

Symmetry eigensolutions on the Cheap

and

Going beyond “Gruppenpest”

Exploiting local symmetry algebra and geometry of a quantum “Mock-Mach” principle

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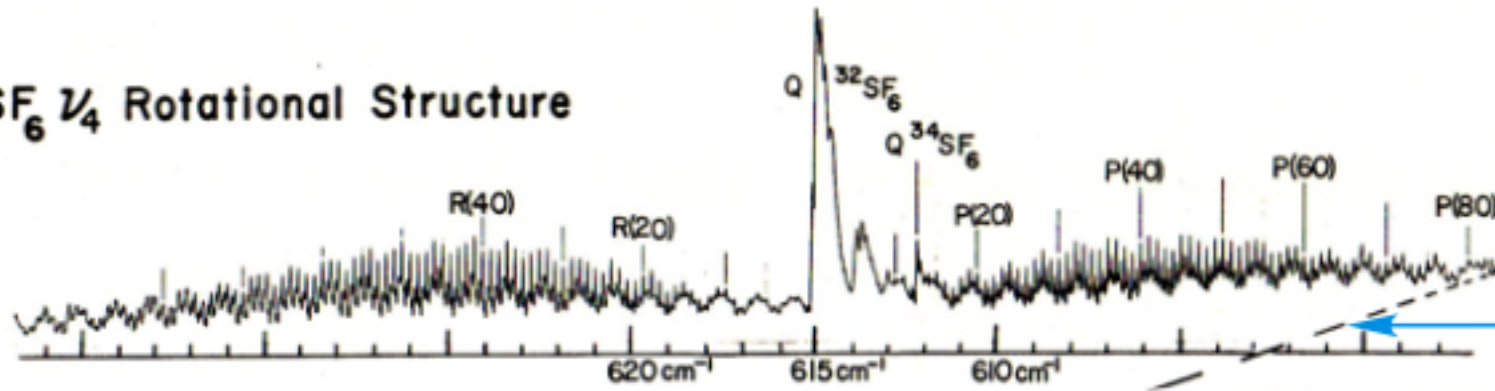
Dr. T. C. Reimer,

Justin Mitchell,

*...and friend**

**(O_h slide rule)*

(a) SF₆ ν₄ Rotational Structure



FT IR and Laser Diode Spectra
K.C. Kim, W.B. Person, D. Seitz, and B.J. Krohn
J. Mol. Spectrosc. 76, 322 (1979).

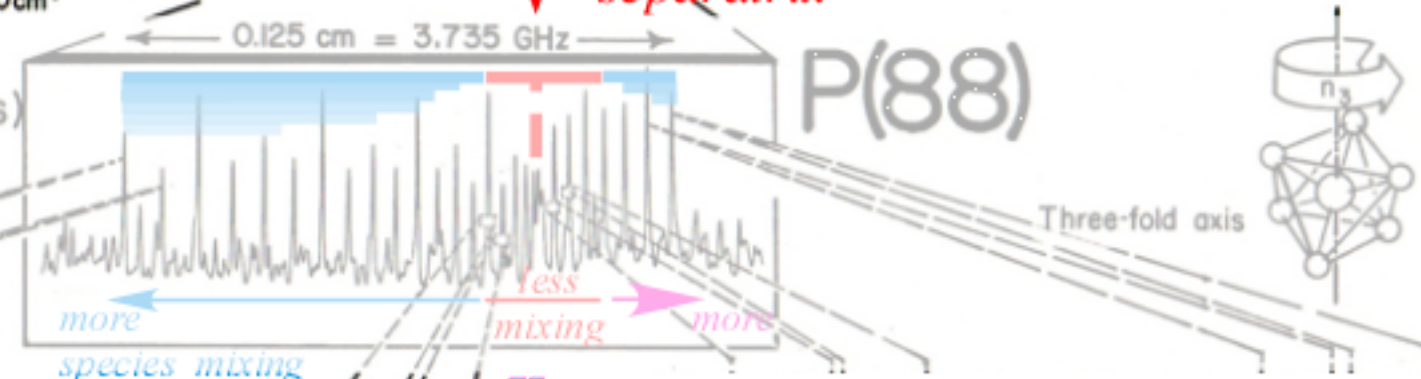
Primary AET species mixing increases with distance from "separatrix"

