

2.12.18 class 9.0: Symmetry Principles for Advanced Atomic-Molecular-Optical-Physics

William G. Harter - University of Arkansas

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ *p*-waves

$D^{L=2}_{m0} \sim Y^2_m$ *d*-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RE or RES) of asymmetric rotor (for following class)

AMOP reference links (Updated list given on 2nd page of each class presentation)

[Web Resources - front page](#)
[UAF Physics UTube channel](#)

[2014 AMOP](#)
[2017 Group Theory for QM](#)
[2018 AMOP](#)

[Frame Transformation Relations And Multipole Transitions In Symmetric Polyatomic Molecules - RMP-1978 \(Alt Scanned version\)](#)
[Rotational energy surfaces and high- J eigenvalue structure of polyatomic molecules - Harter - Patterson - 1984](#)
[Galloping waves and their relativistic properties - aip-1985-Harter](#)
[Asymptotic eigensolutions of fourth and sixth rank octahedral tensor operators - Harter-Patterson-JMP-1979](#)
[Nuclear spin weights and gas phase spectral structure of 12C₆₀ and 13C₆₀ buckminsterfullerene -Harter-Reimer-Cpl-1992 - \(Alt1, Alt2 Erratum\)](#)

Theory of hyperfine and superfine levels in symmetric polyatomic molecules.

- I) [Trigonal and tetrahedral molecules: Elementary spin-1/2 cases in vibronic ground states - PRA-1979-Harter-Patterson \(Alt scan\)](#)
- II) [Elementary cases in octahedral hexafluoride molecules - Harter-PRA-1981 \(Alt scan\)](#)

[Rotation-vibration scalar coupling zeta coefficients and spectroscopic band shapes of buckminsterfullerene - Weeks-Harter-CPL-1991 \(Alt scan\)](#)
[Fullerene symmetry reduction and rotational level fine structure/ the Buckyball isotopomer 12C 13C₅₉ - jcp-Reimer-Harter-1997 \(HiRez\)](#)
[Molecular Eigensolution Symmetry Analysis and Fine Structure - IJMS-harter-mitchell-2013](#)

Rotation-vibration spectra of icosahedral molecules.

- I) [Icosahedral symmetry analysis and fine structure - harter-weeks-jcp-1989](#)
- II) [Icosahedral symmetry, vibrational eigenfrequencies, and normal modes of buckminsterfullerene - weeks-harter-jcp-1989](#)
- III) [Half-integral angular momentum - harter-reimer-jcp-1991](#)

[QTCA Unit 10 Ch 30 - 2013](#)

[AMOP Ch 32 Molecular Symmetry and Dynamics - 2019](#)

[AMOP Ch 0 Space-Time Symmetry - 2019](#)

RESONANCE AND REVIVALS

- I) [QUANTUM ROTOR AND INFINITE-WELL DYNAMICS - ISMSLi2012 \(Talk\) OSU knowledge Bank](#)
- II) [Comparing Half-integer Spin and Integer Spin - Alva-ISMS-Ohio2013-R777 \(Talks\)](#)
- III) [Quantum Resonant Beats and Revivals in the Morse Oscillators and Rotors - \(2013-Li-Diss\)](#)

[Rovibrational Spectral Fine Structure Of Icosahedral Molecules - Cpl 1986 \(Alt Scan\)](#)

[Gas Phase Level Structure of C₆₀ Buckyball and Derivatives Exhibiting Broken Icosahedral Symmetry - reimer-diss-1996](#)

[Resonance and Revivals in Quantum Rotors - Comparing Half-integer Spin and Integer Spin - Alva-ISMS-Ohio2013-R777 \(Talk\)](#)

[Quantum Revivals of Morse Oscillators and Farey-Ford Geometry - Li-Harter-cpl-2013](#)

[Wave Node Dynamics and Revival Symmetry in Quantum Rotors - harter - jms - 2001](#)

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

$$\mathbf{s}_+ = \mathbf{s}_X + i\mathbf{s}_Y$$

and

$$\mathbf{s}_- = \mathbf{s}_X - i\mathbf{s}_Y = \mathbf{s}_+^\dagger$$

[Review Class 8 p92](#)

Starting with $j=1/2$ we see that \mathbf{S}_+ is an *elementary projection operator* $\mathbf{e}_{12} = |1\rangle\langle 2| = \mathbf{P}_{12}$

$$\langle \mathbf{s}_+ \rangle^{\frac{1}{2}} = D^{\frac{1}{2}}(\mathbf{s}_+) = D^{\frac{1}{2}}(\mathbf{s}_X + i\mathbf{s}_Y) = \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{pmatrix} + i \begin{pmatrix} 0 & -\frac{i}{2} \\ \frac{i}{2} & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \mathbf{P}_{12}$$

Such operators can be upgraded to *creation-destruction operator* combinations $\mathbf{a}^\dagger \mathbf{a}$

$$\mathbf{s}_+ = \mathbf{a}_1^\dagger \mathbf{a}_2 = \mathbf{a}_\uparrow^\dagger \mathbf{a}_\downarrow , \quad \mathbf{s}_- = (\mathbf{a}_1^\dagger \mathbf{a}_2)^\dagger = \mathbf{a}_2^\dagger \mathbf{a}_1 = \mathbf{a}_\downarrow^\dagger \mathbf{a}_\uparrow$$

Hamilton-Pauli-Jordan representation of \mathbf{s}_Z is:

This suggests an $\mathbf{a}^\dagger \mathbf{a}$ form for \mathbf{s}_Z .

Let $\mathbf{a}_1^\dagger = \mathbf{a}_\uparrow^\dagger$ create up-spin \uparrow

$$|1\rangle = |\uparrow\rangle = \begin{pmatrix} 1/2 \\ +1/2 \end{pmatrix} = \mathbf{a}_1^\dagger |0\rangle = \mathbf{a}_\uparrow^\dagger |0\rangle$$

destroys dn-spin \downarrow

creates up-spin \uparrow

to raise angular momentum by one \hbar unit

$$\mathbf{a}_\uparrow^\dagger \mathbf{a}_\downarrow | \downarrow \rangle = | \uparrow \rangle \quad \text{or: } \mathbf{a}_1^\dagger \mathbf{a}_2 | 2 \rangle = | 1 \rangle$$

$$\langle \mathbf{s}_Z \rangle^{\left(\frac{1}{2}\right)} = D^{\left(\frac{1}{2}\right)}(\mathbf{s}_Z) = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{pmatrix}$$

$$\mathbf{s}_Z = \frac{1}{2}(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2) = \frac{1}{2}(\mathbf{a}_\uparrow^\dagger \mathbf{a}_\uparrow - \mathbf{a}_\downarrow^\dagger \mathbf{a}_\downarrow)$$

Let $\mathbf{a}_2^\dagger = \mathbf{a}_\downarrow^\dagger$ create dn-spin \downarrow

$$|2\rangle = |\downarrow\rangle = \begin{pmatrix} 1/2 \\ -1/2 \end{pmatrix} = \mathbf{a}_2^\dagger |0\rangle = \mathbf{a}_\downarrow^\dagger |0\rangle$$

$\mathbf{s}_- = \mathbf{a}_2^\dagger \mathbf{a}_1 = \mathbf{a}_\downarrow^\dagger \mathbf{a}_\uparrow$ destroys up-spin \uparrow

creates dn-spin \downarrow

to lower angular momentum by one \hbar unit

$$\mathbf{a}_\downarrow^\dagger \mathbf{a}_\uparrow | \uparrow \rangle = | \downarrow \rangle \quad \text{or: } \mathbf{a}_2^\dagger \mathbf{a}_1 | 1 \rangle = | 2 \rangle$$

Review 2. Angular momentum commutation relations

Given Hamilton-Jordan-Pauli product relations : $\sigma_\alpha \sigma_\beta = \delta_{\alpha\beta} + i\varepsilon_{\alpha\beta\gamma} \sigma_\gamma$ with: $\mathbf{s}_\alpha = \sigma_\alpha / 2$

Commutator formulae for \mathbf{s}_α : $\mathbf{s}_\alpha \mathbf{s}_\beta - \mathbf{s}_\beta \mathbf{s}_\alpha = [\mathbf{s}_\alpha, \mathbf{s}_\beta] = i \varepsilon_{\alpha\beta\gamma} \mathbf{s}_\gamma$

$$\begin{aligned}\sigma_X \sigma_Y &= i \sigma_Z \text{ implies: } [\mathbf{s}_X, \mathbf{s}_Y] = i \mathbf{s}_Z \\ \sigma_Z \sigma_X &= i \sigma_Y \text{ implies: } [\mathbf{s}_Z, \mathbf{s}_X] = i \mathbf{s}_Y \\ \sigma_Y \sigma_Z &= i \sigma_X \text{ implies: } [\mathbf{s}_Y, \mathbf{s}_Z] = i \mathbf{s}_X\end{aligned}$$

Key Lie theorem:

\mathbf{s}_Z and $\mathbf{s}_\pm = \mathbf{s}_X \pm i \mathbf{s}_Y$ obey *eigen-commutation relations*.

$$[\mathbf{s}_Z, \mathbf{s}_+] = (+1) \mathbf{s}_+ \quad \text{and:} \quad [\mathbf{s}_Z, \mathbf{s}_-] = (-1) \mathbf{s}_-$$

Proof using elementary matrix operator multiplication: $\mathbf{e}_{jk} \mathbf{e}_{mn} = \delta_{km} \mathbf{e}_{jn}$ with: $\mathbf{s}_+ = \mathbf{e}_{12}$ and: $\mathbf{s}_- = \mathbf{e}_{21}$

$$\text{Also: } \mathbf{s}_Z = (\mathbf{e}_{11} - \mathbf{e}_{22})/2 \approx \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix} \approx \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \approx \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\mathbf{e}_{jk} \mathbf{e}_{mn} = \delta_{km} \mathbf{e}_{jn} \text{ gives: } [(\underbrace{\mathbf{e}_{11} - \mathbf{e}_{22})/2}_{\mathbf{s}_Z}, \underbrace{\mathbf{e}_{12}}_{\mathbf{s}_+}] = \underbrace{+\mathbf{e}_{12}}_{\mathbf{s}_+} \text{ and: } [(\underbrace{\mathbf{e}_{11} - \mathbf{e}_{22})/2}_{\mathbf{s}_Z}, \underbrace{\mathbf{e}_{21}}_{\mathbf{s}_-}] = \underbrace{-\mathbf{e}_{21}}_{\mathbf{s}_-}$$

Then there are *up-down commutation relations*: $[\mathbf{s}_+, \mathbf{s}_-] = [\mathbf{e}_{12}, \mathbf{e}_{21}] = \mathbf{e}_{11} - \mathbf{e}_{22} = 2 \mathbf{s}_Z$

General eigen-commutation theorem:

If Hamiltonian \mathbf{H} (or any operator such as \mathbf{s}_Z) eigen-commutes with \mathbf{a}_m and \mathbf{a}_n^\dagger , that is:

$[\mathbf{H}, \mathbf{a}_n^\dagger] = \omega_n \mathbf{a}_n^\dagger$ and $[\mathbf{H}, \mathbf{a}_m] = \omega_m \mathbf{a}_m$, then \mathbf{H} is a combination $\omega_n \mathbf{a}_n^\dagger \mathbf{a}_n$ of number operators.

$$\mathbf{H} = \sum_{n=1}^2 \omega_n \mathbf{a}_n^\dagger \mathbf{a}_n = \omega_1 \mathbf{a}_1^\dagger \mathbf{a}_1 + \omega_2 \mathbf{a}_2^\dagger \mathbf{a}_2 \approx \begin{pmatrix} \omega_1 & 0 \\ 0 & \omega_2 \end{pmatrix}$$

U(2) Oscillator eigensolutions:

$$\mathbf{H} |n_1 n_2\rangle = \sum_{n=1}^2 \omega_n \mathbf{a}_n^\dagger \mathbf{a}_n |n_1 n_2\rangle = (\omega_1 n_1 + \omega_2 n_2) |n_1 n_2\rangle = (\omega_1 (j+m) + \omega_2 (j-m)) |j_m\rangle$$

$$\begin{aligned}n_1 &= j+m \\ n_2 &= j-m\end{aligned}$$

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Review Class 8 p 104

$U(2)$ boson oscillator states $|n_1, n_2\rangle = R(3)$ spin or rotor states $\left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle$

Oscillator total quanta: $v = (n_1 + n_2)$

Rotor total momenta: $j = v/2$ and z-momenta: $m = (n_1 - n_2)/2$

$$|n_1 n_2\rangle = \frac{(\mathbf{a}_1^\dagger)^{n_1} (\mathbf{a}_2^\dagger)^{n_2}}{\sqrt{n_1! n_2!}} |0 0\rangle = \frac{(\mathbf{a}_1^\dagger)^{j+m} (\mathbf{a}_2^\dagger)^{j-m}}{\sqrt{(j+m)!(j-m)!}} |0 0\rangle = \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle$$

$$\begin{aligned} j &= v/2 = (n_1 + n_2)/2 \\ m &= (n_1 - n_2)/2 \end{aligned}$$

$$\begin{aligned} n_1 &= j+m \\ n_2 &= j-m \end{aligned}$$

$U(2)$ boson oscillator states = $U(2)$ spinor states

$$|n_\uparrow n_\downarrow\rangle = \frac{(\mathbf{a}_\uparrow^\dagger)^{n_\uparrow} (\mathbf{a}_\downarrow^\dagger)^{n_\downarrow}}{\sqrt{n_\uparrow! n_\downarrow!}} |0 0\rangle = \frac{(\mathbf{a}_\uparrow^\dagger)^{j+m} (\mathbf{a}_\downarrow^\dagger)^{j-m}}{\sqrt{(j+m)!(j-m)!}} |0 0\rangle = \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle$$

Oscillator $\mathbf{a}^\dagger \mathbf{a}$ give \mathbf{s}_\pm matrices.

$$\begin{aligned} \mathbf{a}_1^\dagger \mathbf{a}_2 |n_1 n_2\rangle &= \sqrt{n_1+1} \sqrt{n_2} |n_1+1 n_2-1\rangle \Rightarrow \mathbf{s}_+ \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle = \sqrt{j+m+1} \sqrt{j-m} \left| \begin{smallmatrix} j \\ m+1 \end{smallmatrix} \right\rangle \\ \mathbf{a}_2^\dagger \mathbf{a}_1 |n_1 n_2\rangle &= \sqrt{n_1} \sqrt{n_2+1} |n_1-1 n_2+1\rangle \Rightarrow \mathbf{s}_- \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle = \sqrt{j+m} \sqrt{j-m+1} \left| \begin{smallmatrix} j \\ m-1 \end{smallmatrix} \right\rangle \end{aligned}$$

1/2-difference of number-ops is \mathbf{s}_Z eigenvalue.

$$\left. \begin{aligned} \mathbf{a}_1^\dagger \mathbf{a}_1 |n_1 n_2\rangle &= n_1 |n_1 n_2\rangle \\ \mathbf{a}_2^\dagger \mathbf{a}_2 |n_1 n_2\rangle &= n_2 |n_1 n_2\rangle \end{aligned} \right\} \mathbf{s}_Z \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle = \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2) \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle = \frac{n_1 - n_2}{2} \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle = m \left| \begin{smallmatrix} j \\ m \end{smallmatrix} \right\rangle$$

$j=1$ vector \mathbf{s}_+

$$D^1(\mathbf{s}_+) = D^1(\mathbf{s}_x + i\mathbf{s}_y) = \begin{pmatrix} \cdot & \frac{\sqrt{2}}{2} & \cdot \\ \frac{\sqrt{2}}{2} & \cdot & \frac{\sqrt{2}}{2} \\ \cdot & \frac{\sqrt{2}}{2} & \cdot \end{pmatrix} + i \begin{pmatrix} \cdot & -i\frac{\sqrt{2}}{2} & \cdot \\ i\frac{\sqrt{2}}{2} & \cdot & -i\frac{\sqrt{2}}{2} \\ \cdot & i\frac{\sqrt{2}}{2} & \cdot \end{pmatrix} = \begin{pmatrix} \cdot & \sqrt{2} & \cdot \\ 0 & \cdot & \sqrt{2} \\ \cdot & 0 & \cdot \end{pmatrix}, \quad D^1(\mathbf{s}_z) = \begin{pmatrix} 1 & \cdot & \cdot \\ \cdot & 0 & \cdot \\ \cdot & \cdot & -1 \end{pmatrix}$$

...and \mathbf{s}_Z

$j=3/2$ spinor \mathbf{s}_+

$$D^{\frac{3}{2}}(\mathbf{s}_+) = \begin{pmatrix} \cdot & \sqrt{3} & \cdot & \cdot \\ 0 & \cdot & \sqrt{4} & \cdot \\ \cdot & 0 & \cdot & \sqrt{3} \\ \cdot & \cdot & 0 & \cdot \end{pmatrix} = \left(D^{\frac{3}{2}}(\mathbf{s}_-) \right)^\dagger, \quad D^{\frac{3}{2}}(\mathbf{s}_z) = \begin{pmatrix} \frac{3}{2} & \cdot & \cdot & \cdot \\ \cdot & \frac{1}{2} & \cdot & \cdot \\ \cdot & \cdot & -\frac{1}{2} & \cdot \\ \cdot & \cdot & \cdot & -\frac{3}{2} \end{pmatrix}$$

...and \mathbf{s}_Z

$j=2$ tensor \mathbf{s}_+

$$D^2(\mathbf{s}_+) = \begin{pmatrix} \cdot & \sqrt{4} & \cdot & \cdot & \cdot \\ 0 & \cdot & \sqrt{3} & \cdot & \cdot \\ \cdot & 0 & \cdot & \sqrt{3} & \cdot \\ \cdot & \cdot & 0 & \cdot & \sqrt{4} \\ \cdot & \cdot & \cdot & 0 & \cdot \end{pmatrix} = \left(D^2(\mathbf{s}_-) \right)^\dagger, \quad D^2(\mathbf{s}_z) = \begin{pmatrix} 2 & \cdot & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & \cdot & \cdot \\ \cdot & \cdot & 0 & \cdot & \cdot \\ \cdot & \cdot & \cdot & -1 & \cdot \\ \cdot & \cdot & \cdot & \cdot & -2 \end{pmatrix}$$

...and \mathbf{s}_Z

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude Θ^{J_m} -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^{J_m} -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^{J_m} -analysis of high J atomic beams

Θ^{J_m} -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Angular momentum magnitude and uncertainty

Angular momentum squared $\mathbf{S} \cdot \mathbf{S}$ and Z-component \mathbf{S}_Z share eigenstates

$$\mathbf{S} \cdot \mathbf{S} = \mathbf{S}_X^2 + \mathbf{S}_Y^2 + \mathbf{S}_Z^2 = (\mathbf{S}_+ \mathbf{S}_- + \mathbf{S}_- \mathbf{S}_+)/2 + \mathbf{S}_Z^2$$

$$\mathbf{S}_{\pm} = \mathbf{S}_X \pm i \mathbf{S}_Y$$

$$\mathbf{S}_+ = \mathbf{a}_1^\dagger \mathbf{a}_2$$

$$\mathbf{S}_- = \mathbf{a}_2^\dagger \mathbf{a}_1$$

$$\mathbf{S}_Z = \frac{1}{2}(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)$$

Angular momentum magnitude and uncertainty

$$\mathbf{S}_{\pm} = \mathbf{S}_X \pm i \mathbf{S}_Y$$

$$\mathbf{S}_+ = \mathbf{a}_1^\dagger \mathbf{a}_2$$

$$\mathbf{S}_- = \mathbf{a}_2^\dagger \mathbf{a}_1$$

$$\mathbf{S}_Z = \frac{1}{2}(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)$$

Angular momentum squared $\mathbf{S} \cdot \mathbf{S}$ and Z-component \mathbf{S}_Z share eigenstates

$$\mathbf{S} \cdot \mathbf{S} = \mathbf{S}_X^2 + \mathbf{S}_Y^2 + \mathbf{S}_Z^2 = (\mathbf{S}_+ \mathbf{S}_- + \mathbf{S}_- \mathbf{S}_+)/2 + \mathbf{S}_Z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{S}_X^2 + \mathbf{S}_Y^2 + \mathbf{S}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Angular momentum magnitude and uncertainty

$$\begin{aligned}\mathbf{s}_{\pm} &= \mathbf{s}_X \pm i \mathbf{s}_Y \\ \mathbf{s}_+ &= \mathbf{a}_1^\dagger \mathbf{a}_2 \\ \mathbf{s}_- &= \mathbf{a}_2^\dagger \mathbf{a}_1 \\ \mathbf{s}_z &= \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)\end{aligned}$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+) / 2 + \mathbf{s}_Z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}} (\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Angular momentum magnitude and uncertainty

$$\begin{aligned}\mathbf{s}_\pm &= \mathbf{s}_X \pm i \mathbf{s}_Y \\ \mathbf{s}_+ &= \mathbf{a}_1^\dagger \mathbf{a}_2 \\ \mathbf{s}_- &= \mathbf{a}_2^\dagger \mathbf{a}_1 \\ \mathbf{s}_z &= \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)\end{aligned}$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+)/2 + \mathbf{s}_z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Using $\mathbf{a}_m \mathbf{a}_n^\dagger = \mathbf{a}_n^\dagger \mathbf{a}_m + \delta_{mn} \mathbf{1}$ gives $\mathbf{s} \cdot \mathbf{s}$ as number operators.

(Normal order: *left ← creation, destruct → right.*)

Angular momentum magnitude and uncertainty

$$\begin{aligned}\mathbf{s}_\pm &= \mathbf{s}_X \pm i \mathbf{s}_Y \\ \mathbf{s}_+ &= \mathbf{a}_1^\dagger \mathbf{a}_2 \\ \mathbf{s}_- &= \mathbf{a}_2^\dagger \mathbf{a}_1 \\ \mathbf{s}_z &= \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)\end{aligned}$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+)/2 + \mathbf{s}_z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Using $\mathbf{a}_m \mathbf{a}_n^\dagger = \mathbf{a}_n^\dagger \mathbf{a}_m + \delta_{mn} \mathbf{1}$ gives $\mathbf{s} \cdot \mathbf{s}$ as number operators.

(Normal order: *left ← creation, destruct → right.*)

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2(\mathbf{a}_2^\dagger \mathbf{a}_2 + 1) \mathbf{a}_1^\dagger \mathbf{a}_1 + 2(\mathbf{a}_1^\dagger \mathbf{a}_1 + 1) \mathbf{a}_2^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Angular momentum magnitude and uncertainty

$$\mathbf{s}_{\pm} = \mathbf{s}_X \pm i \mathbf{s}_Y$$

$$\mathbf{s}_+ = \mathbf{a}_1^\dagger \mathbf{a}_2$$

$$\mathbf{s}_- = \mathbf{a}_2^\dagger \mathbf{a}_1$$

$$\mathbf{s}_Z = \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_Z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+)/2 + \mathbf{s}_Z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Using $\mathbf{a}_m \mathbf{a}_n^\dagger = \mathbf{a}_n^\dagger \mathbf{a}_m + \delta_{mn} \mathbf{1}$ gives $\mathbf{s} \cdot \mathbf{s}$ as number operators.

(Normal order: *left ← creation, destruct → right.*)

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2(\mathbf{a}_2^\dagger \mathbf{a}_2 + 1) \mathbf{a}_1^\dagger \mathbf{a}_1 + 2(\mathbf{a}_1^\dagger \mathbf{a}_1 + 1) \mathbf{a}_2^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Eigenvalue formula is then found. (Replace number-operator $\mathbf{a}_k^\dagger \mathbf{a}_k$ with its number n_k)

$$\begin{aligned} \mathbf{s} \cdot \mathbf{s} |n_1 n_2\rangle &= \frac{1}{4} [2(n_2 + 1)n_1 + 2(n_1 + 1)n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle \\ &= \frac{1}{4} [2n_1 + 2n_2 + 4n_1 n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle \end{aligned}$$

$$j = \nu/2 = (n_1 + n_2)/2$$

$$m = (n_1 - n_2)/2$$

$$n_1 = j + m$$

$$n_2 = j - m$$

Angular momentum magnitude and uncertainty

$$\begin{aligned}\mathbf{s}_\pm &= \mathbf{s}_X \pm i \mathbf{s}_Y \\ \mathbf{s}_+ &= \mathbf{a}_1^\dagger \mathbf{a}_2 \\ \mathbf{s}_- &= \mathbf{a}_2^\dagger \mathbf{a}_1 \\ \mathbf{s}_z &= \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)\end{aligned}$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+)/2 + \mathbf{s}_z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Using $\mathbf{a}_m \mathbf{a}_n^\dagger = \mathbf{a}_n^\dagger \mathbf{a}_m + \delta_{mn} \mathbf{1}$ gives $\mathbf{s} \cdot \mathbf{s}$ as number operators.

(Normal order: *left ← creation, destruct → right.*)

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2(\mathbf{a}_2^\dagger \mathbf{a}_2 + 1) \mathbf{a}_1^\dagger \mathbf{a}_1 + 2(\mathbf{a}_1^\dagger \mathbf{a}_1 + 1) \mathbf{a}_2^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Eigenvalue formula is then found. (Replace number-operator $\mathbf{a}_k^\dagger \mathbf{a}_k$ with its number n_k)

$$\begin{aligned}\mathbf{s} \cdot \mathbf{s} |n_1 n_2\rangle &= \frac{1}{4} [2(n_2 + 1)n_1 + 2(n_1 + 1)n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle \\ &= \frac{1}{4} [2n_1 + 2n_2 + 4n_1 n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle\end{aligned}$$

$$j = \nu/2 = (n_1 + n_2)/2$$

$$m = (n_1 - n_2)/2$$

R(3) angular quanta in $n_1 = j + m$ and $n_2 = j - m$ give R(3) eigenvalue formula.

$$\mathbf{s} \cdot \mathbf{s} \Big| \begin{matrix} j \\ m \end{matrix} \Big\rangle = \frac{1}{4} [2(j+m+1)(j-m) + 2(j-m+1)(j+m) + 4m^2] \Big| \begin{matrix} j \\ m \end{matrix} \Big\rangle = j(j+1) \Big| \begin{matrix} j \\ m \end{matrix} \Big\rangle$$

$$n_1 = j + m$$

$$n_2 = j - m$$

Has very simple j -formula...

Angular momentum magnitude and uncertainty

$$\begin{aligned}\mathbf{s}_\pm &= \mathbf{s}_X \pm i \mathbf{s}_Y \\ \mathbf{s}_+ &= \mathbf{a}_1^\dagger \mathbf{a}_2 \\ \mathbf{s}_- &= \mathbf{a}_2^\dagger \mathbf{a}_1 \\ \mathbf{s}_z &= \frac{1}{2} (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)\end{aligned}$$

Angular momentum squared $\mathbf{s} \cdot \mathbf{s}$ and Z-component \mathbf{s}_z share eigenstates

$$\mathbf{s} \cdot \mathbf{s} = \mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2 = (\mathbf{s}_+ \mathbf{s}_- + \mathbf{s}_- \mathbf{s}_+)/2 + \mathbf{s}_z^2$$

$j=1/2$ fundamental matrices square up not to $(1/2)^2 = 1/4$ but to $3/4$.

$$D^{\frac{1}{2}}(\mathbf{s}_X^2 + \mathbf{s}_Y^2 + \mathbf{s}_Z^2) = \frac{1}{4} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{3}{4} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In terms of \mathbf{a} -operators the squared momentum operator is

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2 \mathbf{a}_1^\dagger \mathbf{a}_2 \mathbf{a}_2^\dagger \mathbf{a}_1 + 2 \mathbf{a}_2^\dagger \mathbf{a}_1 \mathbf{a}_1^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Using $\mathbf{a}_m \mathbf{a}_n^\dagger = \mathbf{a}_n^\dagger \mathbf{a}_m + \delta_{mn} \mathbf{1}$ gives $\mathbf{s} \cdot \mathbf{s}$ as number operators.

(Normal order: *left ← creation, destruct → right.*)

$$\mathbf{s} \cdot \mathbf{s} = \frac{1}{4} [2(\mathbf{a}_2^\dagger \mathbf{a}_2 + 1) \mathbf{a}_1^\dagger \mathbf{a}_1 + 2(\mathbf{a}_1^\dagger \mathbf{a}_1 + 1) \mathbf{a}_2^\dagger \mathbf{a}_2 + (\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)(\mathbf{a}_1^\dagger \mathbf{a}_1 - \mathbf{a}_2^\dagger \mathbf{a}_2)]$$

Eigenvalue formula is then found. (Replace number-operator $\mathbf{a}_k^\dagger \mathbf{a}_k$ with its number n_k)

$$\begin{aligned}\mathbf{s} \cdot \mathbf{s} |n_1 n_2\rangle &= \frac{1}{4} [2(n_2 + 1)n_1 + 2(n_1 + 1)n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle \\ &= \frac{1}{4} [2n_1 + 2n_2 + 4n_1 n_2 + (n_1 - n_2)(n_1 - n_2)] |n_1 n_2\rangle\end{aligned}$$

$$j = \nu/2 = (n_1 + n_2)/2$$

$$m = (n_1 - n_2)/2$$

R(3) angular quanta in $n_1 = j + m$ and $n_2 = j - m$ give R(3) eigenvalue formula.

$$\mathbf{s} \cdot \mathbf{s} \left| \begin{matrix} j \\ m \end{matrix} \right\rangle = \frac{1}{4} [2(j+m+1)(j-m) + 2(j-m+1)(j+m) + 4m^2] \left| \begin{matrix} j \\ m \end{matrix} \right\rangle = j(j+1) \left| \begin{matrix} j \\ m \end{matrix} \right\rangle$$

$$n_1 = j + m$$

$$n_2 = j - m$$

Magnitude $|\mathbf{J}| = \sqrt{j(j+1)}$ of angular momentum $\mathbf{s} = \mathbf{J}$:
(approaches $j + \frac{1}{2}$ for large j)

$$|\mathbf{s}| \left| \begin{matrix} j \\ m \end{matrix} \right\rangle = \sqrt{\mathbf{s} \cdot \mathbf{s}} \left| \begin{matrix} j \\ m \end{matrix} \right\rangle = \sqrt{j(j+1)} \left| \begin{matrix} j \\ m \end{matrix} \right\rangle \approx \left| \begin{matrix} j + \frac{1}{2} \\ m \end{matrix} \right\rangle$$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Angular momentum uncertainty angle

The *angular momentum uncertainty angle* Θ_m^j

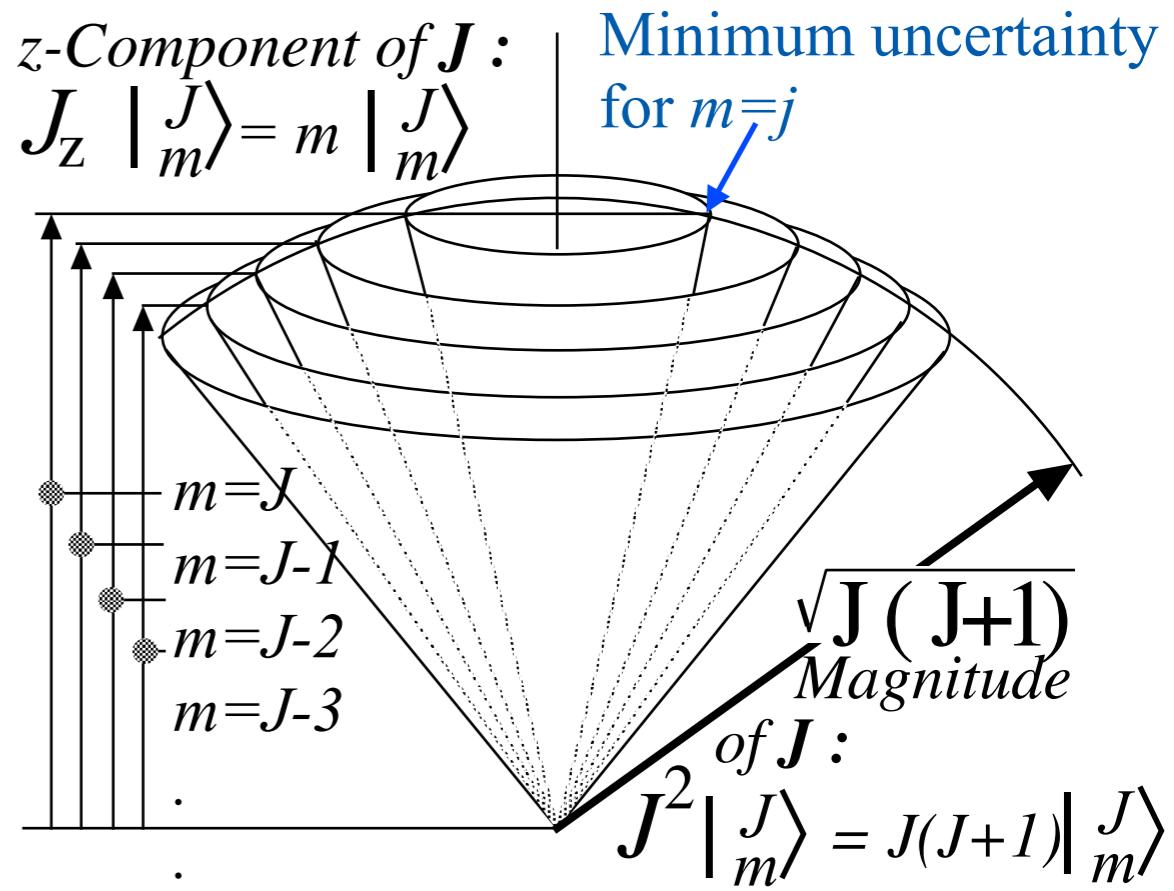
is given by:

$$\Theta_m^j = \arccos\left(\frac{m}{\sqrt{j(j+1)}}\right)$$

Angular momentum uncertainty angle

The *angular momentum uncertainty angle* Θ_m^j is given by:

$$\Theta_m^j = \arccos\left(\frac{m}{\sqrt{j(j+1)}}\right)$$



Angular momentum uncertainty angle

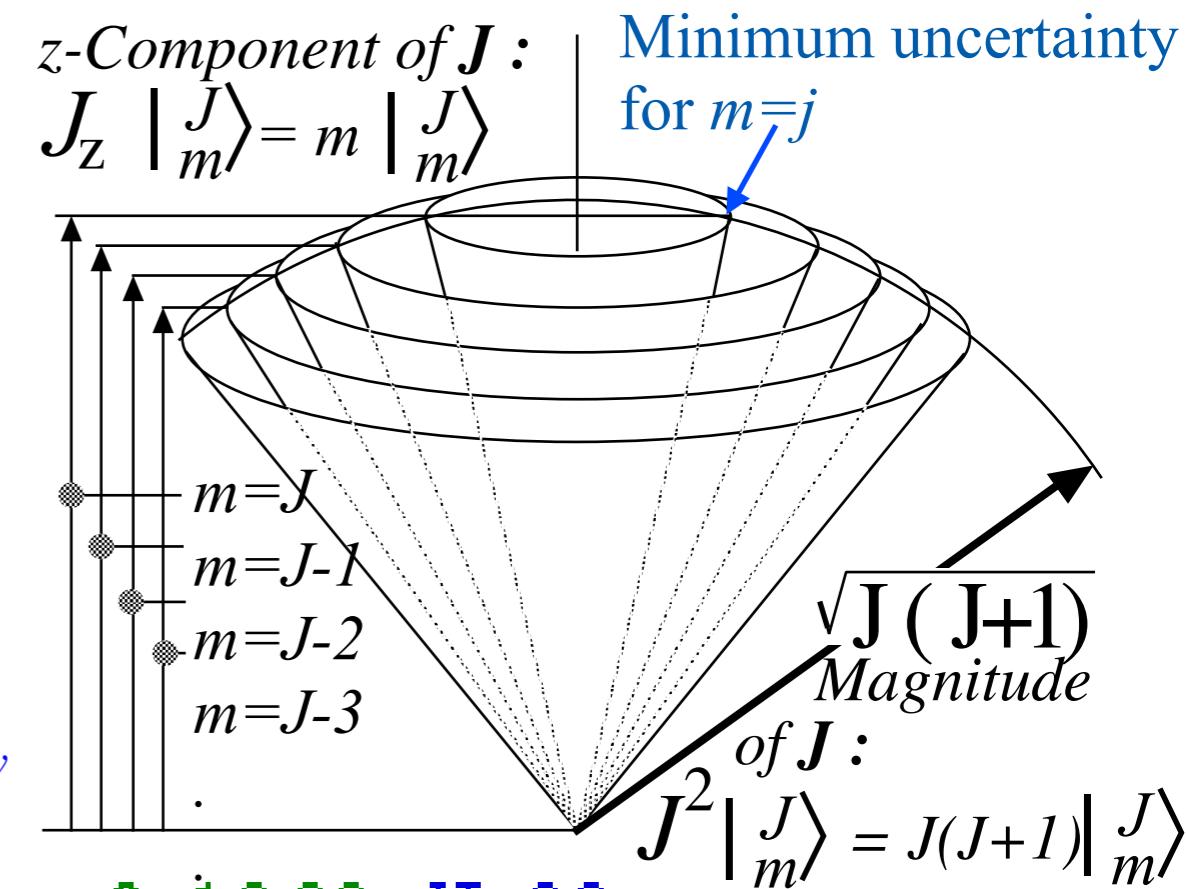
The *angular momentum uncertainty angle* Θ_m^j is given by:

$$\Theta_m^j = \arccos\left(\frac{m}{\sqrt{j(j+1)}}\right)$$

For $j=m=\frac{1}{2}$

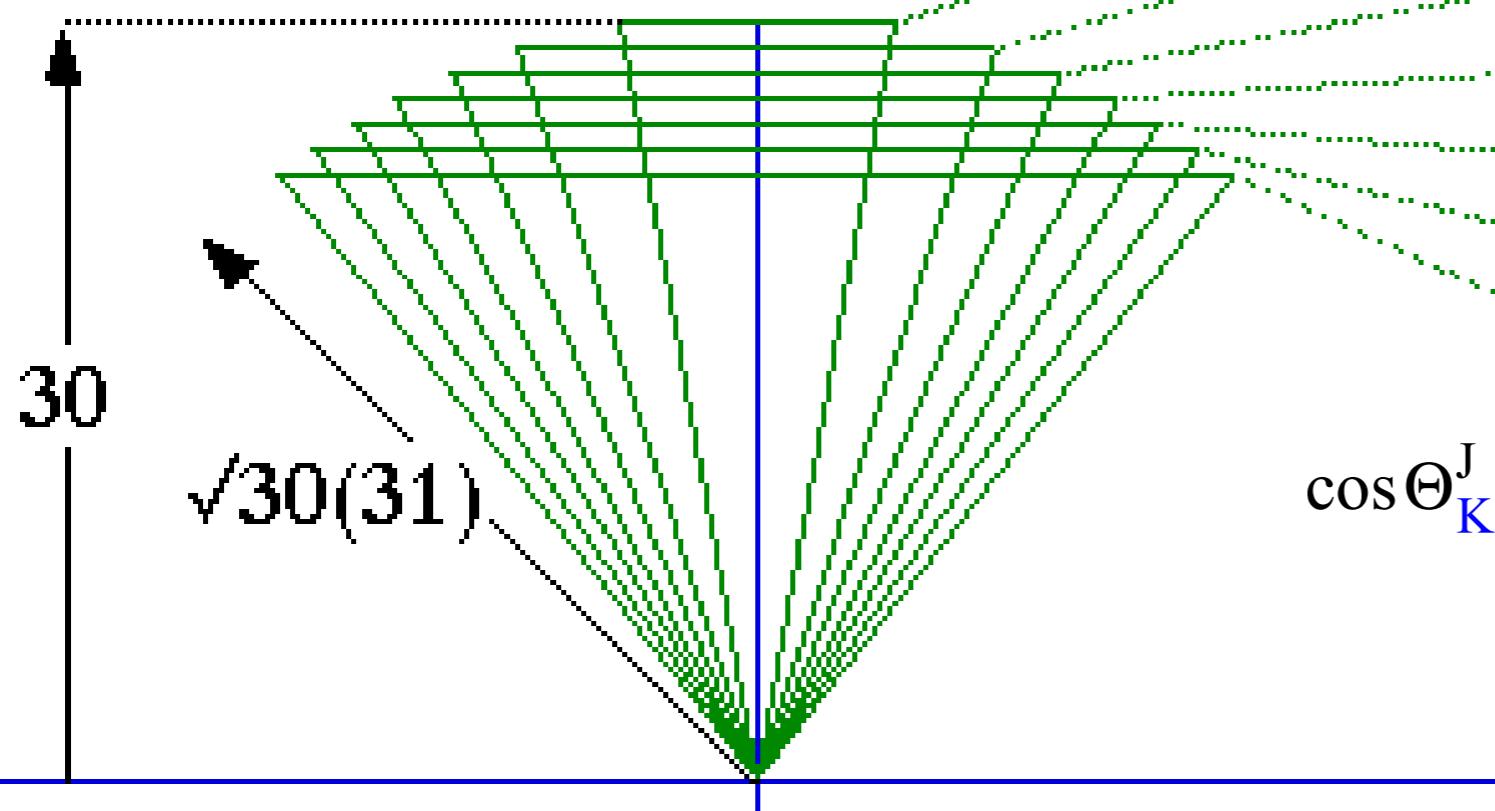
$$\Theta_{1/2}^{1/2} = \arccos\left(\frac{\frac{1}{2}}{\sqrt{\frac{1}{2}\left(\frac{1}{2}+1\right)}}\right) = \cos^{-1}\frac{1}{2\frac{\sqrt{3}}{2}} = 54.7^\circ$$

