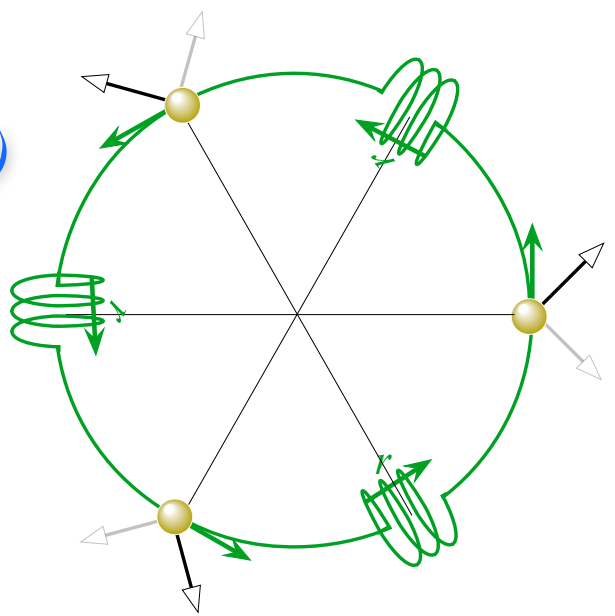
$$\begin{pmatrix} K_{xx}^{E_1} & K_{xy}^{E_1} \\ K_{yx}^{E_1} & K_{yy}^{E_1} \end{pmatrix} = \begin{pmatrix} r_0 & -ir \frac{\sqrt{3}}{2} \\ +ir \frac{\sqrt{3}}{2} & r_0 \end{pmatrix} \Rightarrow \begin{pmatrix} r_0 + r \frac{\sqrt{3}}{2} & 0 \\ 0 & r_0 - r \frac{\sqrt{3}}{2} \end{pmatrix}$$

$$\mathbf{K} \begin{pmatrix} E_1 \\ g(1)_3 \end{pmatrix} = \mathbf{K} \left(\begin{pmatrix} E_1 \\ gx \end{pmatrix} + i \begin{pmatrix} E_1 \\ gy \end{pmatrix} \right) \frac{1}{\sqrt{2}} = +r \frac{\sqrt{3}}{2} \begin{pmatrix} E_1 \\ g(1)_3 \end{pmatrix},$$

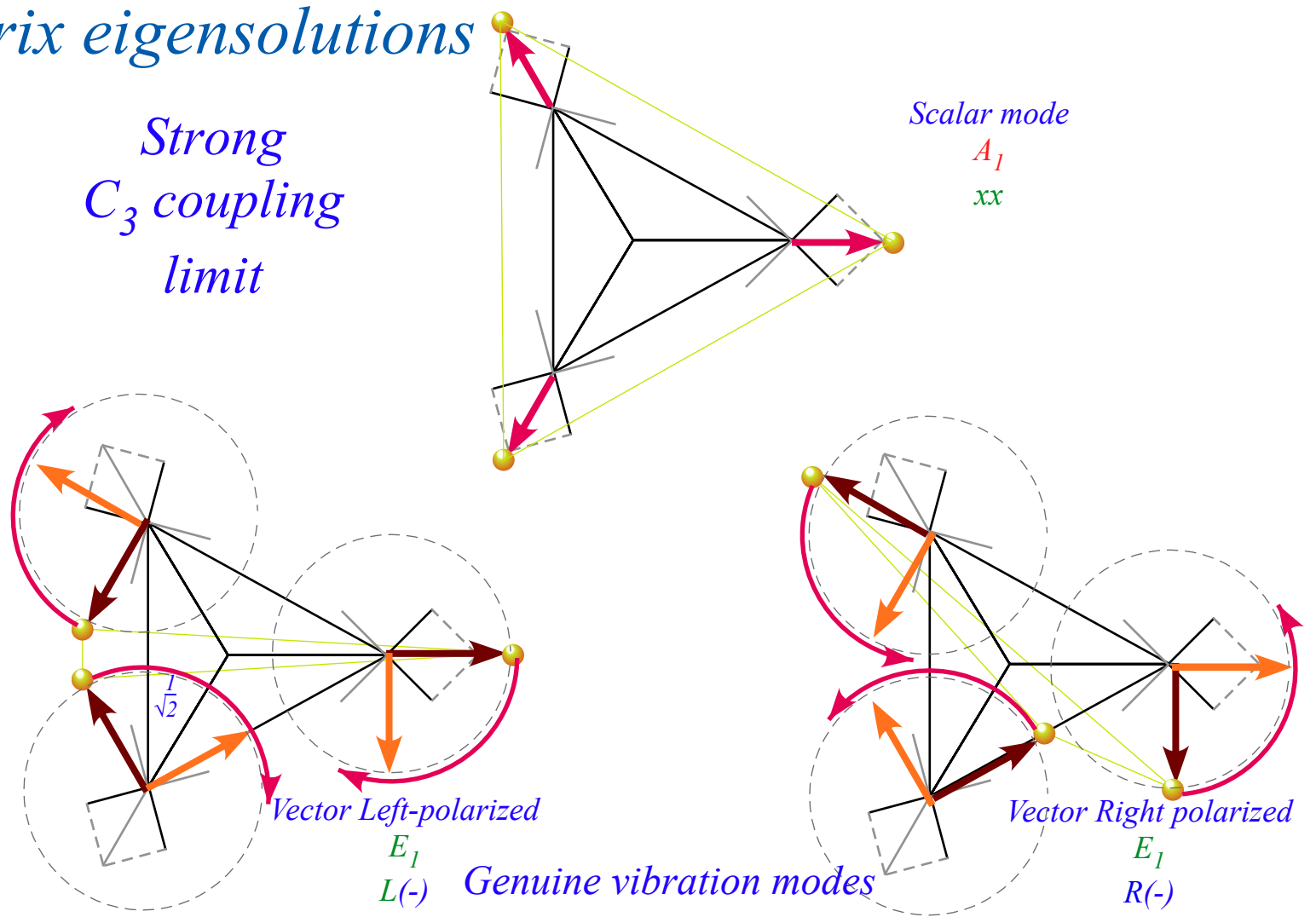
$$\mathbf{K} \begin{pmatrix} E_1 \\ g(2)_3 \end{pmatrix} = \mathbf{K} \left(\begin{pmatrix} E_1 \\ gx \end{pmatrix} - i \begin{pmatrix} E_1 \\ gy \end{pmatrix} \right) \frac{1}{\sqrt{2}} = -r \frac{\sqrt{3}}{2} \begin{pmatrix} E_1 \\ g(2)_3 \end{pmatrix}.$$

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ local symmetry K -matrix eigensolutions

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$
local
symmetry
model



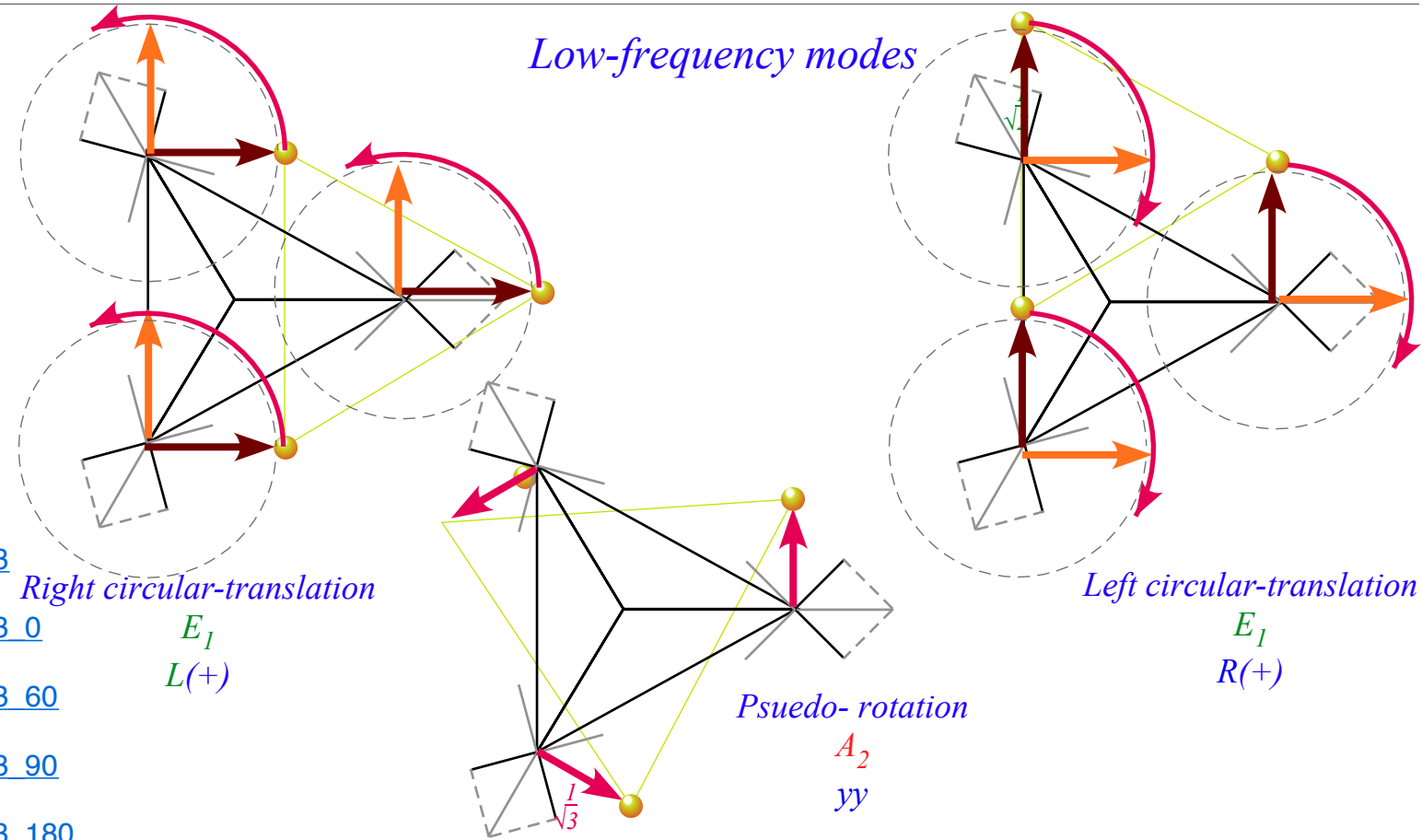
Strong
 C_3 coupling
limit



$$\mathbf{K} \begin{pmatrix} E_1 \\ g(1)_3 \end{pmatrix} = \mathbf{K} \left(\begin{pmatrix} E_1 \\ gx \end{pmatrix} + i \begin{pmatrix} E_1 \\ gy \end{pmatrix} \right) \frac{1}{\sqrt{2}} = +r \frac{\sqrt{3}}{2} \begin{pmatrix} E_1 \\ g(1)_3 \end{pmatrix},$$

$$\mathbf{K} \begin{pmatrix} E_1 \\ g(2)_3 \end{pmatrix} = \mathbf{K} \left(\begin{pmatrix} E_1 \\ gx \end{pmatrix} - i \begin{pmatrix} E_1 \\ gy \end{pmatrix} \right) \frac{1}{\sqrt{2}} = -r \frac{\sqrt{3}}{2} \begin{pmatrix} E_1 \\ g(2)_3 \end{pmatrix}.$$

Low-frequency modes



- <https://modphys.hosted.uark.edu/markup/MolVibesWeb.html?scenario=C3vN3>
- https://modphys.hosted.uark.edu/markup/MolVibesWeb.html?scenario=C3vN3_0
- https://modphys.hosted.uark.edu/markup/MolVibesWeb.html?scenario=C3vN3_60
- https://modphys.hosted.uark.edu/markup/MolVibesWeb.html?scenario=C3vN3_90
- https://modphys.hosted.uark.edu/markup/MolVibesWeb.html?scenario=C3vN3_180

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

 *Applied symmetry reduction and splitting*

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^0_2 \oplus d^1_2 \oplus \dots$ correlation

$D_3 \supset C_2$	0_2	1_2
A_1	1	·
A_2	·	1
E_1	1	1

$\chi_k^\alpha(D_3)$	χ_1^α	$\chi_{\mathbf{r}^{1,2}}^\alpha$	$\chi_{\mathbf{i}_{1,2,3}}^\alpha$
$\alpha = A_1$	1	1	1
$\alpha = A_2$	1	1	-1
$\alpha = E$	2	-1	0

$\chi_k^\alpha(C_2)$	χ_1^α	$\chi_{\mathbf{i}_3}^\alpha$
$\alpha = 0_2$	1	1
$\alpha = 1_2$	1	-1

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$ $= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2} \searrow \omega^{1_2}$	E_1	1	1

$\chi_k^\alpha(D_3)$	χ_1^α	$\chi_{r^{1,2}}^\alpha$	$\chi_{i_{1,2,3}}^\alpha$
$\alpha = A_1$	1	1	1
$\alpha = A_2$	1	1	-1
$\alpha = E$	2	-1	0

$\chi_k^\alpha(C_2)$	χ_1^α	$\chi_{i_3}^\alpha$
$\alpha = 0_2$	1	1
$\alpha = 1_2$	1	-1

Key concept:
Projector splitting
means
Level splitting

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2}$	E_1	1	1

$$= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1} \quad d^{0_2} \oplus d^{1_2} \quad \searrow \omega^{1_2}$$

$\chi_k^\alpha(D_3)$	χ_1^α	$\chi_{r^{1,2}}^\alpha$	$\chi_{i_{1,2,3}}^\alpha$
$\alpha = A_1$	1	1	1
$\alpha = A_2$	1	1	-1
$\alpha = E$	2	-1	0

$\chi_k^\alpha(C_2)$	χ_1^α	$\chi_{i_3}^\alpha$
$\alpha = 0_2$	1	1
$\alpha = 1_2$	1	-1

$\chi_k^\alpha(C_3)$	χ_1^α	$\chi_{r^1}^\alpha$	$\chi_{r^2}^\alpha$
$\alpha = 0_3$	1	1	1
$\alpha = 1_3$	1	$e^{-i\frac{2\pi}{3}}$	$e^{i\frac{2\pi}{3}}$
$\alpha = 2_3$	1	$e^{i\frac{2\pi}{3}}$	$e^{-i\frac{2\pi}{3}}$