(b) P(88) Fine Structure (Rotational anisotropy effects)

SF₆ ν₃ P(88) ~ 16m

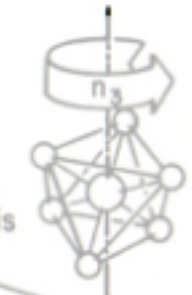


Four fold axis

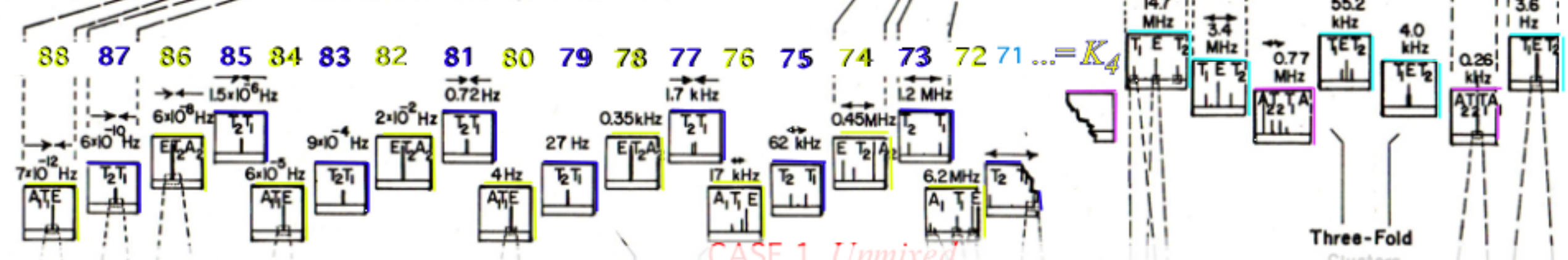


P(88)

Three-fold axis



(c) Superfine Structure (Rotational axis tunneling)



CASE 1 Unmixed

Three-Fold Clusters

Observed repeating sequence(s) ... A₁T₁E T₂T₁ ET₂A₂ T₂T₁ ... A₁T₁E T₂T₁ ET₂A₂ T₂T₁ ...

Some things we're trying to explain / predict / understand: Inner workings of molecules

(e) Superhyperfine Structure (Spin-rotation effects)

CASE 2₃ Major mixing in lowest two C₃-CLUSTERS

Matrix Diagonalization by computer:

The **BLACK BOX** of quantum physics, chemistry, and *spectroscopy*



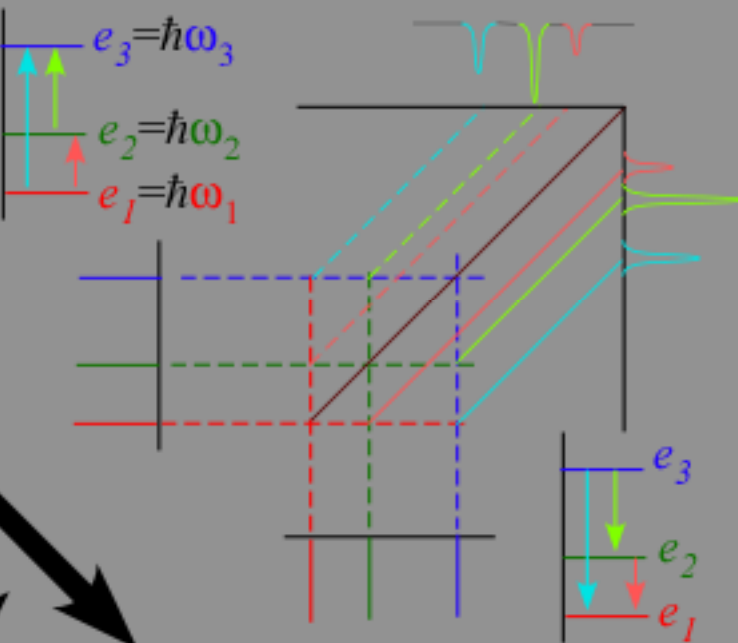
H-matrix

$$\begin{pmatrix} H_{11} & H_{12} & H_{13} & \dots \\ H_{21} & H_{22} & H_{23} & \dots \\ H_{31} & H_{32} & H_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$