Greatest possible uncertainty



Angular Momentum Cones for

$J=30$



$$\cos\Theta_K^J = \frac{K}{\sqrt{J(J+1)}} \approx \frac{K}{J+\frac{1}{2}}$$

$$\theta = 10.3^\circ \quad K = 30$$

$$\theta = 18.0^\circ \quad K = 29$$

$$\theta = 23.3^\circ \quad K = 28$$

$$\theta = 27.7^\circ \quad K = 27$$

$$\theta = 31.5^\circ \quad K = 26$$

$$\theta = 34.9^\circ \quad K = 25$$

$$\theta = 38.1^\circ \quad K = 24$$

3-fold cutoff
19.5°

4-fold cutoff
35.3°

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Corresponding transformation of the fundamental creation operators

$$\mathbf{a}_{1'}^\dagger = D_{11}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{21}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_2^\dagger$$

$$\mathbf{a}_{2'}^\dagger = D_{12}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{22}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_2^\dagger$$

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Corresponding transformation of the fundamental creation operators

$$\mathbf{a}_{1'}^\dagger = D_{11}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{21}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_2^\dagger$$

$$\mathbf{a}_{2'}^\dagger = D_{12}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{22}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_2^\dagger$$

Problem: Find corresponding transformation $D^{(j)}(\alpha\beta\gamma)$ matrix for a ($v=2j$)-oscillator state
($v=2j$)-quantum state is rotated to a new "prime" basis.

$$\mathbf{R}(\alpha\beta\gamma)|_n^j\rangle = \frac{(\mathbf{a}_{1'}^\dagger)^{j+n} (\mathbf{a}_{2'}^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |0\ 0\rangle = \frac{(D_{11}\mathbf{a}_1^\dagger + D_{21}\mathbf{a}_2^\dagger)^{j+n} (D_{21}\mathbf{a}_1^\dagger + D_{22}\mathbf{a}_2^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |0\ 0\rangle$$

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Corresponding transformation of the fundamental creation operators

$$\mathbf{a}_{1'}^\dagger = D_{11}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{21}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_2^\dagger$$

$$\mathbf{a}_{2'}^\dagger = D_{12}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{22}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_2^\dagger$$

Problem: Find corresponding transformation $D^{(j)}(\alpha\beta\gamma)$ matrix for a ($v=2j$)-oscillator state
($v=2j$)-quantum state is rotated to a new "prime" basis.

$$\mathbf{R}(\alpha\beta\gamma)|_n^j\rangle = \frac{(\mathbf{a}_{1'}^\dagger)^{j+n} (\mathbf{a}_{2'}^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle = \frac{(D_{11}\mathbf{a}_1^\dagger + D_{21}\mathbf{a}_2^\dagger)^{j+n} (D_{21}\mathbf{a}_1^\dagger + D_{22}\mathbf{a}_2^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle$$

Binomial expansion is a double sum over binomial coefficients: $\binom{n}{k} = \frac{n!}{k!(n-k)!}$

$$\mathbf{R}(\alpha\beta\gamma)|_n^j\rangle = \frac{\sum_{\ell} \sum_k \binom{j+n}{\ell} (D_{11}\mathbf{a}_1^\dagger)^\ell (D_{21}\mathbf{a}_2^\dagger)^{j+n-\ell} \binom{j-n}{k} (D_{12}\mathbf{a}_1^\dagger)^k (D_{22}\mathbf{a}_2^\dagger)^{j-n-k}}{\sqrt{(j+n)!(j-n)!}} |00\rangle = \sqrt{(j+n)!(j-n)!} \frac{\sum_{\ell} \sum_k \binom{D_{11}\mathbf{a}_1^\dagger}{\ell}^\ell (D_{21}\mathbf{a}_2^\dagger)^{j+n-\ell} \binom{D_{12}\mathbf{a}_1^\dagger}{k}^k (D_{22}\mathbf{a}_2^\dagger)^{j-n-k}}{\ell!(j+n-\ell)! k!(j-n-k)!} |00\rangle$$

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Corresponding transformation of the fundamental creation operators

$$\mathbf{a}_{1'}^\dagger = D_{11}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{21}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_2^\dagger$$

$$\mathbf{a}_{2'}^\dagger = D_{12}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{22}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_2^\dagger$$

Problem: Find corresponding transformation $D^{(j)}(\alpha\beta\gamma)$ matrix for a ($v=2j$)-oscillator state
($v=2j$)-quantum state is rotated to a new "prime" basis.

$$\mathbf{R}(\alpha\beta\gamma)|_n^j\rangle = \frac{(\mathbf{a}_{1'}^\dagger)^{j+n} (\mathbf{a}_{2'}^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle = \frac{(D_{11}\mathbf{a}_1^\dagger + D_{21}\mathbf{a}_2^\dagger)^{j+n} (D_{21}\mathbf{a}_1^\dagger + D_{22}\mathbf{a}_2^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle$$

Binomial expansion is a double sum over binomial coefficients: $\binom{n}{k} = \frac{n!}{k!(n-k)!}$

$$\mathbf{R}(\alpha\beta\gamma)|_n^j\rangle = \frac{\sum_{\ell} \sum_k \binom{j+n}{\ell} (D_{11}\mathbf{a}_1^\dagger)^\ell (D_{21}\mathbf{a}_2^\dagger)^{j+n-\ell} \binom{j-n}{k} (D_{12}\mathbf{a}_1^\dagger)^k (D_{22}\mathbf{a}_2^\dagger)^{j-n-k}}{\sqrt{(j+n)!(j-n)!}} |00\rangle = \sqrt{(j+n)!(j-n)!} \frac{\sum_{\ell} \sum_k \binom{j+n}{\ell} (D_{11}\mathbf{a}_1^\dagger)^\ell (D_{21}\mathbf{a}_2^\dagger)^{j+n-\ell} \binom{j-n}{k} (D_{12}\mathbf{a}_1^\dagger)^k (D_{22}\mathbf{a}_2^\dagger)^{j-n-k}}{\ell!(j+n-\ell)!k!(j-n-k)!} |00\rangle$$

Let \mathbf{a}^\dagger -operator powers be $j\pm m$ forms : $j+m=\ell+k$, $j-m=2j-\ell-k$ so $\ell=j+m-k$ and $j+n-\ell=n-m+k$

$$= \sqrt{(j+n)!(j-n)!} \frac{\sum_{\ell} \sum_k (D_{11})^\ell (D_{21})^{j+n-\ell} (D_{12})^k (D_{22})^{j-n-k}}{\ell!(j+n-\ell)!k!(j-n-k)!} (\mathbf{a}_1^\dagger)^{\ell+k} (\mathbf{a}_2^\dagger)^{2j-\ell-k} |00\rangle = \sqrt{(j+n)!(j-n)!} \frac{\sum_{m} \sum_k (D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)!k!(j-n-k)!} (\mathbf{a}_1^\dagger)^{j+m} (\mathbf{a}_2^\dagger)^{j-m} |00\rangle$$

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

A fundamental (spin-1/2) Euler transformation $\mathbf{R}(\alpha\beta\gamma)$ given in three notations.

$$\begin{pmatrix} \langle 1|1' \rangle & \langle 1|2' \rangle \\ \langle 2|1' \rangle & \langle 2|2' \rangle \end{pmatrix} = \begin{pmatrix} \langle 1|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 1|\mathbf{R}(\alpha\beta\gamma)|2\rangle \\ \langle 2|\mathbf{R}(\alpha\beta\gamma)|1\rangle & \langle 2|\mathbf{R}(\alpha\beta\gamma)|2\rangle \end{pmatrix} = \begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

Corresponding transformation of the fundamental creation operators

$$\mathbf{a}_{1'}^\dagger = D_{11}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{21}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_2^\dagger$$

$$\mathbf{a}_{2'}^\dagger = D_{12}^{1/2}(\alpha\beta\gamma)\mathbf{a}_1^\dagger + D_{22}^{1/2}(\alpha\beta\gamma)\mathbf{a}_2^\dagger = -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \mathbf{a}_1^\dagger + e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \mathbf{a}_2^\dagger$$

Problem: Find corresponding transformation $D^{(j)}(\alpha\beta\gamma)$ matrix for a ($v=2j$)-oscillator state ($v=2j$)-quantum state is rotated to a new "prime" basis.

$$\mathbf{R}(\alpha\beta\gamma)\left| \begin{smallmatrix} j \\ n \end{smallmatrix} \right\rangle = \frac{(\mathbf{a}_{1'}^\dagger)^{j+n} (\mathbf{a}_{2'}^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle = \frac{(D_{11}\mathbf{a}_1^\dagger + D_{21}\mathbf{a}_2^\dagger)^{j+n} (D_{21}\mathbf{a}_1^\dagger + D_{22}\mathbf{a}_2^\dagger)^{j-n}}{\sqrt{(j+n)!(j-n)!}} |00\rangle$$

This gives general *irreducible representation of $U(2)$* :

$$\left\langle \begin{smallmatrix} j \\ m \end{smallmatrix} \middle| \mathbf{R}(\alpha\beta\gamma) \left| \begin{smallmatrix} j \\ n \end{smallmatrix} \right\rangle \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \frac{\sum_k (D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

And general *SU(2) irreducible representation for Euler angles $(\alpha\beta\gamma)$* .

$$\left\langle \begin{smallmatrix} j \\ m \end{smallmatrix} \middle| \mathbf{R}(\alpha\beta\gamma) \left| \begin{smallmatrix} j \\ n \end{smallmatrix} \right\rangle \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \frac{\sum_k (-1)^k \left(\cos \frac{\beta}{2} \right)^{2j+m-n-2k} \left(\sin \frac{\beta}{2} \right)^{n-m+2k} e^{-i(m\alpha+n\gamma)}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

k -sum limited by (-integer) $!=\infty$ and $0!=1=1!$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions.

$D^L m_0 \sim Y^L m$ Spherical harmonics

$D^{L=1} m_0 \sim Y^1 m$ p-waves

$D^{L=2} m_0 \sim Y^2 m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

Evaluating *irreducible representation of $U(2)$* :

$$\left\langle \begin{matrix} j \\ m \end{matrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{matrix} j \\ n \end{matrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \sum_k \frac{(D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

Easily done for *Euler angles* ($\alpha\beta\gamma$)

$$\begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

k -Summation \sum_k limits amount to prohibiting a $p! = (-N)! = \infty$ factor in denominator.

or

Darboux axis angles [$\varphi\vartheta\Theta$]

$$\text{or } \begin{pmatrix} D_{11}^{1/2}[\varphi\vartheta\Theta] & D_{12}^{1/2}[\varphi\vartheta\Theta] \\ D_{21}^{1/2}[\varphi\vartheta\Theta] & D_{22}^{1/2}[\varphi\vartheta\Theta] \end{pmatrix} = \begin{pmatrix} \cos \frac{\Theta}{2} - i \cos \vartheta \sin \frac{\Theta}{2} & -i e^{-i\varphi} \sin \vartheta \sin \frac{\Theta}{2} \\ -i e^{+i\varphi} \sin \vartheta \sin \frac{\Theta}{2} & \cos \frac{\Theta}{2} + i \cos \vartheta \sin \frac{\Theta}{2} \end{pmatrix}$$

$$(j+m-k) \geq 0 \quad (n-m+k) \geq 0 \quad k \geq 0 \quad (j-n-k) \geq 0$$

or: $k \leq j+m$ or: $k \leq m-n$ or: $k \leq j-n$

Power p on $(D_{ab})^p$ must be zero or greater ($p \geq 0$).

Euler angles ($\alpha\beta\gamma$) vs *axis angles* [$\varphi\vartheta\Theta$] Lect.5 p7-11

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

Evaluating *irreducible representation of $U(2)$* :

$$\left\langle \begin{matrix} j \\ m \end{matrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{matrix} j \\ n \end{matrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \sum_k \frac{(D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

Easily done for *Euler angles* ($\alpha\beta\gamma$)

$$\begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

k -Summation \sum_k limits amount to prohibiting a $p! = (-N)! = \infty$ factor in denominator.

Examples: $D_{m,n}^j = D_{2,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8+2=10, \quad k \geq 2-4=-2, \quad k \geq 0, \quad k \leq 8-4=4.$

$D_{m,n}^j = D_{-4,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8-4=4, \quad k \geq 4-4=0. \quad k \geq 0, \quad k \leq 8-4=4$

or

$$\text{or} \quad \begin{pmatrix} D_{11}^{1/2}[\varphi\vartheta\Theta] & D_{12}^{1/2}[\varphi\vartheta\Theta] \\ D_{21}^{1/2}[\varphi\vartheta\Theta] & D_{22}^{1/2}[\varphi\vartheta\Theta] \end{pmatrix} = \begin{pmatrix} \cos \frac{\Theta}{2} - i \cos \vartheta \sin \frac{\Theta}{2} & -ie^{-i\varphi} \sin \vartheta \sin \frac{\Theta}{2} \\ -ie^{+i\varphi} \sin \vartheta \sin \frac{\Theta}{2} & \cos \frac{\Theta}{2} + i \cos \vartheta \sin \frac{\Theta}{2} \end{pmatrix}$$

$$(j+m-k) \geq 0$$

$$\text{or: } k \leq j+m$$

$$(n-m+k) \geq 0$$

$$\text{or: } k \geq m-n$$

$$k \geq 0$$

$$(j-n-k) \geq 0$$

$$\text{or: } k \leq j-n$$

Power p on $(D_{ab})^p$ must be zero or greater ($p \geq 0$).

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

Evaluating *irreducible representation of $U(2)$* :

$$\left\langle \begin{matrix} j \\ m \end{matrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{matrix} j \\ n \end{matrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \sum_k \frac{(D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

Easily done for *Euler angles* ($\alpha\beta\gamma$)

$$\begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

k -Summation \sum_k limits amount to prohibiting a $p! = (-N)! = \infty$ factor in denominator.

Examples: $D_{m,n}^j = D_{2,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8+2=10, \quad k \geq 2-4=-2, \quad k \geq 0, \quad k \leq 8-4=4$.

$D_{m,n}^j = D_{-4,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8-4=4, \quad k \geq 4-4=0, \quad k \geq 0, \quad k \leq 8-4=4$

$D_{m,n}^j = D_{-8,4}^8$ has sum: $\sum_{k=0}^0$ term $k \leq 8-8=0, \quad k \geq -8-4=-12, \quad k \geq 0, \quad k \leq 8-4=4$

or

$$\text{or } \begin{pmatrix} D_{11}^{1/2}[\varphi\vartheta\Theta] & D_{12}^{1/2}[\varphi\vartheta\Theta] \\ D_{21}^{1/2}[\varphi\vartheta\Theta] & D_{22}^{1/2}[\varphi\vartheta\Theta] \end{pmatrix} = \begin{pmatrix} \cos \frac{\Theta}{2} - i \cos \vartheta \sin \frac{\Theta}{2} & -ie^{-i\varphi} \sin \vartheta \sin \frac{\Theta}{2} \\ -ie^{+i\varphi} \sin \vartheta \sin \frac{\Theta}{2} & \cos \frac{\Theta}{2} + i \cos \vartheta \sin \frac{\Theta}{2} \end{pmatrix}$$

$$(j+m-k) \geq 0$$

$$\text{or: } k \leq j+m$$

$$(n-m+k) \geq 0$$

$$\text{or: } k \geq m-n$$

$$k \geq 0$$

$$(j-n-k) \geq 0$$

$$\text{or: } k \leq j-n$$

Power p on $(D_{ab})^p$ must be zero or greater ($p \geq 0$).

Generating irreducible representations of $R(3)$ and $U(2)$ rotations $\mathbf{R}(\alpha\beta\gamma)$

Evaluating *irreducible representation of $U(2)$* :

$$\left\langle \begin{matrix} j \\ m \end{matrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{matrix} j \\ n \end{matrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \sum_k \frac{(D_{11})^{j+m-k} (D_{21})^{n-m+k} (D_{12})^k (D_{22})^{j-n-k}}{(j+m-k)!(n-m+k)! k! (j-n-k)!}$$

Easily done for *Euler angles* ($\alpha\beta\gamma$)

$$\begin{pmatrix} D_{11}^{1/2}(\alpha\beta\gamma) & D_{12}^{1/2}(\alpha\beta\gamma) \\ D_{21}^{1/2}(\alpha\beta\gamma) & D_{22}^{1/2}(\alpha\beta\gamma) \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} & -e^{-i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} \\ e^{i\frac{\alpha-\gamma}{2}} \sin \frac{\beta}{2} & e^{i\frac{\alpha+\gamma}{2}} \cos \frac{\beta}{2} \end{pmatrix}$$

k -Summation \sum_k limits amount to prohibiting a $p! = (-N)! = \infty$ factor in denominator.

Examples: $D_{m,n}^j = D_{2,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8+2=10, \quad k \geq 2-4=-2, \quad k \geq 0, \quad k \leq 8-4=4.$

$D_{m,n}^j = D_{-4,4}^8$ has sum: $\sum_{k=0}^4$ terms $k \leq 8-4=4, \quad k \geq 4-4=0. \quad k \geq 0, \quad k \leq 8-4=4$

$D_{m,n}^j = D_{-8,4}^8$ has sum: $\sum_{k=0}^0$ term $k \leq 8-8=0, \quad k \geq -8-4=-12. \quad k \geq 0, \quad k \leq 8-4=4$

$D_{m,n}^j = D_{-\frac{1}{2}, \frac{1}{2}}^{\frac{1}{2}}$ has sum: $\sum_{k=0}^0$ term $k \leq \frac{1}{2}-\frac{1}{2}=0, \quad k \geq -\frac{1}{2}-\frac{1}{2}=-1. \quad k \geq 0, \quad k \leq \frac{1}{2}-\frac{1}{2}=0$

or

$$\text{or } \begin{pmatrix} D_{11}^{1/2}[\varphi\vartheta\Theta] & D_{12}^{1/2}[\varphi\vartheta\Theta] \\ D_{21}^{1/2}[\varphi\vartheta\Theta] & D_{22}^{1/2}[\varphi\vartheta\Theta] \end{pmatrix} = \begin{pmatrix} \cos \frac{\Theta}{2} - i \cos \vartheta \sin \frac{\Theta}{2} & -ie^{-i\varphi} \sin \vartheta \sin \frac{\Theta}{2} \\ -ie^{+i\varphi} \sin \vartheta \sin \frac{\Theta}{2} & \cos \frac{\Theta}{2} + i \cos \vartheta \sin \frac{\Theta}{2} \end{pmatrix}$$

$$(j+m-k) \geq 0$$

$$\text{or: } k \leq j+m$$

$$(n-m+k) \geq 0$$

$$\text{or: } k \geq m-n$$

$$k \geq 0$$

$$(j-n-k) \geq 0$$

$$\text{or: } k \leq j-n$$

Power p on $(D_{ab})^p$ must be zero or greater ($p \geq 0$).

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

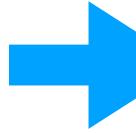
Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

 Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves $\leftarrow D^{L=2}_{m0} \sim Y^2_m$ d-waves $D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space, $\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular $D^{J^} \mathbf{m}\mathbf{n}(\alpha, \beta, \gamma)$ -wavefunctions*

$$\left\langle {}_m^j \middle| \mathbf{R}(\alpha\beta\gamma) \middle| {}_n^j \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \frac{\sum_k (-1)^k \left(\cos \frac{\beta}{2} \right)^{2j+m-n-2k} \left(\sin \frac{\beta}{2} \right)^{n-m+2k} e^{-i(m\alpha+n\gamma)}}{(j+m-k)!(n-m+k)!k!(j-n-k)!}$$

Vector ($j=\ell=1$) representation

$$D^1(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & . & . \\ . & 1 & . \\ . & . & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \begin{pmatrix} e^{-i\gamma} & . & . \\ . & 1 & . \\ . & . & e^{i\gamma} \end{pmatrix} = \begin{pmatrix} e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma} & e^{-i\alpha} \frac{-\sin\beta}{\sqrt{2}} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} e^{-i\gamma} & \frac{1-\cos\beta}{2} e^{-i\gamma} \\ e^{i\alpha} \frac{\sin\beta}{\sqrt{2}} e^{i\gamma} & e^{i\alpha} \frac{1+\cos\beta}{2} e^{i\gamma} \end{pmatrix}$$

Notation Switch:
azimuth angle:
 $\alpha \rightarrow \phi$
polar angle:
 $\beta \rightarrow \theta$

Here half-angle identities were used. $\cos^2 \frac{\beta}{2} = \frac{1+\cos\beta}{2}$, $\sin^2 \frac{\beta}{2} = \frac{1-\cos\beta}{2}$, $\sin \frac{\beta}{2} \cos \frac{\beta}{2} = \frac{\sin\beta}{2}$,

$$Y_1^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{-i\phi} \frac{-\sin\theta}{\sqrt{2}} = D_{1,0}^1(\phi, \theta)$$

$$Y_0^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} \cos\beta = D_{0,0}^1(\phi, \theta)$$

$$Y_{-1}^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{+i\phi} \frac{\sin\theta}{\sqrt{2}} = D_{-1,0}^1(\phi, \theta)$$

Atomic and molecular $D^{J^} \mathbf{m}\mathbf{n}(\alpha, \beta, \gamma)$ -wavefunctions*

$$\left\langle \begin{matrix} j \\ m \end{matrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{matrix} j \\ n \end{matrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!} \sqrt{(j+m)!(j-m)!} \frac{\sum_k (-1)^k \left(\cos \frac{\beta}{2} \right)^{2j+m-n-2k} \left(\sin \frac{\beta}{2} \right)^{n-m+2k} e^{-i(m\alpha+n\gamma)}}{(j+m-k)!(n-m+k)!k!(j-n-k)!}$$

Vector ($j=\ell=1$) representation

$$D^1(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \begin{pmatrix} e^{-i\gamma} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\gamma} \end{pmatrix} = \begin{pmatrix} e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} e^{-i\gamma} \\ e^{i\alpha} \frac{1-\cos\beta}{2} e^{-i\gamma} \end{pmatrix}$$

Notation Switch:
azimuth angle:
 $\alpha \rightarrow \phi$
polar angle:
 $\beta \rightarrow \theta$

Here half-angle identities were used. $\cos^2 \frac{\beta}{2} = \frac{1+\cos\beta}{2}$, $\sin^2 \frac{\beta}{2} = \frac{1-\cos\beta}{2}$, $\sin \frac{\beta}{2} \cos \frac{\beta}{2} = \frac{\sin\beta}{2}$,

Center ($n=0$) column with the factor $\sqrt{\frac{2\ell+1}{4\pi}}$
gives set of *spherical harmonics* Y_m^ℓ .

$$Y_m^\ell(\phi\theta) = D_{m,n=0}^{\ell*}(\phi\theta 0) \sqrt{\frac{2\ell+1}{4\pi}}$$

Dipole ($j=\ell=1$) wavefunctions

$$D_{1,0}^{1*}(\phi\theta 0) = -e^{i\phi} \frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi \sin\theta + i \cos\phi \sin\theta}{\sqrt{2}} = -\frac{x+iy}{r\sqrt{2}}$$

$$D_{0,0}^{1*}(\phi\theta 0) = \cos\theta = \cos\theta = z/r$$

$$D_{-1,0}^{1*}(\phi\theta 0) = e^{-i\phi} \frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi \sin\theta - i \cos\phi \sin\theta}{\sqrt{2}} = \frac{x-iy}{r\sqrt{2}}$$

$e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma}$	$e^{-i\alpha} \frac{-\sin\beta}{\sqrt{2}}$	$e^{-i\alpha} \frac{1-\cos\beta}{2} e^{i\gamma}$
$\cos\beta$	$\frac{-\sin\beta}{\sqrt{2}} e^{i\gamma}$	
$e^{i\alpha} \frac{\sin\beta}{\sqrt{2}}$	$e^{i\alpha} \frac{1+\cos\beta}{2} e^{i\gamma}$	

$Y_1^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{-i\phi} \frac{-\sin\theta}{\sqrt{2}} = D_{1,0}^1(\phi, \theta)$

$Y_0^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} \cos\theta = D_{0,0}^1(\phi, \theta)$

$Y_{-1}^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{+i\phi} \frac{\sin\theta}{\sqrt{2}} = D_{-1,0}^1(\phi, \theta)$

Atomic and molecular D^{J^} $\textcolor{blue}{m}\textcolor{red}{n}(\alpha, \beta, \gamma)$ -wavefunctions*

$$\left\langle \begin{smallmatrix} j \\ \textcolor{blue}{m} \end{smallmatrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{smallmatrix} j \\ \textcolor{green}{n} \end{smallmatrix} \right\rangle = D_{m,n}^j(\alpha\beta\gamma) = \sqrt{(j+\textcolor{green}{n})!(j-\textcolor{green}{n})!} \sqrt{(j+\textcolor{blue}{m})!(j-\textcolor{blue}{m})!} \frac{\sum_k (-1)^k \left(\cos \frac{\beta}{2} \right)^{2j+\textcolor{blue}{m}-\textcolor{green}{n}-2k} \left(\sin \frac{\beta}{2} \right)^{\textcolor{green}{n}-\textcolor{blue}{m}+2k} e^{-i(\textcolor{blue}{m}\alpha+\textcolor{green}{n}\gamma)}}{(j+\textcolor{blue}{m}-k)!(\textcolor{green}{n}-\textcolor{blue}{m}+k)!k!(j-\textcolor{green}{n}-k)!}$$

Vector ($j=\ell=1$) representation

$$D^1(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \begin{pmatrix} e^{-i\gamma} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\gamma} \end{pmatrix} = \begin{pmatrix} e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma} & e^{-i\alpha} \frac{-\sin\beta}{\sqrt{2}} & e^{-i\alpha} \frac{1-\cos\beta}{2} e^{-i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} e^{-i\gamma} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} e^{i\gamma} \\ e^{i\alpha} \frac{\sin\beta}{\sqrt{2}} & e^{i\alpha} \frac{1+\cos\beta}{2} e^{i\gamma} & e^{i\alpha} \frac{1-\cos\beta}{2} e^{i\gamma} \end{pmatrix}$$

Notation Switch:
azimuth angle:
 $\alpha \rightarrow \phi$
polar angle:
 $\beta \rightarrow \theta$

Here half-angle identities were used. $\cos^2 \frac{\beta}{2} = \frac{1+\cos\beta}{2}$, $\sin^2 \frac{\beta}{2} = \frac{1-\cos\beta}{2}$, $\sin \frac{\beta}{2} \cos \frac{\beta}{2} = \frac{\sin\beta}{2}$,

Center ($n=0$) column with the factor $\sqrt{\frac{2\ell+1}{4\pi}}$
gives set of *spherical harmonics* Y_m^ℓ .

$$Y_m^\ell(\phi\theta) = D_{m,n=0}^{\ell*}(\phi\theta 0) \sqrt{\frac{2\ell+1}{4\pi}}$$

Dipole ($j=\ell=1$) wavefunctions

$$D_{1,0}^{1*}(\phi\theta 0) = -e^{i\phi} \frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi \sin\theta + i \cos\phi \sin\theta}{\sqrt{2}} = -\frac{x+iy}{r\sqrt{2}}$$

$$D_{0,0}^{1*}(\phi\theta 0) = \cos\theta = \cos\theta = z/r$$

$$D_{-1,0}^{1*}(\phi\theta 0) = e^{-i\phi} \frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi \sin\theta - i \cos\phi \sin\theta}{\sqrt{2}} = \frac{x-iy}{r\sqrt{2}}$$

3-D linear-circular polarization T-matrix:

$$\begin{pmatrix} \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \\ \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \\ \left\langle \begin{smallmatrix} 1 \\ -1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ -1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ -1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \end{pmatrix} = \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \end{pmatrix}$$

$$\boxed{\begin{array}{ll} Y_1^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{-i\phi} \frac{-\sin\theta}{\sqrt{2}} = D_{1,0}^1(\phi, \theta) & \\ Y_0^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} \cos\theta = D_{0,0}^1(\phi, \theta) & \\ Y_{-1}^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{+i\phi} \frac{\sin\theta}{\sqrt{2}} = D_{-1,0}^1(\phi, \theta) & \end{array}}$$

Atomic and molecular D^{J^} $\textcolor{red}{m}\textcolor{green}{n}(\alpha, \beta, \gamma)$ -wavefunctions*

$$\left\langle \begin{smallmatrix} j \\ \textcolor{blue}{m} \end{smallmatrix} \middle| \mathbf{R}(\alpha\beta\gamma) \middle| \begin{smallmatrix} j \\ \textcolor{green}{n} \end{smallmatrix} \right\rangle = D_{\textcolor{blue}{m}, n}^j(\alpha\beta\gamma) = \sqrt{(j+\textcolor{green}{n})!(j-\textcolor{green}{n})!} \sqrt{(j+m)!(j-m)!} \frac{\sum_k (-1)^k \left(\cos \frac{\beta}{2} \right)^{2j+\textcolor{blue}{m}-\textcolor{green}{n}-2k} \left(\sin \frac{\beta}{2} \right)^{\textcolor{green}{n}-\textcolor{blue}{m}+2k} e^{-i(\textcolor{blue}{m}\alpha+\textcolor{green}{n}\gamma)}}{(j+\textcolor{blue}{m}-k)!(\textcolor{green}{n}-\textcolor{blue}{m}+k)!k!(j-\textcolor{green}{n}-k)!}$$

Vector ($j=\ell=1$) representation

$$D^1(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & -\sin\beta & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \begin{pmatrix} e^{-i\gamma} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\gamma} \end{pmatrix} = \begin{pmatrix} e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma} & \textcolor{blue}{e}^{-i\alpha} \frac{-\sin\beta}{\sqrt{2}} & e^{-i\alpha} \frac{1-\cos\beta}{2} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} e^{-i\gamma} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} e^{i\gamma} \\ e^{i\alpha} \frac{1-\cos\beta}{2} e^{-i\gamma} & e^{i\alpha} \frac{\sin\beta}{\sqrt{2}} & e^{i\alpha} \frac{1+\cos\beta}{2} e^{i\gamma} \end{pmatrix}$$

Notation Switch:
azimuth angle:
 $\alpha \rightarrow \phi$
polar angle:
 $\beta \rightarrow \theta$

Here half-angle identities were used. $\cos^2 \frac{\beta}{2} = \frac{1+\cos\beta}{2}$, $\sin^2 \frac{\beta}{2} = \frac{1-\cos\beta}{2}$, $\sin \frac{\beta}{2} \cos \frac{\beta}{2} = \frac{\sin\beta}{2}$,

$$Y_1^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{-i\phi} \frac{-\sin\theta}{\sqrt{2}} = D_{1,0}^1(\phi, \theta)$$

$$Y_0^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} \cos\beta = D_{0,0}^1(\phi, \theta)$$

$$Y_{-1}^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{+i\phi} \frac{\sin\theta}{\sqrt{2}} = D_{-1,0}^1(\phi, \theta)$$

Center ($n=0$) column with the factor $\sqrt{\frac{2\ell+1}{4\pi}}$
gives set of *spherical harmonics* Y_m^ℓ .

$$Y_m^\ell(\phi\theta) = D_{m,n=0}^{\ell*}(\phi\theta 0) \sqrt{\frac{2\ell+1}{4\pi}}$$

Dipole ($j=\ell=1$) wavefunctions

$$D_{1,0}^{1*}(\phi\theta 0) = -e^{i\phi} \frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi \sin\theta + i \cos\phi \sin\theta}{\sqrt{2}} = -\frac{x+iy}{r\sqrt{2}}$$

$$D_{0,0}^{1*}(\phi\theta 0) = \cos\theta = \cos\theta = z/r$$

$$D_{-1,0}^{1*}(\phi\theta 0) = e^{-i\phi} \frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi \sin\theta - i \cos\phi \sin\theta}{\sqrt{2}} = \frac{x-iy}{r\sqrt{2}}$$

3-D linear-circular polarization T-matrix:

$$\begin{pmatrix} \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \\ \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \\ \left\langle \begin{smallmatrix} -1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ x \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} -1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ y \end{smallmatrix} \right\rangle & \left\langle \begin{smallmatrix} -1 \\ 1 \end{smallmatrix} \middle| \begin{smallmatrix} 1 \\ z \end{smallmatrix} \right\rangle \end{pmatrix} = \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \end{pmatrix}$$

Applying T-matrix:

$$\begin{pmatrix} \frac{-1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} & 0 & \frac{i}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} \frac{1+\cos\beta}{2} & -\sin\beta & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \cdot \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \end{pmatrix} = \begin{pmatrix} \cos\beta & 0 & \sin\beta \\ 0 & 1 & 0 \\ -\sin\beta & 0 & \sin\beta \end{pmatrix}$$

$$\begin{pmatrix} \frac{-1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} & 0 & \frac{i}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} e^{-i\alpha} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \cdot \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{-i}{\sqrt{2}} & 0 \end{pmatrix} = \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} D_{x,x}^1(\alpha\beta\gamma) & D_{x,y}^1 & D_{x,z}^1 \\ D_{y,x}^1 & D_{y,y}^1 & D_{y,z}^1 \\ D_{z,x}^1 & D_{z,y}^1 & D_{z,z}^1 \end{pmatrix} = \begin{array}{l} \text{T-matrix transforms to} \\ \text{linear polarization (xyz) basis} \end{array}$$

$$\begin{pmatrix} \cos\alpha \cos\beta \cos\gamma - \sin\alpha \sin\gamma & -\cos\alpha \cos\beta \sin\gamma - \sin\alpha \cos\gamma & \cos\alpha \sin\beta \\ \sin\alpha \cos\beta \cos\gamma + \cos\alpha \sin\gamma & -\sin\alpha \cos\beta \sin\gamma + \cos\alpha \cos\gamma & \sin\alpha \sin\beta \\ -\cos\gamma \sin\beta & \sin\gamma \sin\beta & \cos\beta \end{pmatrix}$$

Atomic and molecular D^J ^{*}_{mn}(α, β, γ)-wavefunctions

Vector ($j=\ell=1$) representation

$$D^1(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & & & \\ & \ddots & & \\ & & 1 & \cdot \\ & & \cdot & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{2} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \end{pmatrix} \begin{pmatrix} e^{-i\gamma} & & & \\ & \ddots & & \\ & & 1 & \cdot \\ & & \cdot & e^{i\gamma} \end{pmatrix} = \begin{pmatrix} e^{-i\alpha} \frac{1+\cos\beta}{2} e^{-i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} e^{-i\gamma} \\ e^{i\alpha} \frac{1-\cos\beta}{2} e^{-i\gamma} \end{pmatrix}$$

$$\begin{pmatrix} e^{-i\alpha} \frac{-\sin\beta}{\sqrt{2}} \\ \cos\beta \\ e^{i\alpha} \frac{\sin\beta}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} e^{-i\alpha} \frac{1-\cos\beta}{2} e^{i\gamma} \\ \frac{-\sin\beta}{\sqrt{2}} e^{i\gamma} \\ e^{i\alpha} \frac{1+\cos\beta}{2} e^{i\gamma} \end{pmatrix}$$

Notation Switch:
azimuth angle:
 $\alpha \rightarrow \phi$
polar angle:
 $\beta \rightarrow \theta$

$$Y_1^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{-i\phi} \frac{-\sin\theta}{\sqrt{2}} = D_{1,0}^1(\phi, \theta)$$

$$Y_0^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} \cos\theta = D_{0,0}^1(\phi, \theta)$$

$$Y_{-1}^{1*}(\phi, \theta) = \sqrt{\frac{3}{4\pi}} e^{+i\phi} \frac{\sin\theta}{\sqrt{2}} = D_{-1,0}^1(\phi, \theta)$$

Here half-angle identities were used. $\cos^2 \frac{\beta}{2} = \frac{1+\cos\beta}{2}$, $\sin^2 \frac{\beta}{2} = \frac{1-\cos\beta}{2}$, $\sin \frac{\beta}{2} \cos \frac{\beta}{2} = \frac{\sin\beta}{2}$,

Center ($n=0$) column with the factor $\sqrt{\frac{2\ell+1}{4\pi}}$
gives set of *spherical harmonics* Y_m^ℓ .