Key concept:
Projector splitting
means
Level splitting

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2}$	E_1	1	1

$$= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$$

$$d^{0_2} \oplus d^{1_2}$$

$$\searrow \omega^{1_2}$$

$\chi_k^\alpha(D_3)$	χ_1^α	$\chi_{r^{1,2}}^\alpha$	$\chi_{i_{1,2,3}}^\alpha$
$\alpha = A_1$	1	1	1
$\alpha = A_2$	1	1	-1
$\alpha = E$	2	-1	0

$\chi_k^\alpha(C_2)$	χ_1^α	$\chi_{i_3}^\alpha$
$\alpha = 0_2$	1	1
$\alpha = 1_2$	1	-1

$\chi_k^\alpha(C_3)$	χ_1^α	$\chi_{r^1}^\alpha$	$\chi_{r^2}^\alpha$
$\alpha = 0_3$	1	1	1
$\alpha = 1_3$	1	$e^{-i\frac{2\pi}{3}}$	$e^{i\frac{2\pi}{3}}$
$\alpha = 2_3$	1	$e^{i\frac{2\pi}{3}}$	$e^{-i\frac{2\pi}{3}}$

Key concept:
Projector splitting
means
Level splitting

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

$D_3 \supset C_3$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_3$	0_3	1_3	2_3
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_3}$	A_1	1	·	·
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{0_3}$	A_2	1	·	·
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{1_3} + \mathbf{P}^{E_1} \mathbf{P}^{2_3}$	$\Rightarrow D^{E_1} \downarrow C_3 \sim$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{1_3}$	E_1	·	1	1

$$= \mathbf{P}_{1_3 1_3}^{E_1} + \mathbf{P}_{2_3 2_3}^{E_1}$$

$$d^{1_3} \oplus d^{2_3}$$

$$\searrow \omega^{2_3}$$

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·	$D^{A_1}(D_3) \downarrow C_2 \sim d^{0_2}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1	$D^{A_2}(D_3) \downarrow C_2 \sim d^{1_2}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$ $= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2}$ $\searrow \omega^{1_2}$	E_1	1	1	$D^{E_1}(D_3) \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$

$\chi_k^\alpha(D_3)$	χ_1^α	$\chi_{r^{1,2}}^\alpha$	$\chi_{i_{1,2,3}}^\alpha$
$\alpha = A_1$	1	1	1
$\alpha = A_2$	1	1	-1
$\alpha = E$	2	-1	0

$\chi_k^\alpha(C_2)$	χ_1^α	$\chi_{i_3}^\alpha$
$\alpha = 0_2$	1	1
$\alpha = 1_2$	1	-1

$\chi_k^\alpha(C_3)$	χ_1^α	$\chi_{r^1}^\alpha$	$\chi_{r^2}^\alpha$
$\alpha = 0_3$	1	1	1
$\alpha = 1_3$	1	$e^{-i\frac{2\pi}{3}}$	$e^{i\frac{2\pi}{3}}$
$\alpha = 2_3$	1	$e^{i\frac{2\pi}{3}}$	$e^{-i\frac{2\pi}{3}}$

Key concept:
Projector splitting
means
Level splitting
Level

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

$D_3 \supset C_3$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_3$	0_3	1_3	2_3	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_3}$	A_1	1	·	·	$D^{A_1}(D_3) \downarrow C_3 \sim d^{0_3}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{0_3}$	A_2	1	·	·	$D^{A_2}(D_3) \downarrow C_3 \sim d^{0_3}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{1_3} + \mathbf{P}^{E_1} \mathbf{P}^{2_3}$ $= \mathbf{P}_{1_3 1_3}^{E_1} + \mathbf{P}_{2_3 2_3}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{1_3}$ $\searrow \omega^{2_3}$	E_1	·	1	1	$D^{E_1}(D_3) \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$

2.26.18 class 14.0: *Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics*

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

 *Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure*

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·	$D^{A_1}(D_3) \downarrow C_2 \sim d^{0_2}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1	$D^{A_2}(D_3) \downarrow C_2 \sim d^{1_2}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$ $= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim$ $d^{0_2} \oplus d^{1_2}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2}$ $\searrow \omega^{1_2}$	E_1	1	1	$D^{E_1}(D_3) \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

$D_3 \supset C_3$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_3$	0_3	1_3	2_3	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_3}$	A_1	1	·	·	$D^{A_1}(D_3) \downarrow C_3 \sim d^{0_3}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{0_3}$	A_2	1	·	·	$D^{A_2}(D_3) \downarrow C_3 \sim d^{0_3}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{1_3} + \mathbf{P}^{E_1} \mathbf{P}^{2_3}$ $= \mathbf{P}_{1_3 1_3}^{E_1} + \mathbf{P}_{2_3 2_3}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_3 \sim$ $d^{1_3} \oplus d^{2_3}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{1_3}$ $\searrow \omega^{2_3}$	E_1	·	1	1	$D^{E_1}(D_3) \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·	$D^{A_1}(D_3) \downarrow C_2 \sim d^{0_2}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1	$D^{A_2}(D_3) \downarrow C_2 \sim d^{1_2}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$ $= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim$ $d^{0_2} \oplus d^{1_2}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2}$ $\searrow \omega^{1_2}$	E_1	1	1	$D^{E_1}(D_3) \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$
							$d^{0_2}(C_2) \uparrow D_3$
							$\sim D^{A_1} \oplus D^{E_1}$
							$d^{1_2}(C_2) \uparrow D_3$
							$\sim D^{A_2} \oplus D^{E_1}$

Spontaneous symmetry breaking and clustering:

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

$D_3 \supset C_3$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_3$	0_3	1_3	2_3	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_3}$	A_1	1	·	·	$D^{A_1}(D_3) \downarrow C_3 \sim d^{0_3}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{0_3}$	A_2	1	·	·	$D^{A_2}(D_3) \downarrow C_3 \sim d^{0_3}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{1_3} + \mathbf{P}^{E_1} \mathbf{P}^{2_3}$ $= \mathbf{P}_{1_3 1_3}^{E_1} + \mathbf{P}_{2_3 2_3}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_3 \sim$ $d^{1_3} \oplus d^{2_3}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{1_3}$ $\searrow \omega^{2_3}$	E_1	·	1	1	$D^{E_1}(D_3) \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

$D_3 \supset C_2$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_2$	0_2	1_2	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_2} = \mathbf{P}_{0_2 0_2}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_2 \sim d^{0_2}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_2}$	A_1	1	·	$D^{A_1}(D_3) \downarrow C_2 \sim d^{0_2}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{1_2} = \mathbf{P}_{1_2 1_2}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_2 \sim d^{1_2}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{1_2}$	A_2	·	1	$D^{A_2}(D_3) \downarrow C_2 \sim d^{1_2}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{0_2} + \mathbf{P}^{E_1} \mathbf{P}^{1_2}$ $= \mathbf{P}_{0_2 0_2}^{E_1} + \mathbf{P}_{1_2 1_2}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{0_2} \searrow \omega^{1_2}$	E_1	1	1	$D^{E_1}(D_3) \downarrow C_2 \sim d^{0_2} \oplus d^{1_2}$

$d^{0_2}(C_2) \uparrow D_3 \sim D^{A_1} \oplus D^{E_1}$
 $d^{1_2}(C_2) \uparrow D_3 \sim D^{A_2} \oplus D^{E_1}$

Spontaneous symmetry breaking and clustering:

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Applied symmetry reduction and splitting:

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

$D_3 \supset C_3$	\mathbf{P}^α relabel/split	D^α relabel/reduce	ω^α relabel/split	$D_3 \supset C_3$	0_3	1_3	2_3	
A_1	$\mathbf{P}^{A_1} = \mathbf{P}^{A_1} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_1}$	$\Rightarrow D^{A_1} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_1} \rightarrow \omega^{0_3}$	A_1	1	·	·	$D^{A_1}(D_3) \downarrow C_3 \sim d^{0_3}$
A_2	$\mathbf{P}^{A_2} = \mathbf{P}^{A_2} \mathbf{P}^{0_3} = \mathbf{P}_{0_3 0_3}^{A_2}$	$\Rightarrow D^{A_2} \downarrow C_3 \sim d^{0_3}$	$\Rightarrow \omega^{A_2} \rightarrow \omega^{0_3}$	A_2	1	·	·	$D^{A_2}(D_3) \downarrow C_3 \sim d^{0_3}$
E_1	$\mathbf{P}^{E_1} = \mathbf{P}^{E_1} \mathbf{P}^{1_3} + \mathbf{P}^{E_1} \mathbf{P}^{2_3}$ $= \mathbf{P}_{1_3 1_3}^{E_1} + \mathbf{P}_{2_3 2_3}^{E_1}$	$\Rightarrow D^{E_1} \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$	$\Rightarrow \omega^{E_1} \rightarrow \omega^{1_3} \searrow \omega^{2_3}$	E_1	·	1	1	$D^{E_1}(D_3) \downarrow C_3 \sim d^{1_3} \oplus d^{2_3}$

$d^{0_3}(C_3) \uparrow D_3 \sim D^{A_1} \oplus D^{A_2}$
 $d^{1_3}(C_3) \uparrow D_3 \sim D^{E_1}$
 $d^{2_3}(C_3) \uparrow D_3 \sim D^{E_1}$

Spontaneous symmetry breaking and clustering:

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Frobenius Reciprocity Theorem

Number of $D^\alpha(G)$ in $d^k(K)\uparrow G =$ Number of $d^k(K)$ in $D^\alpha(G)\downarrow K$

Frobenius Reciprocity Theorem

Number of $D^\alpha(G)$ in $d^k(K) \uparrow G =$ Number of $d^k(K)$ in $D^\alpha(G) \downarrow K$

..and regular representation

$D_3 \supset C_1$	$0_1 = 1_1$
A_1	1
A_2	1
E_1	2

Frobenius Reciprocity Theorem

Number of $D^\alpha(G)$ in $d^k(K) \uparrow G =$ Number of $d^k(K)$ in $D^\alpha(G) \downarrow K$

..and regular representation

$D_3 \supset C_1$	$0_1 = 1_1$
A_1	1
A_2	1
E_1	2

$D_3 \supset C_2$	0_2	1_2
A_1	1	·
A_2	·	1
E_1	1	1

$D_3 \supset C_3$	0_3	1_3	2_3
A_1	1	·	·
A_2	1	·	·
E_1	·	1	1

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

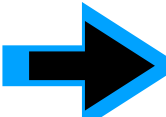
Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

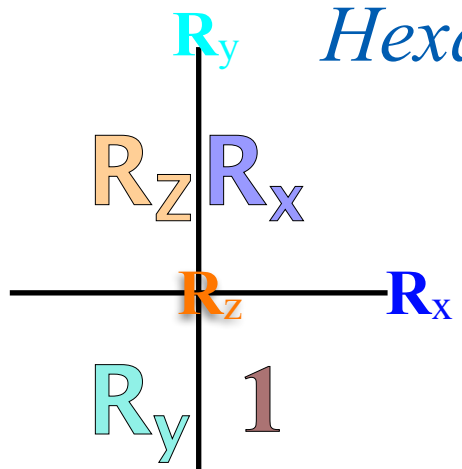
 *D_6 symmetry and Hexagonal Bands*

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

$U(12)$ -Supersymmetry

Hexagonal chains: $D_6 \supset D_3 \supset C_2$ or $D_{6h} \supset D_{2h} \supset D_2$ label 6-fold bands



D_2 Group
"slide-rule"