Eigenvalues
(Quantum levels)

$$\begin{pmatrix} e_1 & e_2 & e_3 & \dots \\ \langle 1|e_1\rangle & \langle 1|e_2\rangle & \langle 1|e_3\rangle & \dots \\ \langle 2|e_1\rangle & \langle 2|e_2\rangle & \langle 2|e_3\rangle & \dots \\ \langle 3|e_1\rangle & \langle 3|e_2\rangle & \langle 3|e_3\rangle & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$



Eigenvectors
(Quantum states)

Most of the information!

perturbation or transition matrix

$$\begin{pmatrix} \langle e_1 | t_q^k | e_1 \rangle & \langle e_1 | t_q^k | e_2 \rangle & \langle e_1 | t_q^k | e_3 \rangle & \dots \\ \langle e_2 | t_q^k | e_1 \rangle & \langle e_2 | t_q^k | e_2 \rangle & \langle e_2 | t_q^k | e_3 \rangle & \dots \\ \langle e_3 | t_q^k | e_1 \rangle & \langle e_3 | t_q^k | e_2 \rangle & \langle e_3 | t_q^k | e_3 \rangle & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

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Eigenvectors
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Silicon Brain knows all...

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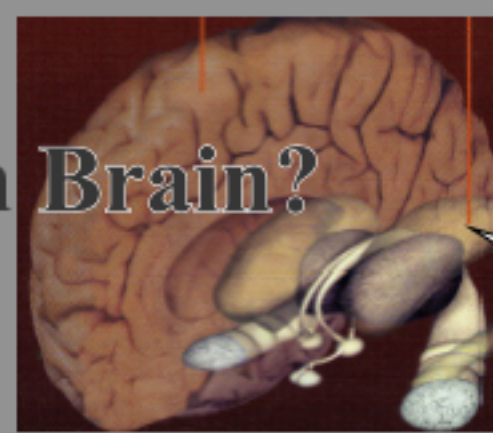
Eigenvalues
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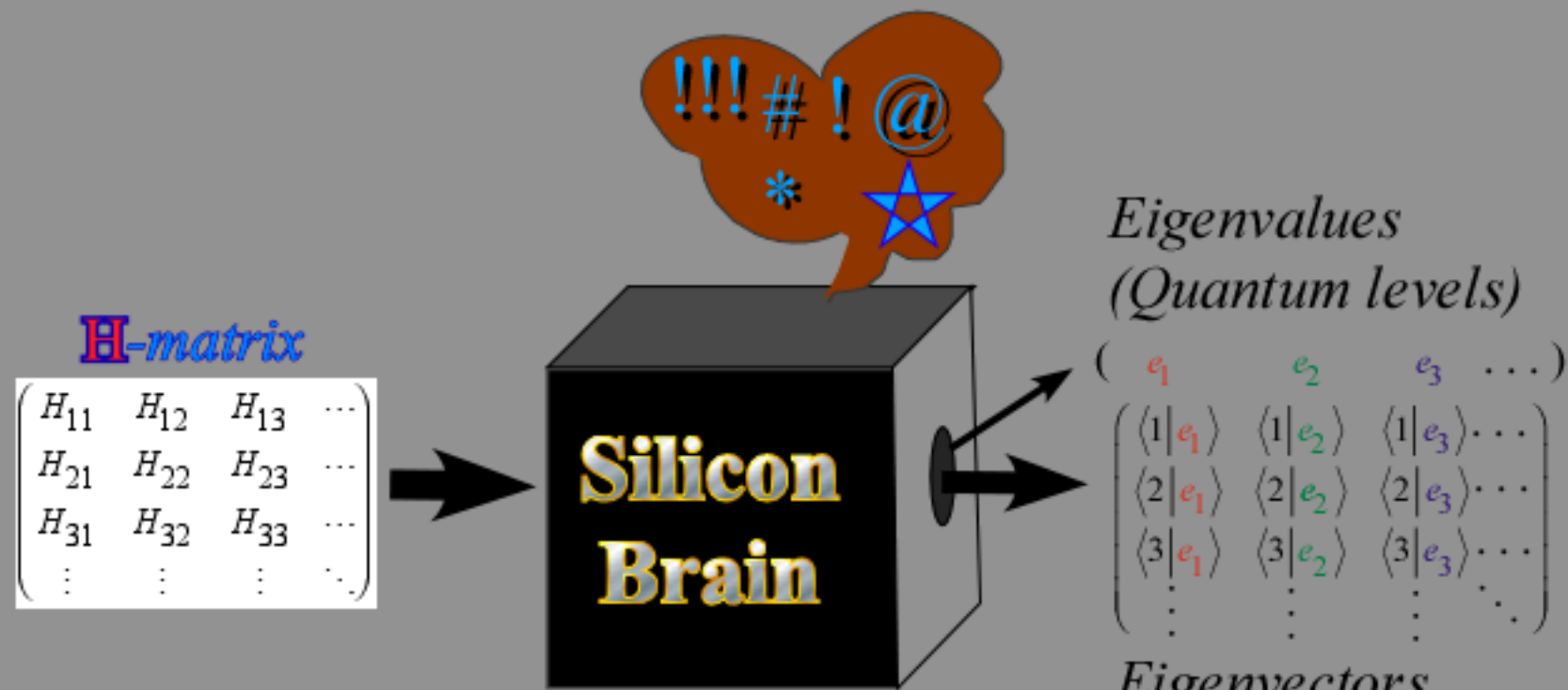
$$\begin{pmatrix} e_1 & e_2 & e_3 & \dots \\ \langle 1|e_1\rangle & \langle 1|e_2\rangle & \langle 1|e_3\rangle & \dots \\ \langle 2|e_1\rangle & \langle 2|e_2\rangle & \langle 2|e_3\rangle & \dots \\ \langle 3|e_1\rangle & \langle 3|e_2\rangle & \langle 3|e_3\rangle & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