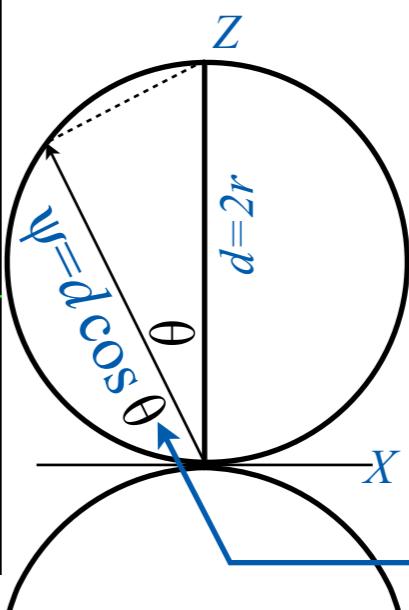
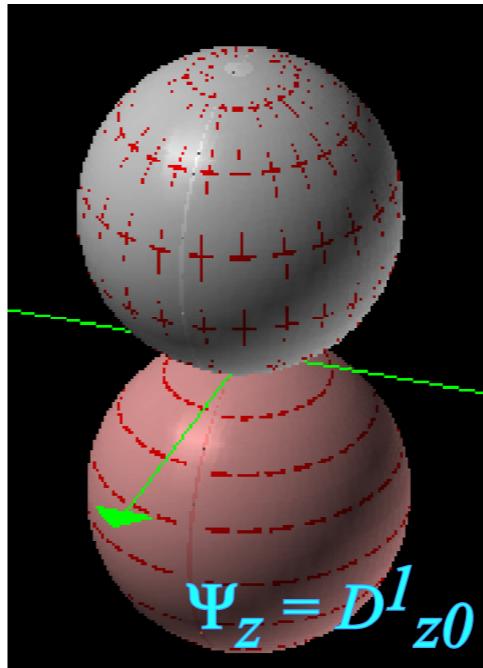
$$Y_m^\ell(\phi\theta) = D_{m,n=0}^{\ell*}(\phi\theta 0) \sqrt{\frac{2\ell+1}{4\pi}}$$

Dipole ($j=\ell=1$) wavefunctions

$$D_{1,0}^{1*}(\phi\theta 0) = -e^{i\phi} \frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi \sin\theta + i \sin\phi \sin\theta}{\sqrt{2}} = -\frac{x+iy}{r\sqrt{2}}$$

$$D_{0,0}^{1*}(\phi\theta 0) = \cos\theta = \cos\theta = z/r$$

$$D_{-1,0}^{1*}(\phi\theta 0) = e^{-i\phi} \frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi \sin\theta - i \sin\phi \sin\theta}{\sqrt{2}} = \frac{x-iy}{r\sqrt{2}}$$



$$\Psi_x^1(\phi, \theta) = D_{x,z}^1(\phi, \theta, 0)$$

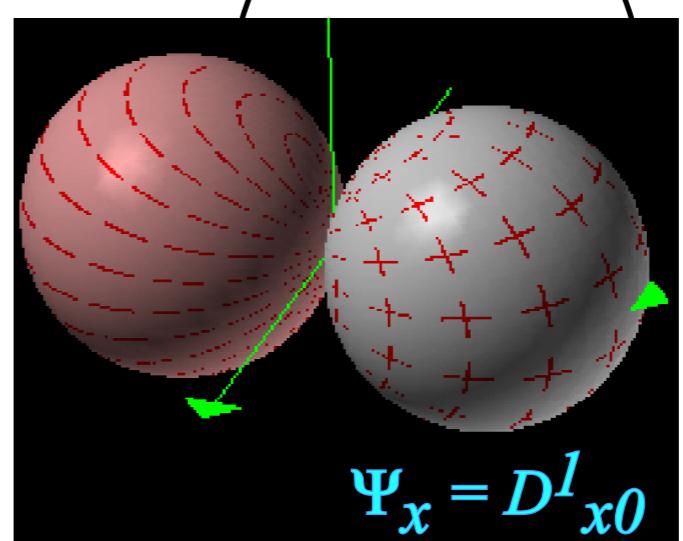
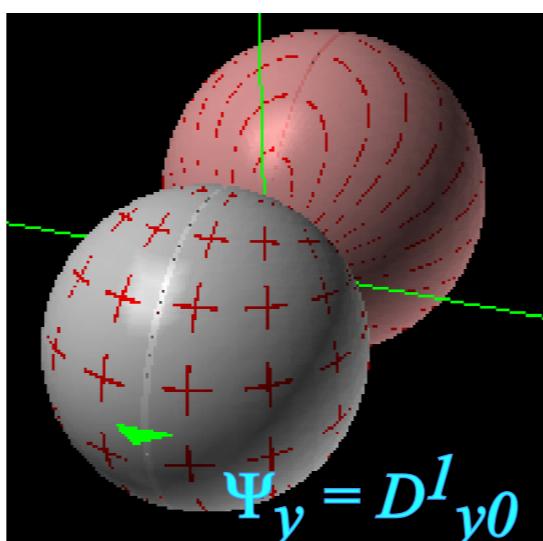
$$= \cos\phi \sin\theta$$

$$\Psi_y^1(\phi, \theta) = D_{y,z}^1(\phi, \theta, 0)$$

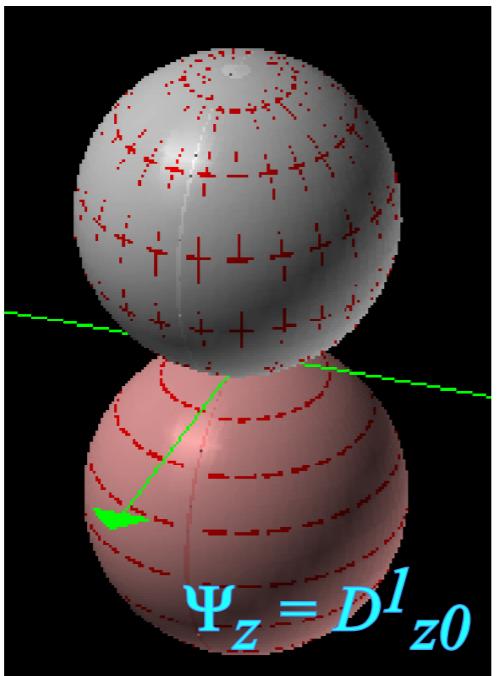
$$= \sin\phi \sin\theta$$

$$\Psi_z^1(\phi, \theta) = D_{z,z}^1(\phi, \theta, 0)$$

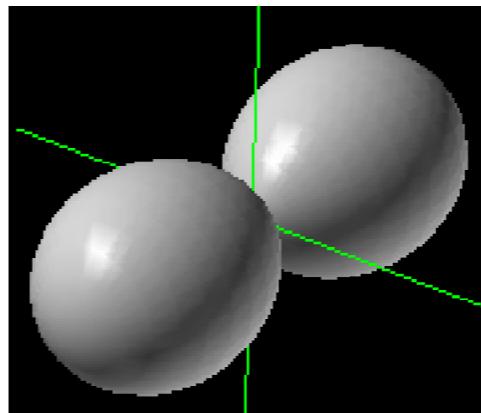
$$= \cos\theta$$



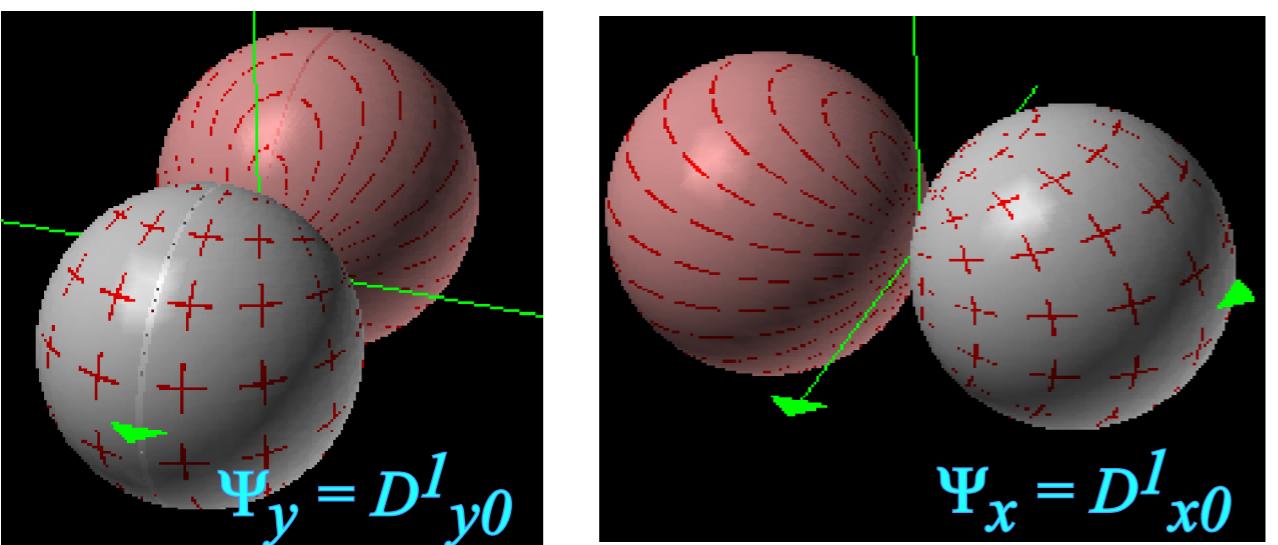
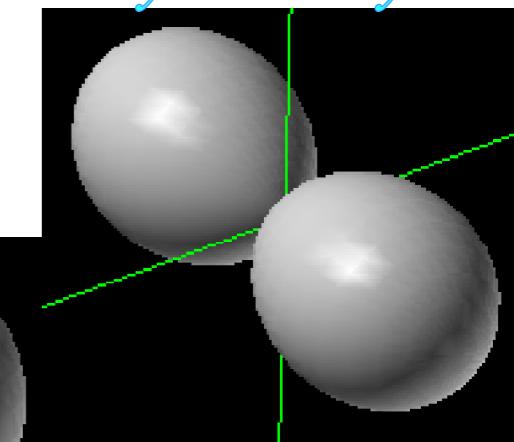
Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions and probability distributions



$$|\Psi_x|^2 = |D^1_{x0}|^2$$



$$|\Psi_y|^2 = |D^1_{y0}|^2$$



Standing *p*-Wave
Distributions

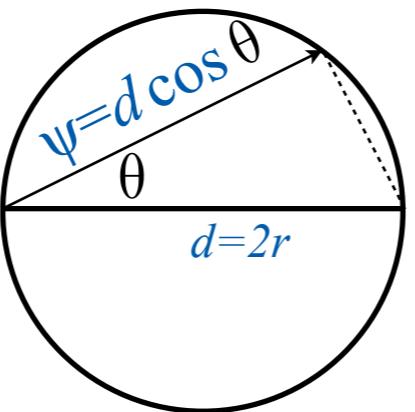
$$|\Psi_z|^2 = |D^1_{z0}|^2$$

Moving *p*-Wave
Distributions

$$|\Psi_{-1}|^2 = |D^1_{-10}|^2$$

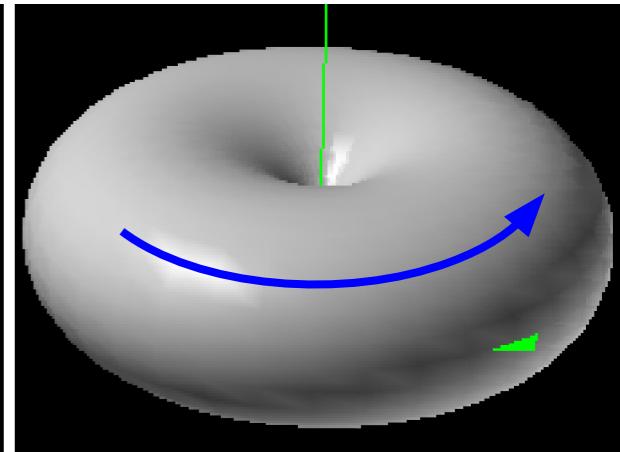
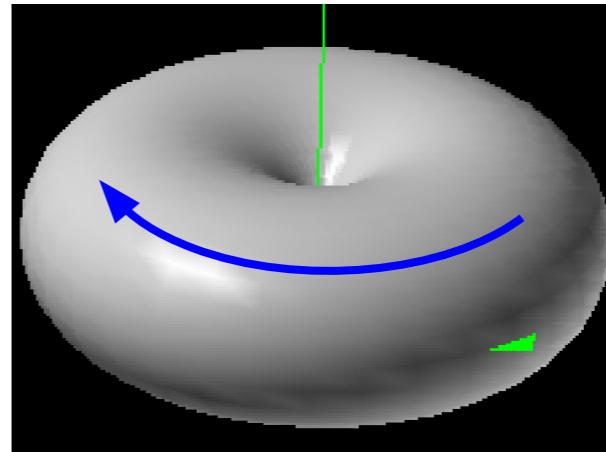
$$|\Psi_1|^2 = |D^1_{10}|^2$$

$$\begin{aligned}\Psi_x^1(\phi, \theta) &= D_{x,z}^1(\phi, \theta, 0) \\ &= \cos\phi \sin\theta\end{aligned}$$



$$\begin{aligned}\Psi_y^1(\phi, \theta) &= D_{y,z}^1(\phi, \theta, 0) \\ &= \sin\phi \sin\theta\end{aligned}$$

$$\begin{aligned}\Psi_z^1(\phi, \theta) &= D_{z,z}^1(\phi, \theta, 0) \\ &= \cos\theta\end{aligned}$$



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

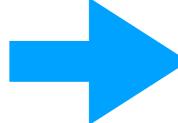
Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations



Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular $D^{J^*} m_n(\alpha, \beta, \gamma)$ -wavefunctions

Tensor ($j=\ell=2$) representation

$$D^2(\alpha\beta\gamma) = \begin{pmatrix} e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)^2 & e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & \sqrt{\frac{3}{8}}e^{-i2\alpha}\sin^2\beta & e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i2\alpha}\left(\frac{1-\cos\beta}{2}\right)^2 \\ e^{-i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i\alpha}\left(\frac{1+\cos\beta}{2}\right)(2\cos\beta-1) & -\sqrt{\frac{3}{2}}e^{-i\alpha}\sin\beta\cos\beta & e^{-i\alpha}\left(\frac{1-\cos\beta}{2}\right)(2\cos\beta+1) & -e^{-i\alpha}\left(\frac{1-\cos\beta}{2}\right)\sin\beta \\ \sqrt{\frac{3}{8}}\sin^2\beta & \sqrt{\frac{3}{2}}\sin\beta\cos\beta & \frac{3\cos^2\beta-1}{2} & \sqrt{\frac{3}{2}}\sin\beta\cos\beta & \sqrt{\frac{3}{8}}\sin^2\beta \\ e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i\alpha}\left(\frac{1-\cos\beta}{2}\right)(2\cos\beta+1) & \sqrt{\frac{3}{2}}e^{i\alpha}\sin\beta\cos\beta & e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)(2\cos\beta-1) & -e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta \\ e^{i2\alpha}\left(\frac{1-\cos\beta}{2}\right)^2 & e^{i2\alpha}\left(\frac{1-\cos\beta}{2}\right)\sin\beta & \sqrt{\frac{3}{8}}e^{i2\alpha}\sin^2\beta & e^{i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i2\alpha}\left(\frac{1+\cos\beta}{2}\right)^2 \end{pmatrix}$$

Atomic and molecular $D^{J^*} m_n(\alpha, \beta, \gamma)$ -wavefunctions

Tensor ($j=\ell=2$) representation

Notation Switch:

azimuth angle:

$$\alpha \rightarrow \phi$$

polar angle:

$$\beta \rightarrow \theta$$

$$D^2(\alpha\beta\theta) = \begin{pmatrix} e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)^2 & e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & \sqrt{\frac{3}{8}}e^{-i2\alpha}\sin^2\beta & e^{-i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i2\alpha}\left(\frac{1-\cos\beta}{2}\right)^2 \\ e^{-i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i\alpha}\left(\frac{1+\cos\beta}{2}\right)(2\cos\beta-1) & -\sqrt{\frac{3}{2}}e^{-i\alpha}\sin\beta\cos\beta & e^{-i\alpha}\left(\frac{1-\cos\beta}{2}\right)(2\cos\beta+1) & -e^{-i\alpha}\left(\frac{1-\cos\beta}{2}\right)\sin\beta \\ \sqrt{\frac{3}{8}}\sin^2\beta & \sqrt{\frac{3}{2}}\sin\beta\cos\beta & \frac{3\cos^2\beta-1}{2} & \sqrt{\frac{3}{2}}e^{i\alpha}\sin\beta\cos\beta & \sqrt{\frac{3}{2}}\sin\beta\cos\beta \\ e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i\alpha}\left(\frac{1-\cos\beta}{2}\right)(2\cos\beta+1) & \sqrt{\frac{3}{2}}e^{i\alpha}\sin\beta\cos\beta & e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)(2\cos\beta-1) & -e^{i\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta \\ e^{i2\alpha}\left(\frac{1-\cos\beta}{2}\right)^2 & e^{i2\alpha}\left(\frac{1-\cos\beta}{2}\right)\sin\beta & \sqrt{\frac{3}{8}}e^{i2\alpha}\sin^2\beta & e^{i2\alpha}\left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i2\alpha}\left(\frac{1+\cos\beta}{2}\right)^2 \end{pmatrix}$$

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}}\frac{(x+iy)^2}{r^2}$$

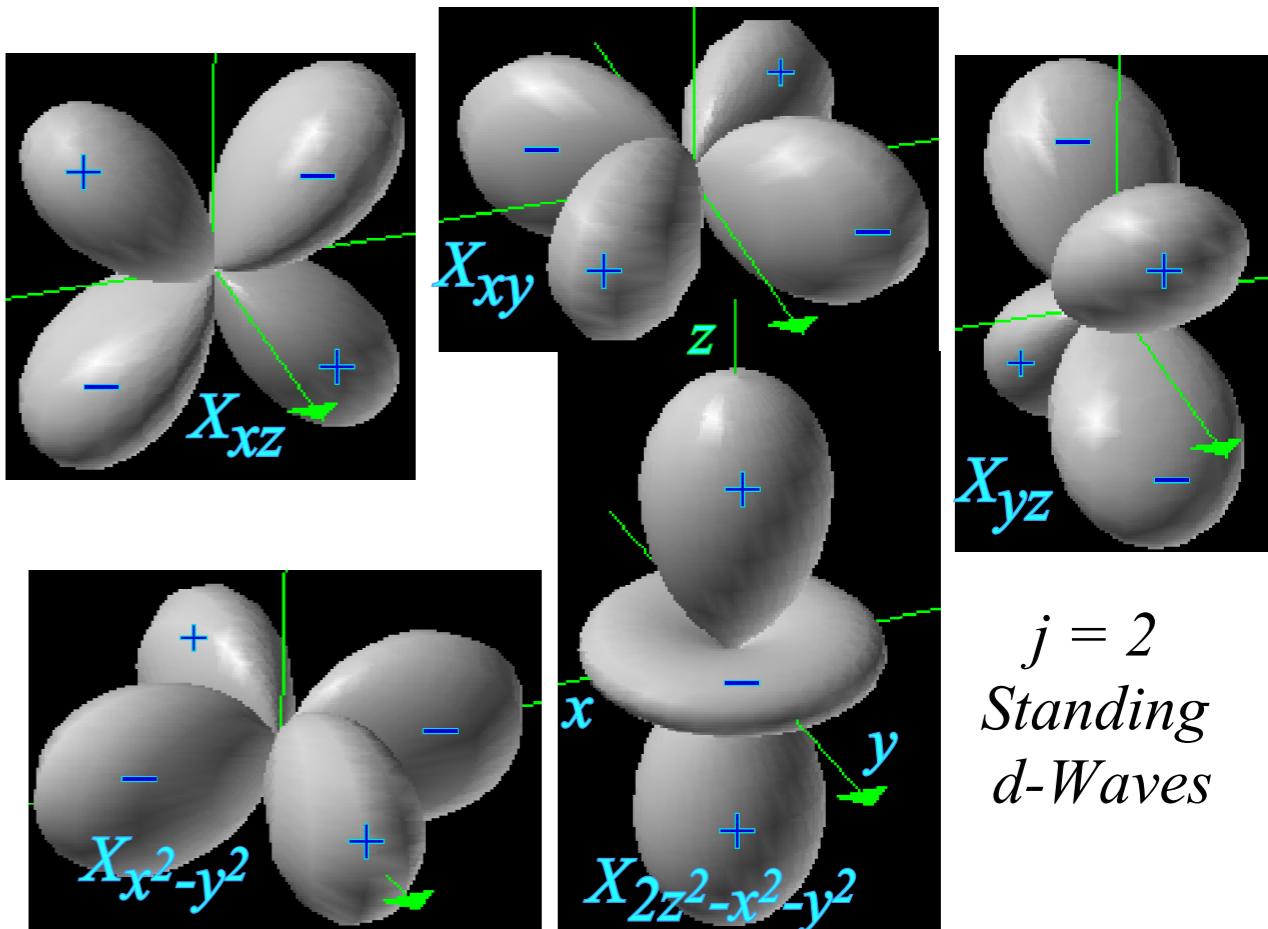
$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}}e^{i\phi}\sin\theta\cos\theta = -\sqrt{\frac{3}{2}}\frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta-1}{2} = \frac{3z^2-r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta = \sqrt{\frac{3}{2}}\frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}}\frac{(x-iy)^2}{r^2}$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$



Atomic and molecular $D^{J^*} m_n(\alpha, \beta, \gamma)$ -wavefunctions

Tensor ($j=\ell=2$) representation

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

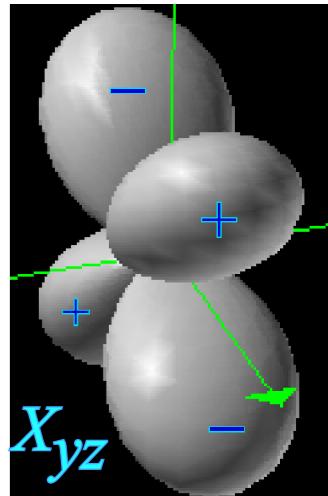
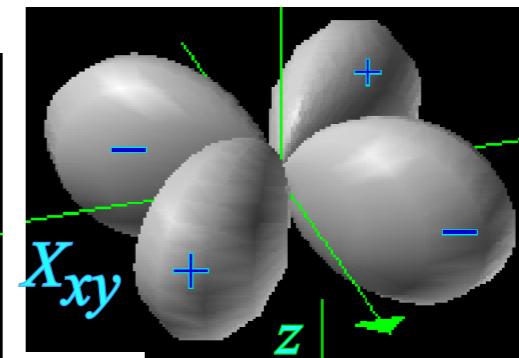
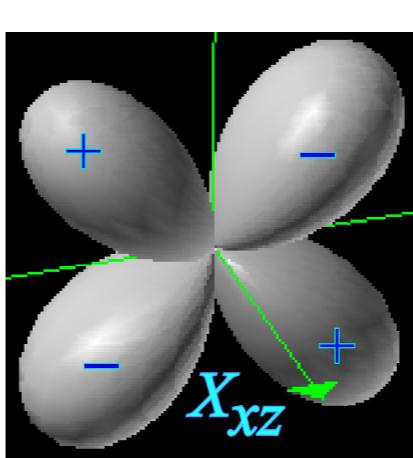
$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

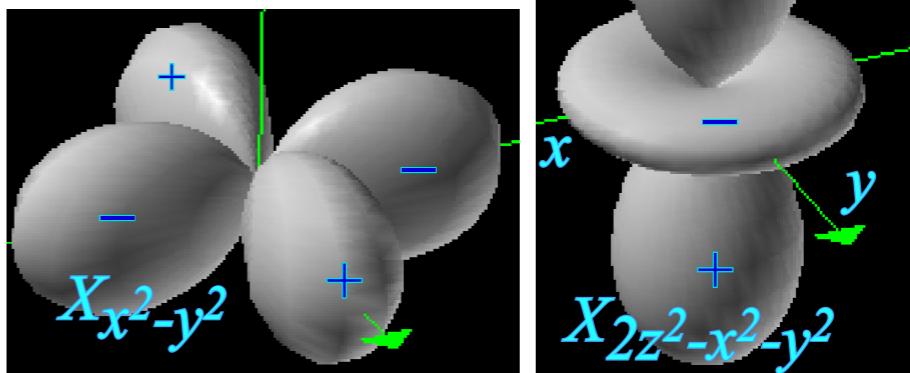
$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

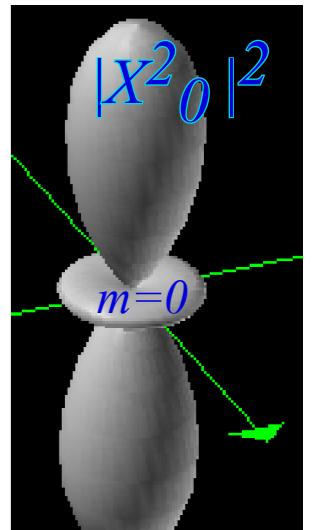
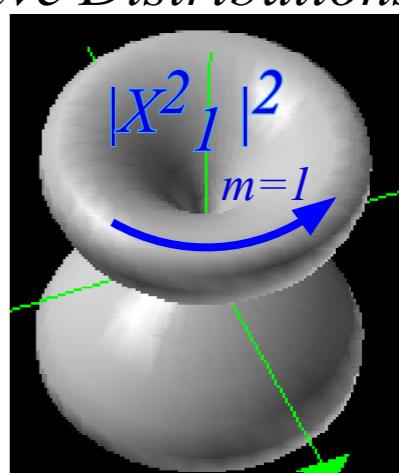
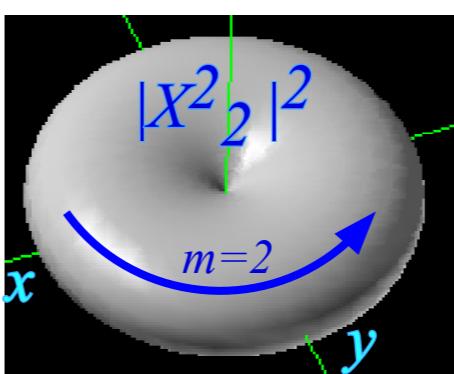
$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$



$j = 2$
Standing
 d -Waves



$j = 2$ Moving d -Wave Distributions



Notation Switch:

azimuth angle:

$\alpha \rightarrow \phi$

polar angle:

$\beta \rightarrow \theta$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

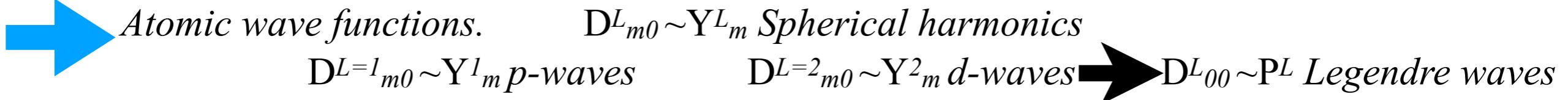
Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations



Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space, $\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular D^J $m_n(\alpha, \beta, \gamma)$ -wavefunctions

Legendre $P_\ell(\Theta)$ Multipole

Symmetric ($m = 0$) Polynomials

$$X_0^\ell = r^\ell D_{0,0}^{\ell*} = \sqrt{\frac{4\pi}{2\ell+1}} r^\ell Y_0^\ell$$

$$P_\ell(\Theta) = D_{0,0}^\ell(0, \Theta, 0)$$

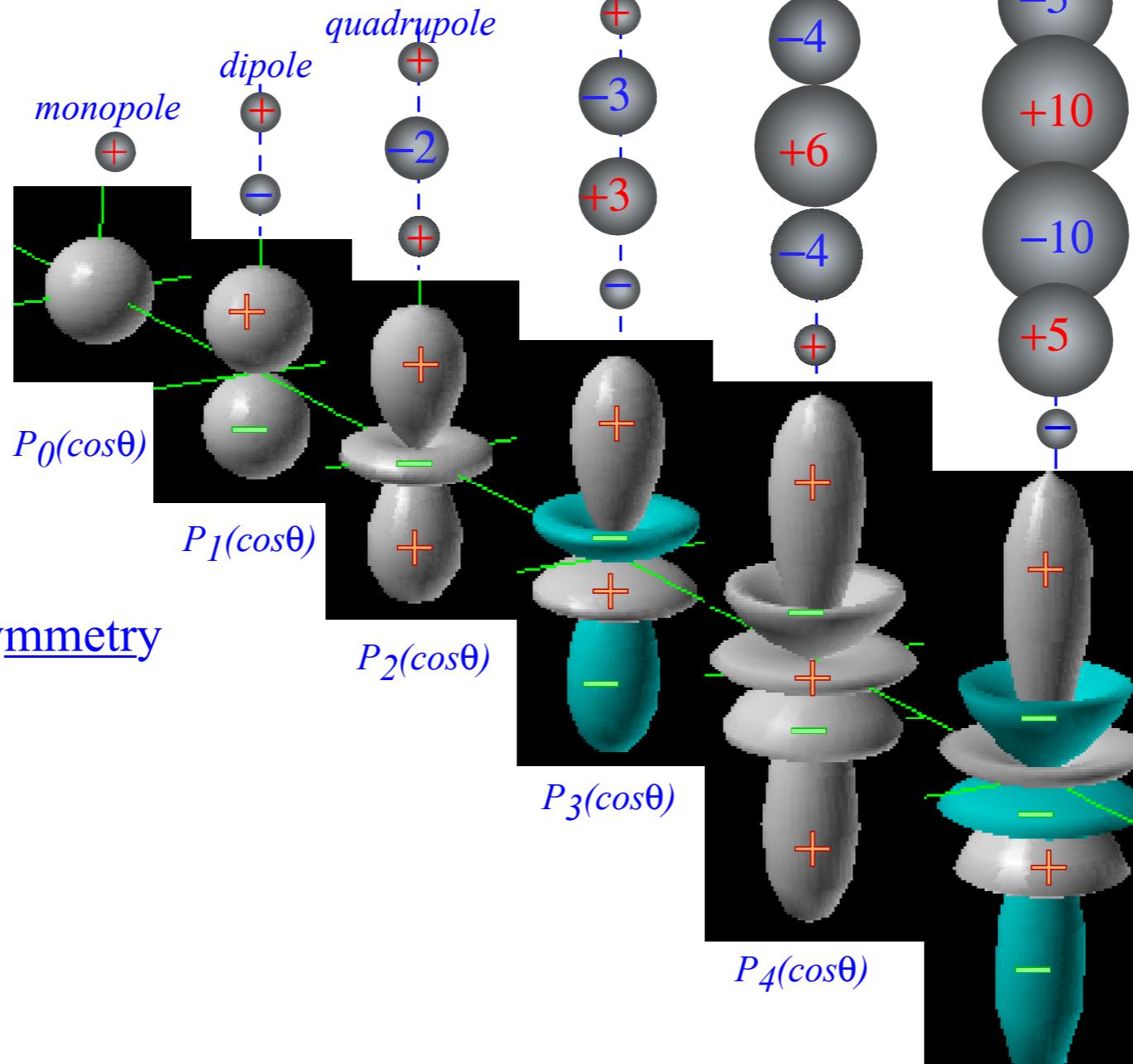
Notation Switch:

azimuth angle:

$\alpha \rightarrow \phi$

polar angle:

$\beta \rightarrow \theta$



$P_\ell(\cos\theta)$ cylindrical symmetry

If $m=0$ then wave is independent of the azimuth angle ϕ and only function of polar angle θ .

1	+1	+1	+1	+1	+1	+1
	-1	-1	-1	-1	-1	-1
	+1	+1	+1	+1	+1	+1
	-2	-2	-2	-2	-2	-2
	+3	+3	+3	+3	+3	+3
	-3	-3	-3	-3	-3	-3
	+6	+6	+6	+6	+6	+6
	-4	-4	-4	-4	-4	-4
	+10	+10	+10	+10	+10	+10
	-10	-10	-10	-10	-10	-10
	+5	+5	+5	+5	+5	+5
	-5	-5	-5	-5	-5	-5

Note

Pascal Triangle
of (+) and (-)
charges

Each charge distribution fits in a tiny space at origin of its $P_\ell(\cos\theta)$ wave

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

→ Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$ ←

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular $D^{J^*} m_n(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*} m_n(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

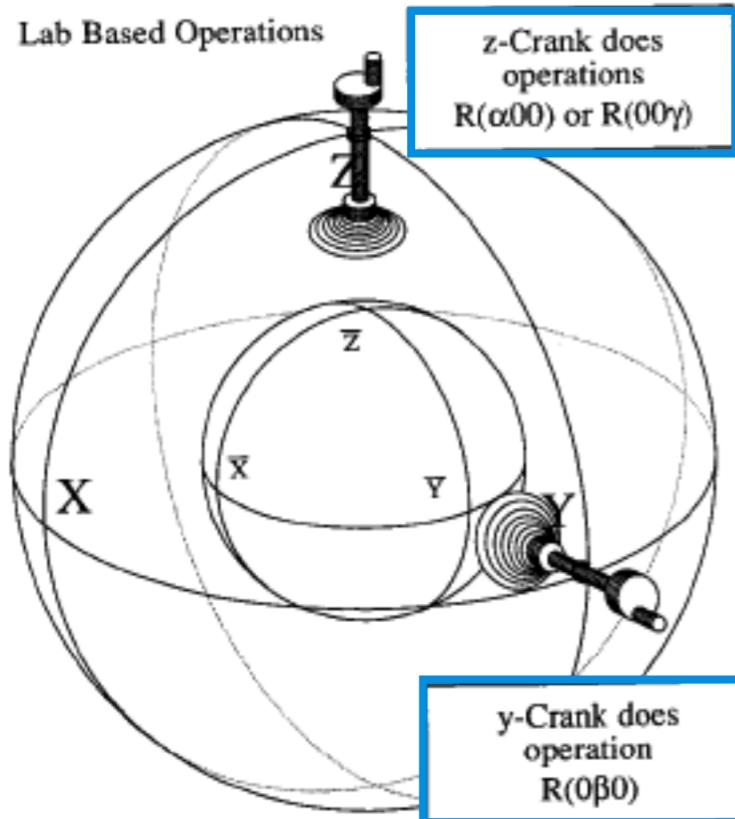
From [GroupThLect 25 p.15.](#)

*“Give me a place to stand...
and I will move the Earth”*

Archimedes 287-212 B.C.E

Ideas of duality/relativity go way back (...VanVleck, Casimir..., Mach, Newton, Archimedes...)

Lab-fixed(Extrinsic-Global) $\mathbf{R}, \mathbf{S}, \dots$ vs. Body-fixed (Intrinsic-Local) $\bar{\mathbf{R}}, \bar{\mathbf{S}}, \dots$



all $\mathbf{R}, \mathbf{S}, \dots$
commute with
all $\bar{\mathbf{R}}, \bar{\mathbf{S}}, \dots$

*“Mock-Mach”
relativity principles*

$$\begin{aligned} \mathbf{R}|1\rangle &= \bar{\mathbf{R}}^{-1}|1\rangle \\ \mathbf{S}|1\rangle &= \bar{\mathbf{S}}^{-1}|1\rangle \\ &\vdots \end{aligned}$$

...for one state $|1\rangle$ only!

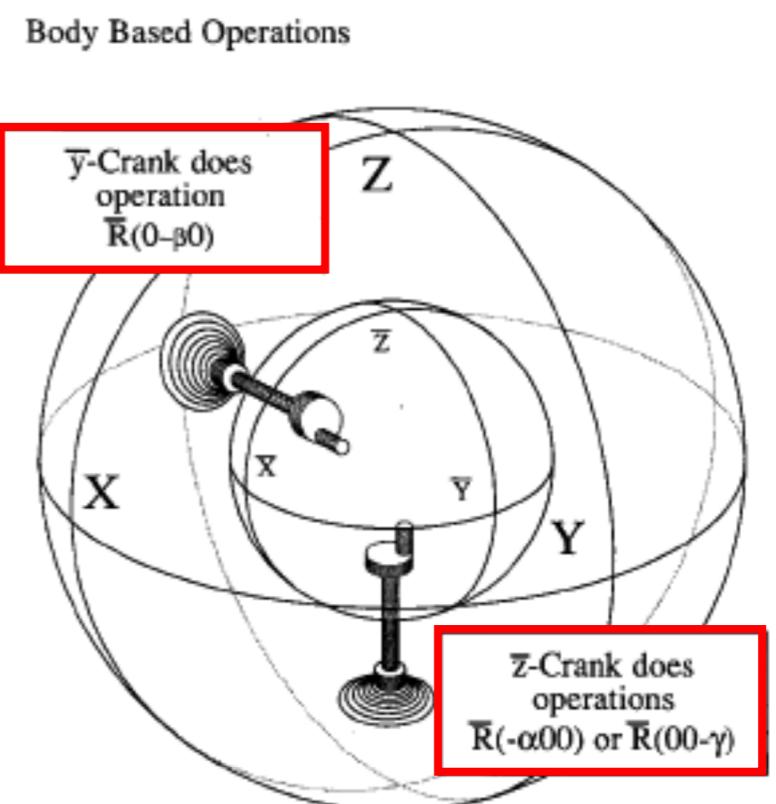
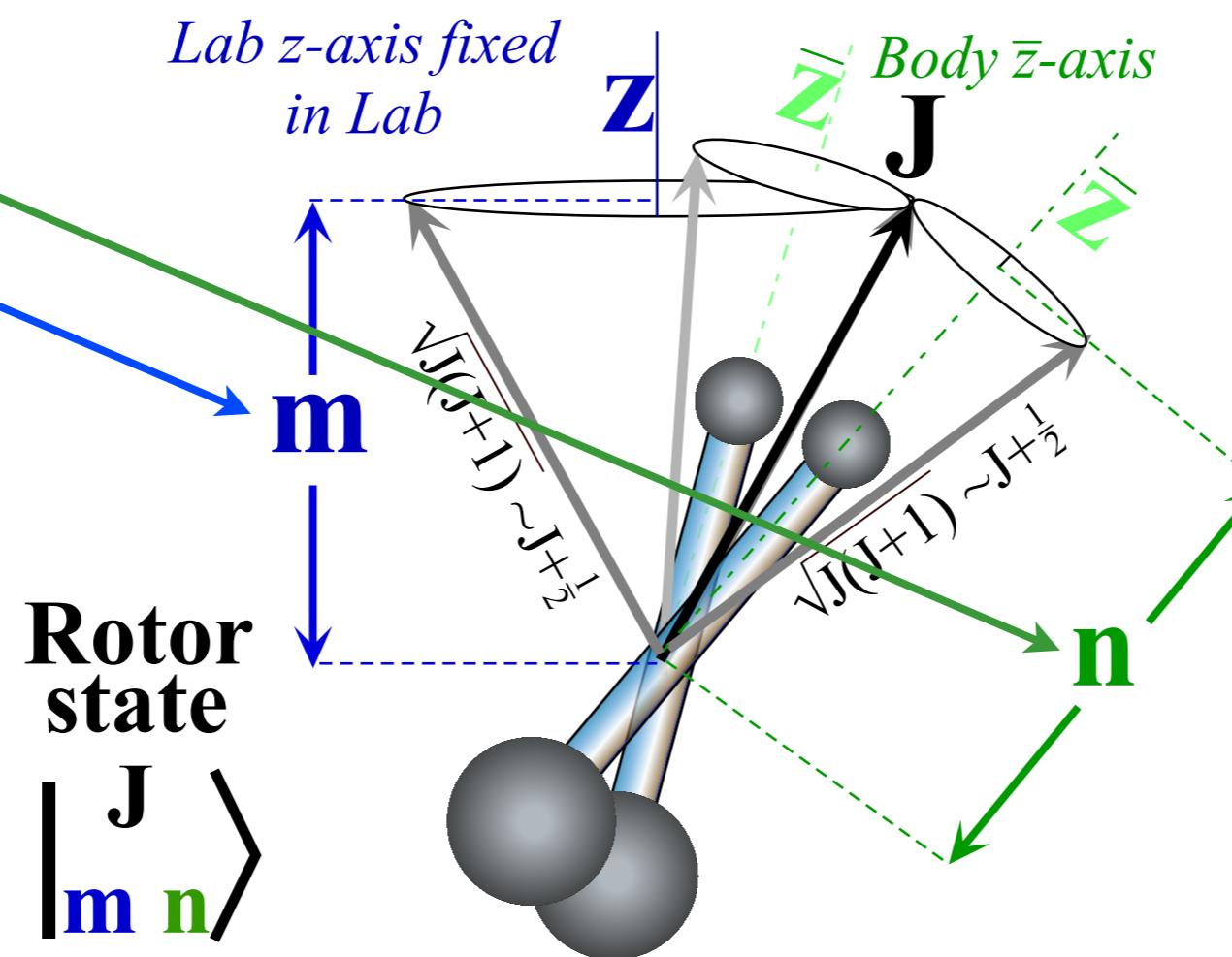


Figure from Ch. 5 of PSDS (Originally in Rev. Mod. Phys. 50, 1, p.37 (1978) Fig. 2)
[Ch. 5 of PSDS p328](#) [RModPhys50p37](#)

Atomic and molecular D^{J^}* $_{mn}(\alpha, \beta, \gamma)$ -wavefunctions
 “Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$|j_{m,n}\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}}$$



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

→ P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function ←

D^j_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^j_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

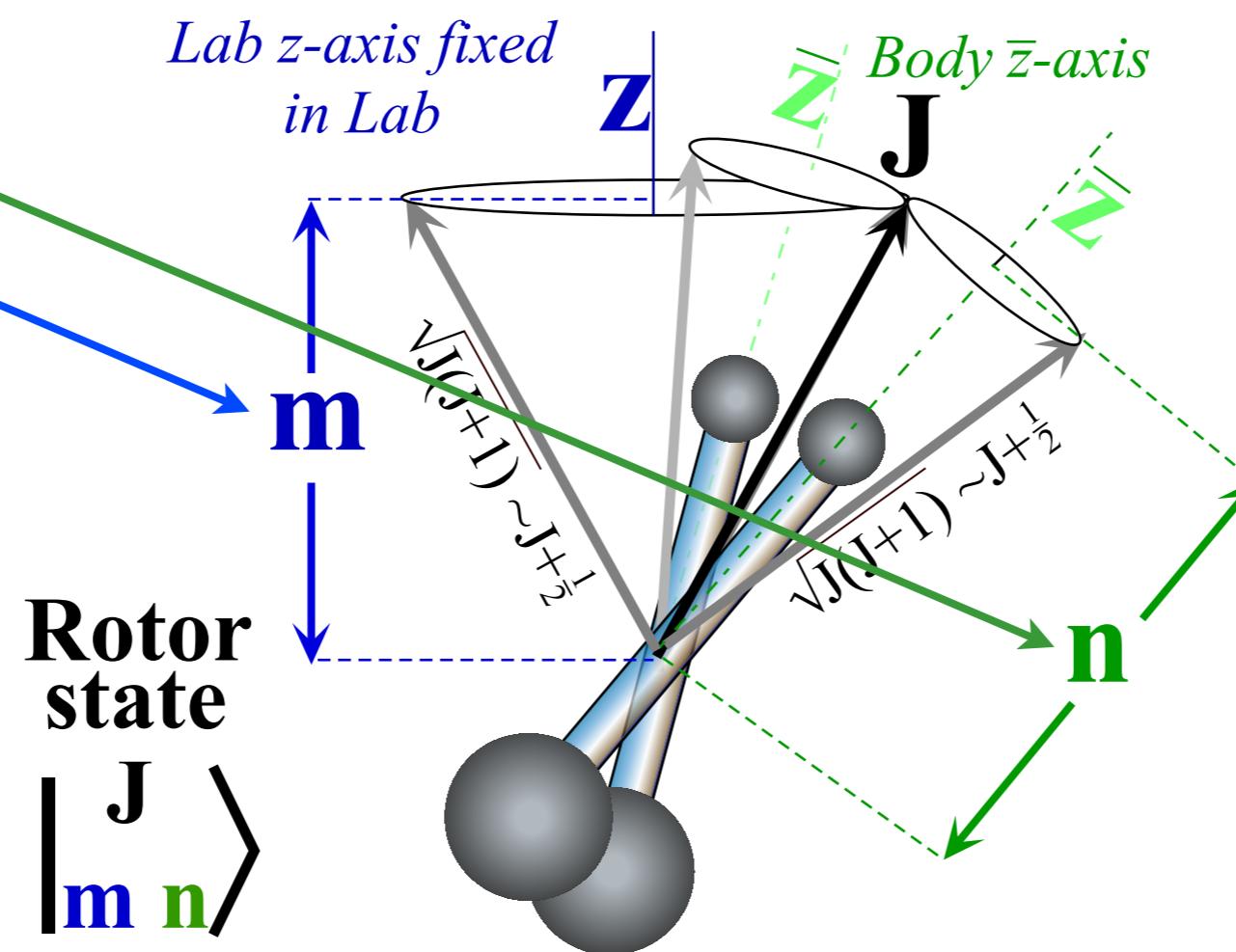
Atomic and molecular $D^{J^*}{}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}{}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, a sum over rotations is an integral over Euler angles (α, β, γ) .