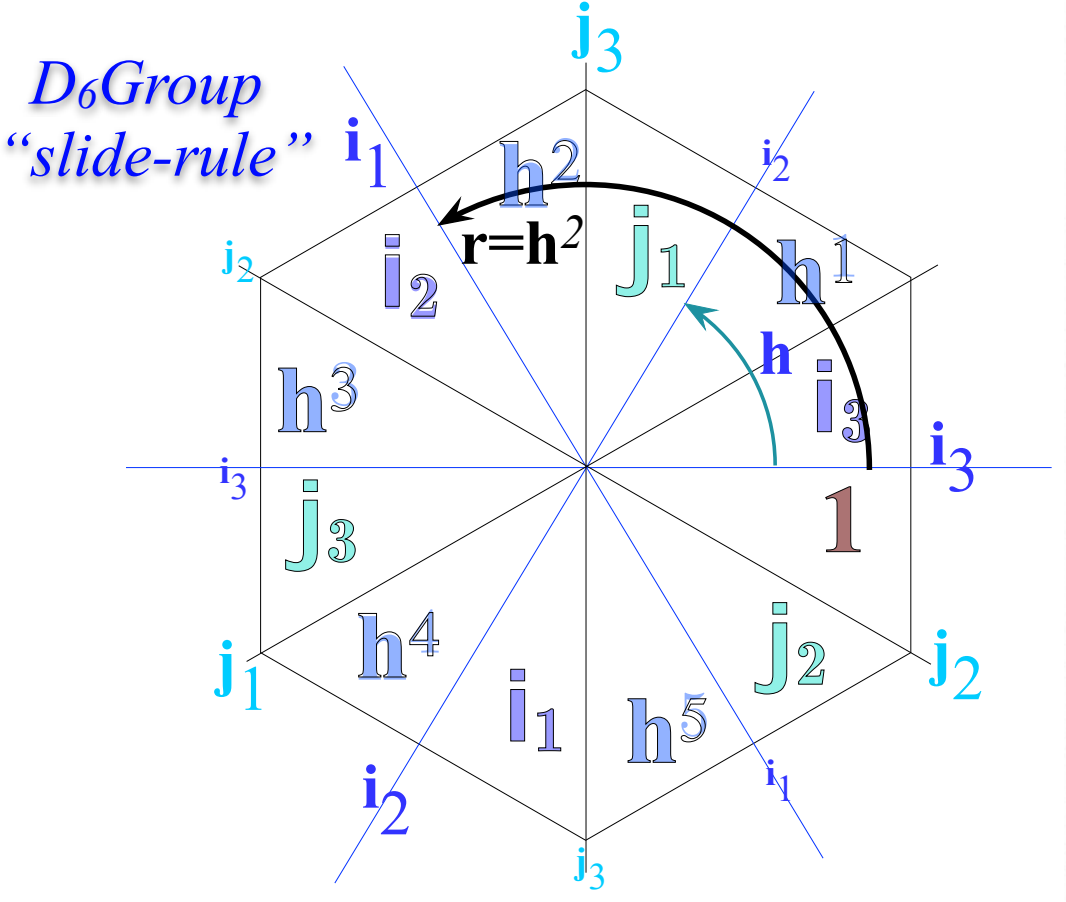
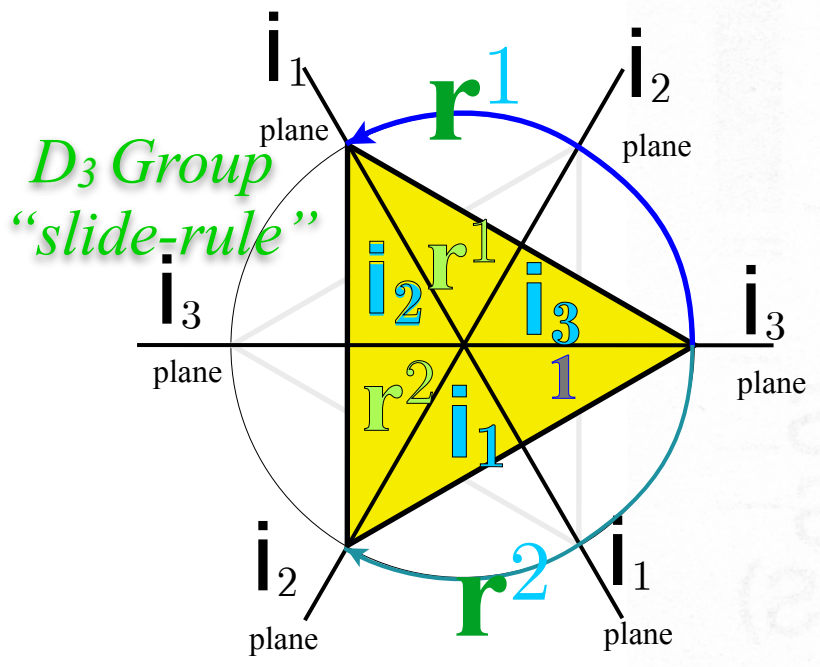
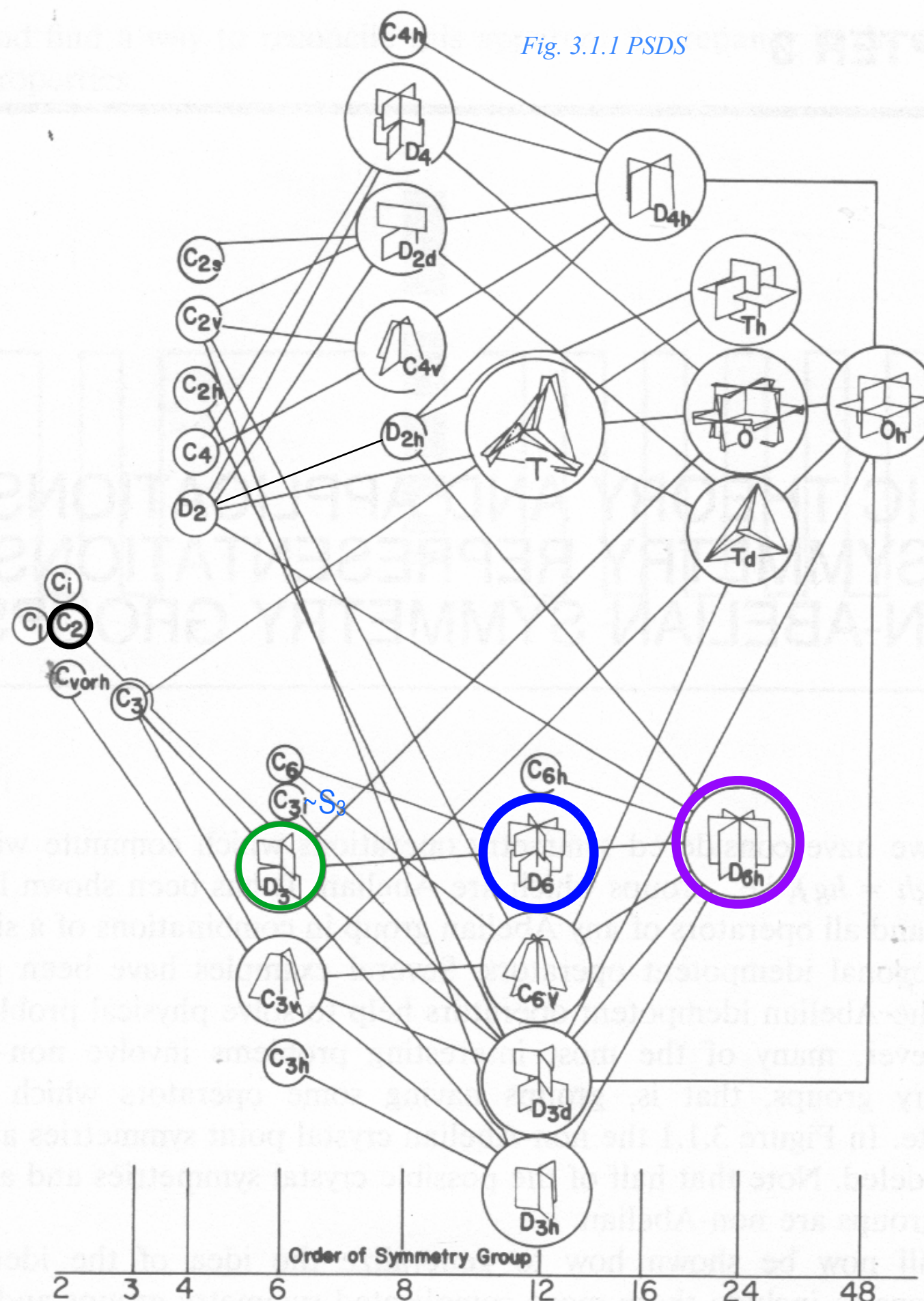


Fig. 3.1.1 PSDS



Hexagonal chains: $D_6 \supset D_3 \supset C_2$ or $D_{6h} \supset D_{2h} \supset D_2$ label 6-fold bands

D_6 is the outer product (\times) product $D_3 \times C_2$ of D_3 and C_2 . (Requires C_2 to commute with all of D_3 .)

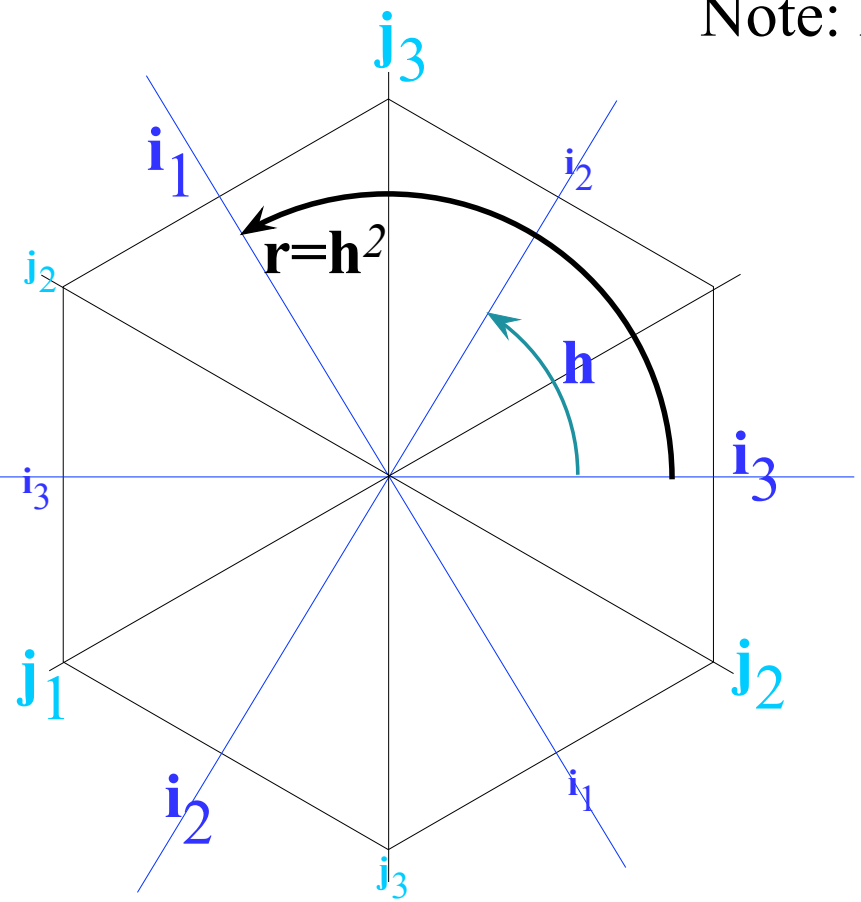
$$D_6 = D_3 \times C_2 = \{ \mathbf{1}, \mathbf{r}, \mathbf{r}^2, \mathbf{i}_1, \mathbf{i}_2, \mathbf{i}_3 \} \times \{ \mathbf{1}, \mathbf{R}_z \}$$

D_6 is product \times of D_3 and C_2 . Define 60° hexagonal generator \mathbf{h} of subgroup $C_6 = \{ \mathbf{1}, \mathbf{h}, \mathbf{h}^2, \mathbf{h}^3, \mathbf{h}^4, \mathbf{h}^5 \}$

$$D_6 = D_3 \times C_2 = \{ \mathbf{1}, \mathbf{r}, \mathbf{r}^2, \mathbf{i}_1, \mathbf{i}_2, \mathbf{i}_3 \} \times \{ \mathbf{1}, \mathbf{R}_z \} = \{ \mathbf{1}, \mathbf{r}, \mathbf{r}^2, \mathbf{i}_1, \mathbf{i}_2, \mathbf{i}_3, \mathbf{1} \cdot \mathbf{R}_z, \mathbf{r} \cdot \mathbf{R}_z, \mathbf{r}^2 \cdot \mathbf{R}_z, \mathbf{i}_1 \cdot \mathbf{R}_z, \mathbf{i}_2 \cdot \mathbf{R}_z, \mathbf{i}_3 \cdot \mathbf{R}_z \}$$

$$D_6 = D_3 \times C_2 = \{ \mathbf{1}, \mathbf{h}^2, \mathbf{h}^4, \mathbf{i}_1, \mathbf{i}_2, \mathbf{i}_3, \mathbf{h}^3, \mathbf{h}^5, \mathbf{h}, \mathbf{j}_1, \mathbf{j}_2, \mathbf{j}_3 \}$$

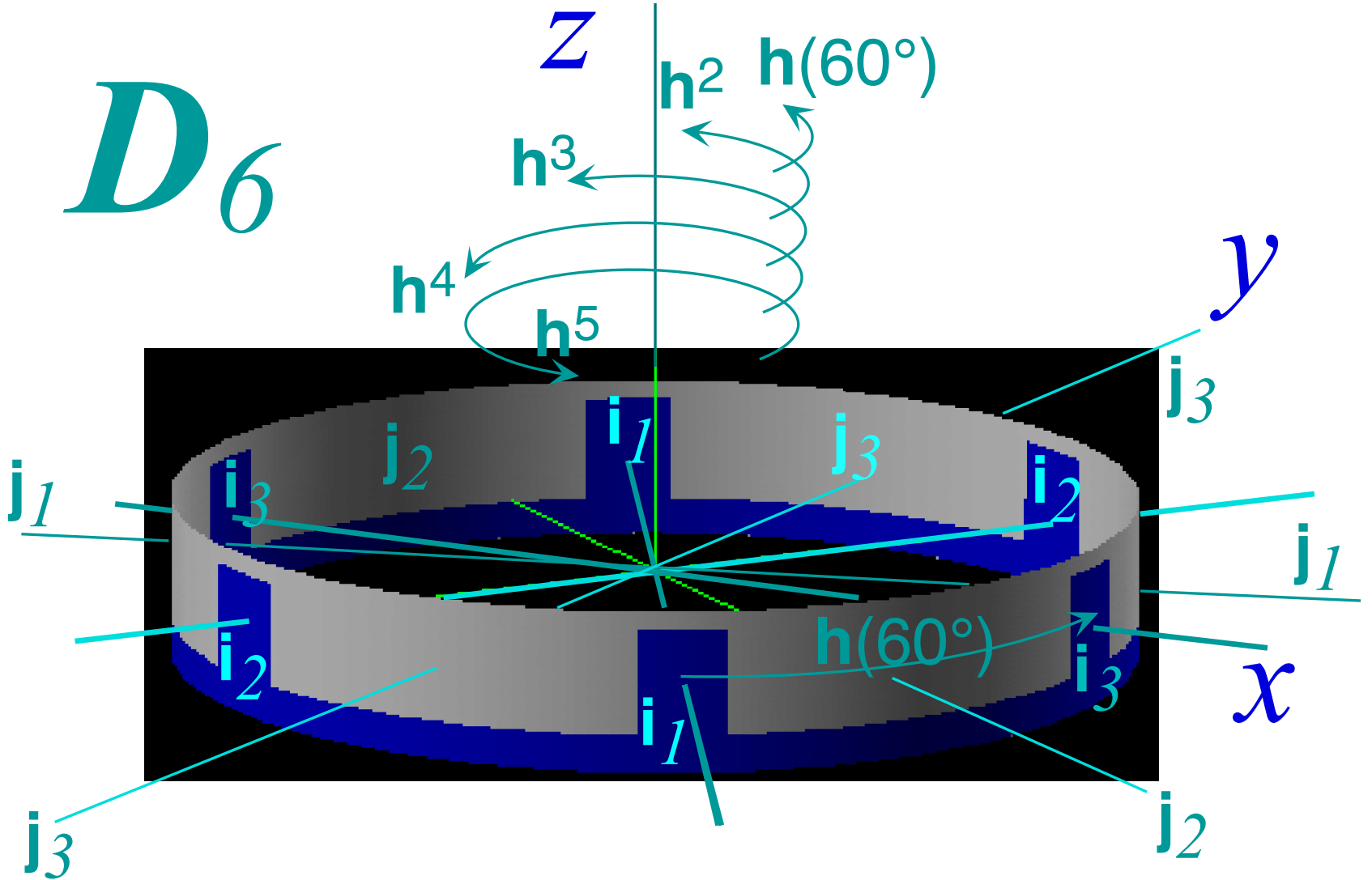
Note: $\mathbf{h}^2 = \mathbf{r}$ and $\mathbf{h}^3 = \mathbf{R}_z$ and $\mathbf{h}^4 = \mathbf{r}^2$ and $\mathbf{h}^5 = \mathbf{r} \cdot \mathbf{R}_z$



NOTE:
The \mathbf{i}_a and \mathbf{j}_b do not flip over the potential plot.