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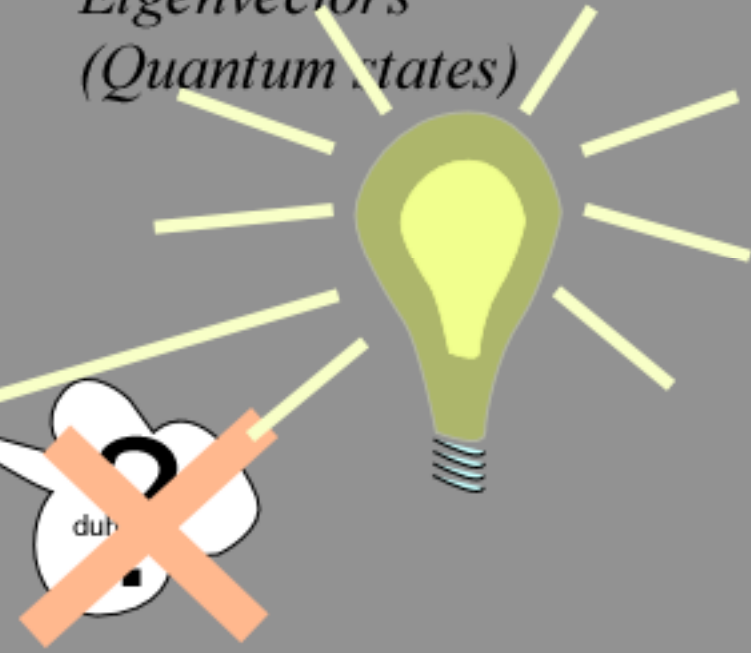
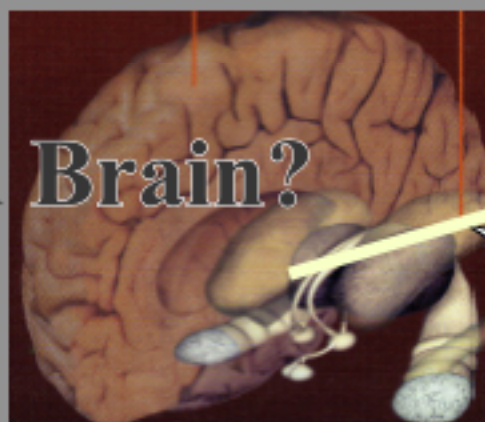
..but what's left for the
Carbon Brain?