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$|j_{m,n}\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha, \beta, \gamma) D_{m,n}^{j*}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha, \beta, \gamma) D_{m,n}^{j*}(\alpha, \beta, \gamma) \sqrt{\ell^j} |\alpha, \beta, \gamma\rangle$$



Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

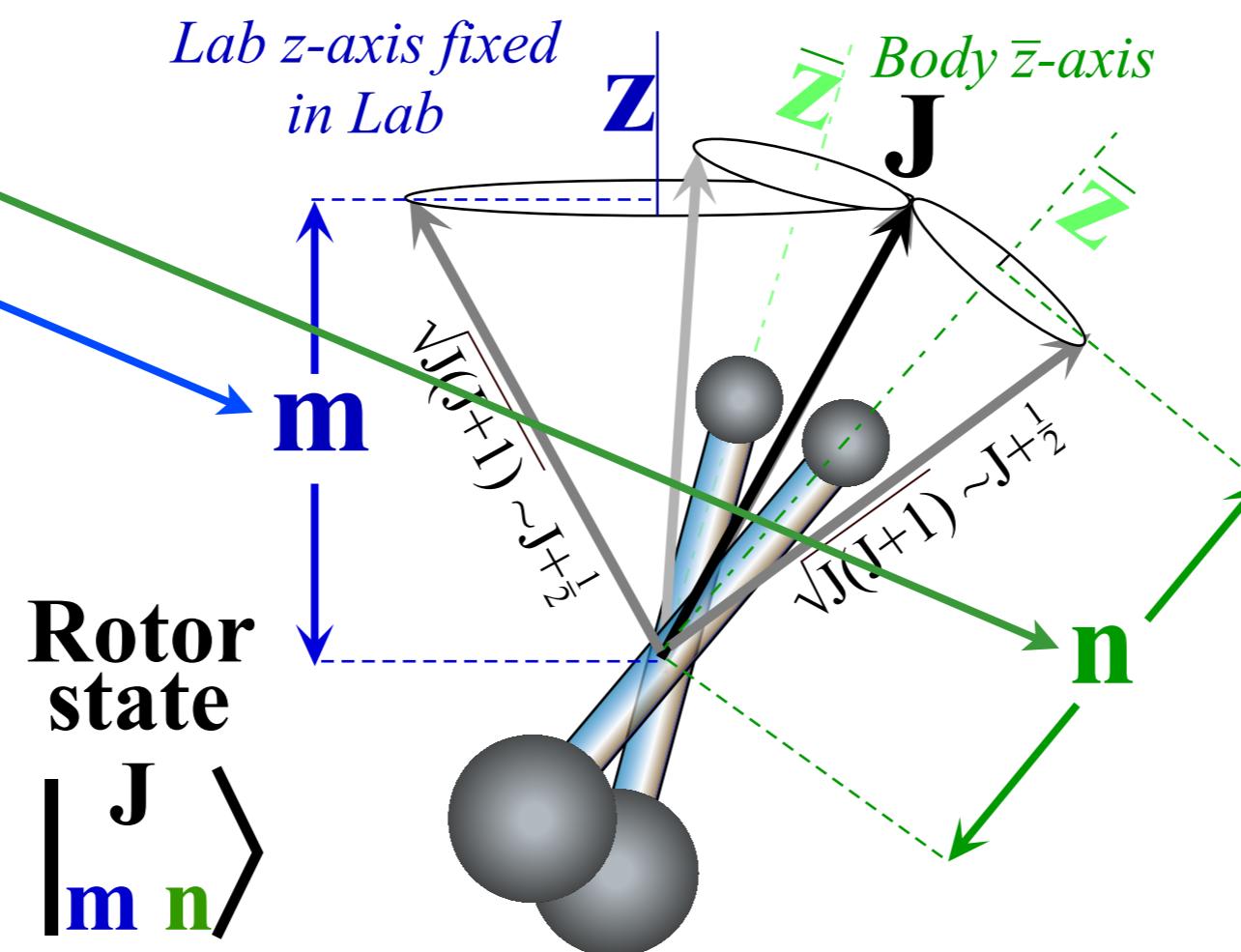
For $SU(2)$ and $R(3)$, a sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$|j_{m,n}\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} |\alpha \beta \gamma\rangle$$



Atomic and molecular $D^{J^*}{}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}{}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, a sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

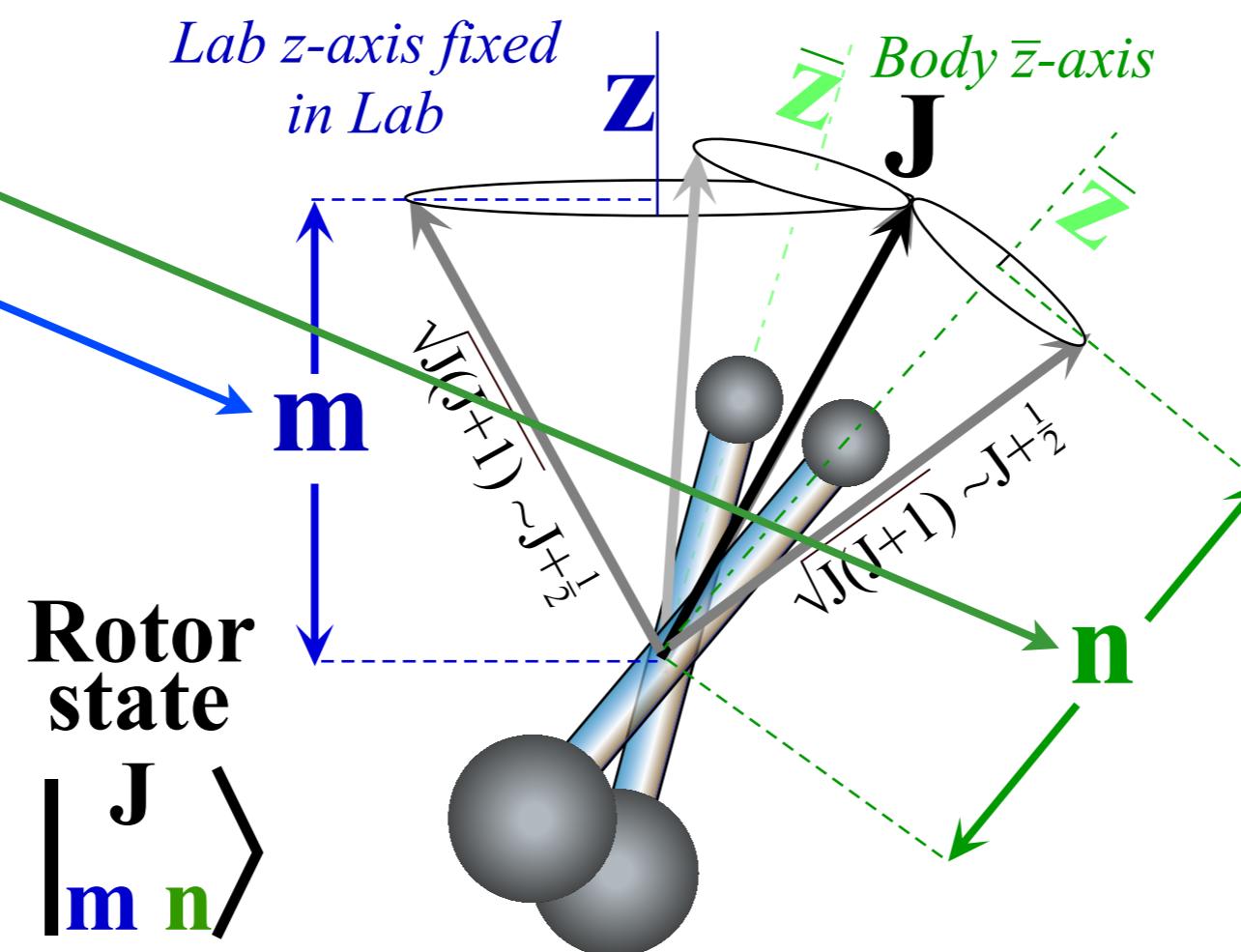
$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$|j_{m,n}\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} |\alpha \beta \gamma\rangle$$



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

→ D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space, ← $\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} |000\rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^j_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^j_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} |000\rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^J_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^J_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha \beta \gamma) |000\rangle = |\alpha \beta \gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha \beta \gamma) |000\rangle \quad (\alpha \beta \gamma) \text{ and } (\alpha' \beta' \gamma') \text{ for all } \bar{\mathbf{R}}(\alpha \beta \gamma) \bar{\mathbf{R}}(\alpha' \beta' \gamma') = \bar{\mathbf{R}}(\alpha' \beta' \gamma') \mathbf{R}(\alpha \beta \gamma)$$

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} | \alpha \beta \gamma \rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^j_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^j_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha \beta \gamma) |000\rangle = |\alpha \beta \gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha \beta \gamma) |000\rangle \quad (\alpha \beta \gamma) \text{ and } (\alpha' \beta' \gamma') \text{ for all } \bar{\mathbf{R}}(\alpha \beta \gamma) \bar{\mathbf{R}}(\alpha' \beta' \gamma') = \bar{\mathbf{R}}(\alpha' \beta' \gamma') \mathbf{R}(\alpha \beta \gamma)$$

Left hand (LAB- m) and right hand (BODY- n) quantum $SU(2)$ or $R(3)$ numbers apply to same state.

$$\text{LAB } m \leftrightarrow m' \text{ transform} \quad \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{m'=-j}^j D_{m',m}^j(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m', n \end{array} \right\rangle$$

$$\text{BOD } n \leftrightarrow n' \text{ transform} \quad \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{n'=-j}^j D_{n',n}^{j^*}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n' \end{array} \right\rangle$$

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} | \alpha \beta \gamma \rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^j_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^j_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha \beta \gamma) |000\rangle = |\alpha \beta \gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha \beta \gamma) |000\rangle \quad (\alpha \beta \gamma) \text{ and } (\alpha' \beta' \gamma') \text{ for all } \mathbf{R}(\alpha \beta \gamma) \bar{\mathbf{R}}(\alpha' \beta' \gamma') = \bar{\mathbf{R}}(\alpha' \beta' \gamma') \mathbf{R}(\alpha \beta \gamma)$$

Left hand (LAB- m) and right hand (BODY- n) quantum $SU(2)$ or $R(3)$ numbers apply to same state.

$$\text{LAB } m \leftrightarrow m' \text{ transform} \quad \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{m'=-j}^j D_{m',m}^j(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m', n \end{array} \right\rangle$$

$$\text{BOD } n \leftrightarrow n' \text{ transform} \quad \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{n'=-j}^j D_{n',n}^{j^*}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n' \end{array} \right\rangle$$

$$\left\langle \begin{array}{c} j \\ m', n \end{array} \right| \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = D_{m',m}^j(\alpha \beta \gamma)$$

$$\text{Dirac matrix notation} \quad \left\langle \begin{array}{c} j \\ m, n' \end{array} \right| \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = D_{n',n}^{j^*}(\alpha \beta \gamma)$$

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} | \alpha \beta \gamma \rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^j_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^j_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha \beta \gamma) |000\rangle = |\alpha \beta \gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha \beta \gamma) |000\rangle \quad (\alpha \beta \gamma) \text{ and } (\alpha' \beta' \gamma') \text{ for all } \mathbf{R}(\alpha \beta \gamma) \bar{\mathbf{R}}(\alpha' \beta' \gamma') = \bar{\mathbf{R}}(\alpha' \beta' \gamma') \mathbf{R}(\alpha \beta \gamma)$$

Left hand (LAB- m) and right hand (BODY- n) quantum $SU(2)$ or $R(3)$ numbers apply to same state.

$$\text{LAB } m \leftrightarrow m' \text{ transform} \quad \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{m'=-j}^j D_{m',m}^j(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m', n \end{array} \right\rangle$$

$$\text{BOD } n \leftrightarrow n' \text{ transform} \quad \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{n'=-j}^j D_{n',n}^{j^*}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n' \end{array} \right\rangle$$

$$\left\langle \begin{array}{c} j \\ m', n \end{array} \right| \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = D_{m',m}^j(\alpha \beta \gamma) \\ = 0 \text{ for unequal } n's$$

$$\text{Dirac matrix notation} \quad \left\langle \begin{array}{c} j \\ m, n' \end{array} \right| \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = D_{n',n}^{j^*}(\alpha \beta \gamma) \\ = 0 \text{ for unequal } m's$$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

→ D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space, ← ↔ $\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

“Mock-Mach” lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J |(0,0,0)\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathbf{R}(\alpha, \beta, \gamma) |(0,0,0)\rangle$

For $SU(2)$ and $R(3)$, sum over rotations is an integral over Euler angles (α, β, γ) .

For integral- $j=0, 1, 2, \dots$ the $R(3)$ integral over polar angle β ranges from 0 to π .

$$\text{for } R(3): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^2} \int_0^{2\pi} d\alpha \int_0^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

For integral- $j=1/2, 3/2, \dots$ the $U(2)$ integral over polar angle β ranges from $-\pi$ to π .

$$\text{for } SU(2): \frac{\ell^j}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{16\pi^2} \int_0^{2\pi} d\alpha \int_{-\pi}^\pi d\beta \sin \beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \frac{\mathbf{P}_{m,n}^j |000\rangle}{\sqrt{\ell^j}} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \mathbf{R}(\alpha \beta \gamma) |000\rangle \sqrt{\ell^j} = \frac{1}{N} \int d(\alpha \beta \gamma) D_{m,n}^{j^*}(\alpha \beta \gamma) \sqrt{\ell^j} | \alpha \beta \gamma \rangle$$

$R(3)$ rotation and $U(2)$ unitary $D^j_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^j_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha \beta \gamma) |000\rangle = |\alpha \beta \gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha \beta \gamma) |000\rangle \quad (\alpha \beta \gamma) \text{ and } (\alpha' \beta' \gamma') \text{ for all } \mathbf{R}(\alpha \beta \gamma) \bar{\mathbf{R}}(\alpha' \beta' \gamma') = \bar{\mathbf{R}}(\alpha' \beta' \gamma') \mathbf{R}(\alpha \beta \gamma)$$

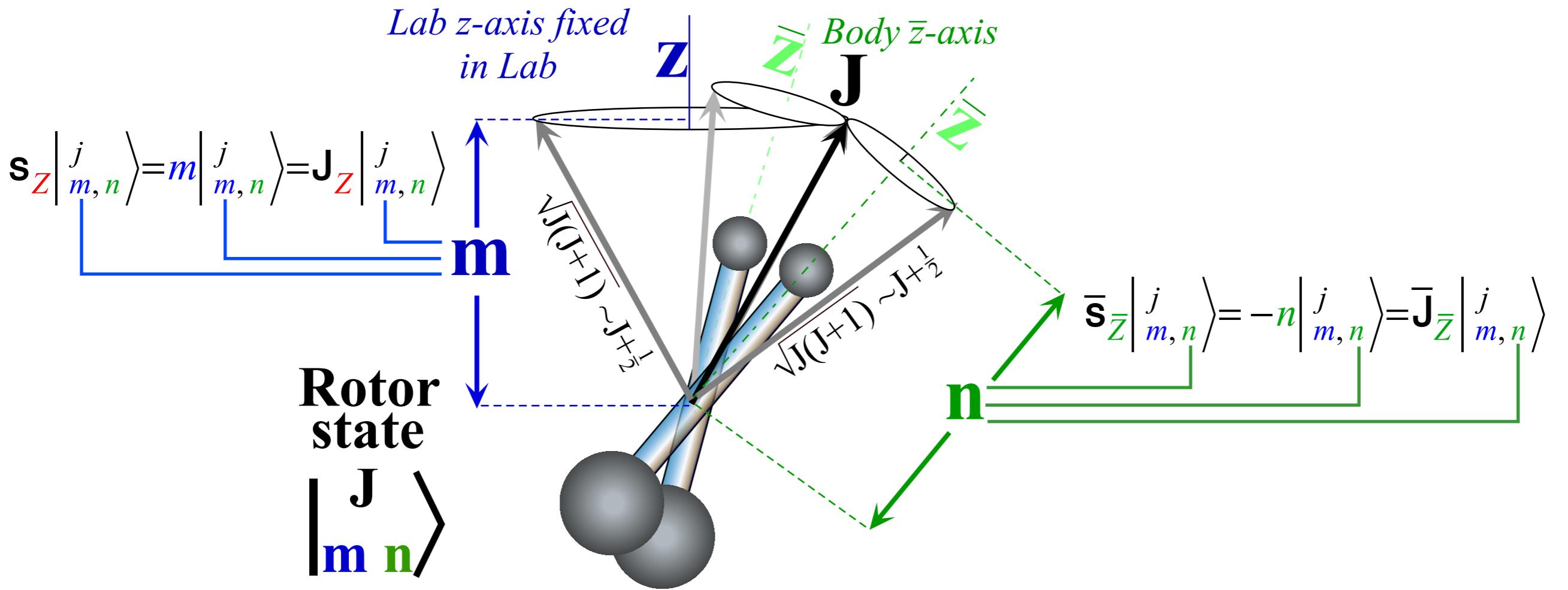
Left hand (LAB- m) and right hand (BODY- n) quantum $SU(2)$ or $R(3)$ numbers apply to same state.

$$\text{LAB } m \leftrightarrow m' \text{ transform} \quad \mathbf{R}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{m'=-j}^j D_{m',n}^j(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m', n \end{array} \right\rangle$$

$$\text{BOD } n \leftrightarrow n' \text{ transform} \quad \bar{\mathbf{R}}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = \sum_{n'=-j}^j D_{n',n}^{j^*}(\alpha \beta \gamma) \left| \begin{array}{c} j \\ m, n' \end{array} \right\rangle$$

$$\text{LAB } m \text{ eigenvalues} \quad \mathbf{s}_Z \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = m \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle \quad \text{LAB } m \text{ Z-quanta}$$

$$\text{BOD } n \text{ eigenvalues} \quad \bar{\mathbf{s}}_{\bar{Z}} \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle = -n \left| \begin{array}{c} j \\ m, n \end{array} \right\rangle \quad \text{BOD } -n \text{ Z-quanta}$$



R(3) rotation and U(2) unitary $D^J_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D^J_{m'm}(\alpha, \beta, \gamma) |J'_{m'n}\rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha\beta\gamma) |000\rangle = |\alpha\beta\gamma\rangle = \bar{\mathbf{R}}^\dagger(\alpha\beta\gamma) |000\rangle \quad \text{for all } (\alpha\beta\gamma) \text{ and } (\alpha'\beta'\gamma') \quad \mathbf{R}(\alpha\beta\gamma) \bar{\mathbf{R}}(\alpha'\beta'\gamma') = \bar{\mathbf{R}}(\alpha'\beta'\gamma') \mathbf{R}(\alpha\beta\gamma)$$

Left hand (LAB-*m*) and right hand (BODY-*n*) quantum *SU(2)* or *R(3)* numbers apply to same state.

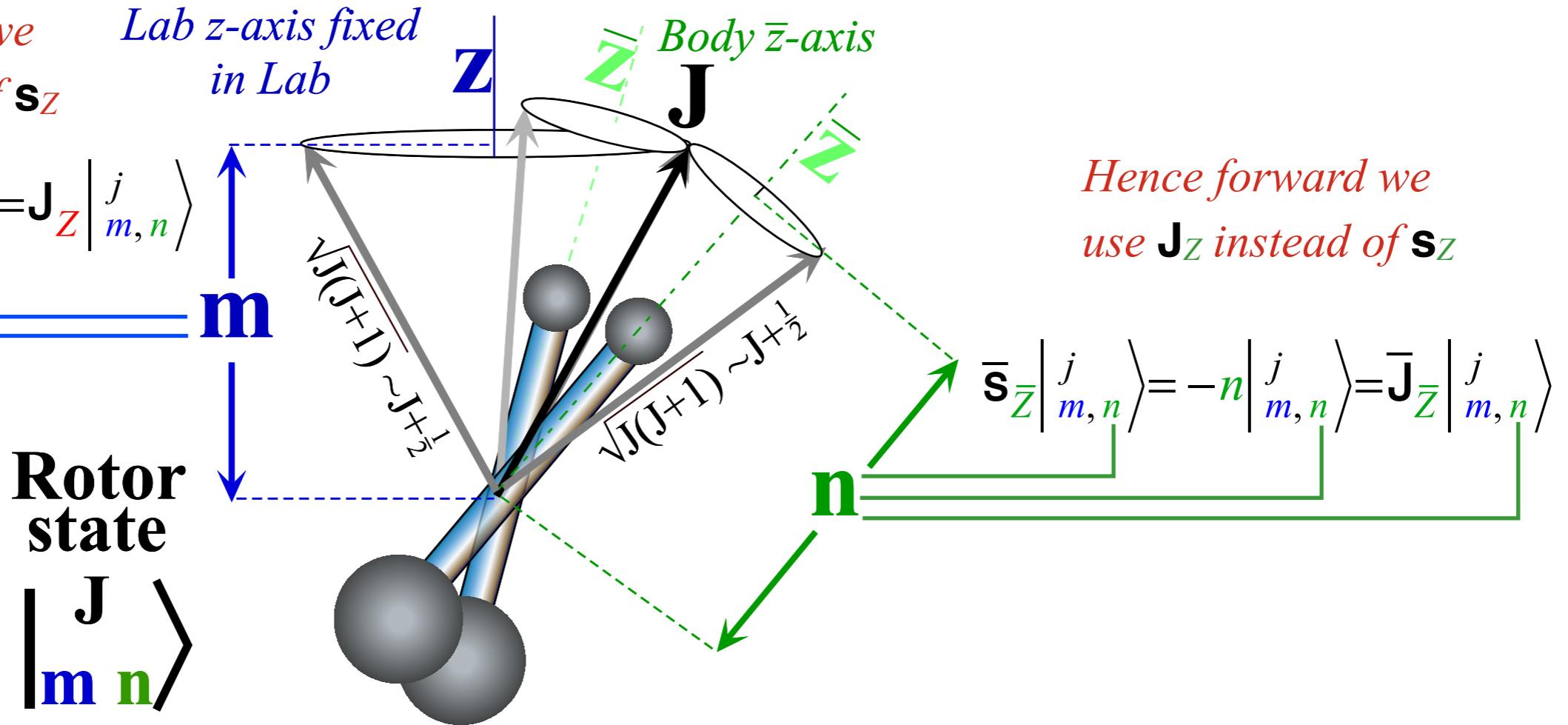
$$\begin{array}{l} \text{LAB } m \leftrightarrow m' \\ \text{transform} \end{array} \quad \mathbf{R}(\alpha\beta\gamma) |j_{m,n}\rangle = \sum_{m'=-j}^j D^j_{m',n}(\alpha\beta\gamma) |j_{m',n}\rangle$$

$$\begin{array}{l} \text{BOD } n \leftrightarrow n' \\ \text{transform} \end{array} \quad \bar{\mathbf{R}}(\alpha\beta\gamma) |j_{m,n}\rangle = \sum_{n'=-j}^j D^{j*}_{n',n}(\alpha\beta\gamma) |j_{m,n'}\rangle$$

$$\begin{array}{ll} \text{LAB } m \\ \text{eigenvalues} \end{array} \quad s_Z |j_{m,n}\rangle = m |j_{m,n}\rangle \quad \begin{array}{ll} \text{LAB } m \\ \text{Z-quanta} \end{array}$$

$$\begin{array}{ll} \text{BOD } n \\ \text{eigenvalues} \end{array} \quad \bar{s}_{\bar{Z}} |j_{m,n}\rangle = -n |j_{m,n}\rangle \quad \begin{array}{ll} \text{BOD } -n \\ \text{Z-quanta} \end{array}$$

Hence forward we use \mathbf{J}_Z instead of \mathbf{s}_Z



Hence forward we use \mathbf{J}_Z instead of \mathbf{s}_Z

$R(3)$ rotation and $U(2)$ unitary $D_{mn}^{Jm}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) | J_{mn} \rangle = \sum_{m'} D_{m'm}^{Jm}(\alpha, \beta, \gamma) | J_{m'n} \rangle$

Angular position is defined by a *rotational duality relativity relation* or “Mock-Mach” principle

$$\mathbf{R}(\alpha\beta\gamma) | 000 \rangle = | \alpha\beta\gamma \rangle = \bar{\mathbf{R}}^\dagger(\alpha\beta\gamma) | 000 \rangle \quad \text{for all } (\alpha\beta\gamma) \text{ and } (\alpha'\beta'\gamma') \quad \mathbf{R}(\alpha\beta\gamma)\bar{\mathbf{R}}(\alpha'\beta'\gamma') = \bar{\mathbf{R}}(\alpha'\beta'\gamma')\mathbf{R}(\alpha\beta\gamma)$$

Left hand (LAB- m) and right hand (BODY- n) quantum $SU(2)$ or $R(3)$ numbers apply to same state.

LAB $m \leftrightarrow m'$ transform $\mathbf{R}(\alpha\beta\gamma) | j_{m,n} \rangle = \sum_{m'=-j}^j D_{m',n}^j(\alpha\beta\gamma) | j_{m',n} \rangle$

BOD $n \leftrightarrow n'$ transform $\bar{\mathbf{R}}(\alpha\beta\gamma) | j_{m,n} \rangle = \sum_{n'=-j}^j D_{n',n}^{j*}(\alpha\beta\gamma) | j_{m,n'} \rangle$

LAB m eigenvalues $\mathbf{J}_Z | j_{m,n} \rangle = m | j_{m,n} \rangle$ LAB m Z-quanta

BOD n eigenvalues $\bar{\mathbf{J}}_{\bar{Z}} | j_{m,n} \rangle = -n | j_{m,n} \rangle$ BOD $-n$ Z-quanta

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

→ D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization) ←

Θ^J_m -cone properties of lab transforms: $J=20, J=10, J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

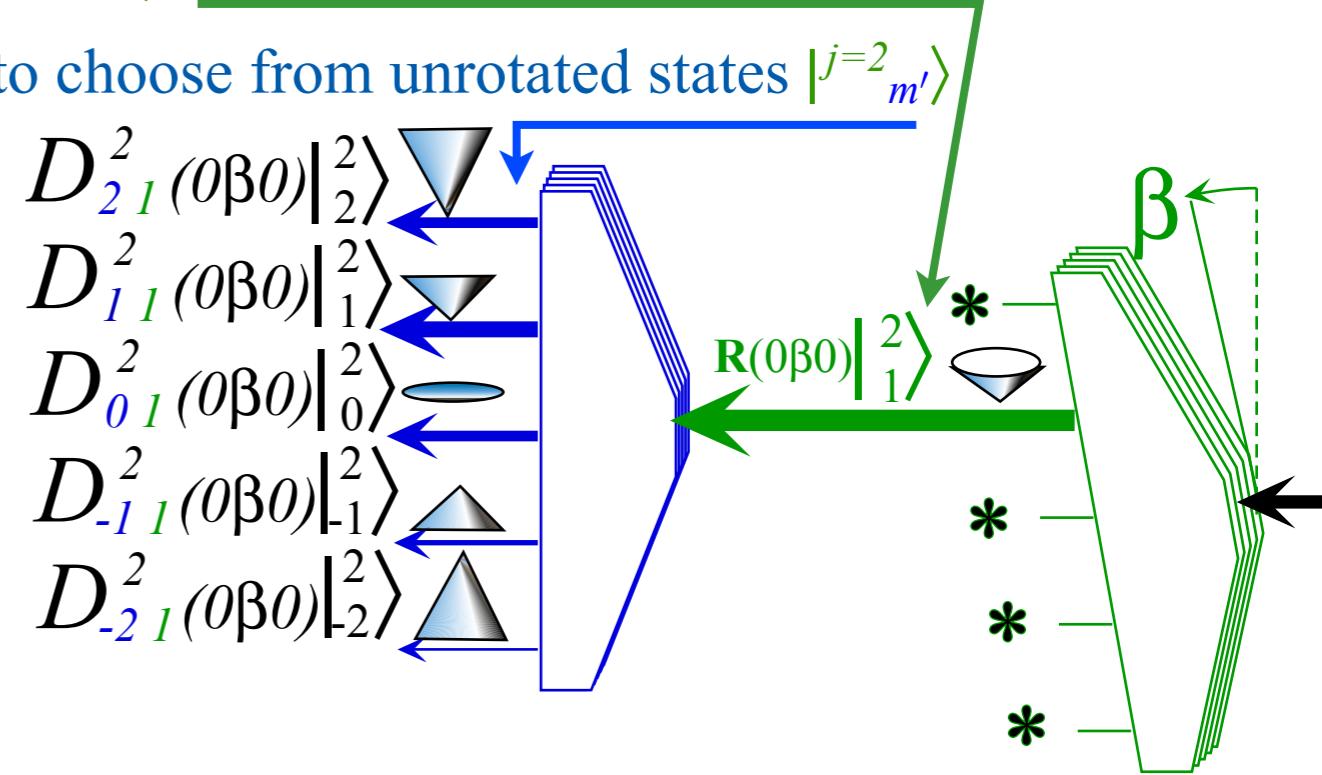
R(3) rotation and U(2) unitary $D^J_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'm}(\alpha, \beta, \gamma)|J_{m'n}\rangle$

Polarization analysis: Suppose a spin-j state $\mathbf{R}(0\beta 0)|^{j=2}_{n=1}\rangle$ exits an analyzer rotated by β

and then enters a vertical ($\beta=0$) analyzer and forced to choose from unrotated states $|^{j=2}_{m'}\rangle$

$$\begin{aligned}\mathbf{R}(0\beta 0)|^j_n\rangle &= \sum_{m'=-j}^j |^j_{m'}\rangle \langle^j_{m'}| \mathbf{R}(0\beta 0)|^j_n\rangle \\ &= \sum_{m'=-j}^j |^j_{m'}\rangle D^j_{m'n}(0\beta 0)\end{aligned}$$



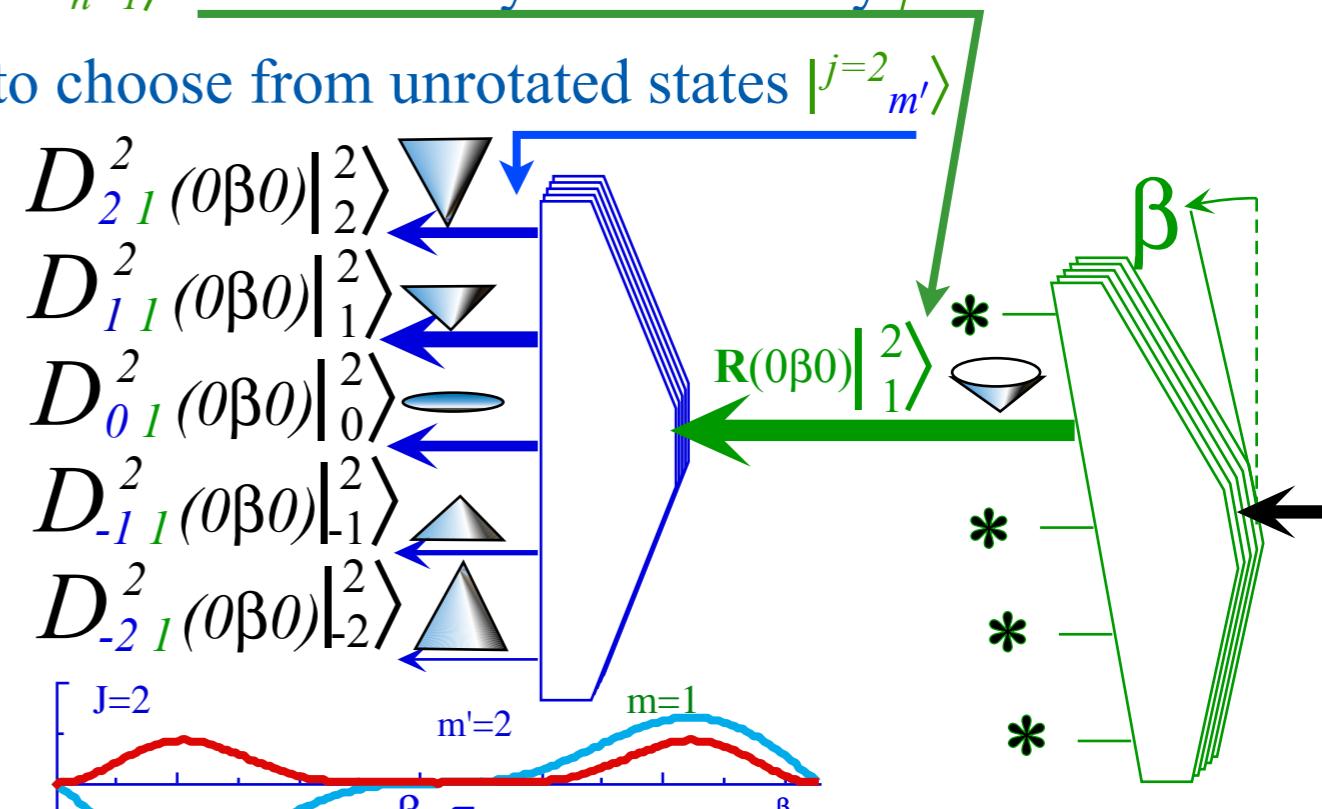
$R(3)$ rotation and $U(2)$ unitary $D_{mn}^j(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{mn}\rangle = \sum_{m'} D_{m'm}^j(\alpha, \beta, \gamma) |J_{m'n}\rangle$

Polarization analysis: Suppose a spin- j state $\mathbf{R}(0\beta 0) |J_{n=1}\rangle$ exits an analyzer rotated by β

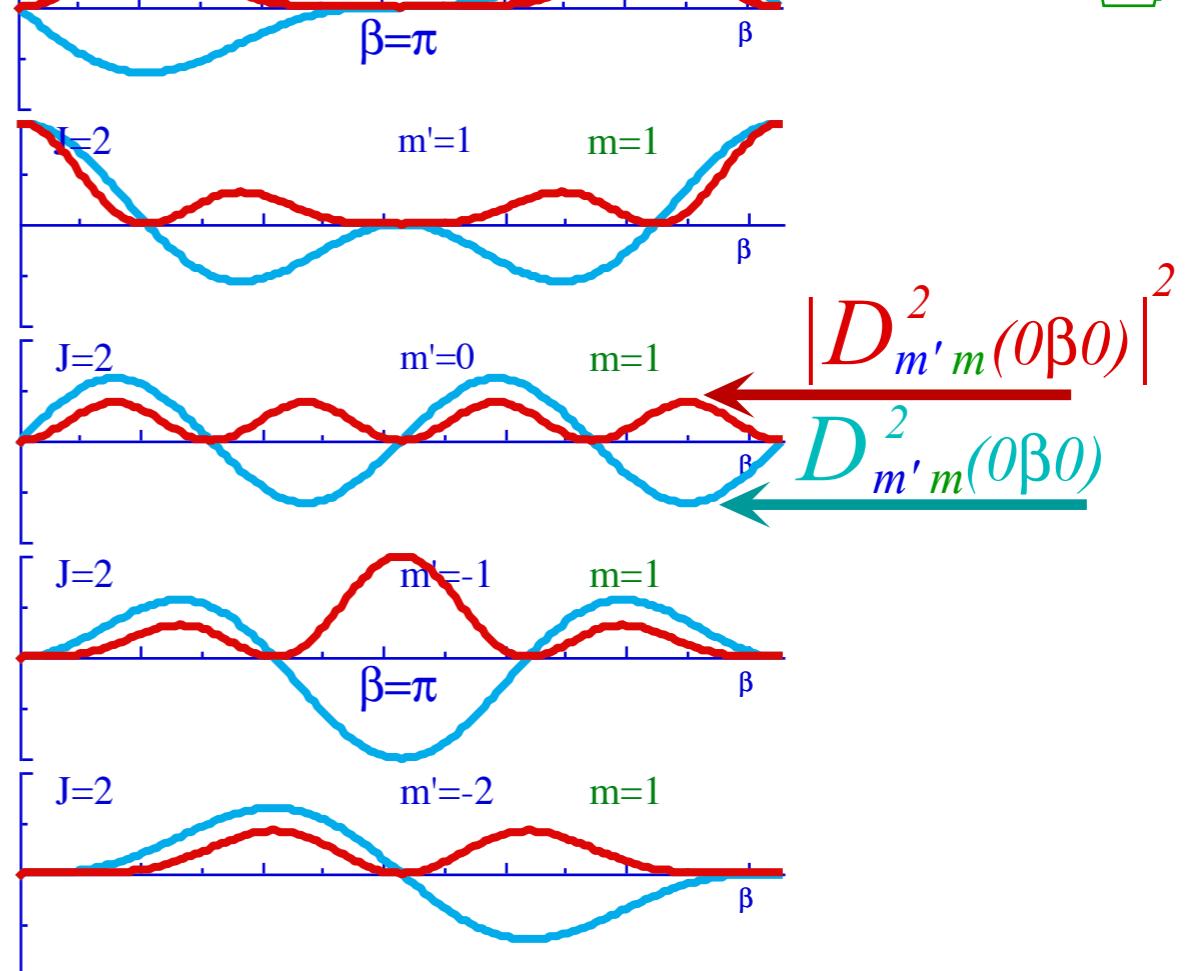
and then enters a vertical ($\beta=0$) analyzer and forced to choose from unrotated states $|J_{m'}^2\rangle$

$$\begin{aligned} \mathbf{R}(0\beta 0) |J_n\rangle &= \sum_{m'=-j}^j |J_{m'}^2\rangle \langle J_{m'}^2| \mathbf{R}(0\beta 0) |J_n\rangle \\ &= \sum_{m'=-j}^j |J_{m'}^2\rangle D_{m'n}^j(0\beta 0) \end{aligned}$$