D_6



Electrostatic potential $V(\phi)$ doesn't care which way is "up." Wells remain wells, and barriers remain barriers under all D_6 operations.

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands



Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example

U(12)-Supersymmetry

Hexagonal chains: $D_{6h} \supset D_6 \supset D_3 \supset C_2$ or $D_{6h} \supset D_{2h} \supset D_2$ label 6-fold bands

Recall $C_2 \times C_2 = D_2$ characters made of two C_2 groups (Lecture 10 p.26)

$$\begin{array}{c|cc} C_2^x & \mathbf{1} & \mathbf{R}_x \\ \hline + & 1 & 1 \\ - & 1 & -1 \end{array} \times \begin{array}{c|cc} C_2^y & \mathbf{1} & \mathbf{R}_y \\ \hline + & 1 & 1 \\ - & 1 & -1 \end{array}$$

$$= \begin{array}{c|cccc} C_2^x \times C_2^y & \mathbf{1} \cdot \mathbf{1} & \mathbf{R}_x \cdot \mathbf{1} & \mathbf{1} \cdot \mathbf{R}_y & \mathbf{R}_x \cdot \mathbf{R}_y \\ \hline + \cdot + & 1 \cdot 1 & 1 \cdot 1 & 1 \cdot 1 & 1 \cdot 1 \\ - \cdot + & 1 \cdot 1 & -1 \cdot 1 & 1 \cdot 1 & -1 \cdot 1 \\ + \cdot - & 1 \cdot 1 & 1 \cdot 1 & 1 \cdot (-1) & 1 \cdot (-1) \\ - \cdot - & 1 \cdot 1 & -1 \cdot 1 & 1 \cdot (-1) & -1 \cdot (-1) \end{array}$$

$$= \begin{array}{c|cccc} D_2 & \mathbf{1} & \mathbf{R}_x & \mathbf{R}_y & \mathbf{R}_z \\ \hline ++ = A_1 & 1 & 1 & 1 & 1 \\ -+ = A_2 & 1 & -1 & 1 & -1 \\ +- = B_1 & 1 & 1 & -1 & -1 \\ -- = B_2 & 1 & -1 & -1 & 1 \end{array}$$

↑ Note
common
notation

Recall $C_2 \times C_2 = D_2$ characters made of two C_2 groups (Lecture 10 p.26)

C_2^x	1	R_x		
+	1	1		
-	1	-1		

 \times

C_2^y	1	R_y		
+	1	1		
-	1	-1		

$C_2^x \times C_2^y$	1·1	$R_x \cdot 1$	$1 \cdot R_y$	$R_x \cdot R_y$
++	1·1	1·1	1·1	1·1
-·+	1·1	-1·1	1·1	-1·1
+·-	1·1	1·1	1·(-1)	1·(-1)
-·-	1·1	-1·1	1·(-1)	-1·(-1)

D_2	1	R_x	R_y	R_z
++ = A_1	1	1	1	1
-+ = A_2	1	-1	1	-1
+ - = B_1	1	1	-1	-1
-- = B_2	1	-1	-1	1

↑ Note
common
notation

$C_2 \times C_3 = C_6$ characters Lect.3 p36
Here made of $C_2 \times C_3$ Cartesian product

C_2^x	1	ρ				
0_2	1	1				
1_2	1	-1				

 \times

C_3^y	1	r^1	r^2			
0_3	1	1	1			
1_3	1	ϵ	ϵ^*			
2_3	1	ϵ^*	ϵ			

$C_2^x \times C_3^y$	1·1	$1 \cdot r^1$	$1 \cdot r^2$	$\rho \cdot 1$	$\rho \cdot r^1$	$\rho \cdot r^2$
$0_2 \cdot 0_3$	1·1	1·1	1·1	1·1	1·1	1·1
$0_2 \cdot 1_3$	1·1	1· ϵ	1· ϵ^*	1·1	1· ϵ	1· ϵ^*
$0_2 \cdot 2_3$	1·1	1· ϵ^*	1· ϵ	1·1	1· ϵ^*	1· ϵ
$1_2 \cdot 0_3$	1·1	1·1	1·1	-1·1	-1·1	-1·1
$1_2 \cdot 1_3$	1·1	1· ϵ	1· ϵ^*	-1·1	-1· ϵ	-1· ϵ^*
$1_2 \cdot 2_3$	1·1	1· ϵ^*	1· ϵ	-1·1	-1· ϵ^*	-1· ϵ

C_6^{xy}	0°	120°	240°	180°	-60°	60°
0_6	1·1	1·1	1·1	1·1	1·1	1·1
2_6	1·1	1· ϵ	1· ϵ^*	1·1	1· ϵ	1· ϵ^*
4_6	1·1	1· ϵ^*	1· ϵ	1·1	1· ϵ^*	1· ϵ
3_6	1·1	1·1	1·1	-1·1	-1·1	-1·1
5_6	1·1	1· ϵ	1· ϵ^*	-1·1	-1· ϵ	-1· ϵ^*
1_6	1·1	1· ϵ^*	1· ϵ	-1·1	-1· ϵ^*	-1· ϵ

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters.

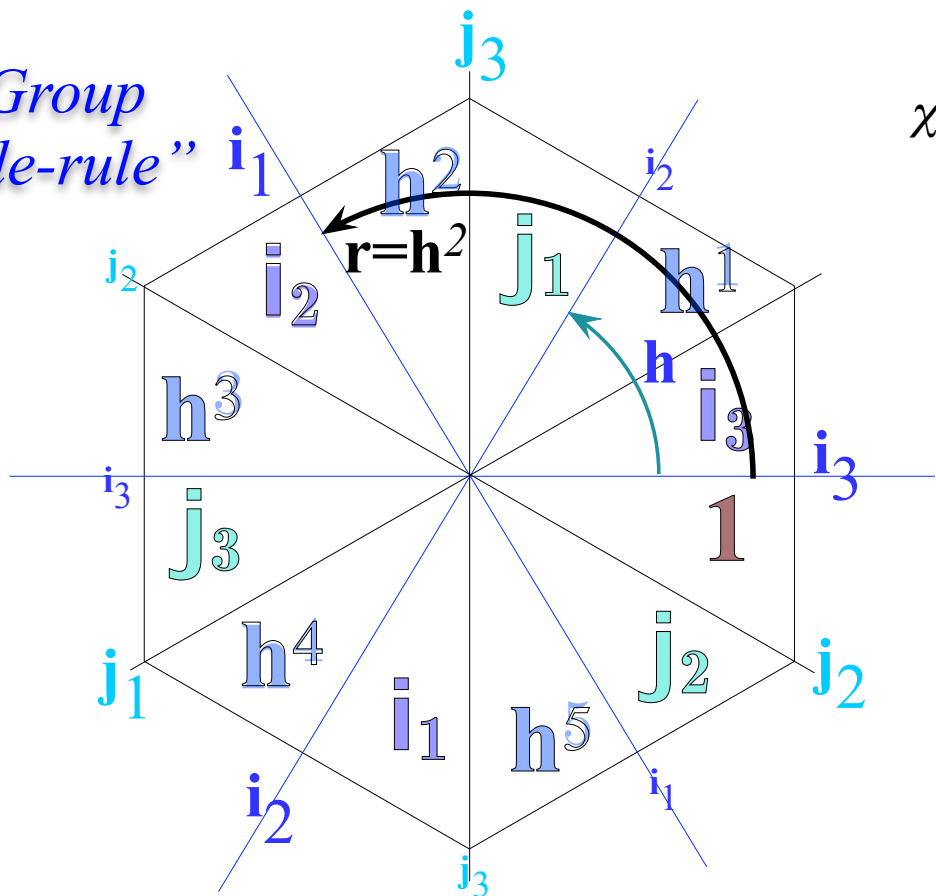
$$\begin{array}{c|ccc}
 D_3 & \mathbf{1} & \{r, r^2\} & \{i_1, i_2, i_3\} \\
 \hline
 \chi^{A_1}(\mathbf{g}) & 1 & 1 & 1 \\
 \chi^{A_2}(\mathbf{g}) & 1 & 1 & -1 \\
 \chi^{E_1}(\mathbf{g}) & 2 & -1 & 0
 \end{array}
 \times
 \begin{array}{c|cc}
 C_2^z & \mathbf{1} & \mathbf{R}_z \\
 \hline
 (A) & 1 & 1 \\
 (B) & 1 & -1
 \end{array}
 =$$

$D_3 \times C_2^z$	$\mathbf{1}$	$\{r, r^2\}$	$\{i_1, i_2, i_3\}$	$\mathbf{1} \cdot \mathbf{R}_z$	$\{r, r^2\} \cdot \mathbf{R}_z$	$\{i_1, i_2, i_3\} \cdot \mathbf{R}_z$
$A_1 \cdot (A)$	1·1	1·1	1·1	1·1	1·1	1·1
$A_2 \cdot (A)$	1·1	1·1	-1·1	1·1	1·1	-1·1
$E_2 \cdot (A)$	2·1	-1·1	0·1	2·1	-1·1	0·1
$A_1 \cdot (B)$	1·1	1·1	1·1	1·(-1)	1·(-1)	1·(-1)
$A_2 \cdot (B)$	1·1	1·1	-1·1	1·(-1)	1·(-1)	-1·(-1)
$E_1 \cdot (B)$	2·1	-1·1	0·1	2·(-1)	-1·(-1)	0·(-1)

$D_3 \times C_2^z$	$\mathbf{1}$	$\{h^2, h^4\}$	$\{i_1, i_2, i_3\}$	h^3	$\{h, h^5\}$	$\{j_1, j_2, j_3\}$
A_1	1	1	1	1	1	1
A_2	1	1	-1	1	1	-1
E_2	2	-1	0	2	-1	0
B_2	1	1	1	-1	-1	-1
B_1	1	1	-1	-1	-1	1
E_1	2	-1	0	-2	1	0

$$\chi_g^\mu(D_6) =$$

D_6 Group
"slide-rule"



Unit translation
or
60° hex rotation h
determines
 A_p vs B_p
(+1) vs (-1)

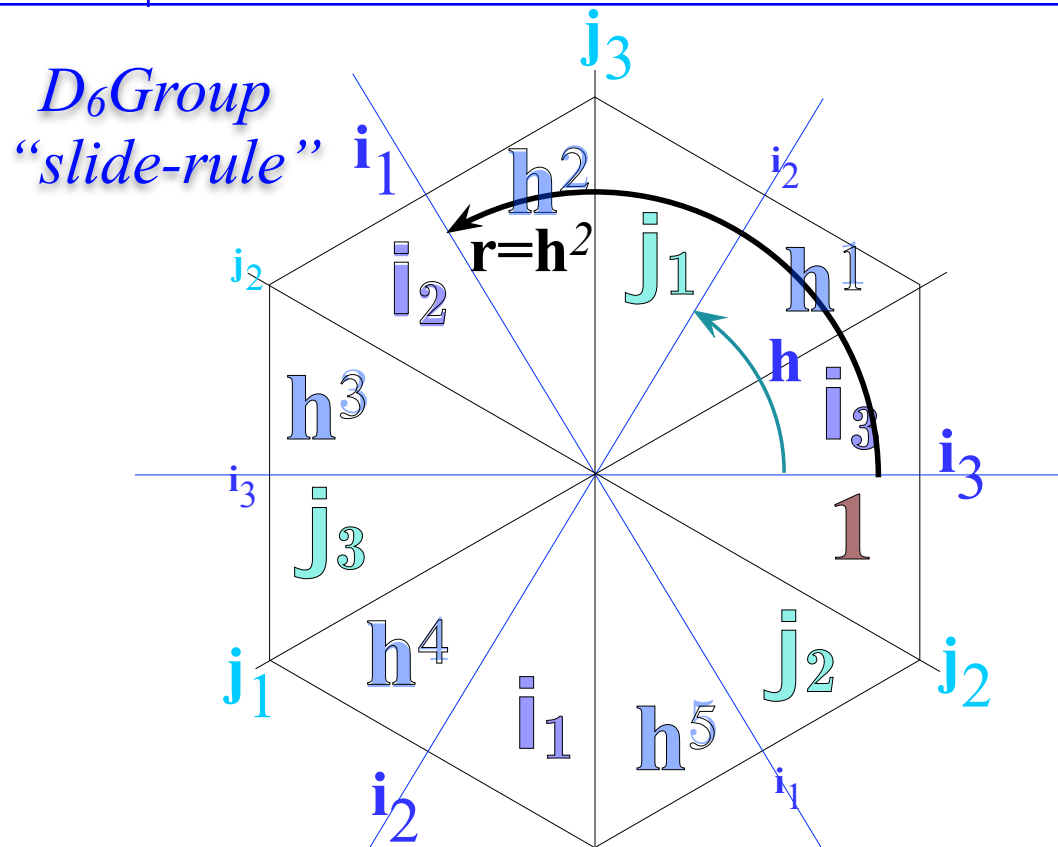
Odd vs Even
Y-rotation
or
180° flip j_3
determines
 X_1 vs X_2
(+1) vs (-1)

"Always-the-same vs Back-and-forth"

Recall $C_2 \times C_2 = D_2$ characters made of two C_2 groups (Lecture 10 p.26)

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters.