Silicon Brain knows all...

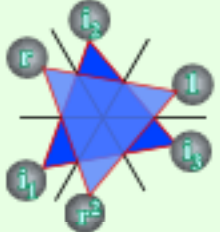
..but what's left for the **Carbon Brain?**

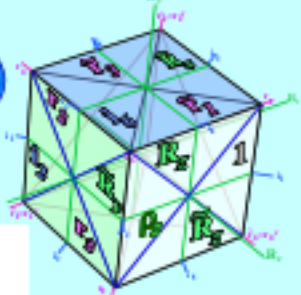
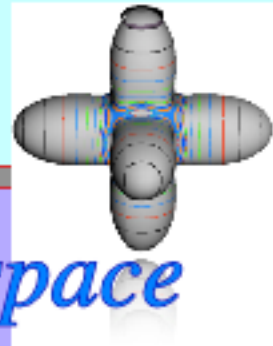


New symmetry analysis techniques
come to rescue old Carbon Brain!


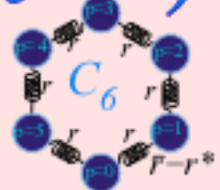
- (Commuting)
- **Abelian symmetry = Fourier analysis** (Back to our roots $1^{1/N} = e^{2\pi im/N}$)
 Group $\hat{\Lambda}$ product table \Rightarrow Hamiltonian \mathbf{H} -matrices (C_2 and C_6 examples)  C_2  C_6
 - Group roots \Rightarrow \mathbf{H} -matrix spectral resolution by $P^{(m)}$ projectors

- Commutivity conundrum... ? $\mathbf{H} \cdot g = g \cdot \mathbf{H}$?
- **New symmetry insights:** Local vs. Global symmetry Projector invariance
 "Mock-Mach" principle Conway, et.al, May (2008) Cvitanovic, (2008)

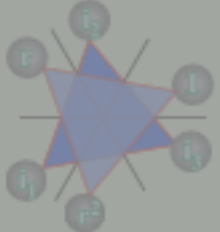
- (Non-Commuting)
- **Non-Abelian symmetry analysis I.** (Simplest example: D_3) 
 - Local vs. Global $\hat{\Lambda}$ product tables \Rightarrow \mathbf{H} -matrices
 - All-commuting invariants \Rightarrow Global invariant (character) $P^{(\alpha)}$ projectors
 - Mutually-commuting sets \Rightarrow Local vs. Global eigensolutions by $P_{m,n}^{(\alpha)}$ projectors
 \Rightarrow \mathbf{H} -matrix spectral resolution by $P_{m,n}^{(\alpha)}$ projectors

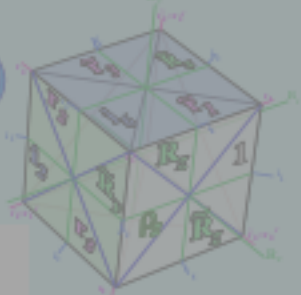

- **Non-Abelian symmetry analysis II.** (Octahedral example: O_h) 
- Global-local product tables \Rightarrow \mathbf{H} -matrices...
 ... and all the above ...
- \Rightarrow eigensolution formulas by local-symmetry defined $P_{n,n}^{(\alpha)}$ projectors 

- **Local vs Global symmetry in rovibronic phase space** 
- How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples)

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- **Local vs Global symmetry in rovibronic phase space** 
- How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples)

1st Step

Expand C_6 symmetric $\mathbf{H} =$

E	W	0	0	0	W
W	E	W	0	0	0
0	W	E	W	0	0
0	0	W	E	W	0
0	0	0	W	E	W
W	0	0	0	W	E

using C_6 group table ($g g^\dagger$ form)

$$\mathbf{H} = r_0 \mathbf{r}^0 + r_1 \mathbf{r}^1 + r_2 \mathbf{r}^2 + \dots + r_{n-1} \mathbf{r}^{n-1} = \sum r_q \mathbf{r}^k$$