Overlap of state $\mathbf{R}(\alpha\beta\gamma) |J_1^2\rangle$ with unrotated $|J_{m'}^2\rangle$ is the corresponding D-matrix element.

$$\langle J_{m'}^2 | \mathbf{R}(\alpha\beta\gamma) | J_1^2 \rangle = \delta^{j'2} D_{m'1}^2(\alpha\beta\gamma) = \langle J_{m'}^2 | J_1^2 \rangle_R$$



$D_{m'n}^j(0\beta 0)$ plotted vs. β for fixed j, m', n

$R(3)$ rotation and $U(2)$ unitary $D^J_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}(\alpha, \beta, \gamma) |J_{m'n}\rangle = \sum_{m'} D^J_{m'm}(\alpha, \beta, \gamma) |J_{m'n}\rangle$

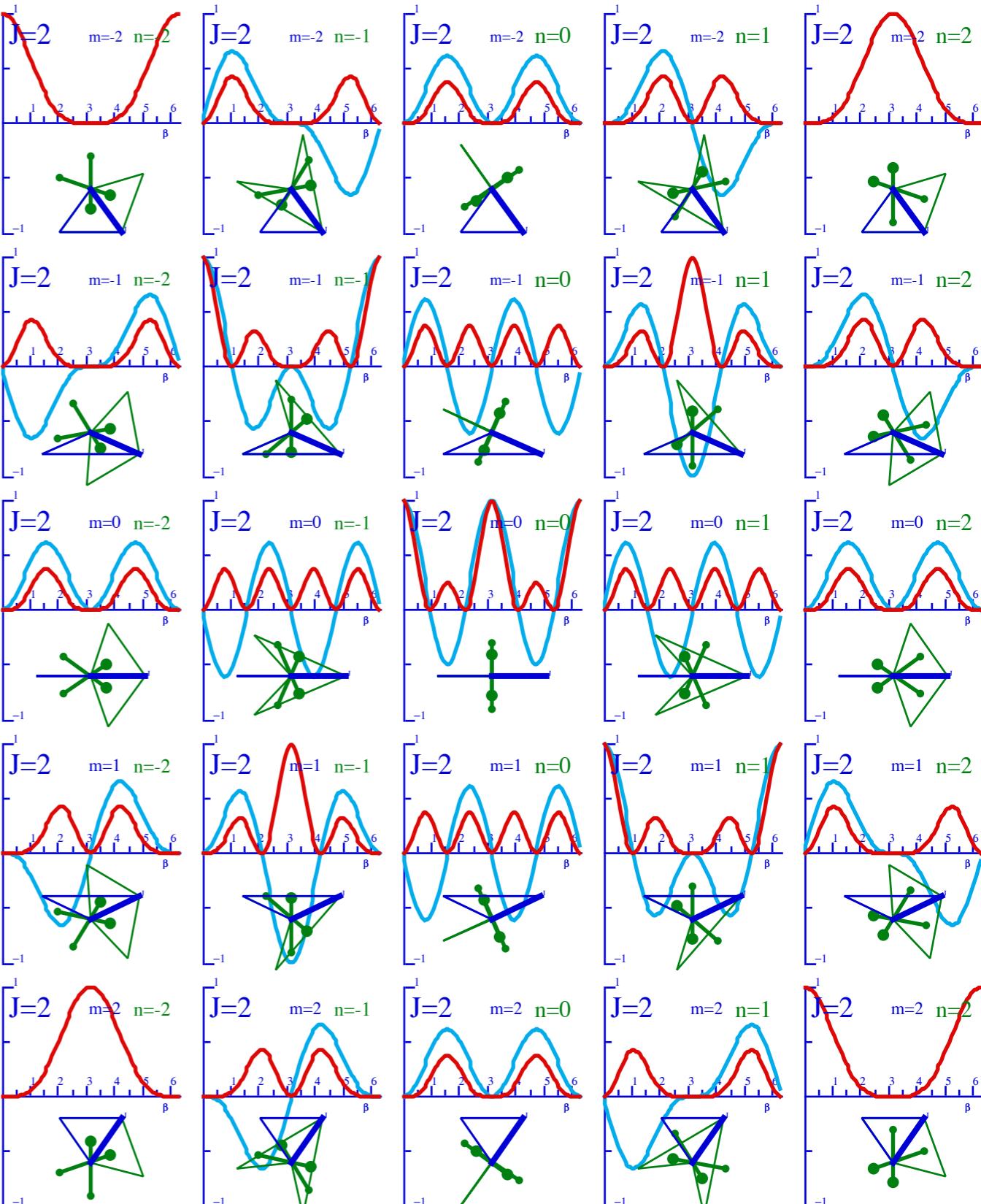
$$D^2(\alpha\beta0) = \begin{pmatrix} e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^2 & e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & \sqrt{\frac{3}{8}} e^{-i2\alpha} \sin^2\beta & e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{-i2\alpha} \left(\frac{1-\cos\beta}{2}\right)^2 \\ e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta - 1) & -\sqrt{\frac{3}{2}} e^{-i\alpha} \sin\beta \cos\beta & e^{-i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta + 1) & -e^{-i\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ \sqrt{\frac{3}{8}} \sin^2\beta & \sqrt{\frac{3}{2}} \sin\beta \cos\beta & \frac{3\cos^2\beta - 1}{2} & \sqrt{\frac{3}{2}} \sin\beta \cos\beta & \sqrt{\frac{3}{8}} \sin^2\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta + 1) & \sqrt{\frac{3}{2}} e^{i\alpha} \sin\beta \cos\beta & e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta - 1) & -e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right)^2 & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta & \sqrt{\frac{3}{8}} e^{i2\alpha} \sin^2\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^2 \end{pmatrix}$$

$$\begin{aligned} \mathbf{R}(0\beta0) |j_{m'n}\rangle &= \sum_{m'=-j}^j |j_{m'}\rangle \langle j_{m'}| \mathbf{R}(0\beta0) |j_{m'n}\rangle \\ &= \sum_{m'=-j}^j |j_{m'}\rangle D^j_{m'n}(0\beta0) \end{aligned}$$

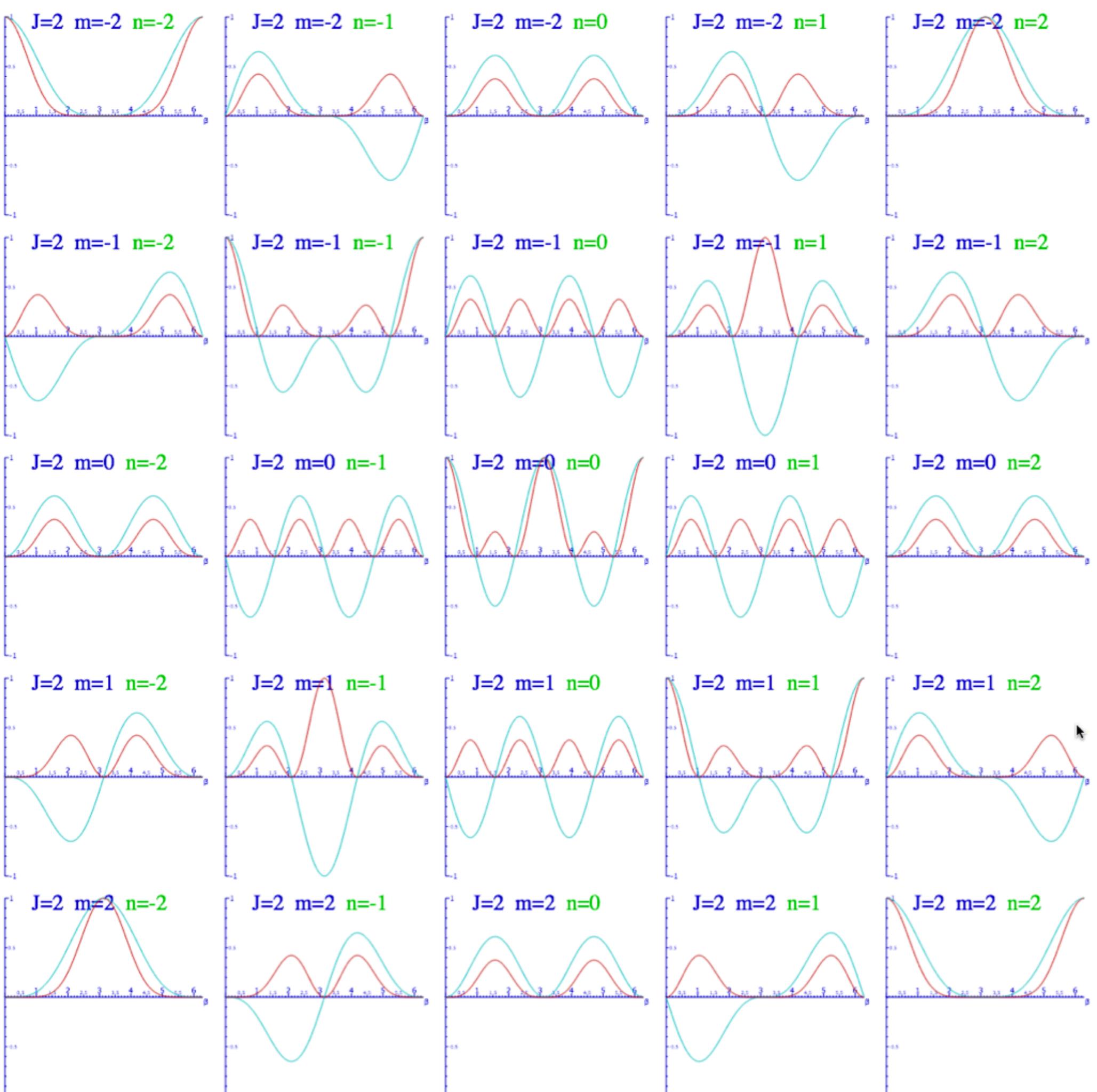
Overlap of state $\mathbf{R}(\alpha\beta\gamma) |^2_1\rangle$ on unrotated $|j=2_{m'}\rangle$ is the corresponding D-matrix element.

$$\langle j'_{m'} | \mathbf{R}(\alpha\beta\gamma) |^2_1 \rangle = \delta^{j'2} D^2_{m'1}(\alpha\beta\gamma) = \langle j'_{m'} | ^2_1 \rangle_R$$

$D^j_{m'n}(0\beta0)$ plotted vs. β for fixed j, m', n



$D_{m'n}^{J=2}(0|\beta|0)$
 plotted
 vs. β
 for fixed
 J, m', n



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

→ Θ^J_m -cone properties of lab transforms: $J=20, \leftarrow J=10, J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

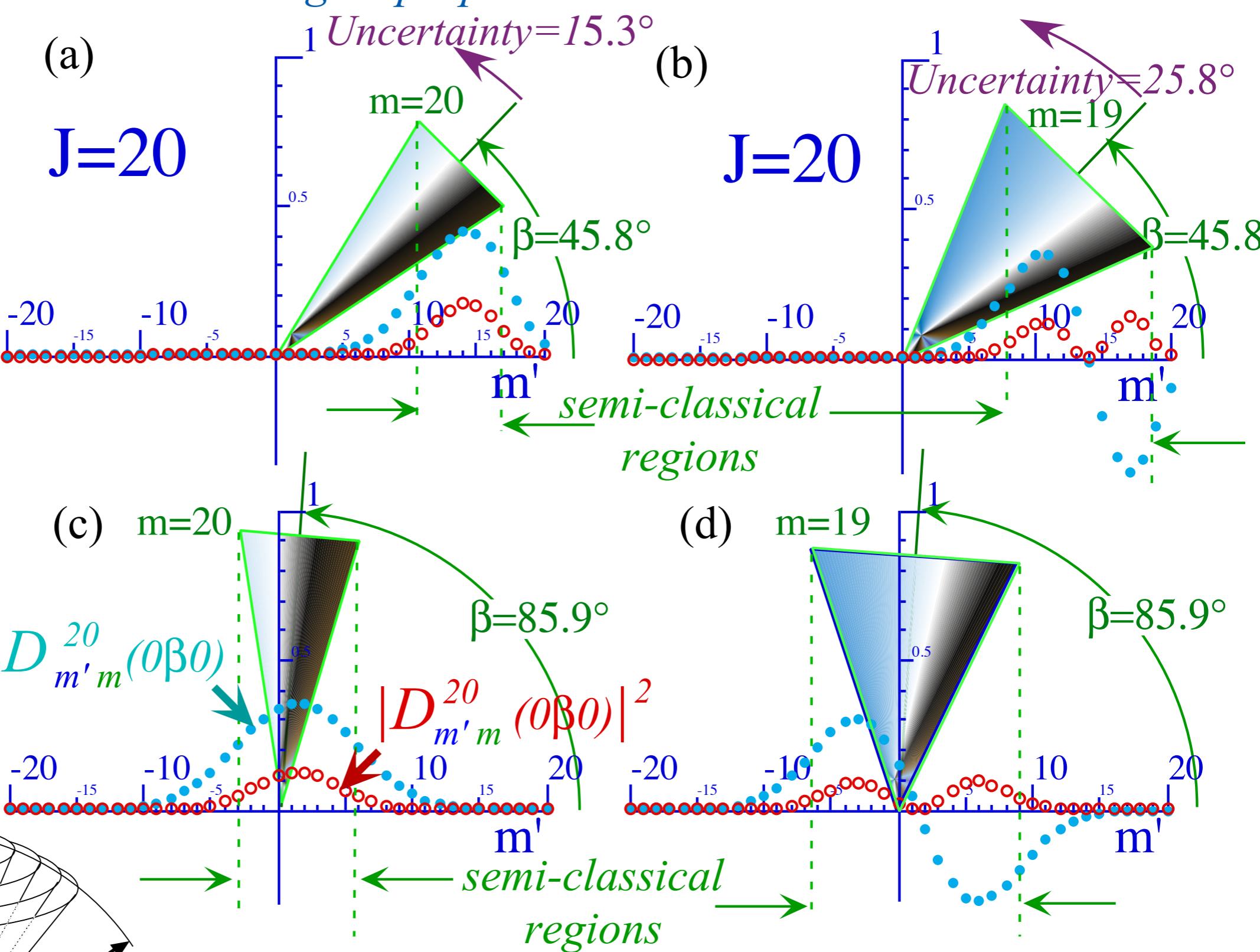
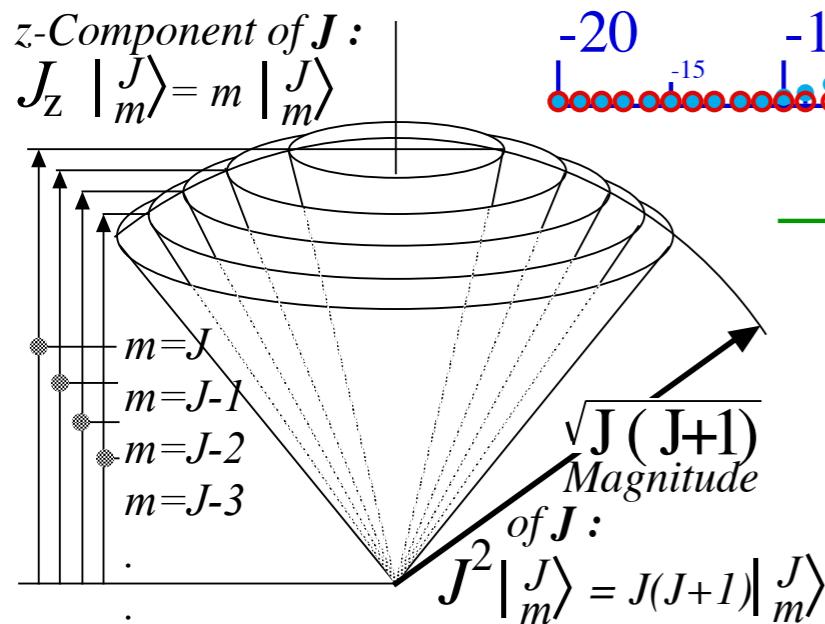
Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Angular momentum cones and high J properties

$D_{m'm}^{J=20}(0\beta0)$
plotted
vs. m'
for fixed
 J, β, m

$J=20$
Discrete
plots

QTforCA Unit 8.
Ch. 23 Fig. 23.1.1



QuantIt web simulation:
Visualizing D representations

QTforCA Unit 8. Ch. 23 Fig. 23.2.2

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

→ Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, ← $J=30$.

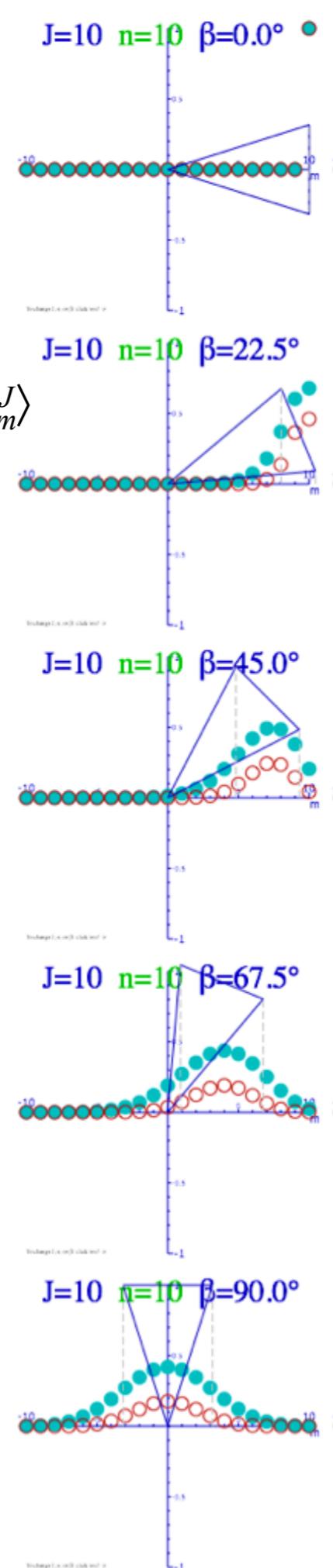
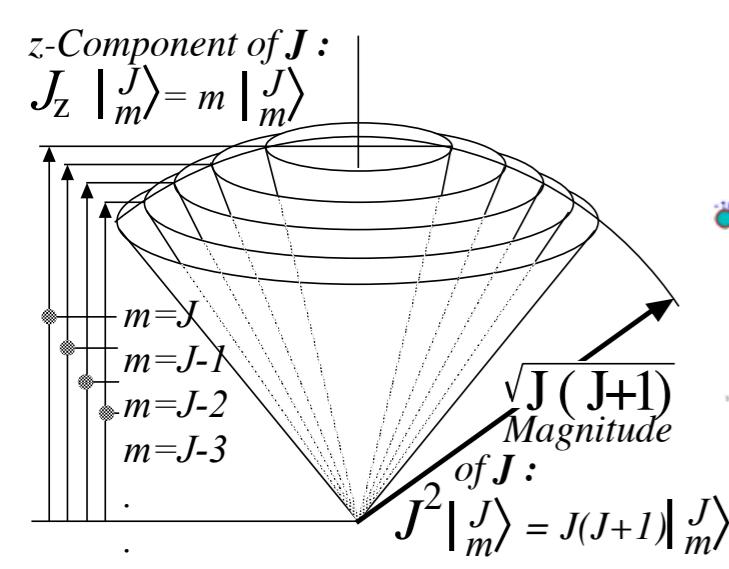
Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

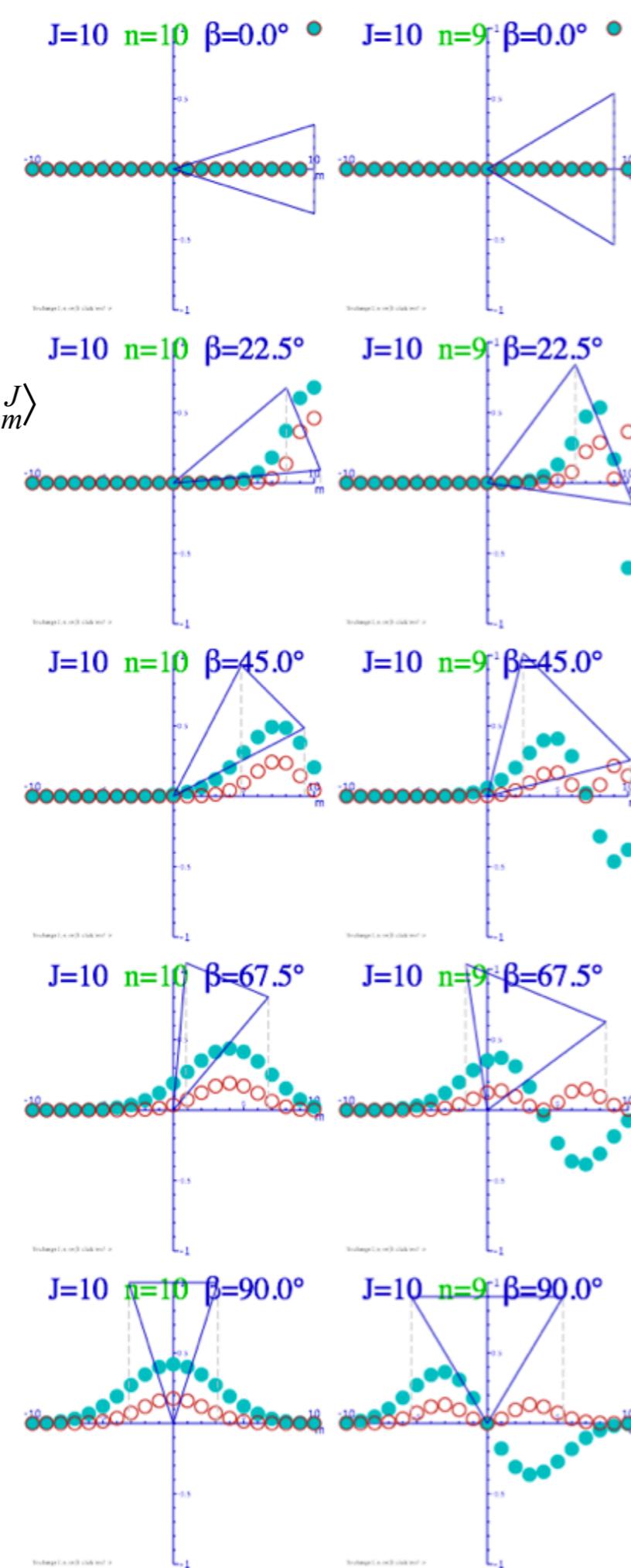
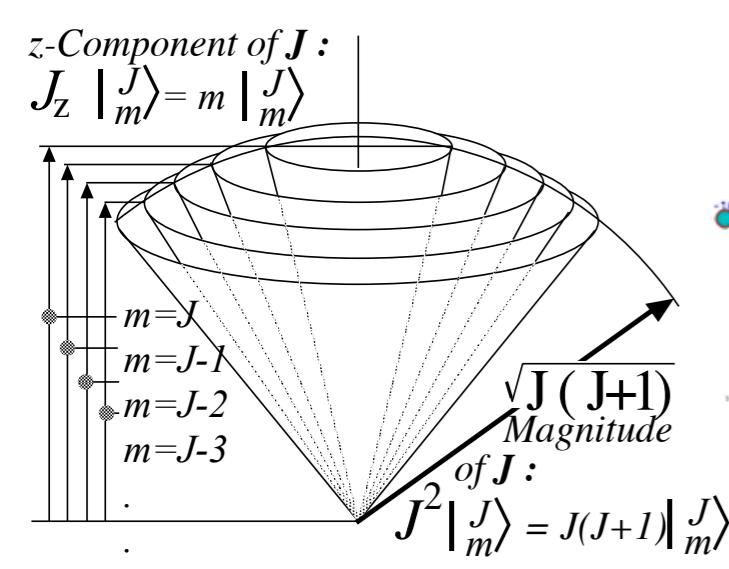


$D_{m,n}^{J,\beta}(0)$
plotted
vs. m
for fixed
 $J=10, \beta, n$
to $n=10$

$J=10$

Discrete plots

QuantIt web simulation:
Visualizing D representations

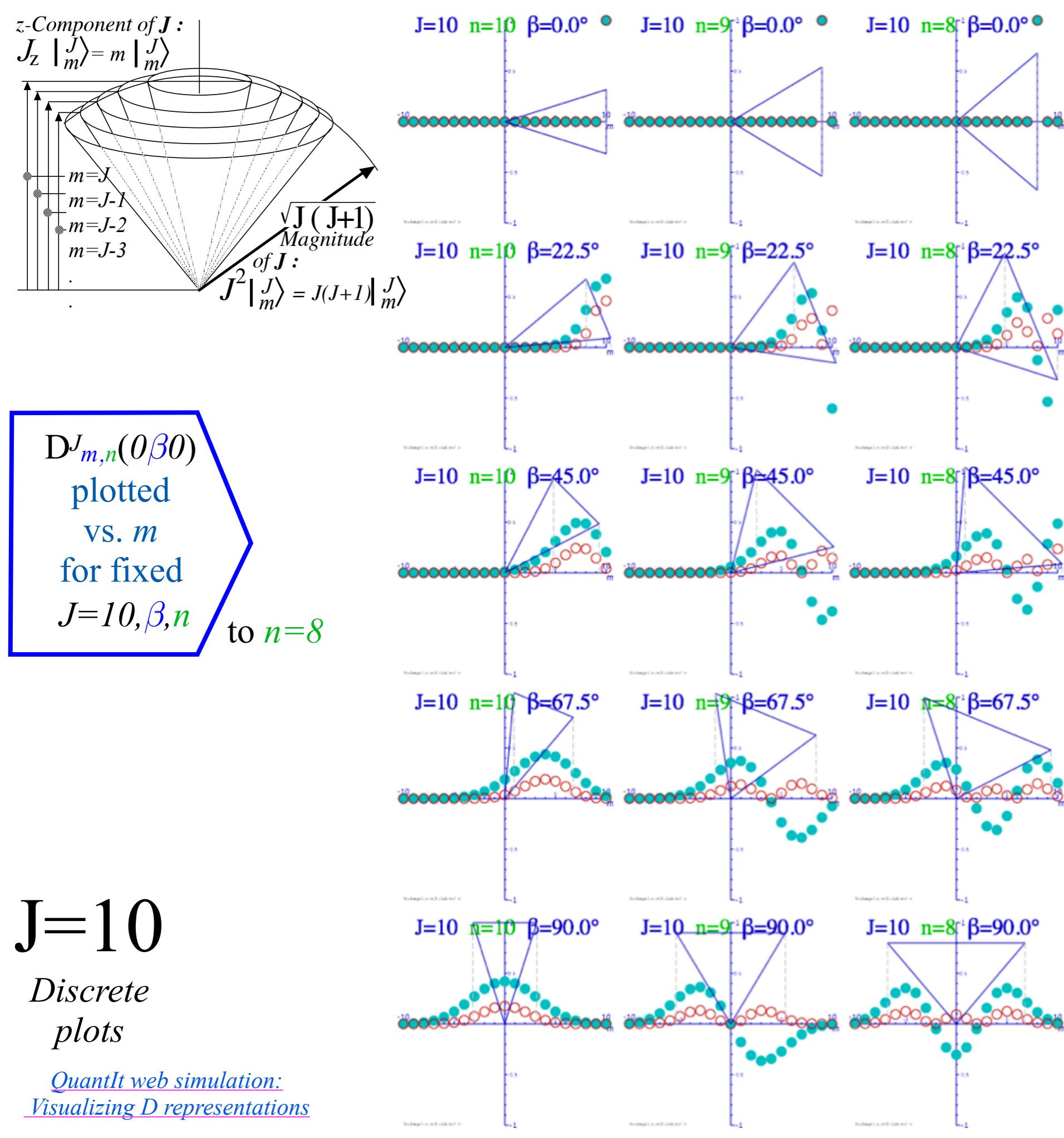


$D_{m,n}^{J,\beta}(0)$
plotted
vs. m
for fixed
 $J=10, \beta, n$
to $n=9$

$J=10$

*Discrete
plots*

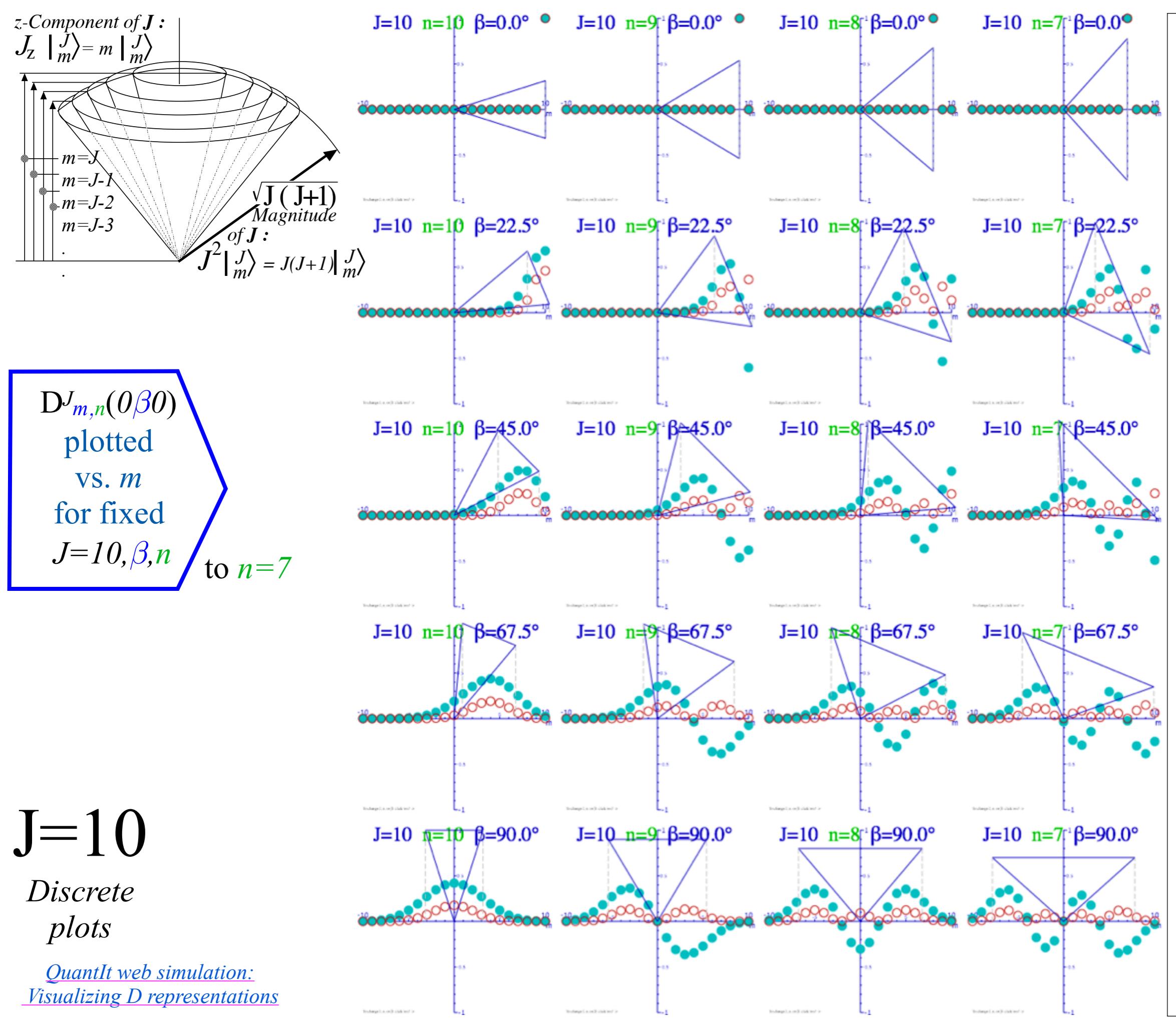
QuantIt web simulation:
Visualizing D representations

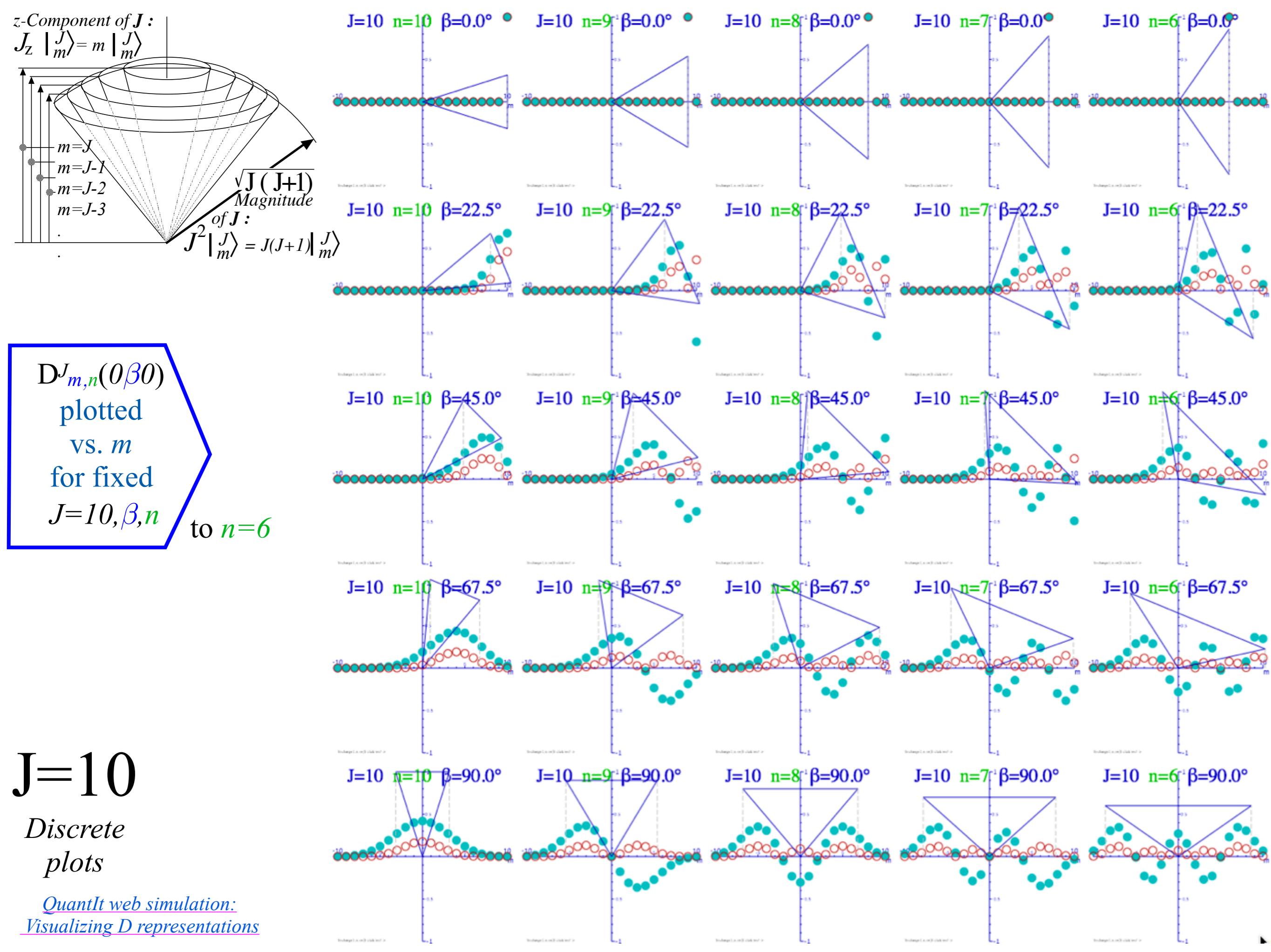


$J=10$

Discrete plots

QuantIt web simulation:
Visualizing D representations





Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

→ Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$. ←

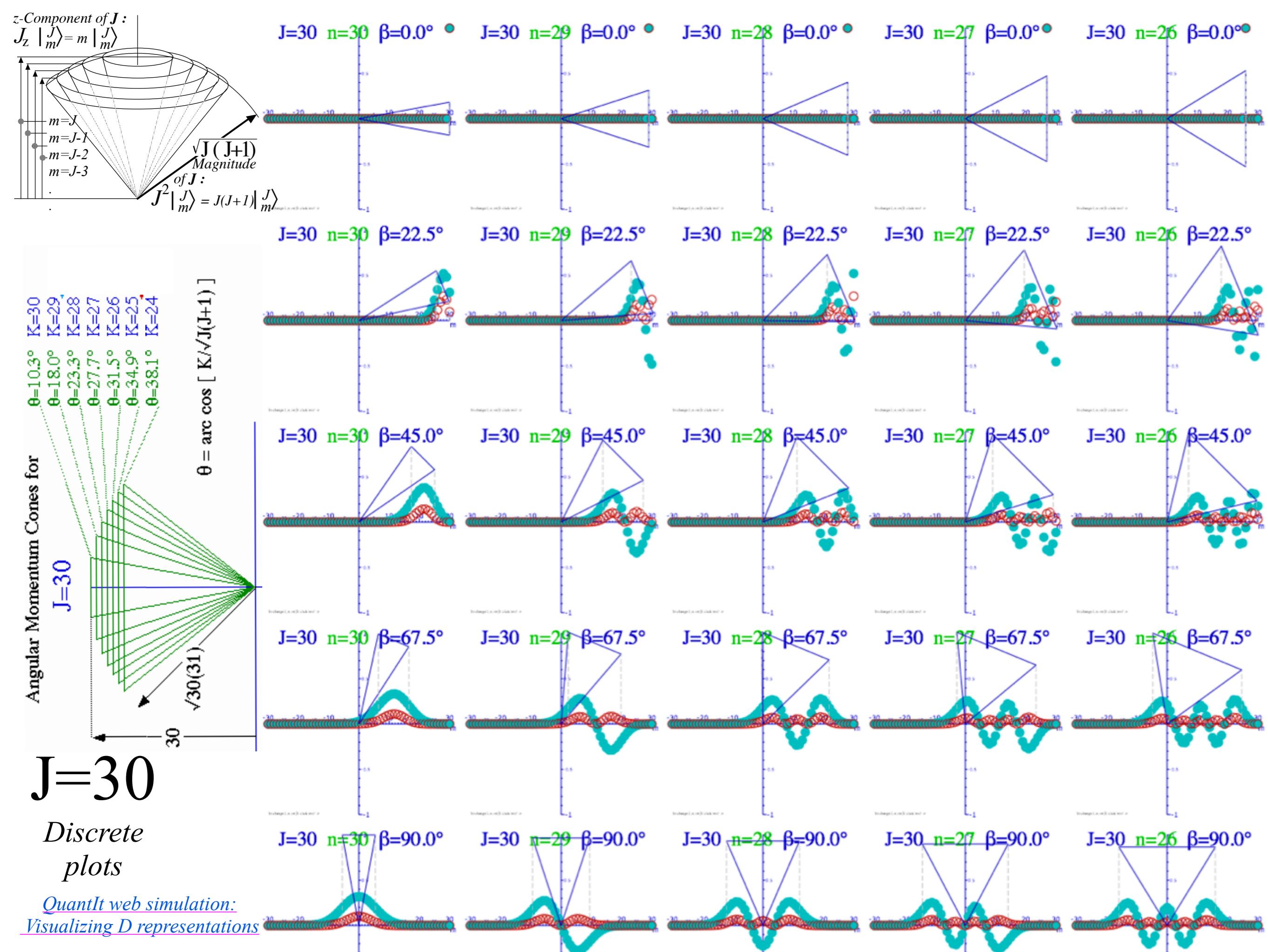
Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

→ Θ^J_m -analysis of high J atomic beams ←

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

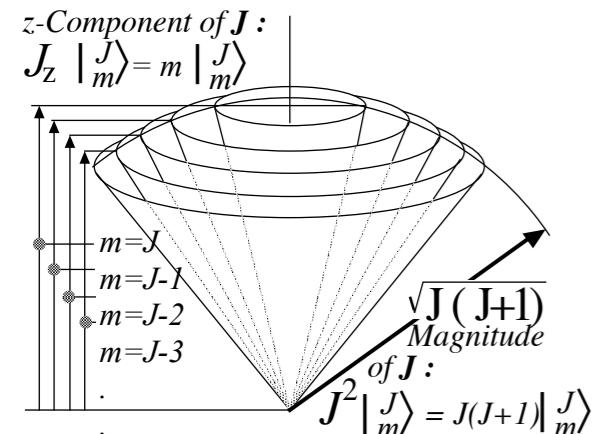
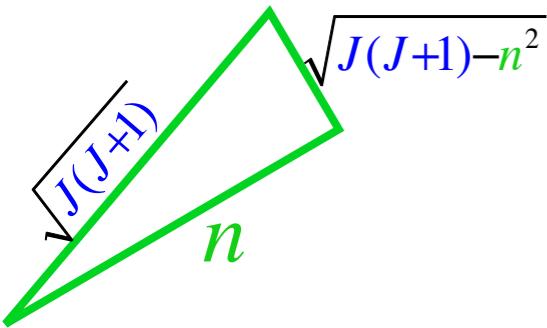
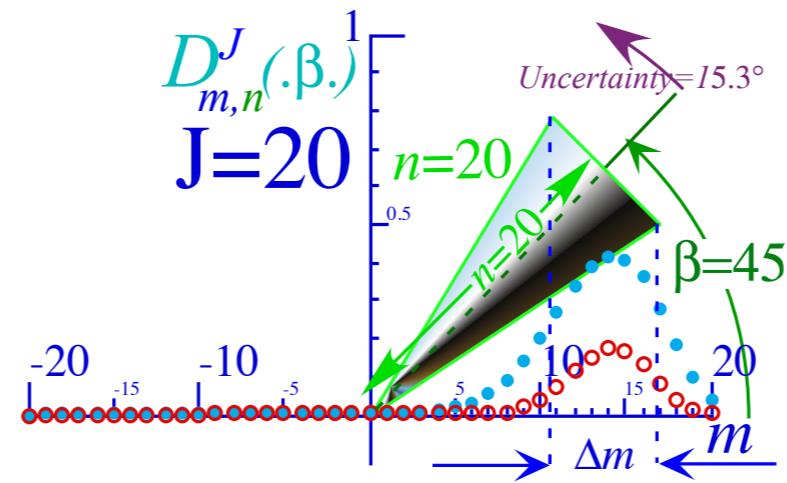
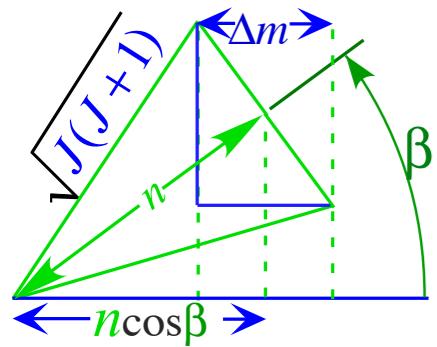
Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

Angular momentum cones and high J properties

Using literal interpretation of $| \begin{smallmatrix} J \\ m \end{smallmatrix} \rangle$ to derive approximate number Δm of “most-busy” counters and determine most probable m -values.