$g =$	0°	z 120°	z -120°	180°	x 180°	z 180°	z -60°	z $+60^\circ$	180°	180°	y 180°	
$g =$	1	$r=h^2$	$r^2=h^4$	i_1	i_2	i_3	h^3	$h^3r=h^5$	$h^3r^2=h^1$	$h^3i_1=j_1$	$h^3i_2=j_2$	$h^3i_3=j_3$
$D^{A_1}(g) =$	1	1	1	1	1	1	1	1	1	1	1	1
$D^{A_2}(g) =$	1	1	1	-1	-1	-1	1	1	1	-1	-1	-1
$D^{E_2}(g) =$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$
$D^{B_2}(g) =$	1	1	1	1	1	1	-1	-1	-1	-1	-1	-1
$D^{B_1}(g) =$	1	1	1	-1	-1	-1	-1	-1	-1	1	1	1
$D^{E_1}(g) =$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & \sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & -\sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$



Unit translation
or
60° hex rotation h
determines
 A_p vs B_p
(+1) vs (-1)

Y -rotation
or
180° flip j_3
determines
 X_1 vs X_2
(+1) vs (-1)

“Always-the-same vs Back-and-forth”

Odd vs Even

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters.

	0°	z 120°	z -120°	180°	180°	x 180°	z 180°	z -60°	z $+60^\circ$	180°	180°	y 180°
$g =$	1	$r=h^2$	$r^2=h^4$	i_1	i_2	i_3	h^3	$h^3r=h^5$	$h^3r^2=h^1$	$h^3i_1=j_1$	$h^3i_2=j_2$	$h^3i_3=j_3$
$D^{A_1}(g) =$	1	1	1	1	1	1	1	1	1	1	1	1
$D^{A_2}(g) =$	1	1	1	-1	-1	-1	1	1	1	-1	-1	-1
$D^{E_2}(g) =$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$
$D^{B_2}(g) =$	1	1	1	1	1	1	-1	-1	-1	-1	-1	-1
$D^{B_1}(g) =$	1	1	1	-1	-1	-1	-1	-1	-1	1	1	1
$D^{E_1}(g) =$	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & \sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}$	$\begin{pmatrix} 1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} 1 & -\sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}$	$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

Unit translation
or
60° hex rotation h
determines
 A_p vs B_p
(+1) vs (-1)

Y-rotation
or
180° flip j_3
determines
 X_1 vs X_2
(+1) vs (-1)

$D_6 \supset C_2(j_3)$	0_2	1_2
A_1	1	·
A_2	·	1
E_2	1	1
B_2	·	1
B_1	1	·
E_1	1	1

$D_6 \supset C_6(h)$	0_6	1_6	2_6	3_6	4_6	5_6
A_1	1	·	·	·	·	·
A_2	1	·	·	·	·	·
E_2	·	·	1	·	1	·
B_2	·	·	·	1	·	·
B_1	·	·	·	1	·	·
E_1	·	1	·	·	·	1

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

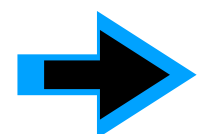
Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps



D_6 Band structure and related Global vs Local induced representations,

D_4 example

$U(12)$ -Supersymmetry

D_6 Band structure and related Global vs Local induced representations
 High above low barriers $D_6 \supset C_6$ global symmetry rules

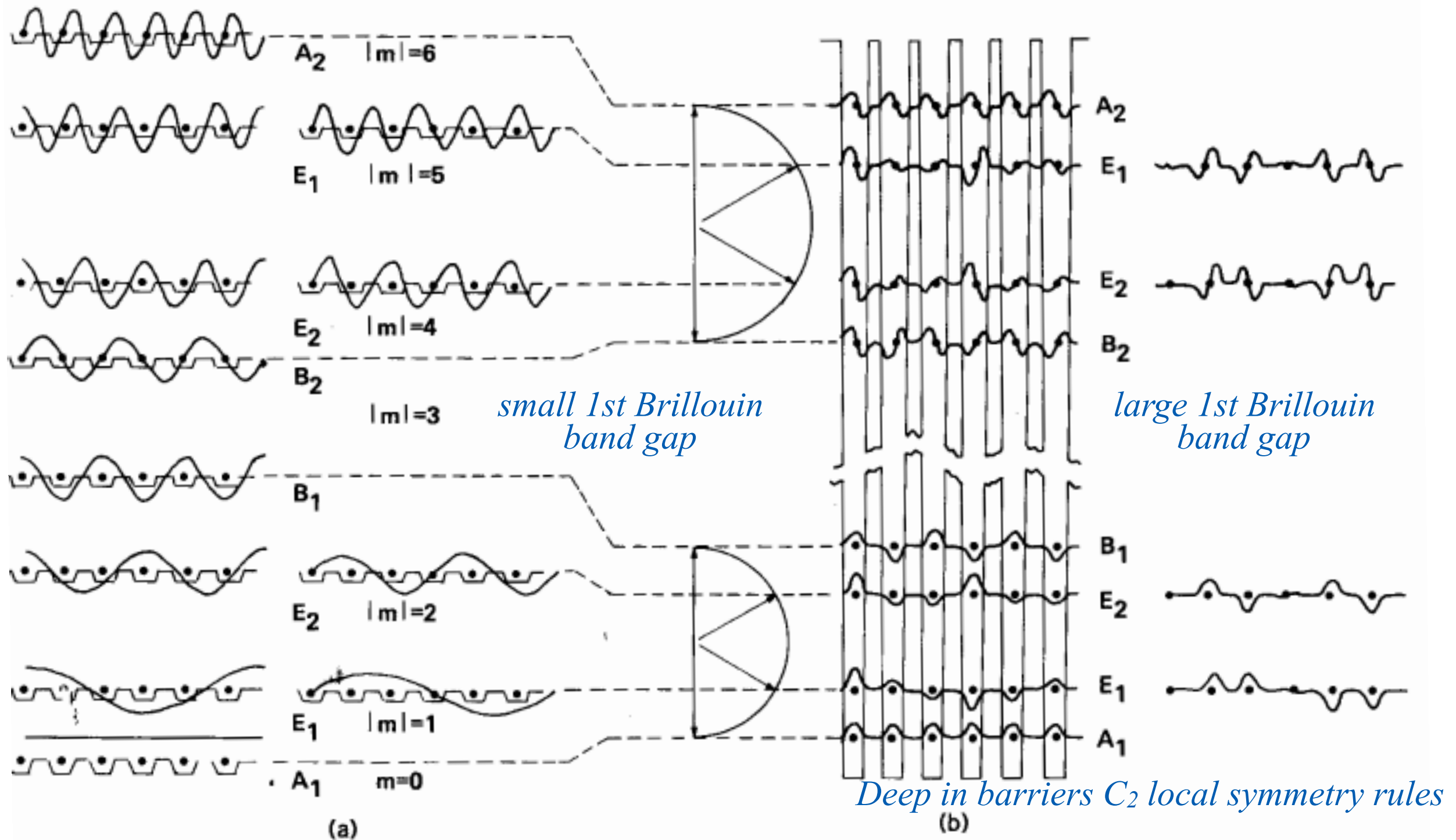
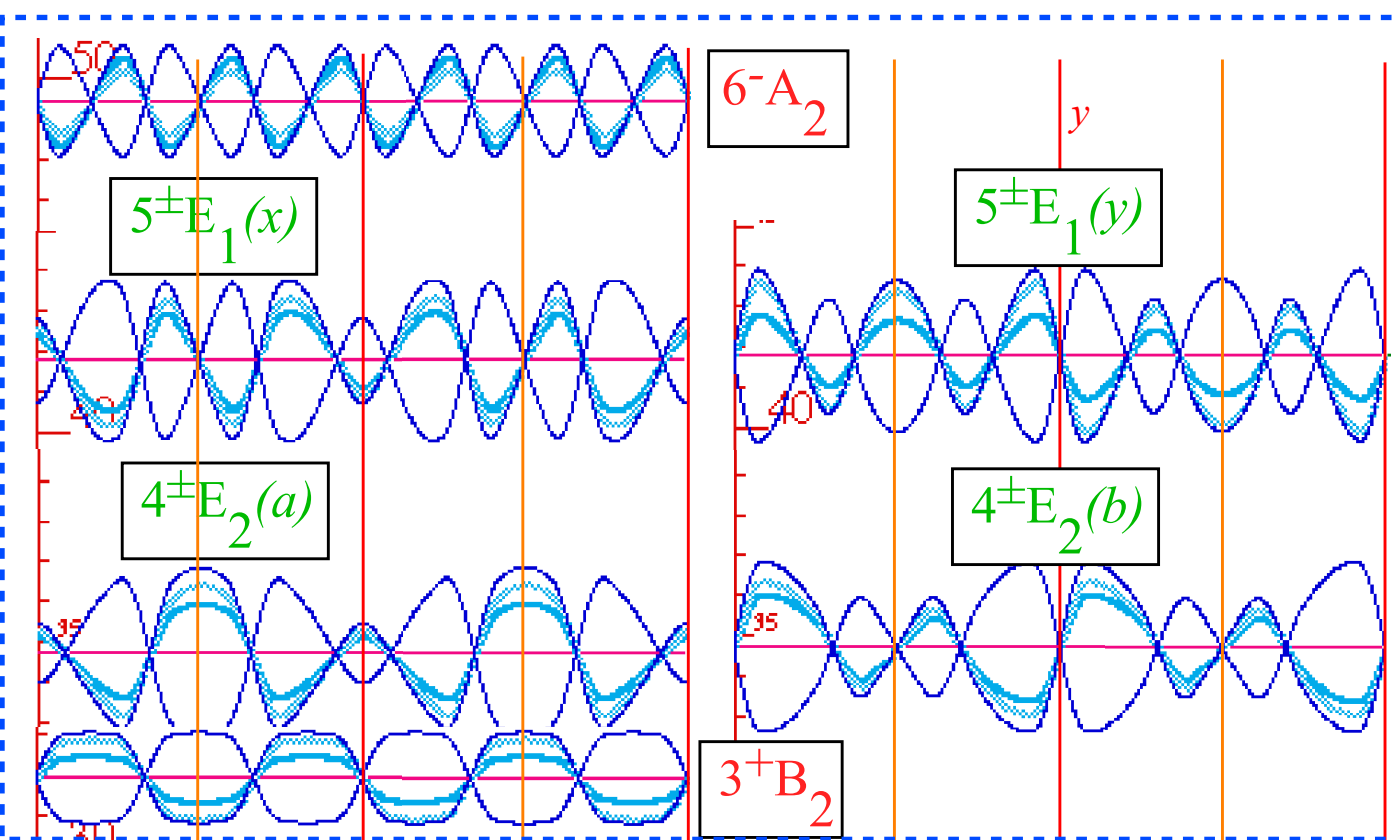


Figure 3.6.5 One-dimensional Bohr and Bloch waves in D_6 symmetry. (a) Weak D_6 potential. (b) Strong D_6 potential.

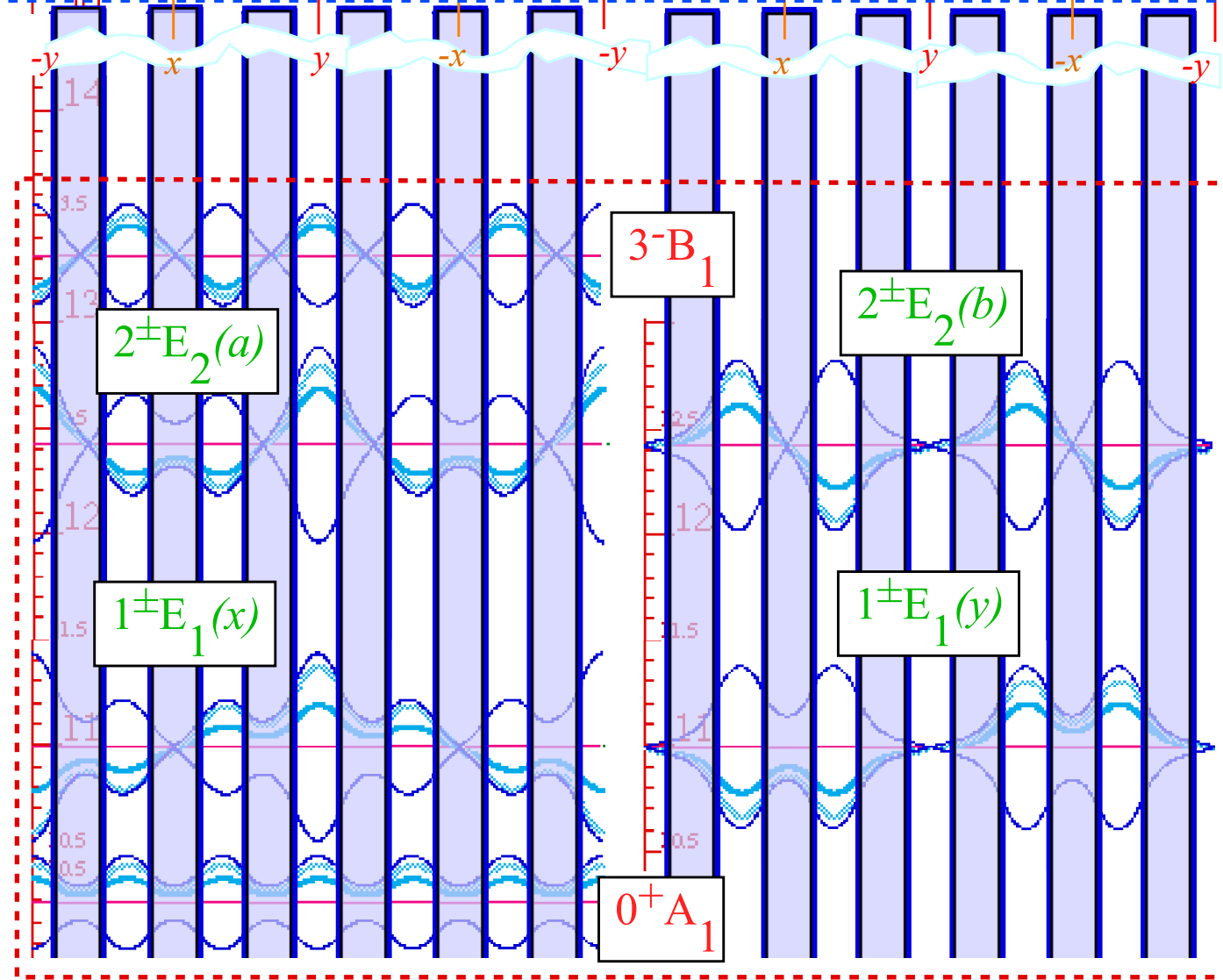
D_6
Band structure
and related
Global vs Local
induced
representations
(BohrIt Mac OS-9)