C_6	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}
1	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}
\mathbf{r}	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2
\mathbf{r}^2	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3
\mathbf{r}^3	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4
\mathbf{r}^4	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5
\mathbf{r}^5	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1

$$\mathbf{H} = r_0 \mathbf{r}^0 + r_1 \mathbf{r}^1 + r_2 \mathbf{r}^2 + r_3 \mathbf{r}^3 + r_4 \mathbf{r}^4 + r_5 \mathbf{r}^5$$

$$\begin{pmatrix} r_0 & r_5 & r_4 & r_3 & r_2 & r_1 \\ r_1 & r_0 & r_5 & r_4 & r_3 & r_2 \\ r_2 & r_1 & r_0 & r_5 & r_4 & r_3 \\ r_3 & r_2 & r_1 & r_0 & r_5 & r_4 \\ r_4 & r_3 & r_2 & r_1 & r_0 & r_5 \\ r_5 & r_4 & r_3 & r_2 & r_1 & r_0 \end{pmatrix} = r_0 \begin{pmatrix} 1 & \dots & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \end{pmatrix} + r_1 \begin{pmatrix} \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix} + r_2 \begin{pmatrix} \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix} + r_3 \begin{pmatrix} \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix} + r_4 \begin{pmatrix} \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix} + r_5 \begin{pmatrix} \dots & 1 & \dots & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}$$

C_6 group table gives \mathbf{r} -matrices,...

1st Step (contd.)

Expand C_6 symmetric $\mathbf{H} =$

E	W	0	0	0	W
W	E	W	0	0	0
0	W	E	W	0	0
0	0	W	E	W	0
0	0	0	W	E	W
W	0	0	0	W	E

using C_6 group table (g, g^\dagger form)

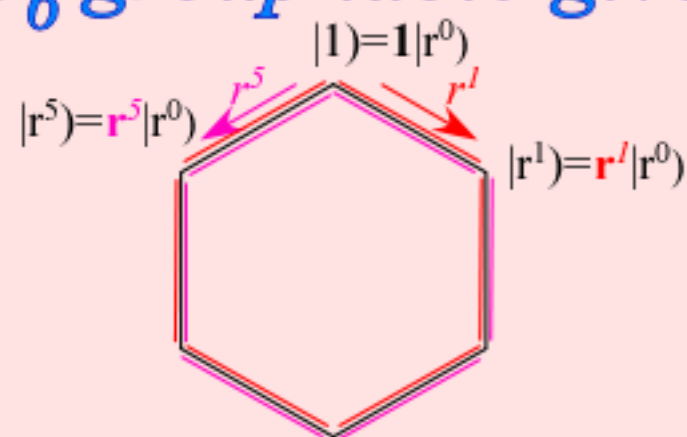
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\mathbf{r}	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2
\mathbf{r}^2	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3
\mathbf{r}^3	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5	\mathbf{r}^4
\mathbf{r}^4	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1	\mathbf{r}^5
\mathbf{r}^5	\mathbf{r}^5	\mathbf{r}^4	\mathbf{r}^3	\mathbf{r}^2	\mathbf{r}	1

$$\mathbf{H} = r_0 \mathbf{r}^0 + r_1 \mathbf{r}^1 + r_2 \mathbf{r}^2 + r_3 \mathbf{r}^3 + r_4 \mathbf{r}^4 + r_5 \mathbf{r}^5$$