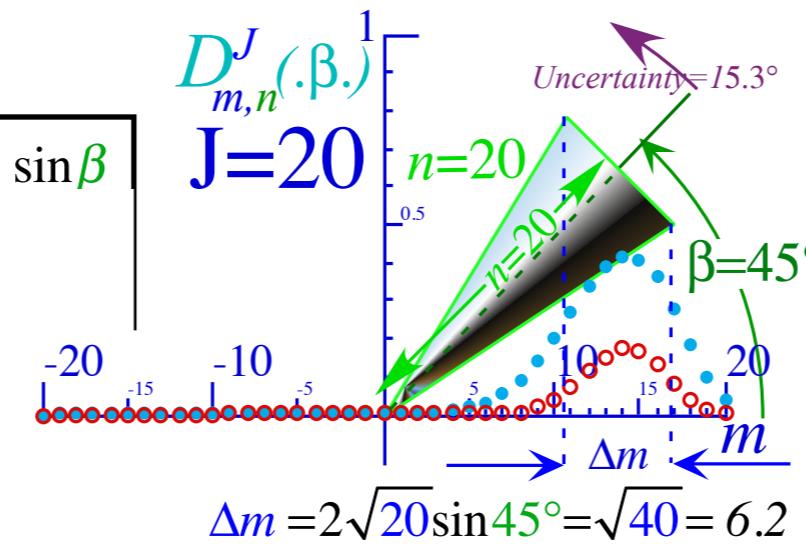
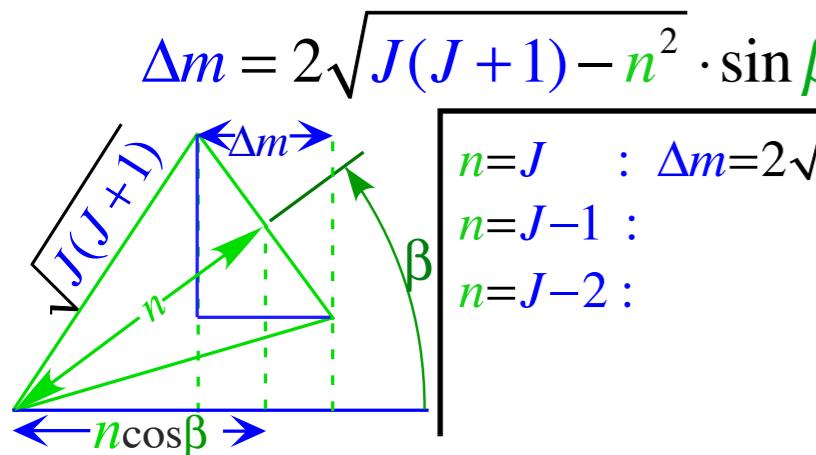
$$\Delta m = 2\sqrt{J(J+1)-n^2} \cdot \sin \beta$$



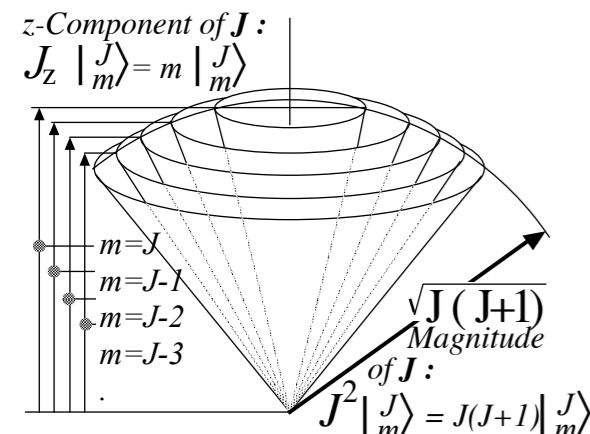
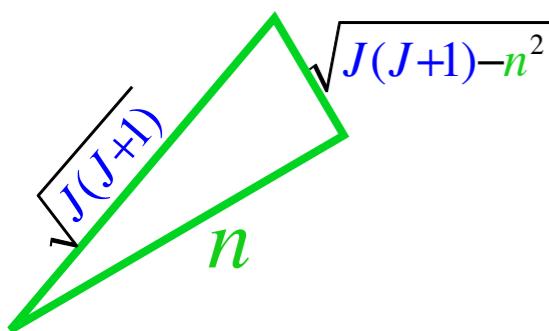
QuantIt web simulation:
Visualizing D representations

Angular momentum cones and high J properties

Using literal interpretation of $| \begin{smallmatrix} J \\ m \end{smallmatrix} \rangle$ to derive approximate number Δm of “most-busy” counters and determine most probable m -values.



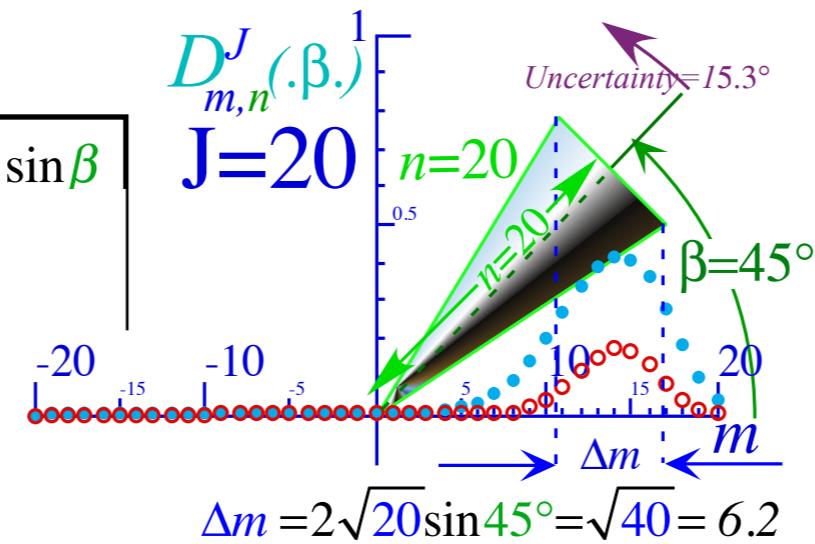
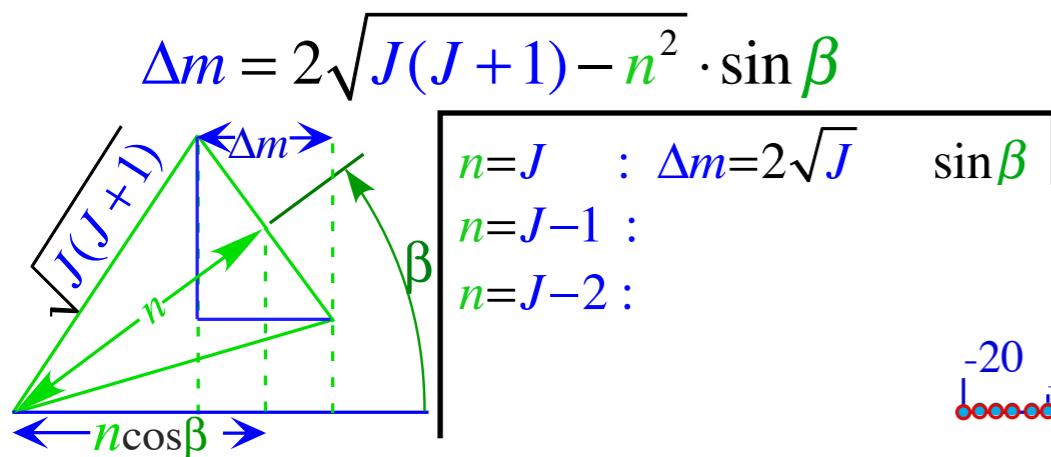
Testing formula with $J=20$ for $\beta=45^\circ$...



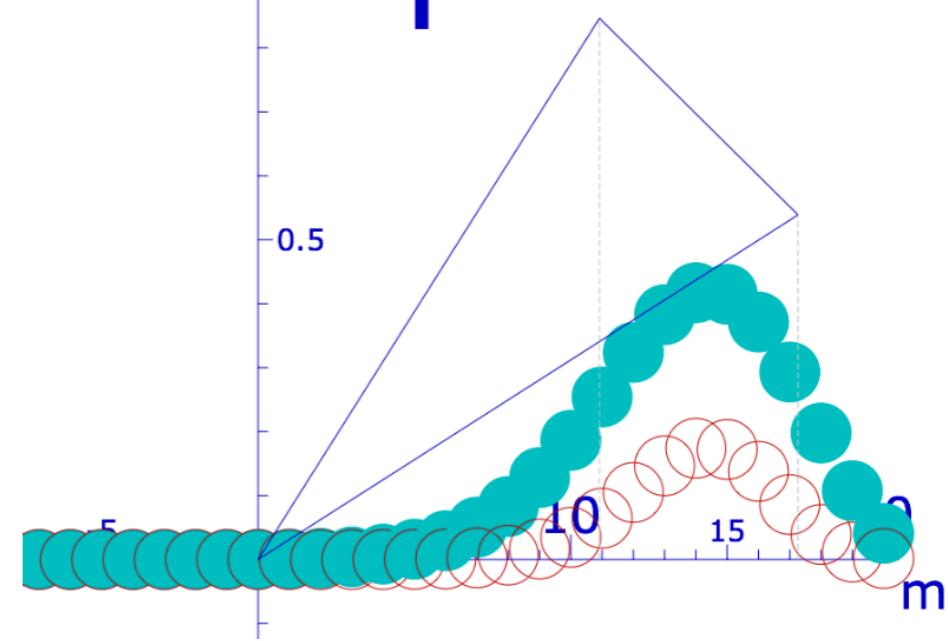
QuantIt web simulation:
Visualizing D representations

Angular momentum cones and high J properties

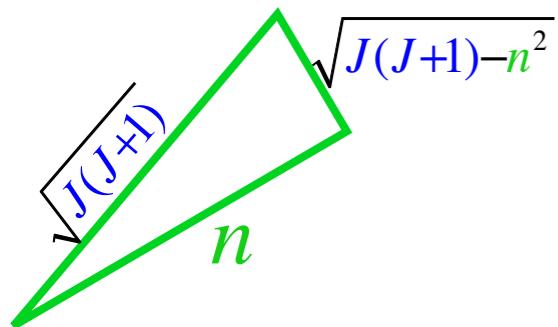
Using literal interpretation of $| \begin{smallmatrix} J \\ m \end{smallmatrix} \rangle$ to derive approximate number Δm of “most-busy” counters and determine most probable m -values.



$n=20$ $\beta=45.2^\circ$

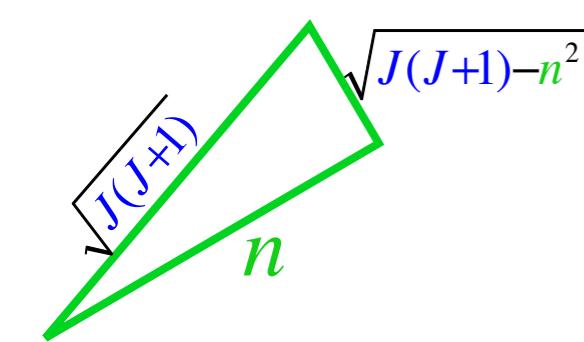
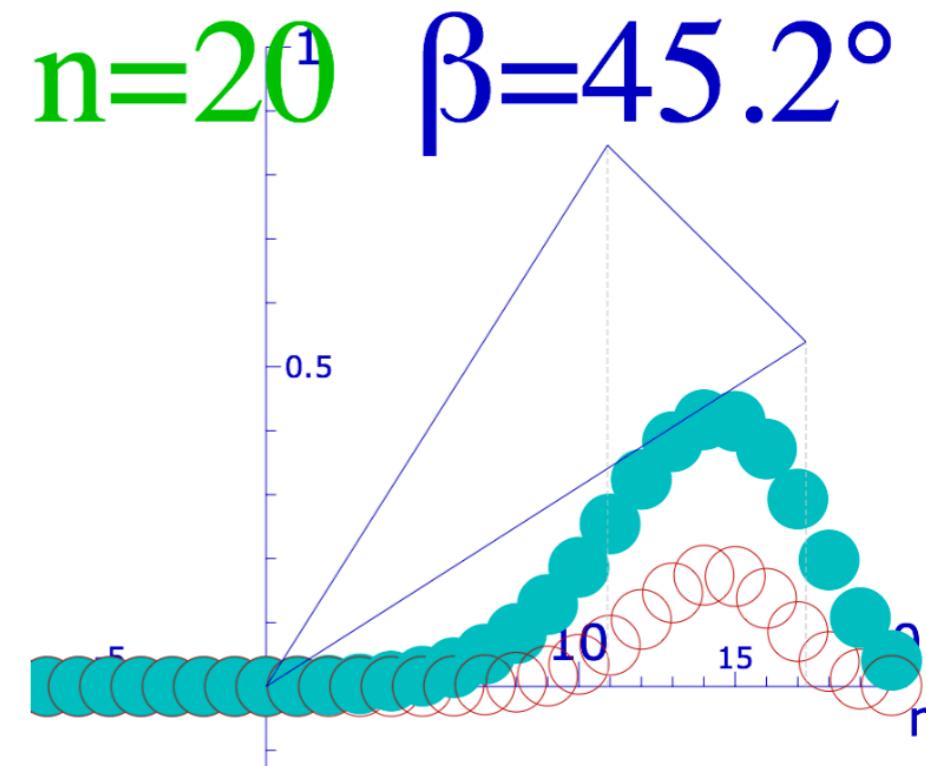
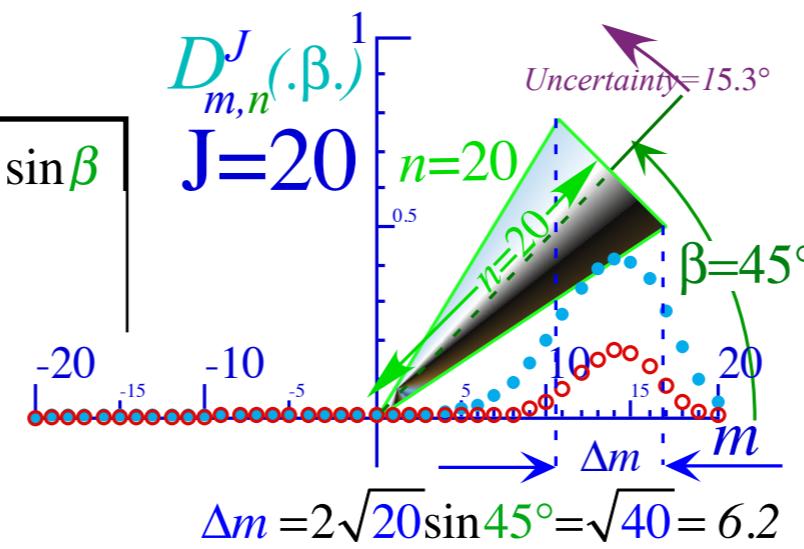
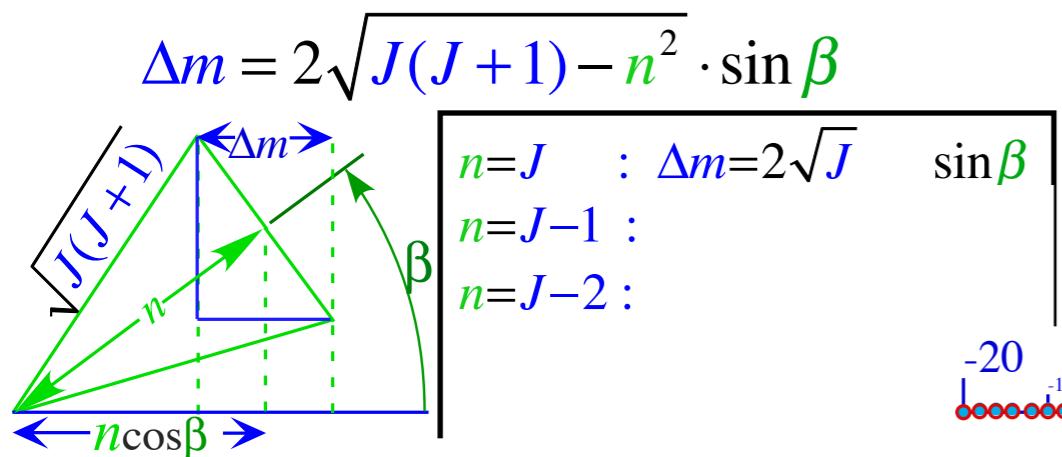


Testing formula with $J=20$ for $\beta=45^\circ$...

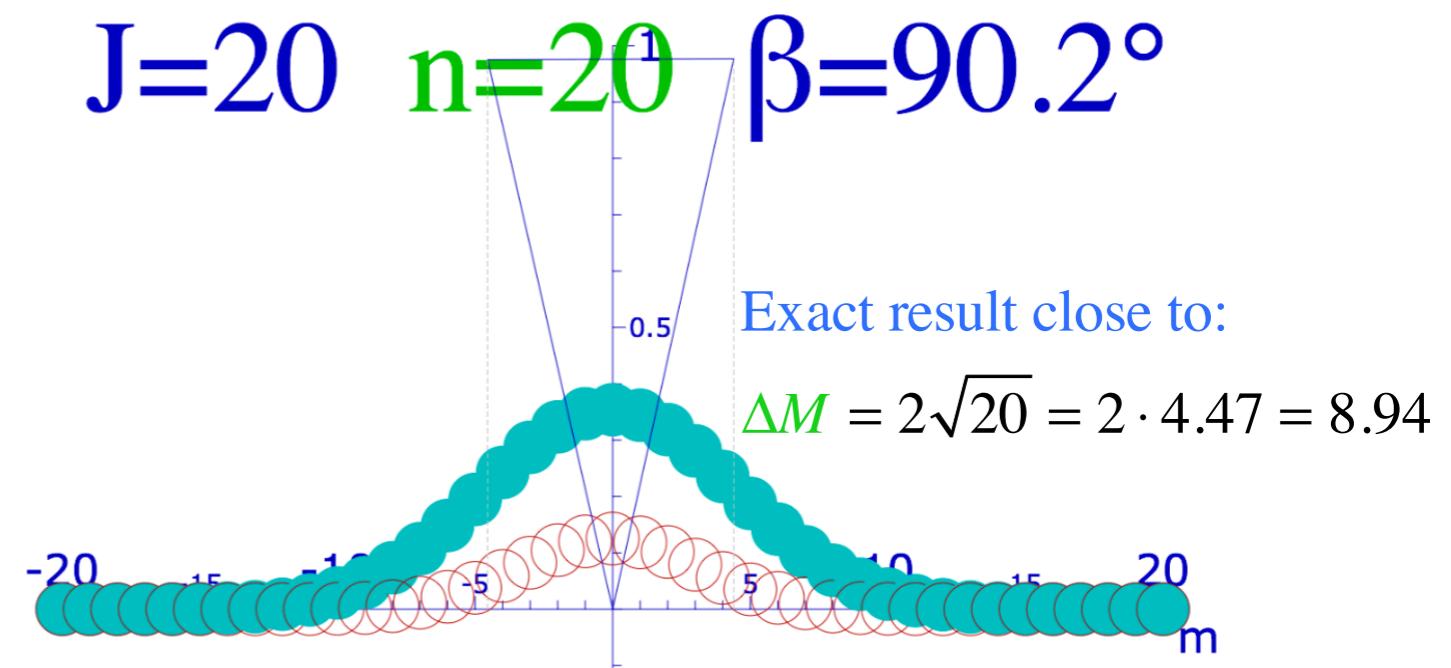


Angular momentum cones and high J properties

Using literal interpretation of $| \begin{smallmatrix} J \\ m \end{smallmatrix} \rangle$ to derive approximate number Δm of “most-busy” counters and determine most probable m -values.

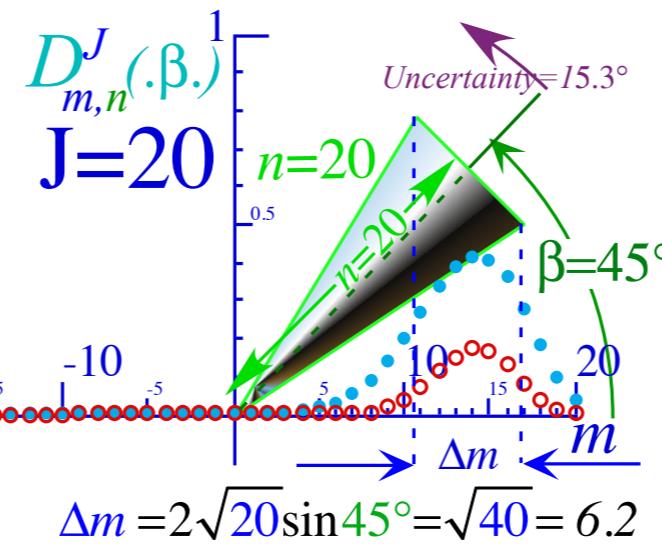
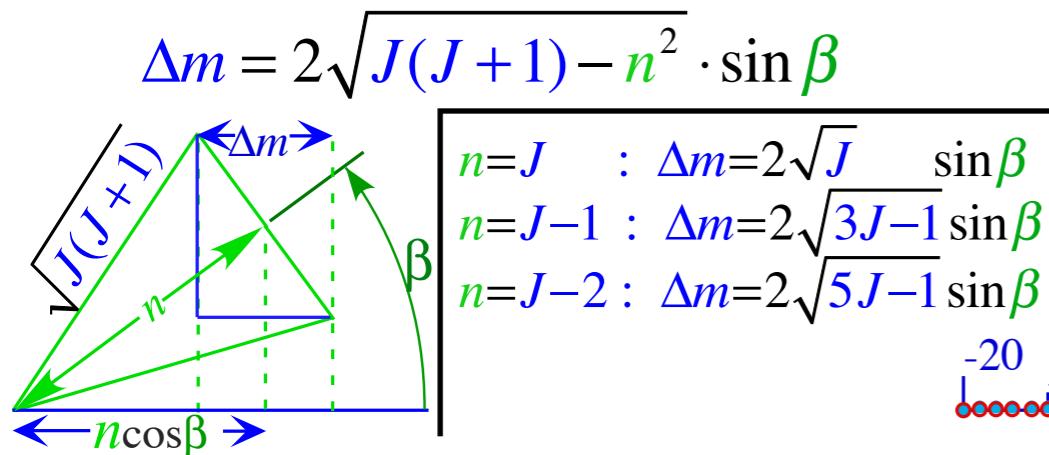


...and for $\beta=90^\circ$

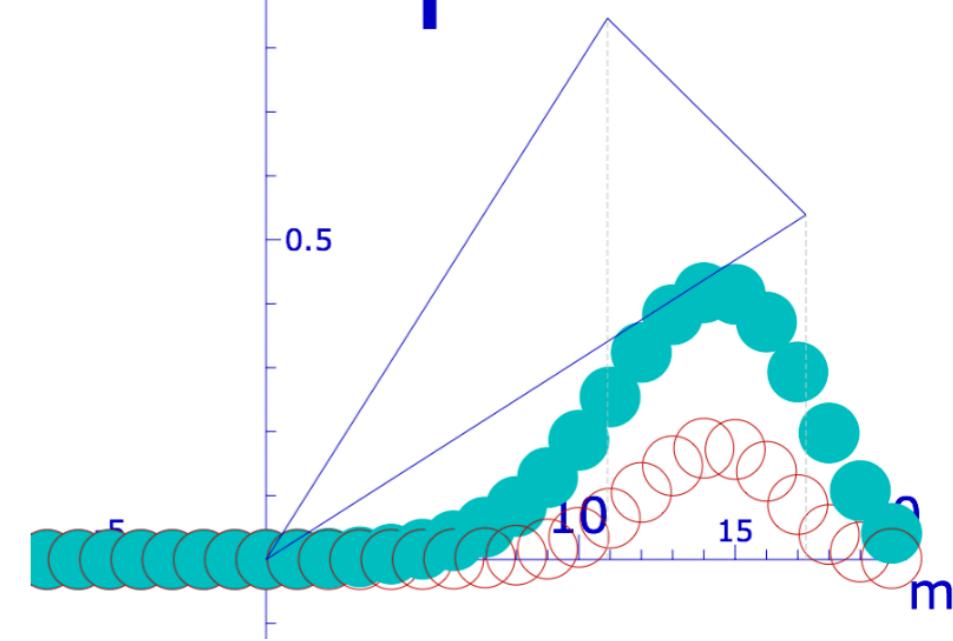


Angular momentum cones and high J properties

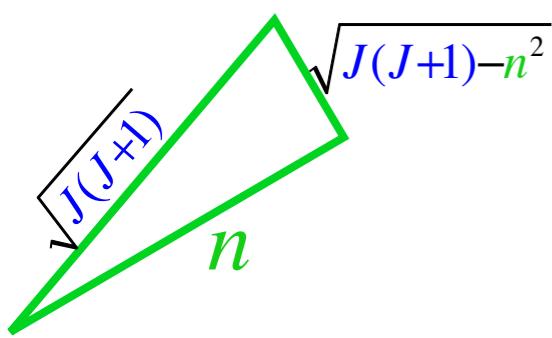
Using literal interpretation of $| \frac{J}{m} \rangle$ to derive approximate number Δm of “most-busy” counters and determine most probable m -values.



$n=20$ $\beta=45.2^\circ$



Testing formula with $J=20$ for $\beta=45^\circ$...

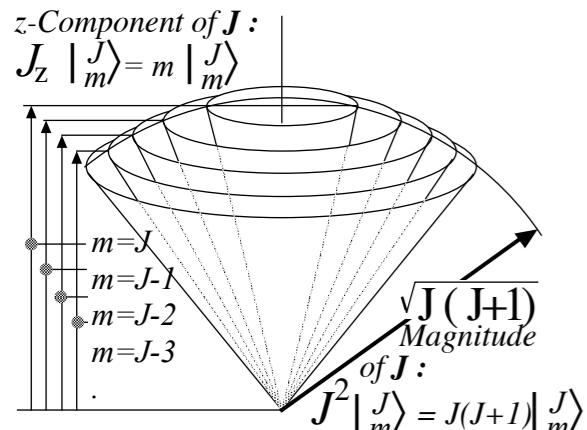
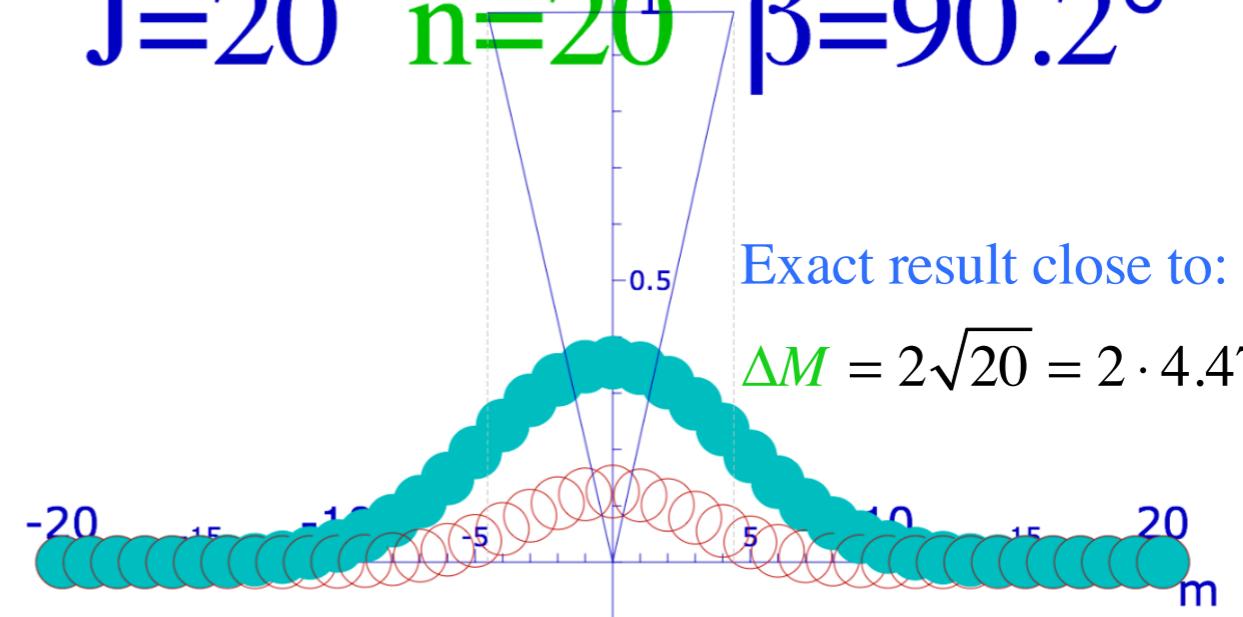


...and for $\beta=90^\circ$

$J=20$ $n=20$ $\beta=90.2^\circ$

Exact result close to:

$$\Delta M = 2\sqrt{20} = 2 \cdot 4.47 = 8.94$$



QuantIt web simulation:
Visualizing D representations

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

→ Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$ ←

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

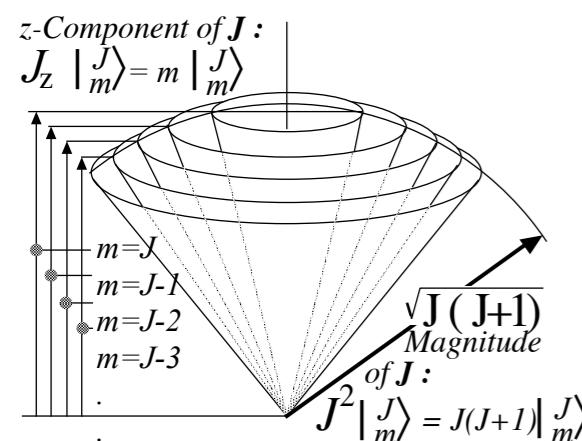
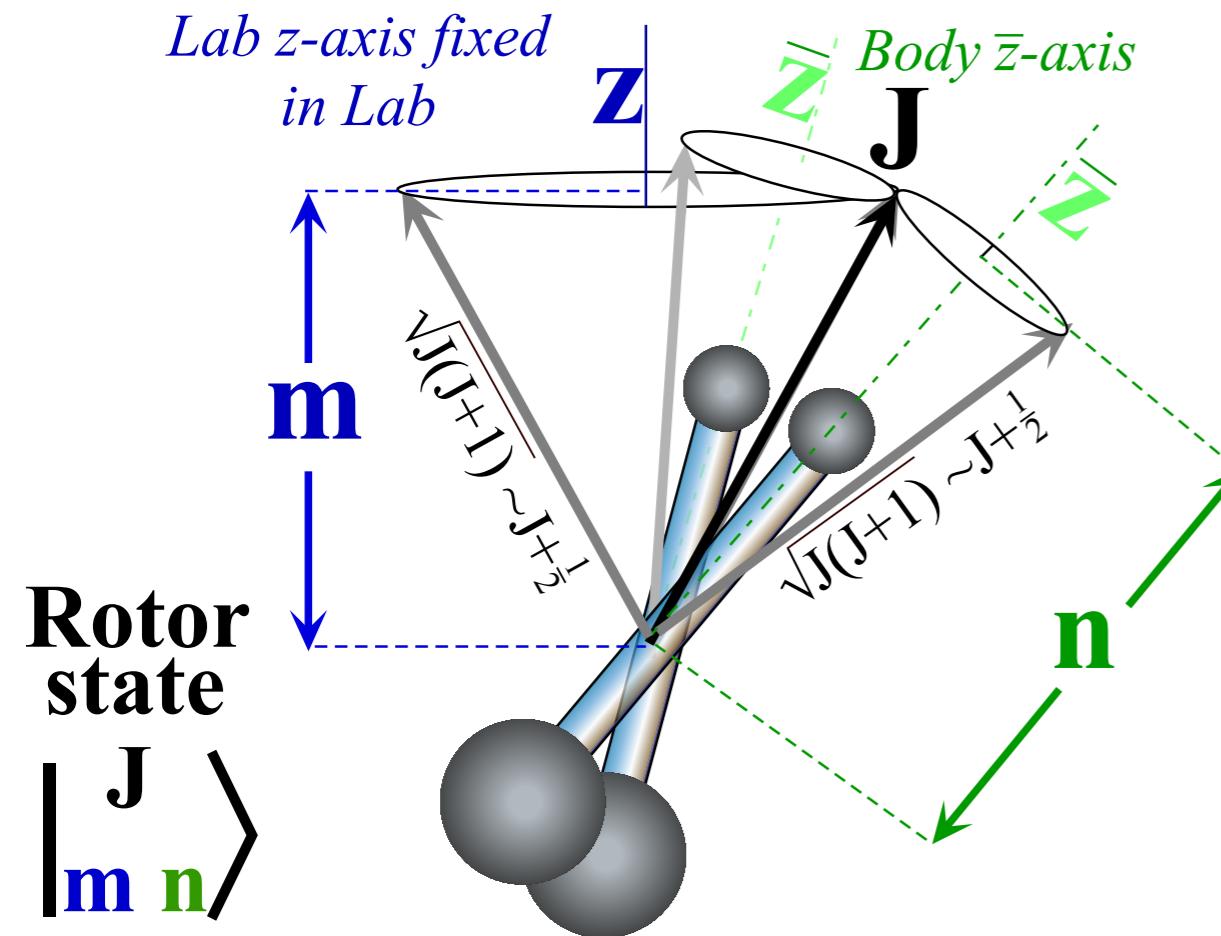
Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RES) of asymmetric rotor (for following class)