Low barrier $\rightarrow D_6$ global symm.
 m_6 still valid quantum number

$D_6 \supset C_6(h)$	0_6	1_6	2_6	3_6	4_6	5_6
A_1	1	·	·	·	·	·
A_2	1	·	·	·	·	·
E_2	·	·	1	·	1	·
B_2	·	·	·	1	·	·
B_1	·	·	·	1	·	·
E_1	·	1	·	·	·	1

D_6
Band structure
QTCA
Unit 5
p96



$1_2 \uparrow D_6 \sim A_2 \oplus E_2 \oplus E_1 \oplus B_2$
Odd Band or Cluster

$0_2 \uparrow D_6 \sim A_1 \oplus E_1 \oplus E_2 \oplus B_1$
Even Band or Cluster

$D_6 \supset C_2(j_3)$	0_2	1_2
A_1	1	·
A_2	·	1
E_2	1	1
B_2	·	1
B_1	1	·
E_1	1	1

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

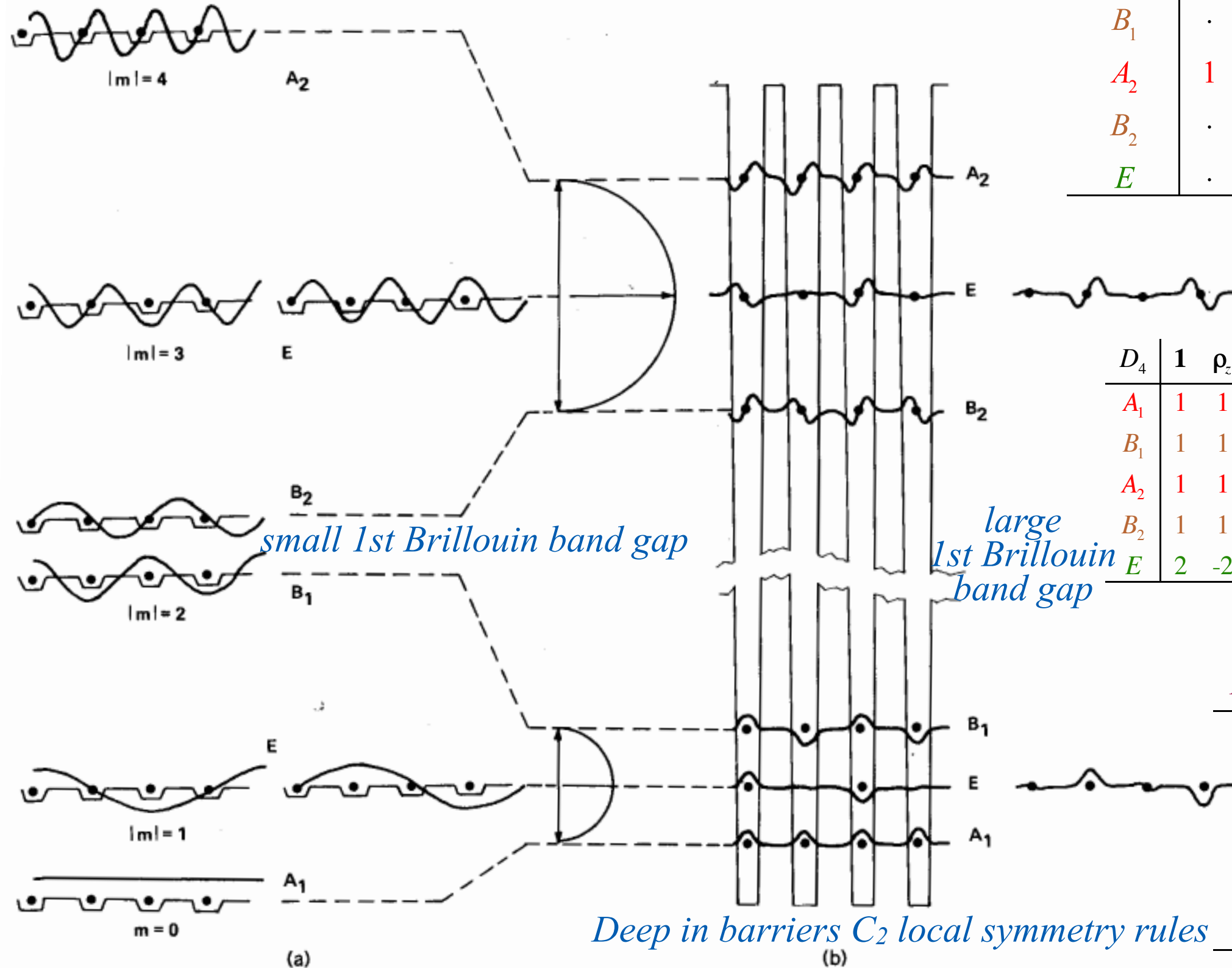
D_6 Band structure and related Global vs Local induced representations,  D_4 example

$U(12)$ -Supersymmetry

D_4 : Simplest example of ring-lattice band structure and symmetry

High above low barriers $D_4 \supset C_4$ global symmetry rules

$D_4 \downarrow C_4$	0_4	1_4	2_4	-1_4
A_1	1	·	·	·
B_1	·	·	1	·
A_2	1	·	·	·
B_2	·	·	1	·
E	·	1	·	1



D_4	1	ρ_z	R_z	$\rho_{x,y}$	$i_{3,4}$
A_1	1	1	1	1	1
B_1	1	1	-1	1	-1
A_2	1	1	1	-1	-1
B_2	1	1	-1	-1	1
E	2	-2	0	0	0

$D_4 \downarrow C_2$	0_2	1_2
A_1	1	·
B_1	·	1
A_2	1	·
B_2	·	1
E	1	1

Figure 3.6.2 One-dimensional Bohr and Bloch waves in D_4 symmetry. (a) Weak D_4 potential. (b) Strong D_4 potential.

D_4 Mol-vibe
band-analog
animation

?

PSDS Ch.3 p 45.

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

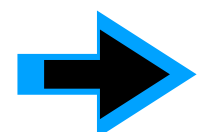
Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps



D_6 Band structure and related Global vs Local induced representations,

D_4 example

$U(12)$ -Supersymmetry

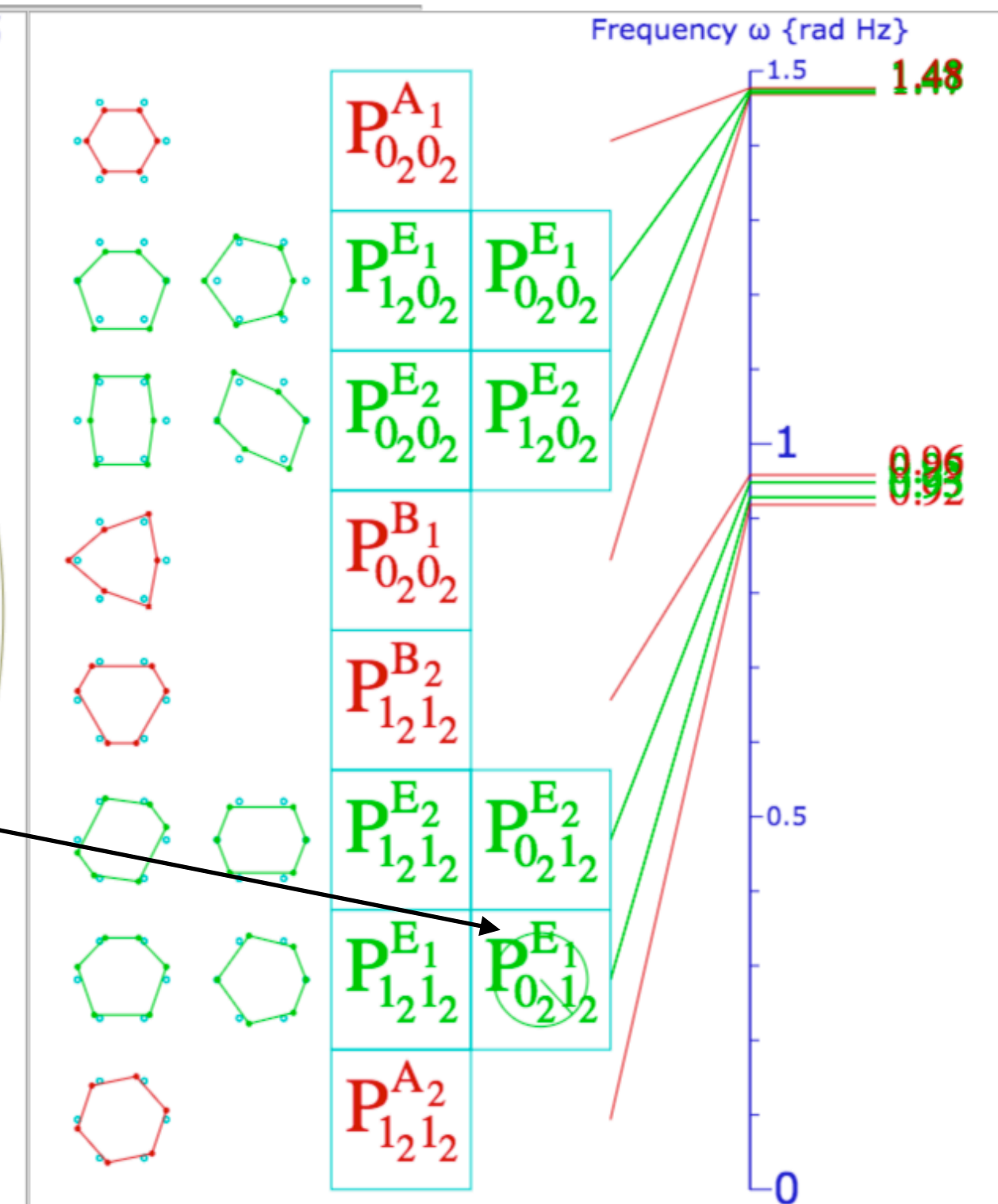
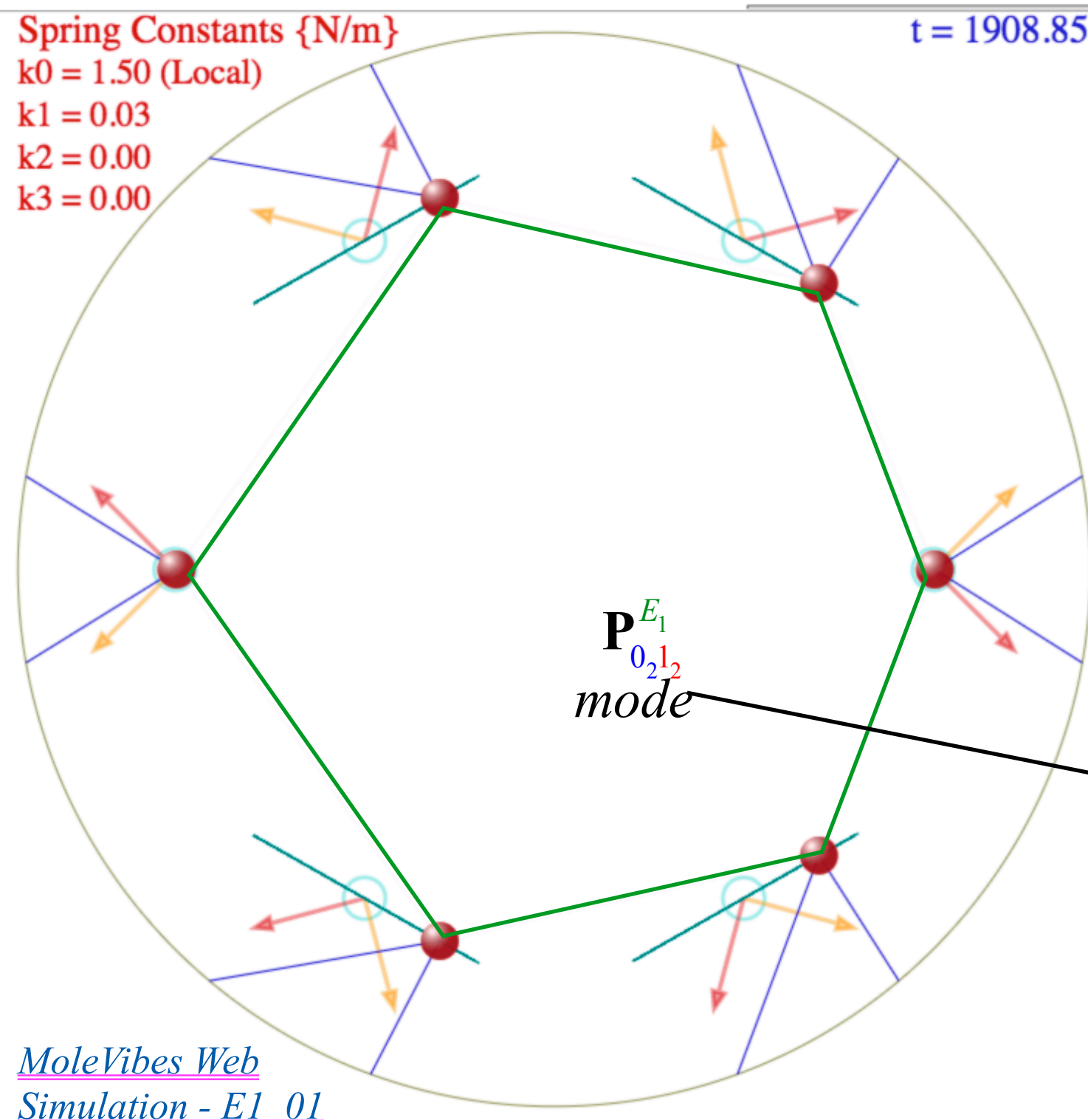
D_6 Band structure and related induced representations (Web MolVibes)