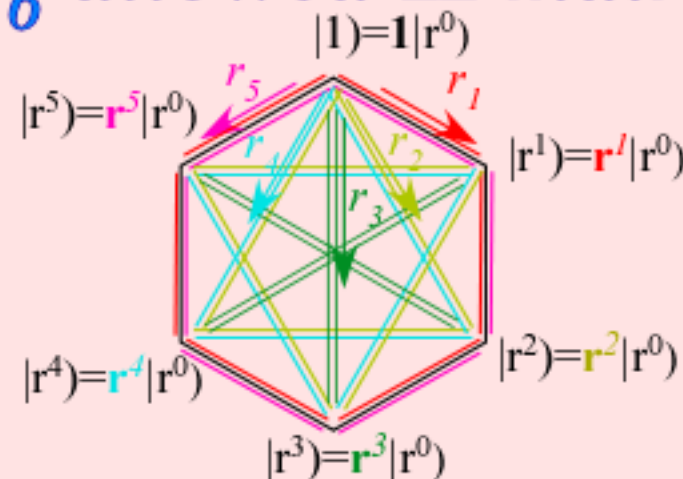
$$\begin{pmatrix} r_0 & r_5 & r_4 & r_3 & r_2 & r_1 \\ r_1 & r_0 & r_5 & r_4 & r_3 & r_2 \\ r_2 & r_1 & r_0 & r_5 & r_4 & r_3 \\ r_3 & r_2 & r_1 & r_0 & r_5 & r_4 \\ r_4 & r_3 & r_2 & r_1 & r_0 & r_5 \\ r_5 & r_4 & r_3 & r_2 & r_1 & r_0 \end{pmatrix} = r_0 \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} + r_1 \begin{pmatrix} & & & & & 1 \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + r_2 \begin{pmatrix} & & & & 1 & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + r_3 \begin{pmatrix} & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + r_4 \begin{pmatrix} & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \\ & & & & & \\ & & & & & \end{pmatrix} + r_5 \begin{pmatrix} & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \\ & & & & & \end{pmatrix}$$

C_6 group table gives \mathbf{r} -matrices, ... C_6 -allowed \mathbf{H} -matrices...



Nearest neighbor coupling

$$\begin{pmatrix} r_0 & r_5 & & & & r_1 \\ r_1 & r_0 & r_5 & & & \\ & r_1 & r_0 & r_5 & & \\ & & r_1 & r_0 & r_5 & \\ & & & r_1 & r_0 & r_5 \\ r_5 & & & & & r_0 \end{pmatrix}$$



ALL neighbor coupling

$$\begin{pmatrix} r_0 & r_5 & r_4 & r_3 & r_2 & r_1 \\ r_1 & r_0 & r_5 & r_4 & r_3 & r_2 \\ r_2 & r_1 & r_0 & r_5 & r_4 & r_3 \\ r_3 & r_2 & r_1 & r_0 & r_5 & r_4 \\ r_4 & r_3 & r_2 & r_1 & r_0 & r_5 \\ r_5 & r_4 & r_3 & r_2 & r_1 & r_0 \end{pmatrix}$$

2nd Step

H diagonalized by spectral resolution of $r, r^2, \dots, r^6 = 1$

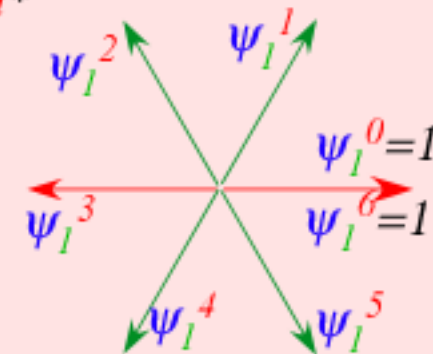
All $x = r^p$ satisfy $x^6 = 1$ and use **6th-roots-of-1** for eigenvalues

$$\begin{aligned}\psi_1^0 &= 1 \\ \psi_1^1 &= e^{2\pi i/6} \\ \psi_1^2 &= \psi_2^1 = e^{4\pi i/6} \\ \psi_1^3 &= \psi_3^1 = -1 \\ \psi_1^4 &= \psi_4^1 = \psi_1^{-2} = e^{-4\pi i/6} \\ \psi_1^5 &= \psi_5^1 = \psi_1^{-1} = e^{-2\pi i/6}\end{aligned}$$

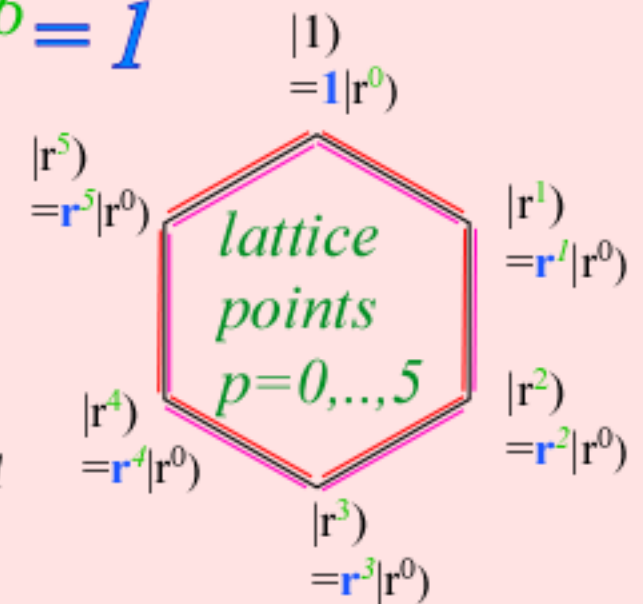
$$D^m(\mathbf{r}) = e^{-2\pi i m/6} = \chi_1^m = \psi_1^{m*}$$