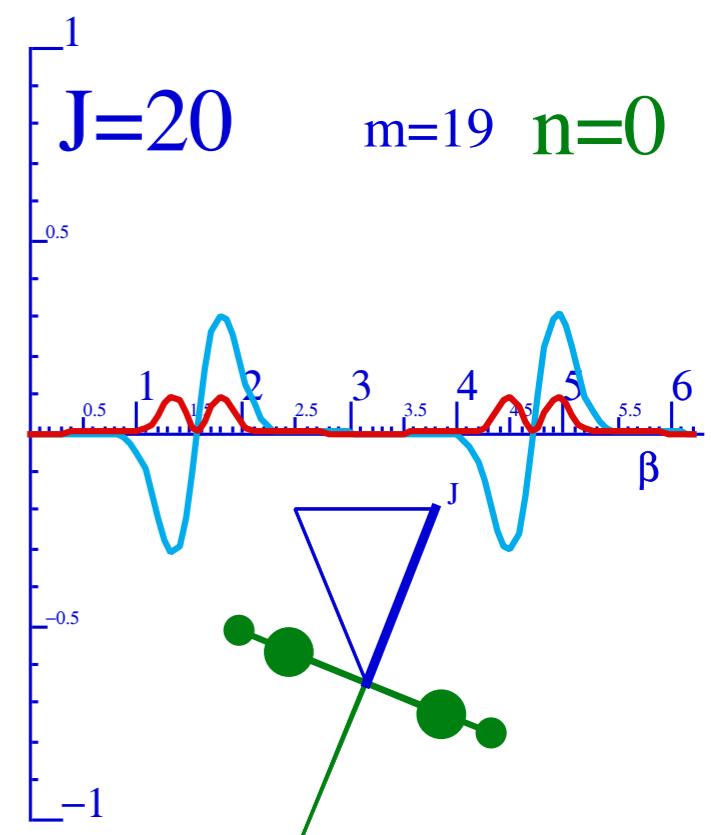
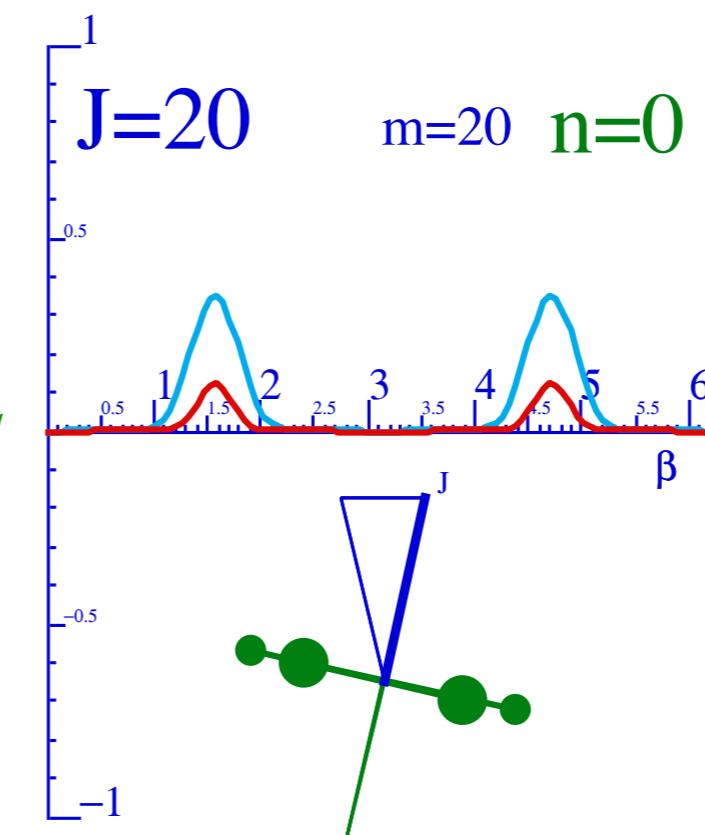
Angular momentum cones and high J properties of LAB vs BOD wavefunctions

$D^{J=20}_{m,n}(0\beta0)$
plotted
vs. β
for fixed
 $J=20, m, n$

Using literal interpretation of $| \begin{smallmatrix} J \\ m \ n \end{smallmatrix} \rangle$ to describe approximate rotor wave-functions



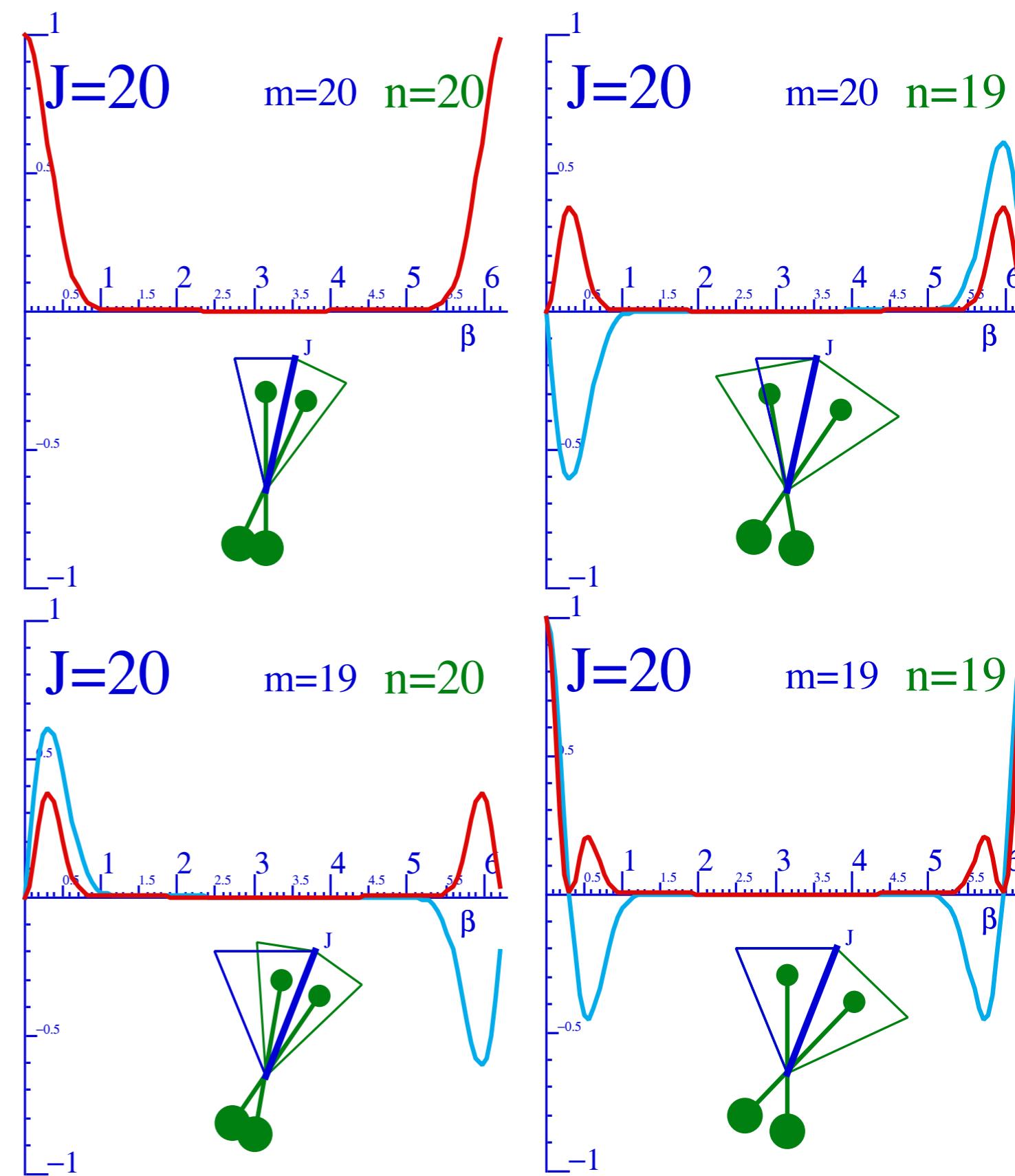
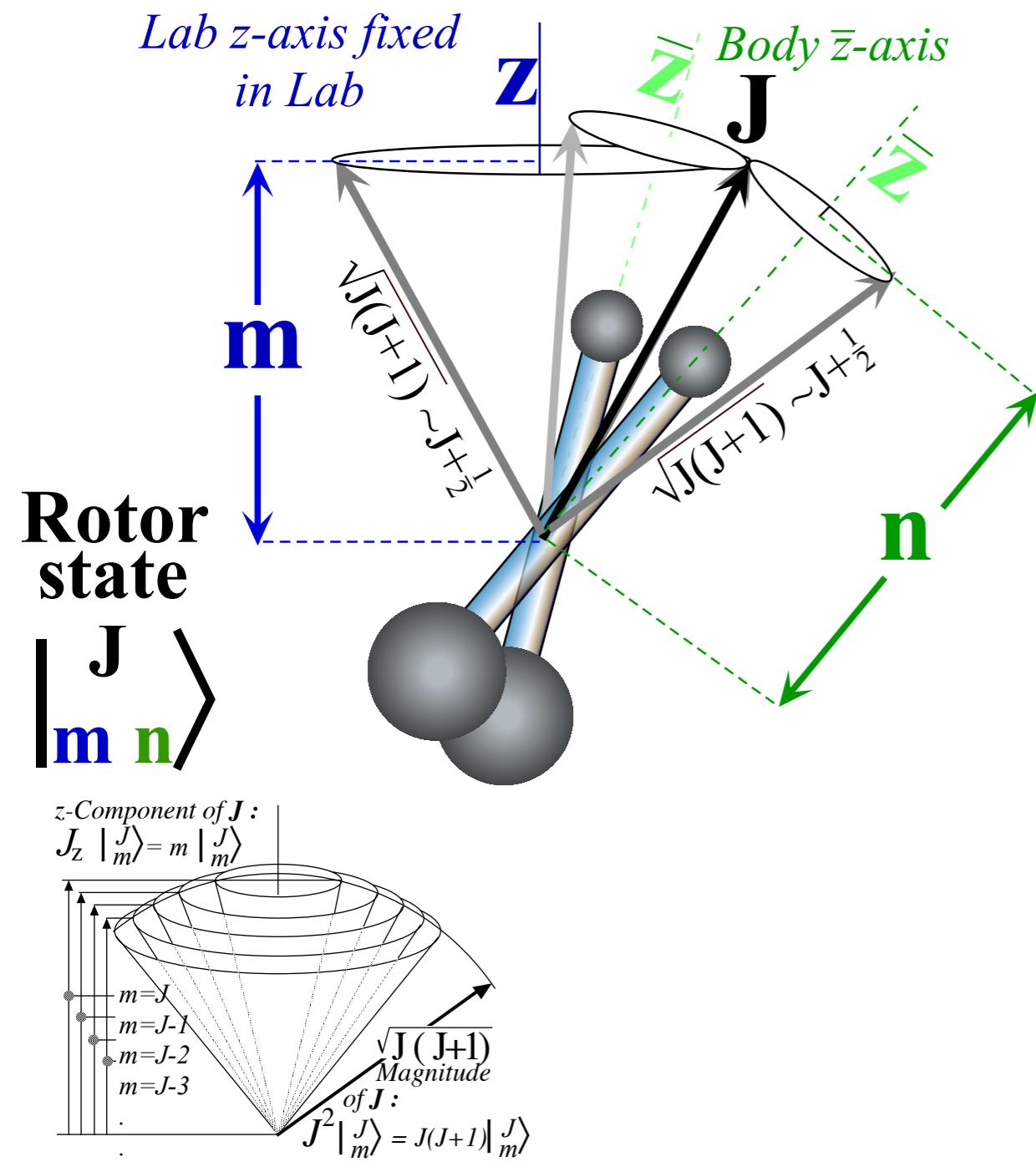
QTforCA Unit 8. Ch. 23 Fig. 23.2.4



QTforCA Unit 8. Ch. 23 Fig. 23.2.7

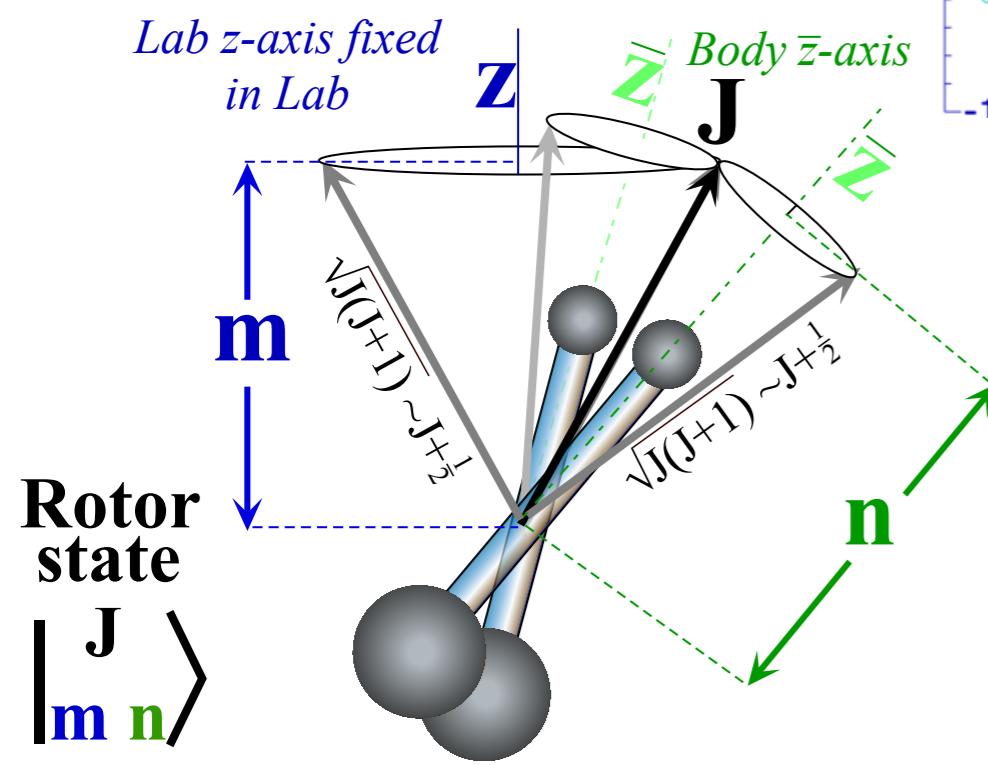
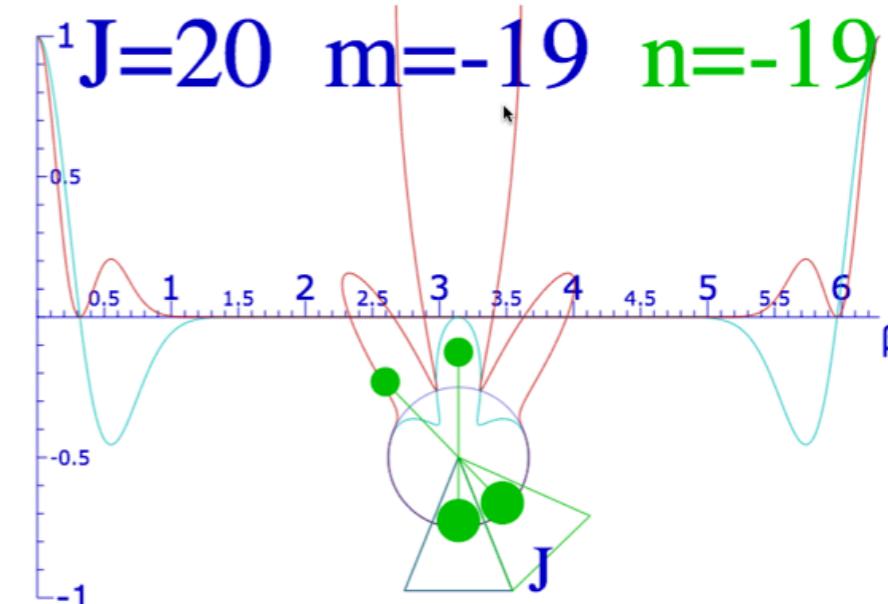
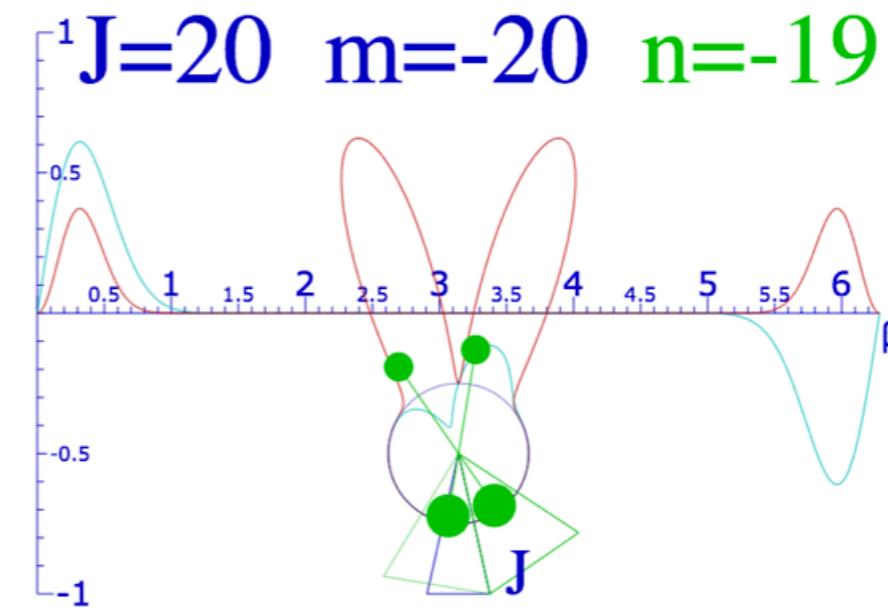
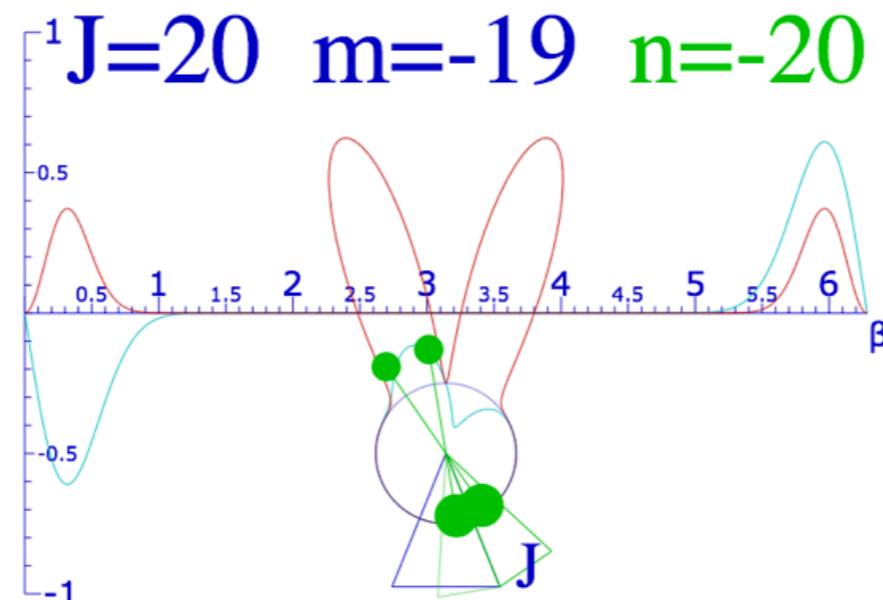
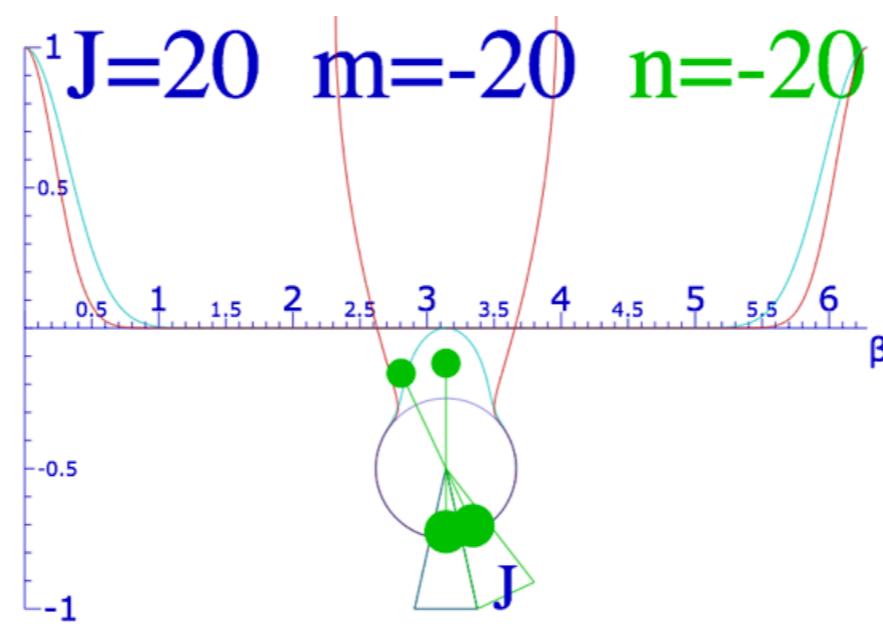
Angular momentum cones and high J properties of LAB vs BOD wavefunctions

$D^{J=20} m, n(0\beta0)$
plotted
vs. β
for fixed
 $J=20, m, n$



Angular momentum cones and high J properties of LAB vs BOD wavefunctions

$D^{J=20}_{m,n}(0\beta0)$
plotted
vs. β
for fixed
 $J=20, m, n$



[QuantIt web simulation:](#)
[Visualizing D representations](#)

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

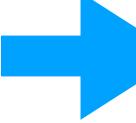
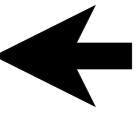
$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

 Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators 

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

Rotational Energy Surfaces (RE or RES) of asymmetric rotor (for following class)

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2} \quad X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k \textcolor{blue}{Y}_q^k$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\begin{aligned} \sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) &= D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2} & X_q^k &= r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k \\ \sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) &= D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2} \\ \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) &= D_{0,0}^{2*}(\phi\theta0) = \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2} \quad \longrightarrow \quad \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2} \\ \sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) &= D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2} \\ \sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) &= D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2} \end{aligned}$$

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\begin{aligned} \sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) &= D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2} & X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k \\ \sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) &= D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2} \\ \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) &= D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2} \quad \rightarrow \quad \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2} \\ \sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) &= D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2} \\ \sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) &= D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2} \end{aligned}$$

The (x,y,z) polynomials become
 $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\rightarrow \mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}} r^2 e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x+iy)^2 = \sqrt{\frac{3}{8}} (x^2 + 2ixy - y^2)$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$$

The (x,y,z) polynomials become
 $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3\cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$$

The (x,y,z) polynomials become
 $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}} r^2 e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x+iy)^2 = \sqrt{\frac{3}{8}} (x^2 + 2ixy - y^2)$$

$$X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x-iy)^2 = \sqrt{\frac{3}{8}} (x^2 - 2ixy - y^2)$$

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$$

The (x,y,z) polynomials become $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3 \cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}} r^2 e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x+iy)^2 = \sqrt{\frac{3}{8}} (x^2 + 2ixy - y^2)$$

$$+ X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x-iy)^2 = \sqrt{\frac{3}{8}} (x^2 - 2ixy - y^2)$$

$$= X_2^2(\phi\theta0) + X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{2}} r^2 \frac{e^{i2\phi} + e^{-i2\phi}}{2} \sin^2 \theta = \sqrt{\frac{3}{2}} (x^2 - y^2) = \sqrt{\frac{3}{2}} r^2 \cos 2\phi \sin^2 \theta$$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$$

The (x,y,z) polynomials become $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3 \cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}} r^2 e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x+iy)^2 = \sqrt{\frac{3}{8}} (x^2 + 2ixy - y^2)$$

$$+ X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x-iy)^2 = \sqrt{\frac{3}{8}} (x^2 - 2ixy - y^2)$$

$$= X_2^2(\phi\theta0) + X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{2}} r^2 \frac{e^{i2\phi} + e^{-i2\phi}}{2} \sin^2 \theta = \sqrt{\frac{3}{2}} r^2 \cos 2\phi \sin^2 \theta$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar and tensor operators

Spherical 2^k -multipole functions X_q^k or X -functions are D^* -functions times the k^{th} power of radius (r^k).

Consider $k=2$ “quadrupole” functions

$$\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

$$\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin \theta \cos \theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2}$$

$$\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} \frac{(x-iy)^2}{r^2}$$

$$X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$

$$\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = X_0^2(\phi\theta0) = r^2 \frac{3 \cos^2 \theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$$

The (x,y,z) polynomials become $(\mathbf{J}_x, \mathbf{J}_y, \mathbf{J}_z)$ rotor tensor operators

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3 \cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}} r^2 e^{i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x+iy)^2 = \sqrt{\frac{3}{8}} (x^2 + 2ixy - y^2)$$

$$+ X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{8}} e^{-i2\phi} \sin^2 \theta = \sqrt{\frac{3}{8}} (x-iy)^2 = \sqrt{\frac{3}{8}} (x^2 - 2ixy - y^2)$$

$$= X_2^2(\phi\theta0) + X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{2}} r^2 \frac{e^{i2\phi} + e^{-i2\phi}}{2} \sin^2 \theta = \sqrt{\frac{3}{2}} r^2 \cos 2\phi \sin^2 \theta$$

$$= X_2^2(\phi\theta0) - X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{2}} r^2 \frac{e^{i2\phi} - e^{-i2\phi}}{2} \sin^2 \theta = \sqrt{\frac{3}{8}} (i4xy) = i\sqrt{6} xy = i\sqrt{\frac{3}{2}} r^2 \sin 2\phi \sin^2 \theta \rightarrow \mathbf{T}_2^2 - \mathbf{T}_{-2}^2 = i\sqrt{6} \mathbf{J}_x \mathbf{J}_y$$

etc.

And, don't forget scalar: $\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

→ Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions ←

Rotational Energy Surfaces (RE or RES) of asymmetric rotor (for following class)

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

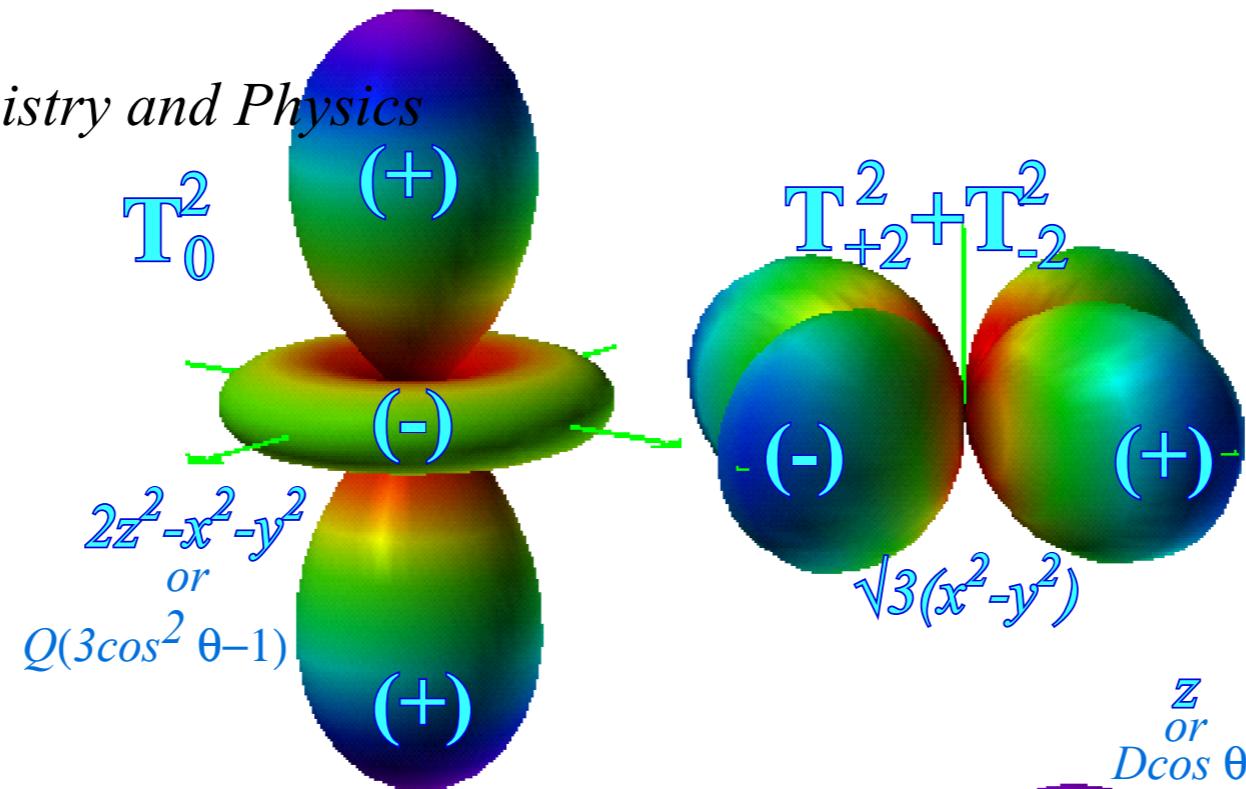
$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

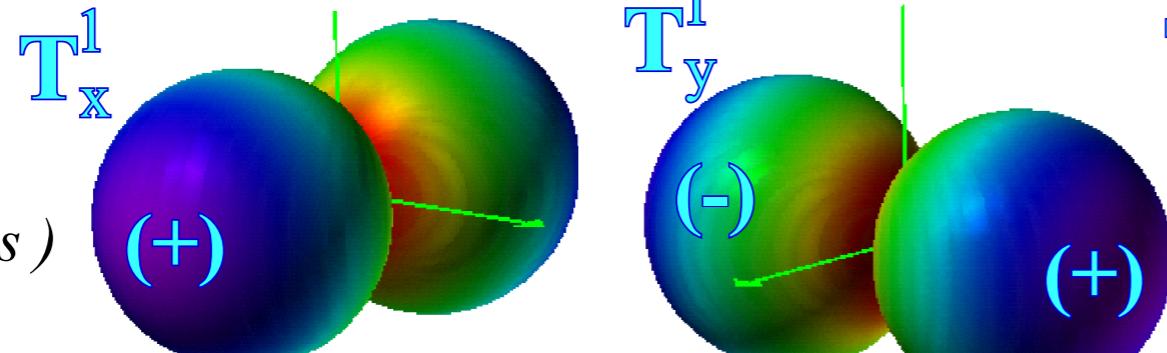
$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

*Review of freshman Chemistry and Physics
Electronic orbitals 101*

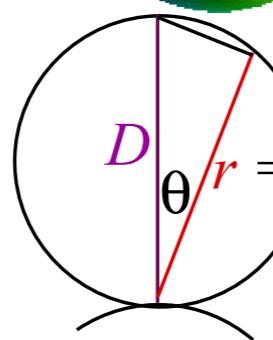
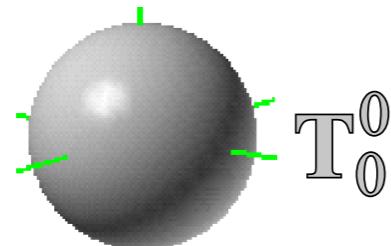
*Quadrupoles
(d-orbitals)*



*Dipoles
(p-orbitals)*



*Monopole
(s-orbital)*



Thales geometry of \mathbf{T}^1 “wave balls” ($P_1(\cos\theta) = \cos\theta$)

Polar vector \mathbf{T}^1 dipoles lack inversion symmetry. They are used to describe gyro-rotors.

Rotor Hamiltonian $\mathbf{H} = \textcolor{red}{A}\mathbf{J}_x^2 + \textcolor{brown}{B}\mathbf{J}_y^2 + \textcolor{green}{C}\mathbf{J}_z^2$ made of scalar and tensor operators

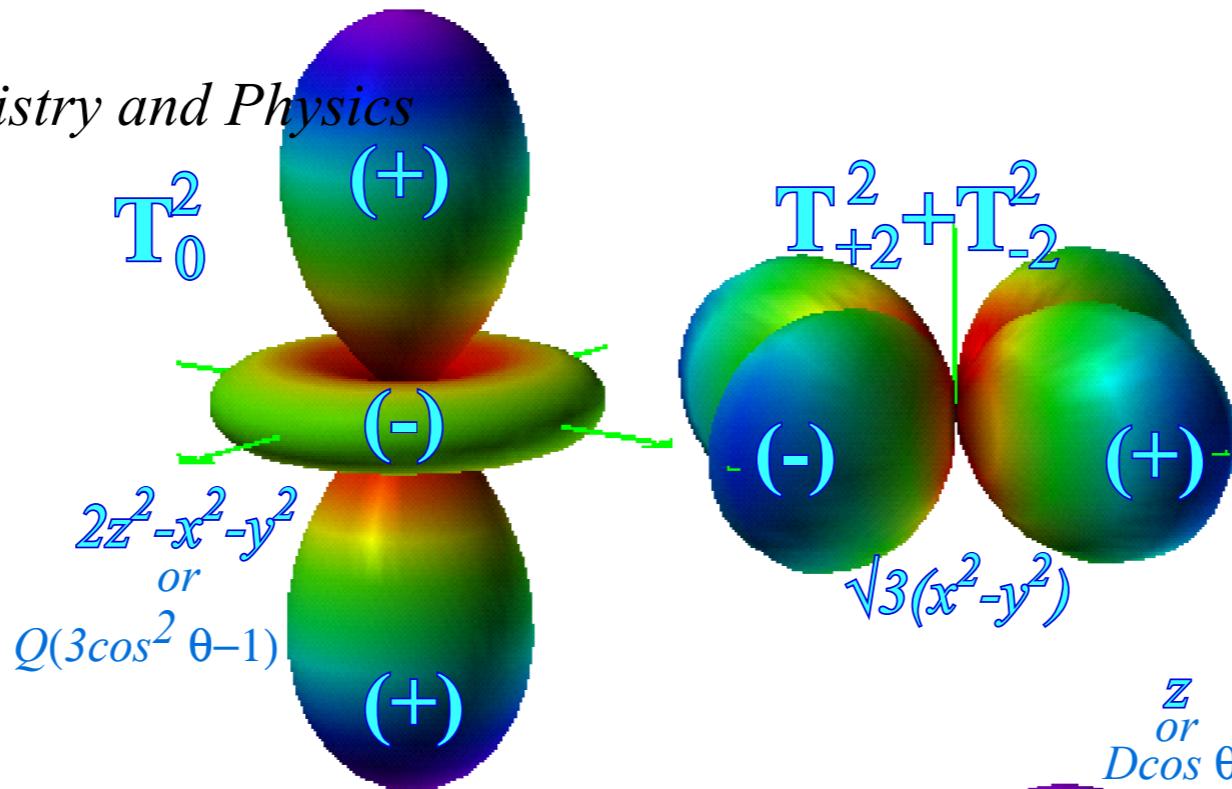
$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

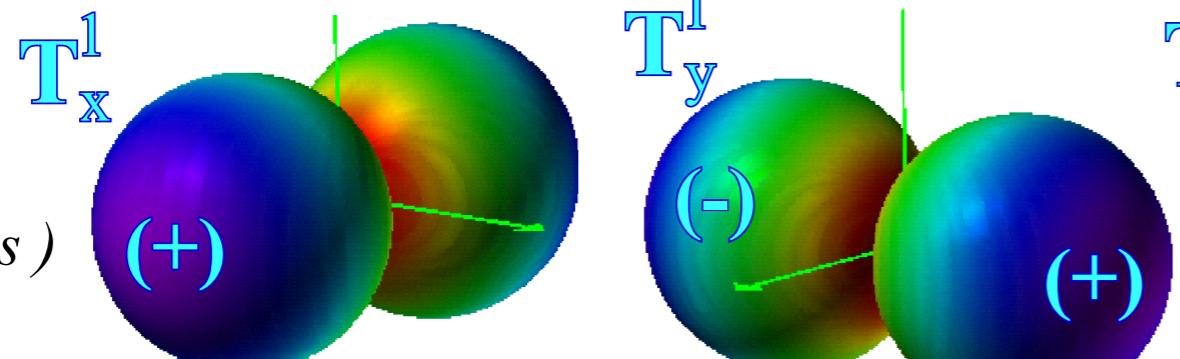
$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

*Review of freshman Chemistry and Physics
Electronic orbitals 101*

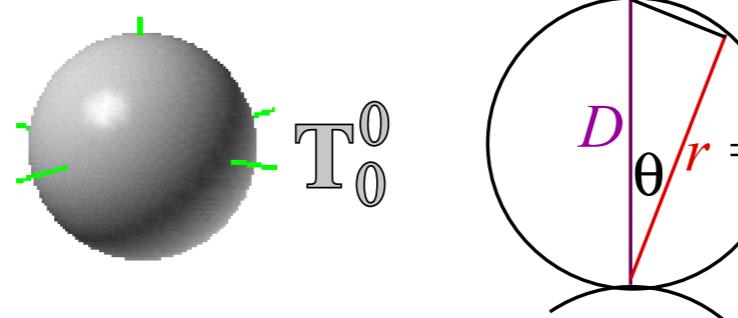
*Quadrupoles
(d-orbitals)*



*Dipoles
(p-orbitals)*

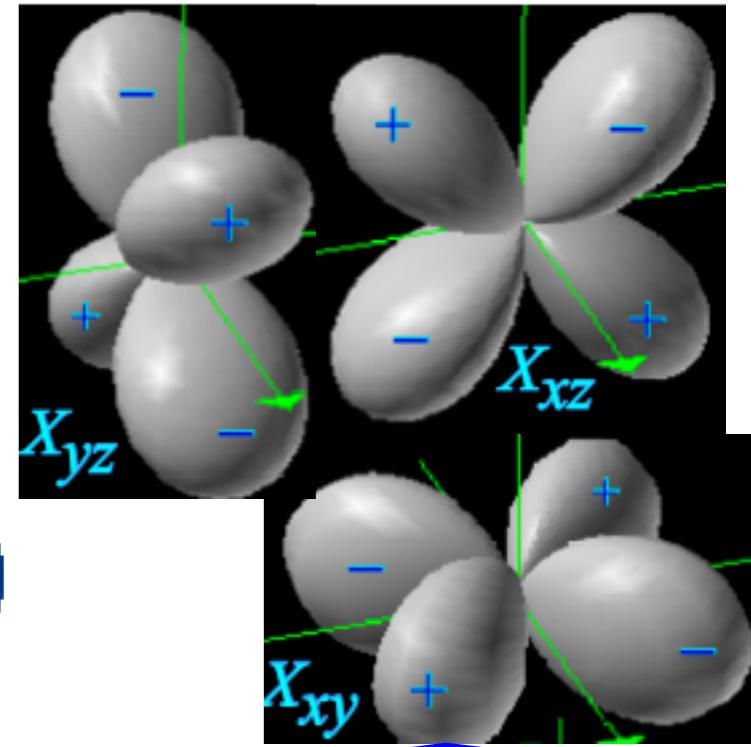


*Monopole
(s-orbital)*



$$D \frac{r}{\theta} = D \cos \theta$$

Thales geometry of \mathbf{T}^1 “wave balls” ($P_1(\cos\theta) = \cos\theta$)



*Axial \mathbf{T}^2 tensor-poles
not needed in a diagonal
rotor Hamiltonian that
has no $\mathbf{J}_x\mathbf{J}_y$, $\mathbf{J}_x\mathbf{J}_z$, or $\mathbf{J}_y\mathbf{J}_z$*

*Polar vector \mathbf{T}^1 dipoles
lack inversion symmetry.
They are used to describe
gyro-rotors.*