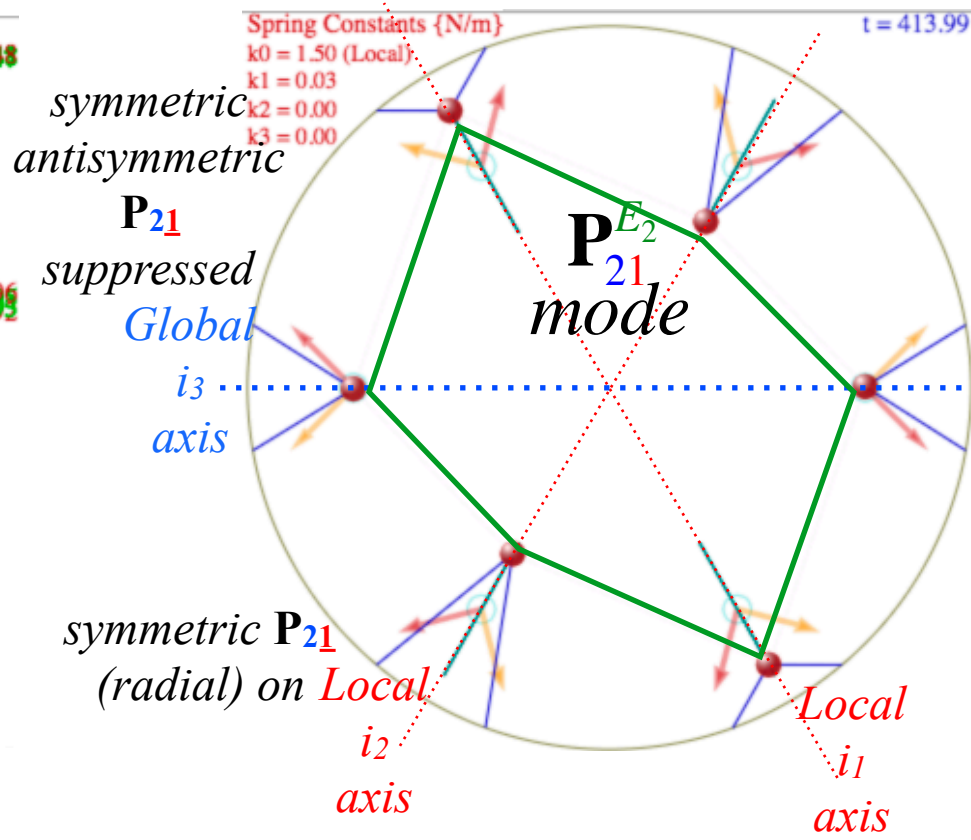
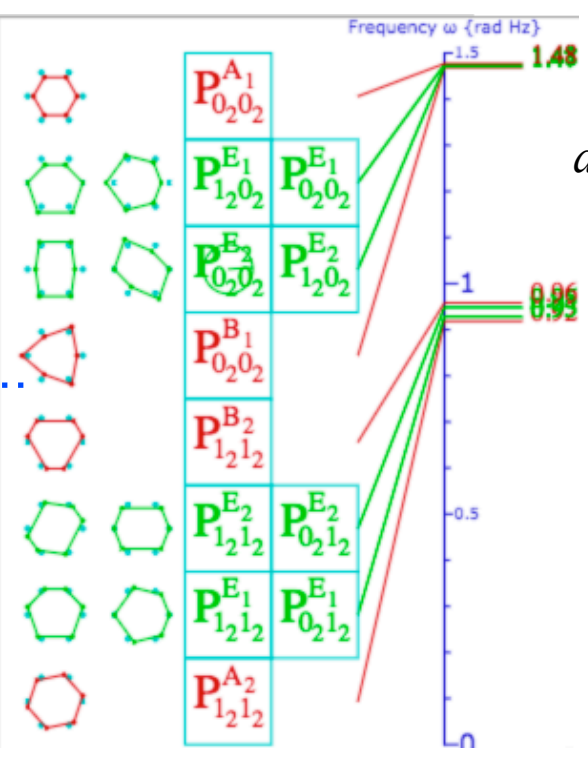
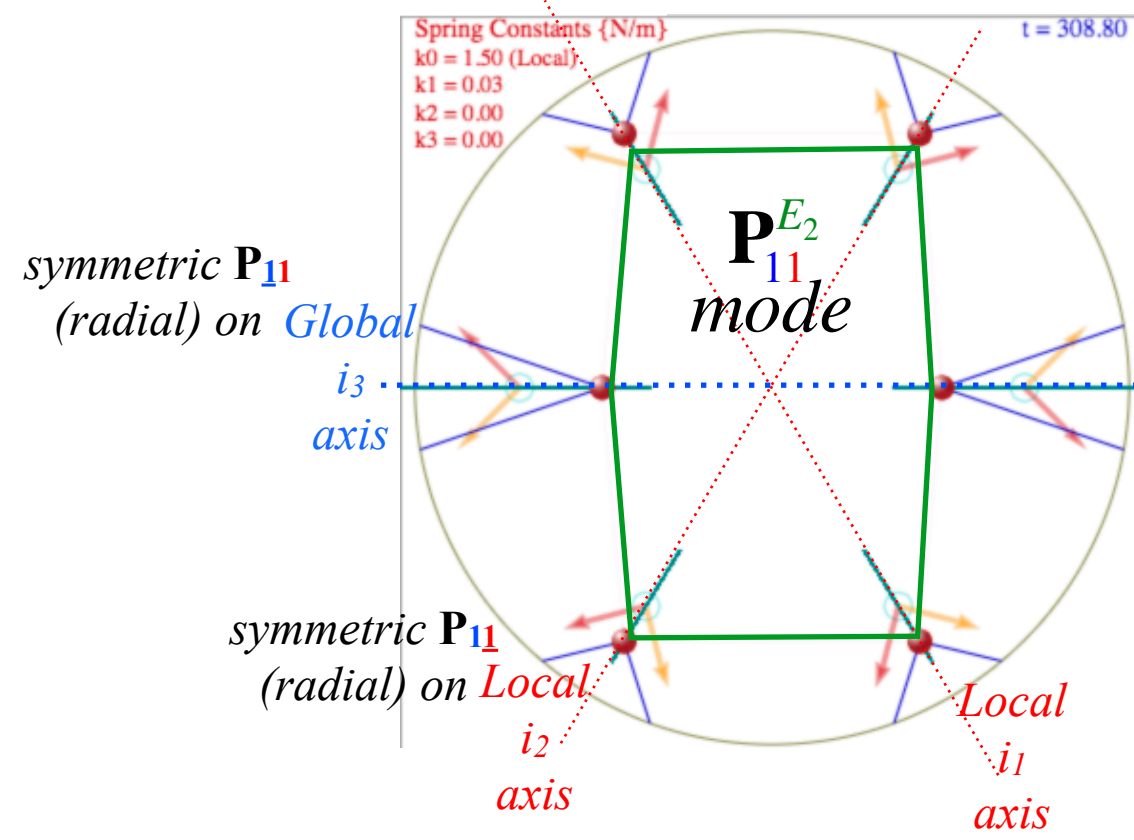
The testing config:
http://www.uark.edu/ua/modphys/markup/MolVibesWeb.html?scenario=C6vN6_Testing

www.uark.edu/ua/modphys/markup/MolVibesWeb.html?scenario=C6vN6_Testing

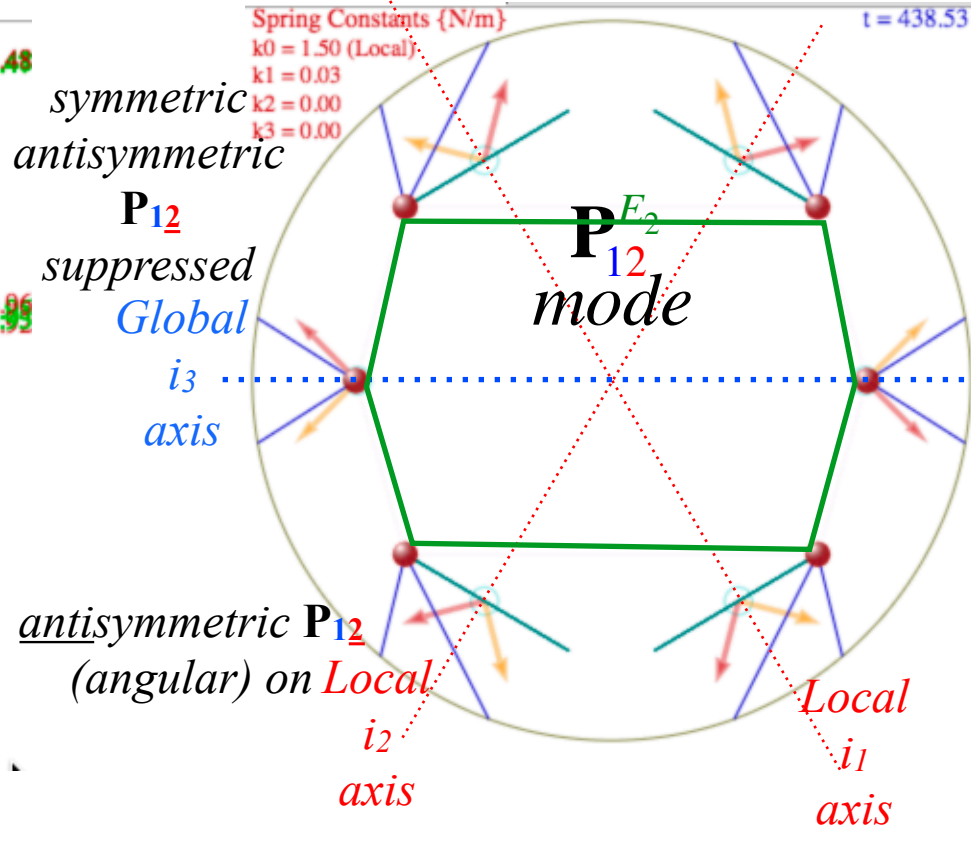
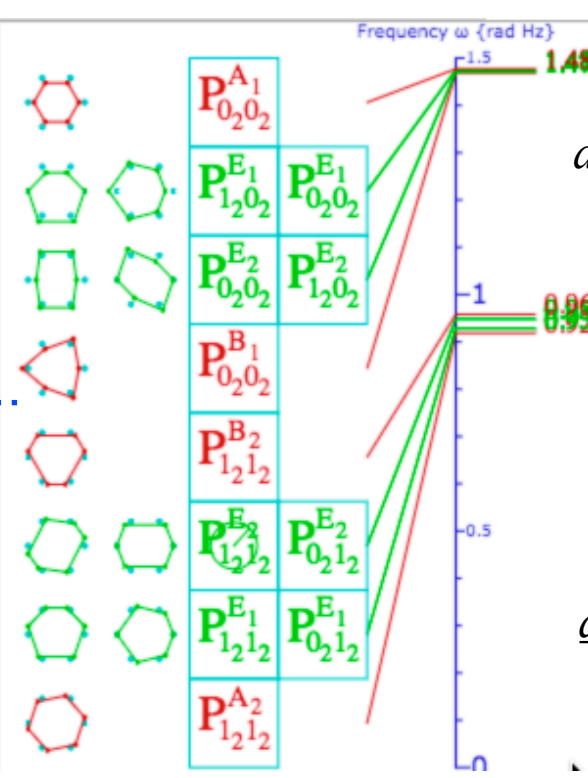
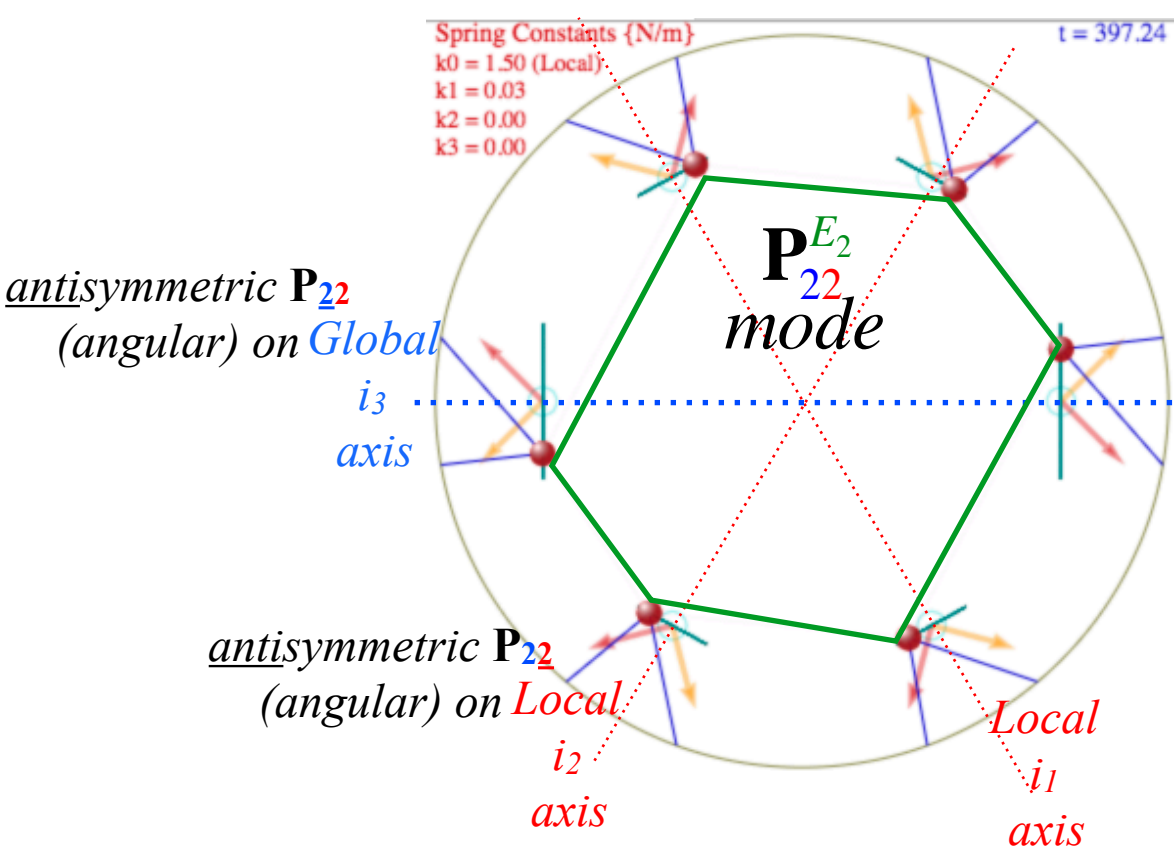
Most Visited Getting Started Harter-Soft Bohrlt Relativt RelaWavity ISIS MaleOutlook

Local Control Scenarios Resume Set T=0 Zero Amps Erase $\Delta T = 0.025$





[MoleVibes Web](#)
 Simulation - E2_00



[MoleVibes Web](#)
 Simulation - E2_11

2.26.18 class 14.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Discrete symmetry subgroups of $O(3)$ using Mock-Mach principle: $D_3 \sim C_{3v}$ LAB vs BOD
Vibrational eigensolutions, $D_6 \sim C_{6v}$ bands, subgroup correlation, and Frobenius reciprocity

Review: *H-matrix Global vs Local symmetry*

Molecular vibration K-matrix symmetry analogous to quantum H-matrix

Molecular K-matrix construction

$D_3 \supset C_2(i_3)$ local-symmetry K-matrix eigensolutions

D_3 -direct-connection K-matrix eigenstates mix local symmetry

$D_3 \supset C_3(\mathbf{r}^{\pm 1})$ moving-wave local symmetry K-matrix “Coriolis” eigensolutions

Applied symmetry reduction and splitting

Subduced irep $D^\alpha(D^3) \downarrow C_2 = d^{0_2} \oplus d^{1_2} \oplus \dots$ correlation

Subduced irep $D^\alpha(D^3) \downarrow C_3 = d^{0_3} \oplus d^{1_3} \oplus \dots$ correlation

Spontaneous symmetry breaking and clustering: Frobenius Reciprocity and band structure

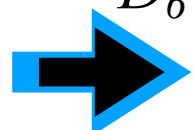
Induced rep $d^a(C_2) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

Induced rep $d^a(C_3) \uparrow D^3 = D^\alpha \oplus D^\beta \oplus \dots$ correlation

D_6 symmetry and Hexagonal Bands

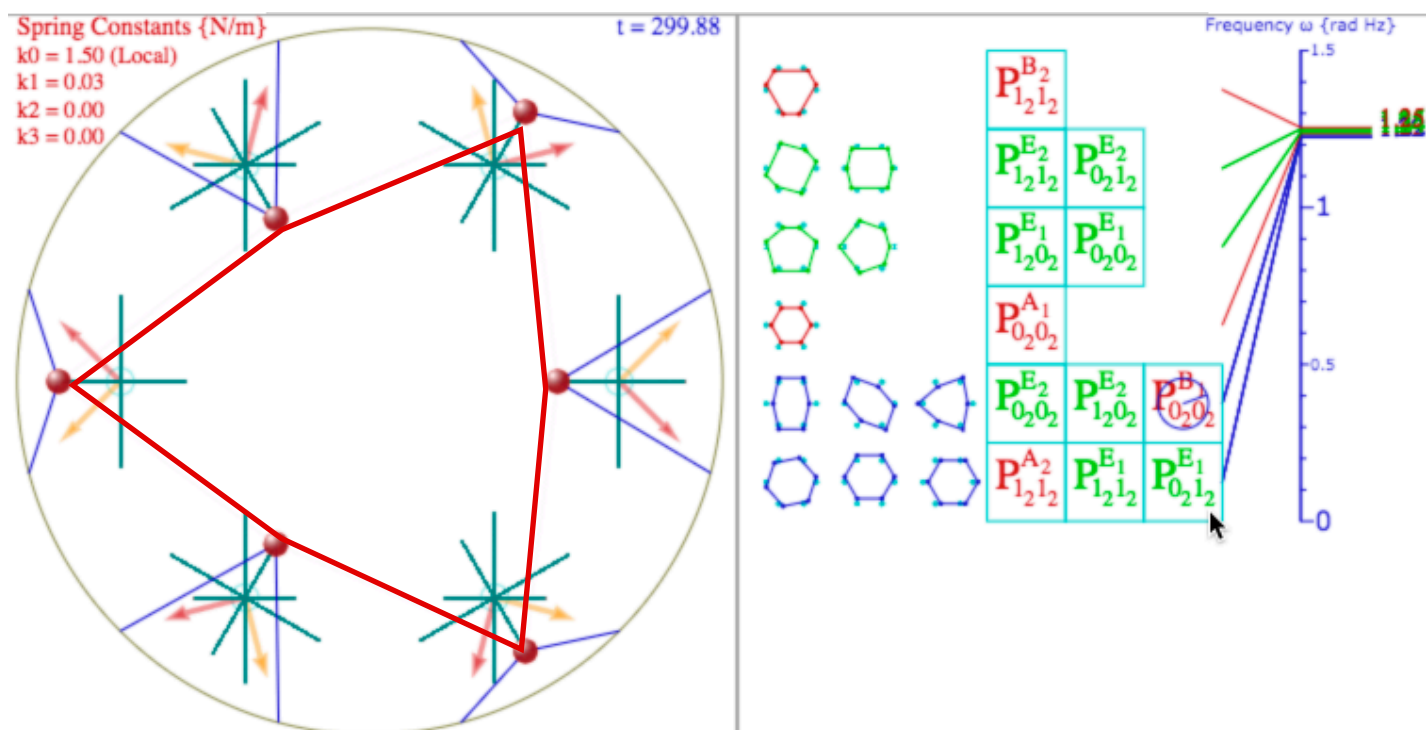
Cross product of the C_2 and D_3 characters gives all $D_6 = D_3 \times C_2$ characters and ireps

D_6 Band structure and related Global vs Local induced representations, D_4 example



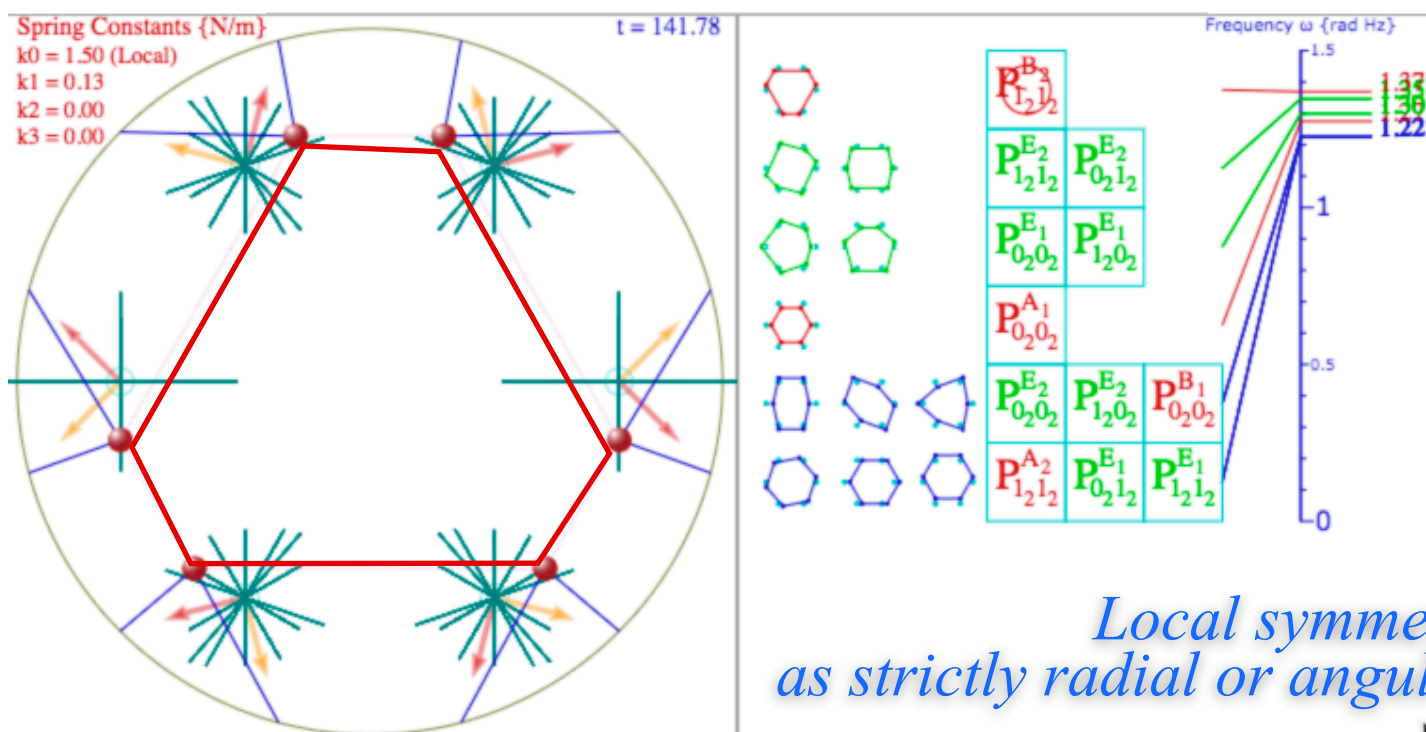
U(12)-Supersymmetry

*U(12)-Supersymmetry: When D_6 Band structure approaches single 12-fold degeneracy
Setting mutually orthogonal external k_0 connection springs (and tiny k_1, k_2, \dots coupling)*



*U(12)-Supersymmetry
QTCA Unit5 p89*

Even moderate k_1 coupling lifts a band of single-doublet-doublet-singlet above 6-fold degenerate sextet



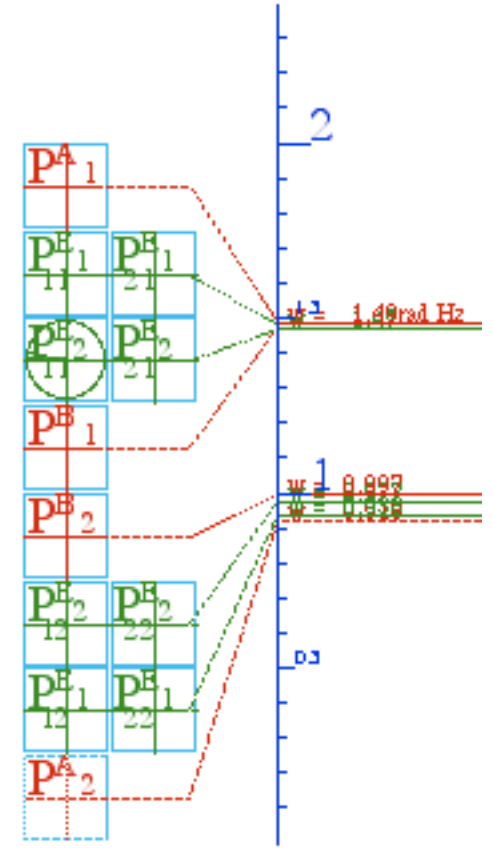
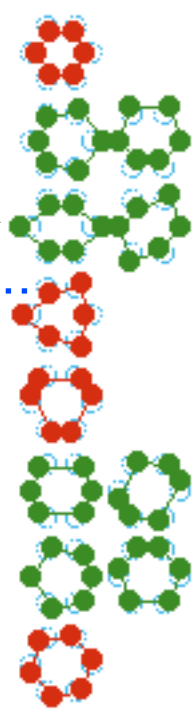
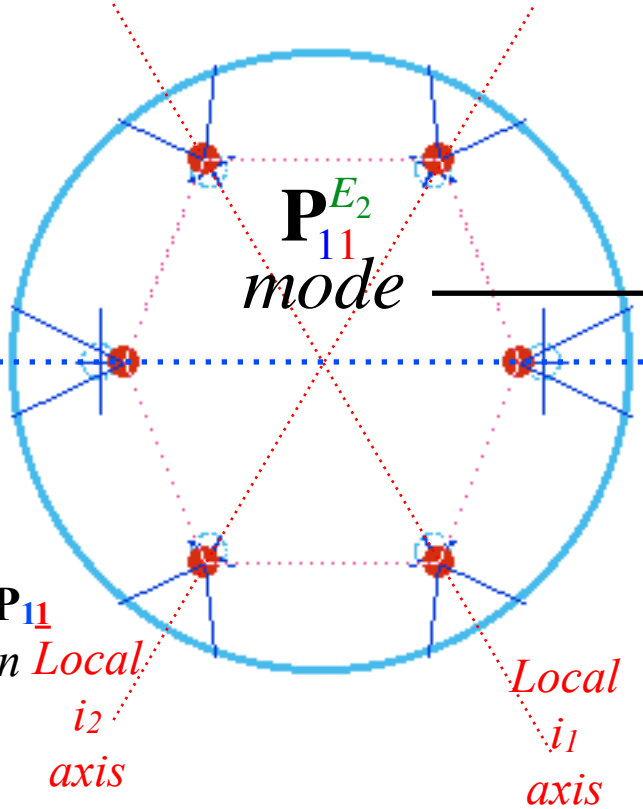
*Local symmetry-asymmetry is well broken
as strictly radial or angular paths are avoided by masses off x-axis*

D_6 Band structure and related induced representations (Mac OS-9)

Local $k_0 = 1.5 \text{ N/m}$
 $k_1 = 0.05 \text{ N/m}$
 $k_2 = 0 \text{ N/m}$

symmetric \mathbf{P}_{11}
 (radial) on *Global*
 i_3
 axis

symmetric \mathbf{P}_{11}
 (radial) on *Local*
 i_2
 axis



antisymmetric \mathbf{P}_{22}
 (angular) on *Global*
 i_3
 axis

antisymmetric \mathbf{P}_{22}
 (angular) on *Local*
 i_2
 axis