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2 \quad \boxed{\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)} \quad \mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2)$$

$$+ \left(\frac{1}{2}A + \frac{-1}{2}B + 0 \cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$Kinetic\ energy\ inertial\ coefficients : A = \frac{1}{2I_x}, B = \frac{1}{2I_y}, C = \frac{1}{2I_z}$$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2)$$

$$+ \left(\frac{1}{2}A + \frac{-1}{2}B + 0\cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

$$+ \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0\cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients : $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2)$$

$$+ \left(\frac{1}{2}A + \frac{-1}{2}B + 0\cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

$$+ \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0\cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$= \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{T}_0^0)$$

$$+ \frac{1}{3}(-\mathbf{A} - \mathbf{B} + 2\mathbf{C})(\mathbf{T}_0^2)$$

$$+ \frac{1}{\sqrt{6}}(\mathbf{A} - \mathbf{B})(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2) \\ + \left(\frac{1}{2}A + \frac{-1}{2}B + 0\cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right) \\ + \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0\cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$= \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{T}_0^0)$$

$$+ \frac{1}{3}(-\mathbf{A} - \mathbf{B} + 2\mathbf{C})(\mathbf{T}_0^2)$$

$$+ \frac{1}{\sqrt{6}}(\mathbf{A} - \mathbf{B})(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting asymmetric top Hamiltonian expansion:

asymmetry term

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{T}_0^0) + \frac{1}{3}(2\mathbf{C} - \mathbf{A} - \mathbf{B})(\mathbf{T}_0^2) + \frac{\mathbf{A} - \mathbf{B}}{\sqrt{6}}(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2) \\ + \left(\frac{1}{2}A + \frac{-1}{2}B + 0\cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right) \\ + \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0\cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$= \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{T}_0^0)$$

$$+ \frac{1}{3}(-\mathbf{A} - \mathbf{B} + 2\mathbf{C})(\mathbf{T}_0^2)$$

$$+ \frac{1}{\sqrt{6}}(\mathbf{A} - \mathbf{B})(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{T}_0^0) + \frac{1}{3}(2\mathbf{C} - \mathbf{A} - \mathbf{B})(\mathbf{T}_0^2) + \frac{\mathbf{A} - \mathbf{B}}{\sqrt{6}}(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

asymmetry term

Resulting semi-classical asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(\mathbf{A} + \mathbf{B} + \mathbf{C})(\mathbf{J}^2) + \frac{1}{3}(2\mathbf{C} - \mathbf{A} - \mathbf{B})(\mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2}) + \frac{\mathbf{A} - \mathbf{B}}{\sqrt{6}}(\sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi)$$

asymmetry term

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2) \\ + \left(\frac{1}{2}A + \frac{-1}{2}B + 0 \cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ + \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right) \\ + \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0 \cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$= \frac{1}{3} (A + B + C) (\mathbf{T}_0^0)$$

$$+ \frac{1}{3} (-A - B + 2C) (\mathbf{T}_0^2)$$

$$+ \frac{1}{\sqrt{6}} (A - B) (\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{T}_0^0) + \frac{1}{3}(2C - A - B)(\mathbf{T}_0^2) + \frac{A - B}{\sqrt{6}}(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

asymmetry term

Resulting semi-classical asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{J}^2) + \frac{1}{3}(2C - A - B)(\mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2}) + \frac{A - B}{\sqrt{6}}(\sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi)$$

asymmetry term

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \mathbf{J}^2 \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6} (3\cos^2 \theta - 1) + \frac{A - B}{2} \sin^2 \theta \cos 2\phi \right]$$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2)$$

$$+ \left(\frac{1}{2}A + \frac{-1}{2}B + 0 \cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0)$$

$$= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2)$$

$$+ \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

$$+ \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0 \cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right)$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$= \frac{1}{3} (A + B + C) (\mathbf{T}_0^0)$$

$$+ \frac{1}{3} (-A - B + 2C) (\mathbf{T}_0^2)$$

$$+ \frac{1}{\sqrt{6}} (A - B) (\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{T}_0^0) + \frac{1}{3}(2C - A - B)(\mathbf{T}_0^2) + \frac{A - B}{\sqrt{6}}(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting semi-classical asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{J}^2) + \frac{1}{3}(2C - A - B)\left(\mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2}\right) + \frac{A - B}{\sqrt{6}}\left(\sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi\right)$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \mathbf{J}^2 \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6} (3\cos^2 \theta - 1) + \frac{A - B}{2} \sin^2 \theta \cos 2\phi \right]$$

Resulting semi-classical symmetric top Hamiltonian expansion: ($A = B$) (asymmetry term not present)

$$\mathbf{H} = B\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \mathbf{J}^2 \left[\frac{B + B + C}{3} + \frac{2C - B - B}{6} (3\cos^2 \theta - 1) + \frac{B - B}{2} \sin^2 \theta \cos 2\phi \right] = \mathbf{J}^2 \left[B + \frac{C - B}{3} 3\cos^2 \theta \right]$$

Rotor Hamiltonian $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$ made of scalar and tensor operators

$$\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$$

$$\mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2} = \mathbf{J}^2 P_2(\cos \theta)$$

$$\mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2$$

$$\begin{aligned} &= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ &+ \left(\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2) \\ &+ \left(\frac{1}{2}A + \frac{-1}{2}B + 0 \cdot C \right) (-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 0) \end{aligned}$$

Kinetic energy inertial coefficients: $A = \frac{1}{2I_x}$, $B = \frac{1}{2I_y}$, $C = \frac{1}{2I_z}$

$$\begin{aligned} &= \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C \right) (\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ &+ \left(\frac{-1}{3}A + \frac{-1}{3}B + \frac{2}{3}C \right) \left(\frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right) \\ &+ \left(\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0 \cdot C \right) \left(\sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \right) \end{aligned}$$

asymmetry term

Resulting asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{T}_0^0) + \frac{1}{3}(2C - A - B)(\mathbf{T}_0^2) + \frac{A - B}{\sqrt{6}}(\mathbf{T}_2^2 + \mathbf{T}_{-2}^2)$$

Resulting semi-classical asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \frac{1}{3}(A + B + C)(\mathbf{J}^2) + \frac{1}{3}(2C - A - B)\left(\mathbf{J}^2 \frac{3\cos^2 \theta - 1}{2}\right) + \frac{A - B}{\sqrt{6}}\left(\sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2 \theta \cos 2\phi\right)$$

$$\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 = \mathbf{J}^2 \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6}(3\cos^2 \theta - 1) + \frac{A - B}{2}\sin^2 \theta \cos 2\phi \right]$$

asymmetry term

Resulting semi-classical symmetric top Hamiltonian expansion: ($A = B$) *(asymmetry term not present)*

$$\begin{aligned} \mathbf{H} = B\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 &= \mathbf{J}^2 \left[\frac{B + B + C}{3} + \frac{2C - B - B}{6}(3\cos^2 \theta - 1) + \frac{B - B}{2}\sin^2 \theta \cos 2\phi \right] = \mathbf{J}^2 \left[B + (C - B)\cos^2 \theta \right] \\ &= B\mathbf{J}^2 + (C - B)\mathbf{J}_z^2 = B\mathbf{J}^2 + (C - B)\mathbf{J}^2 \cos^2 \theta \end{aligned}$$

Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

→ Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions ←

Rotational Energy Surfaces (RE or RES) of asymmetric rotor (for following class)

Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions

Plot Hamiltonian $\mathbf{H} = \mathbf{B}\mathbf{J}^2 + (\mathbf{C} - \mathbf{B})\mathbf{J}_z^2$ radially as $H(\Theta) = \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})J(J+1)\cos^2 \Theta$

$$\left| j_{m,n} \right\rangle$$

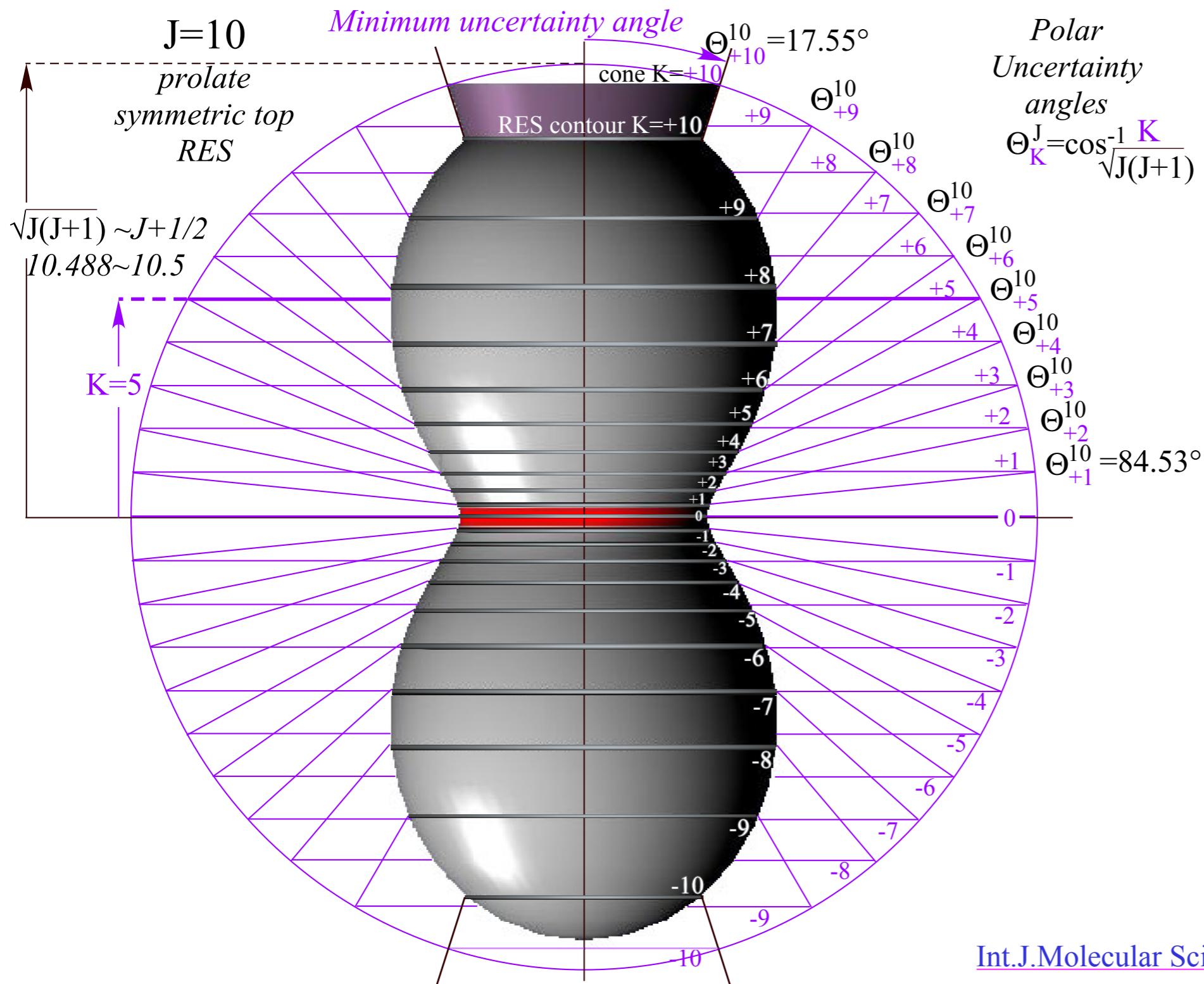
Conventional notation:

$$LAB \quad m=M$$

$$BOD \quad n=K$$

$$n=K = \mathbf{J}_z = \sqrt{J(J+1)} \cos \Theta$$

where: $\mathbf{J}_z = |\mathbf{J}| \cos \Theta$
 $= \sqrt{J(J+1)} \cos \Theta$



Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions

Plot Hamiltonian $\mathbf{H} = \mathbf{B}\mathbf{J}^2 + (\mathbf{C} - \mathbf{B})\mathbf{J}_z^2$ radially as $H(\Theta) = \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})J(J+1)\cos^2\Theta$

$$\left| j_{m,n} \right\rangle$$

Conventional notation:

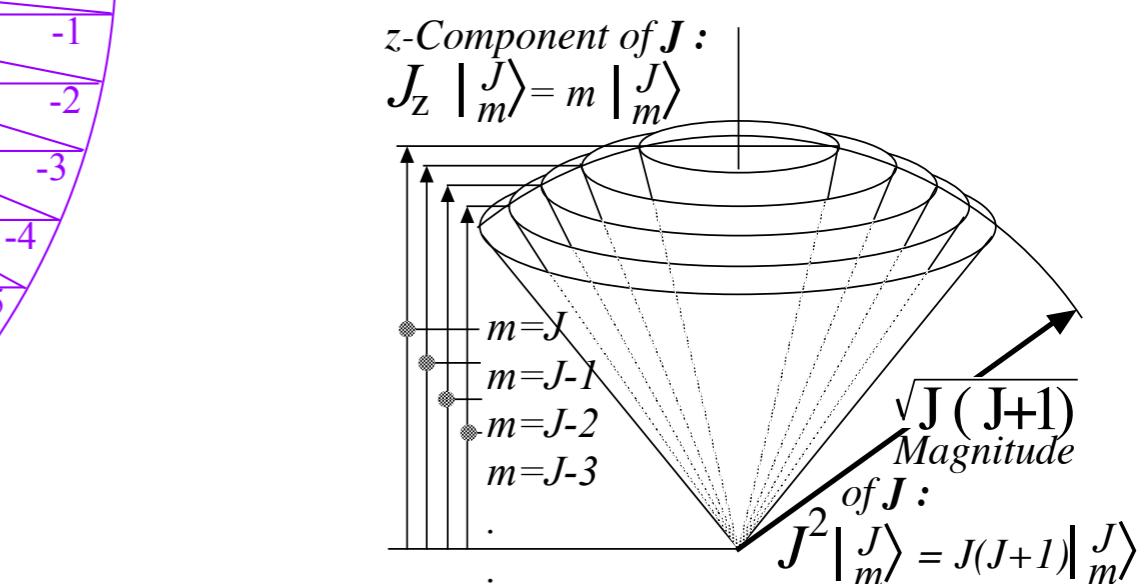
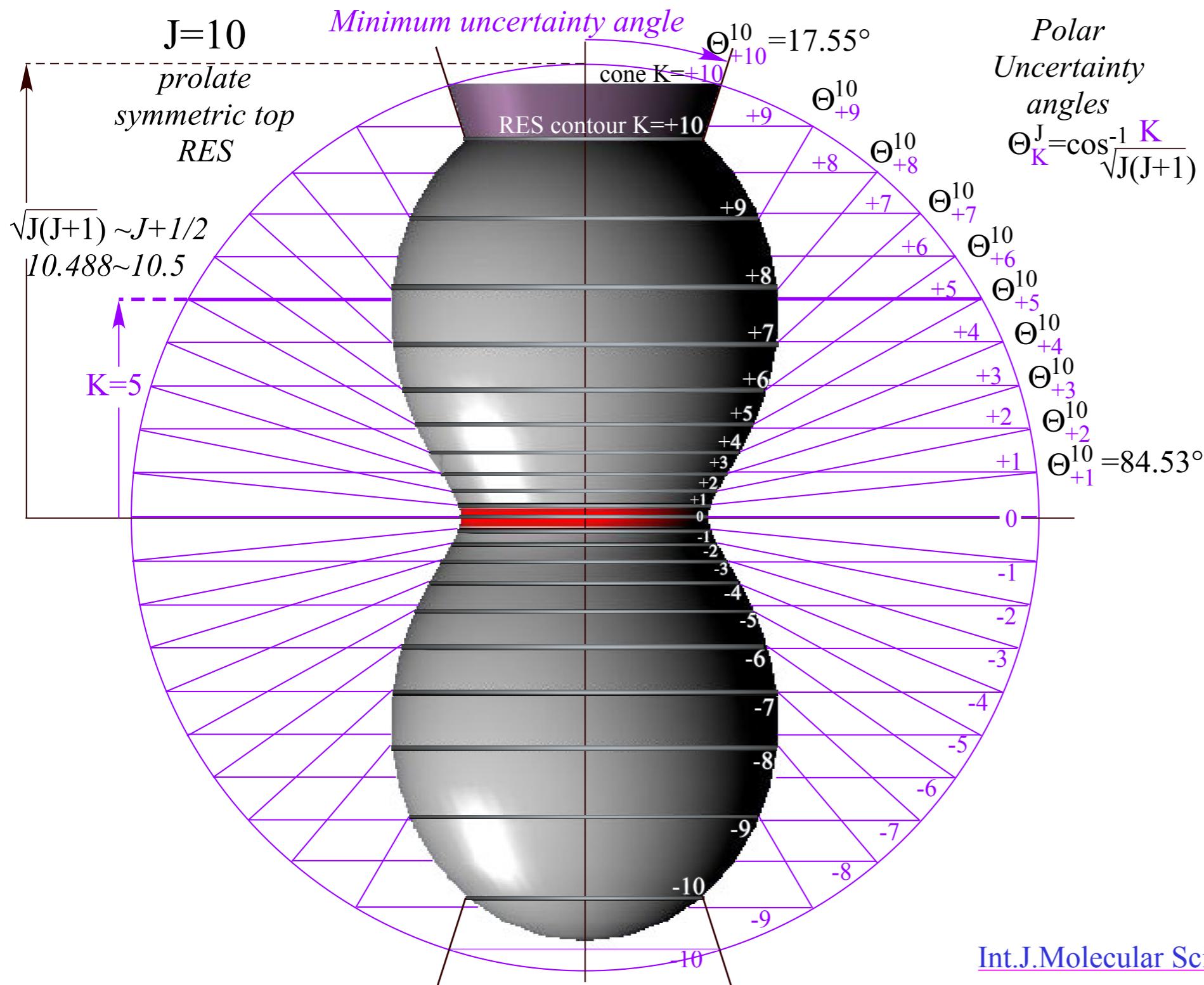
$$\begin{array}{ll} LAB & BOD \\ m=M & n=K \end{array}$$

$$n=K = \mathbf{J}_z = \sqrt{J(J+1)} \cos\Theta$$

$$H(\Theta_K^J) = \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})J(J+1)\cos^2\Theta_K^J$$

$$= \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})K^2$$

where: $\mathbf{J}_z = |\mathbf{J}| \cos\Theta$
 $= \sqrt{J(J+1)} \cos\Theta$



Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions

Plot Hamiltonian $\mathbf{H} = \mathbf{B}\mathbf{J}^2 + (\mathbf{C} - \mathbf{B})\mathbf{J}_z^2$ radially as $H(\Theta) = \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})J(J+1)\cos^2\Theta$

$$\left| j_{m,n} \right\rangle$$

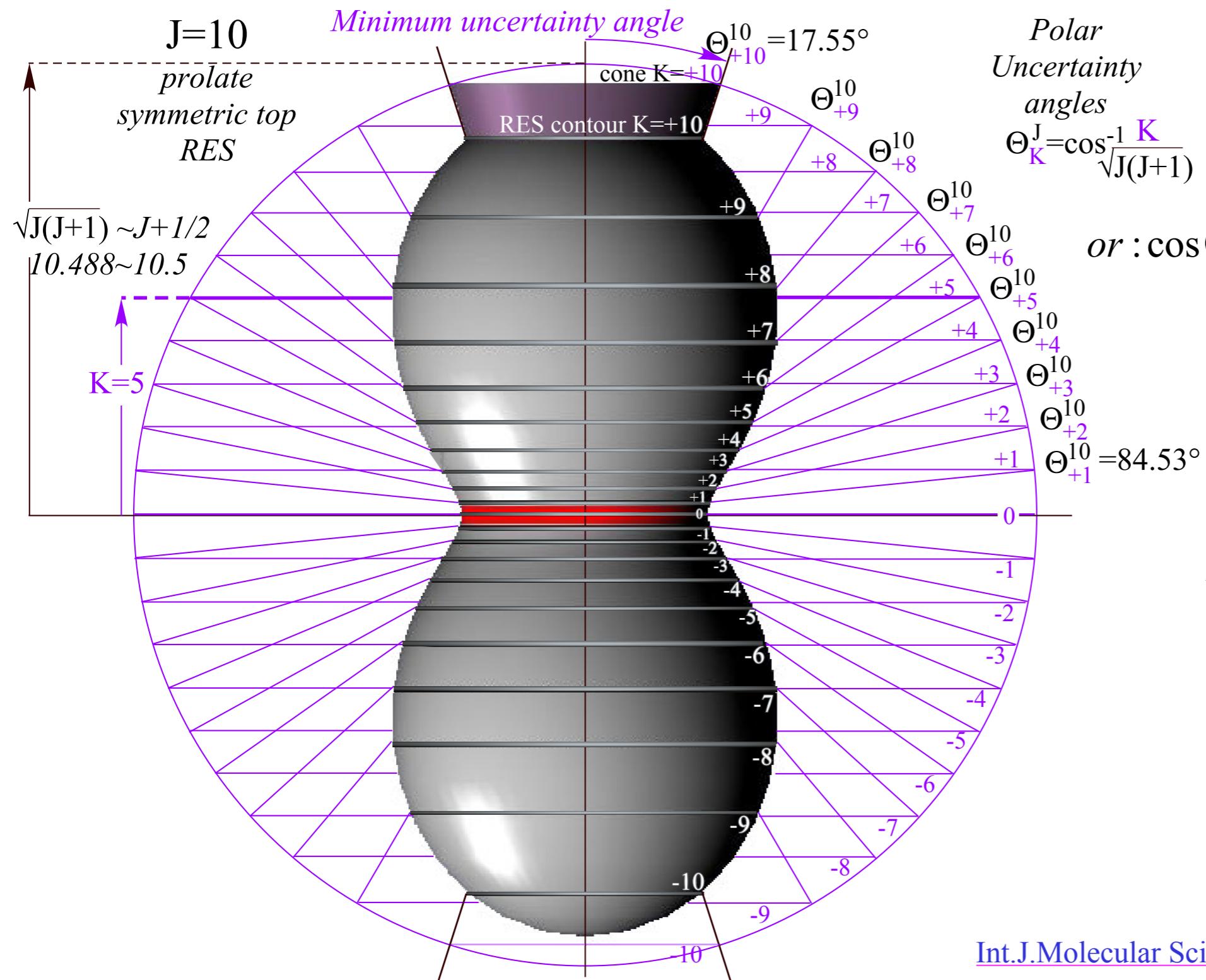
Conventional notation:

$$\begin{array}{ll} LAB & BOD \\ m=M & n=K \\ \end{array} \quad \mathbf{n} = \mathbf{K} = \mathbf{J}_z = \sqrt{J(J+1)} \cos\Theta$$

$$H(\Theta_K^J) = \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})J(J+1)\cos^2\Theta_K^J$$

$$= \mathbf{B}J(J+1) + (\mathbf{C} - \mathbf{B})K^2$$

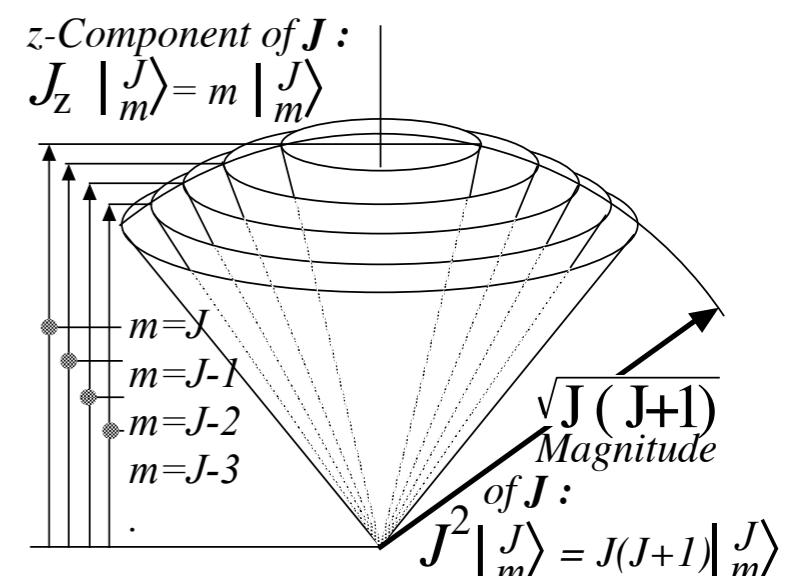
where: $\mathbf{J}_z = |\mathbf{J}| \cos\Theta$
 $= \sqrt{J(J+1)} \cos\Theta$



Polar
Uncertainty
angles
 $\Theta_K^J = \cos^{-1} \frac{K}{\sqrt{J(J+1)}}$

or: $\cos\Theta_K^J = \frac{K}{\sqrt{J(J+1)}}$

(Here this gives exact quantum eigenvalues!)



Wigner D^J_{mn} irreps of $U(2) \sim R(3)$ give atomic and molecular eigenfunctions $\Psi_{m,n}$ of 3D rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ and angular momentum uncertainty effects.

Review 1. Angular momentum raise-n-lower operators \mathbf{S}_+ and \mathbf{S}_-

Review 2. Angular momentum commutation

Review 3. $SU(2) \subset U(2)$ oscillators vs. $R(3) \subset O(3)$ rotors

Angular momentum magnitude and Θ^J_m -uncertainty cone polar angles

Generating higher- j representations D^j_{mn} of $R(3)$ rotation and $U(2)$ from spinor $D^{1/2}$ irreps

Evaluating D^j_{mn} representations

Applications of D^j_{mn} representations

Atomic wave functions. $D^L_{m0} \sim Y^L_m$ Spherical harmonics

$D^{L=1}_{m0} \sim Y^1_m$ p-waves

$D^{L=2}_{m0} \sim Y^2_m$ d-waves

$D^L_{00} \sim P^L$ Legendre waves

Molecular D^j_{mn} wave functions in “Mock-Mach” lab-vs-body state space $|J_{mn}\rangle$

P^j_{mn} projector and $D^j_{mn}(\alpha, \beta, \gamma)$ wave function

D^J_{mn} transform $\mathbf{R}(\alpha, \beta, \gamma)|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha, \beta, \gamma)|J_{m'n}\rangle$ in lab-space,

$\bar{\mathbf{R}}(\alpha, \beta, \gamma)$ in body-space.

D^2_{mn} transform in lab-space (Generalized Stern-Gerlach beam polarization)

Θ^J_m -cone properties of lab transforms: $J=20$, $J=10$, $J=30$.

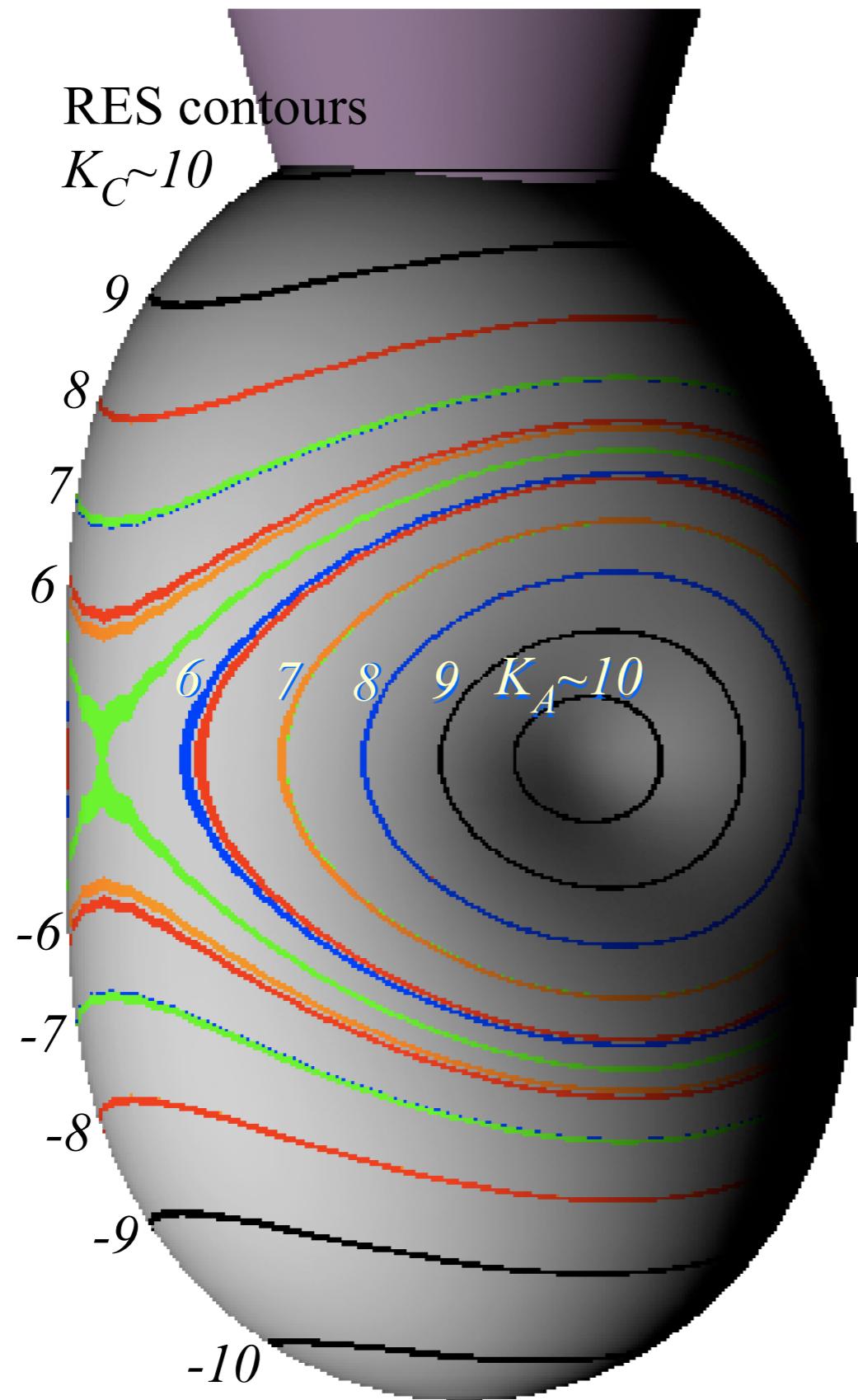
Θ^J_m -analysis of high J atomic beams

Θ^J_m -properties of high J molecular lab-vs-body states $|J_{mn}\rangle$

Rotor Hamiltonian $\mathbf{H} = \mathbf{A}\mathbf{J}_x^2 + \mathbf{B}\mathbf{J}_y^2 + \mathbf{C}\mathbf{J}_z^2$ made of scalar \mathbf{T}_0^0 or tensor \mathbf{T}_q^2 operators

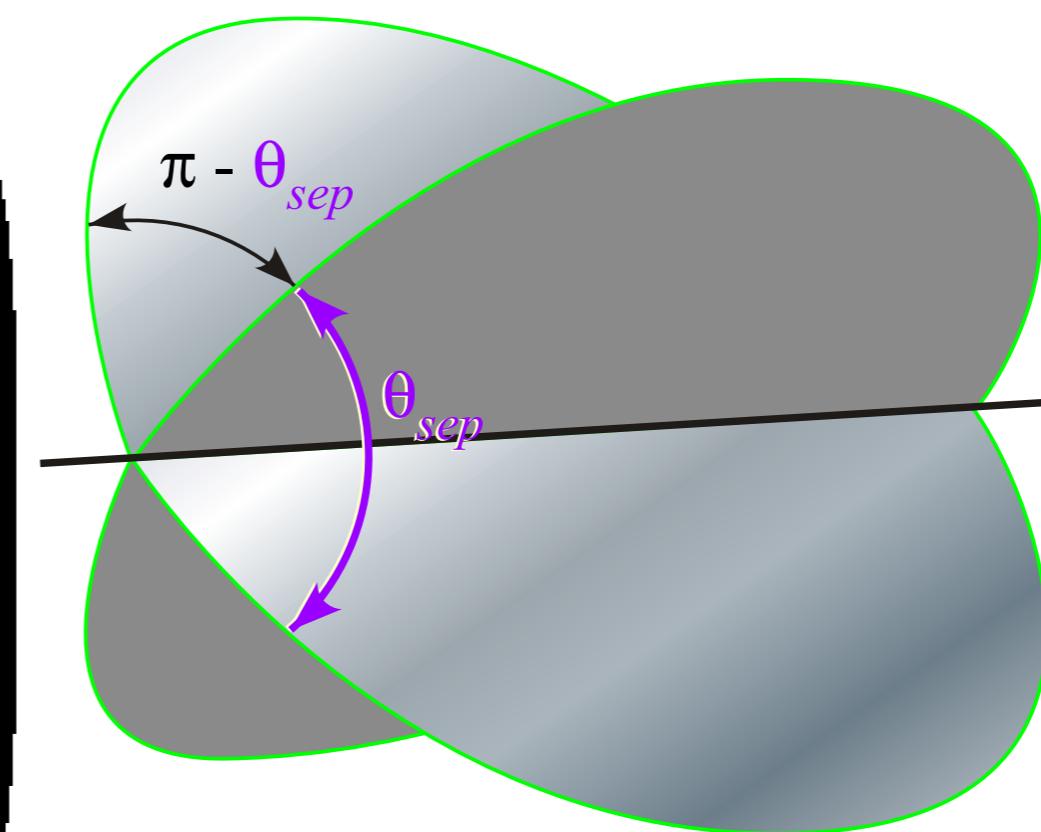
Rotational Energy Surfaces (RES) of symmetric rotor and eigensolutions

→ Rotational Energy Surfaces (RE or RES) of asymmetric rotor (for following class) ←



Separatrix circle pair
dihedral angle

$$\theta_{sep} = \text{atan}\left(\frac{A-B}{B-C}\right)$$



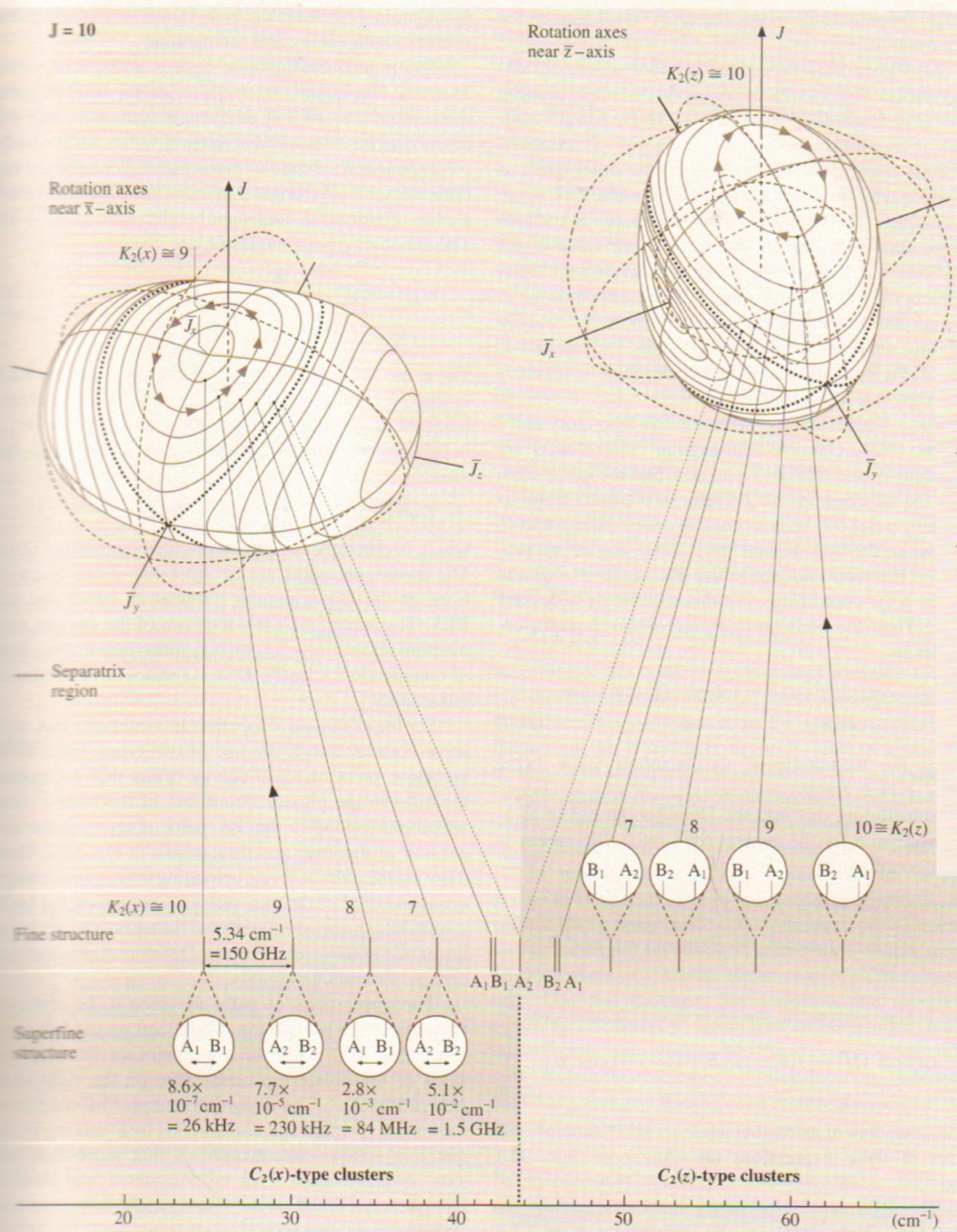
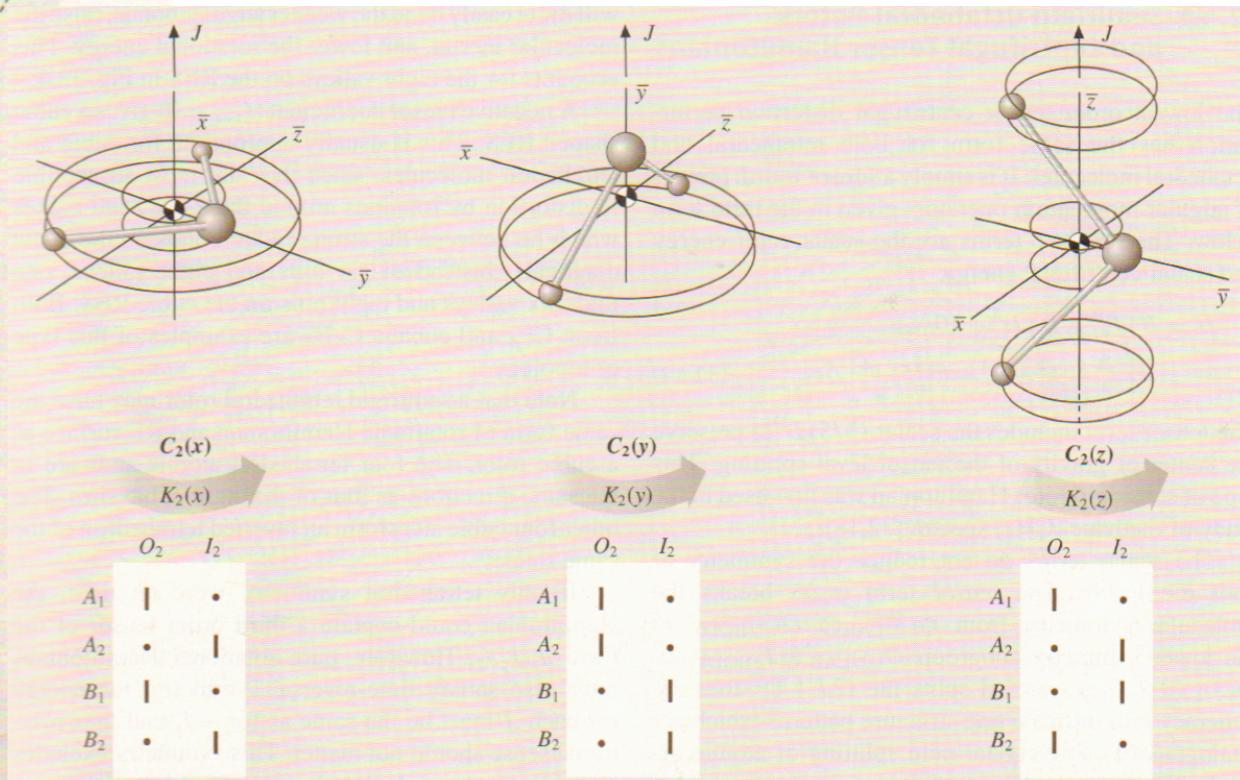


Fig. 32.2 $J = 10$ rotational energy surface and related level spectrum for an asymmetric rigid rotator ($A = 0.2$, $B = 0.4$, $C = 0.6 \text{ cm}^{-1}$)

Examples of Group ⊂ Sub-group correlation
 $D_2 \supset C_2(x)$ $D_2 \supset C_2(y)$ $D_2 \supset C_2(z)$



Springer Handbook
of
Atomic, Molecular, and Optical
Physics (2005)
Fig. 32.2 and 32.3 p. 495-497

after QTforCA Unit 8. Ch. 25 Fig. 25.4.2

Properties of 1D-HO coherent state

???

Coherent wave packet uncertainty relation: $\Delta n \cdot \Delta \phi > \pi/n$

Some uncertainty remains about this uncertainty
???