$$D^m(\mathbf{r}^p) = e^{-2\pi i m \cdot p/6} = \chi_p^m = \psi_p^{m*}$$

p = power (exponent)
or position point
 m = momentum
or wave-number



6th-roots of 1
 $m = 0, \dots, 5$



Groups “know” their roots and will tell you them if you ask nicely!

You efficiently get:

- invariant projectors
- irreducible projectors
- irreducible representations (irreps)
- H eigenvalues
- H eigenvectors
- T matrices
- dispersion functions

2nd Step (contd.)

H diagonalized by spectral resolution of $r, r^2, \dots, r^6 = 1$

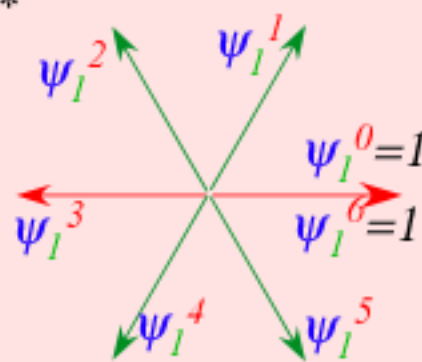
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$$D^m(r) = e^{-2\pi i m/6} = \chi_1^m = \psi_1^{m*}$$

$$D^m(r^p) = e^{-2\pi i m \cdot p/6} = \chi_p^m = \psi_p^{m*}$$

p = power (exponent)
or position point
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top-row flip
not needed...

$$\mathbf{P}^{(m)} = \mathbf{P}^{(m)\dagger}$$

6 ring	$\mathbf{P}^{(0)}$	$\mathbf{P}^{(1)}$	$\mathbf{P}^{(2)}$	$\mathbf{P}^{(3)}$	$\mathbf{P}^{(4)}$	$\mathbf{P}^{(5)}$
$\mathbf{P}^{(0)}$	$\mathbf{P}^{(0)}$
$\mathbf{P}^{(1)}$.	$\mathbf{P}^{(1)}$
$\mathbf{P}^{(2)}$.	.	$\mathbf{P}^{(2)}$.	.	.
$\mathbf{P}^{(3)}$.	.	.	$\mathbf{P}^{(3)}$.	.
$\mathbf{P}^{(4)}$	$\mathbf{P}^{(4)}$.
$\mathbf{P}^{(5)}$	$\mathbf{P}^{(5)}$

$$\mathbf{r}^p = \chi_p^0 \mathbf{P}^{(0)} + \chi_p^1 \mathbf{P}^{(1)} + \chi_p^2 \mathbf{P}^{(2)} + \chi_p^3 \mathbf{P}^{(3)} + \chi_p^4 \mathbf{P}^{(4)} + \chi_p^5 \mathbf{P}^{(5)}$$

$$\begin{pmatrix} \chi_p^0 & & & & & \\ & \chi_p^1 & & & & \\ & & \chi_p^2 & & & \\ & & & \chi_p^3 & & \\ & & & & \chi_p^4 & \\ & & & & & \chi_p^5 \end{pmatrix} = \chi_p^0 \begin{pmatrix} 1 & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + \chi_p^1 \begin{pmatrix} & 1 & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + \chi_p^2 \begin{pmatrix} & & 1 & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + \chi_p^3 \begin{pmatrix} & & & 1 & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + \chi_p^4 \begin{pmatrix} & & & & 1 & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} + \chi_p^5 \begin{pmatrix} & & & & & 1 \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{pmatrix}$$

Projectors $\mathbf{P}^{(m)}$ are eigenvalue “placeholders” having orthogonal-idempotent products, eigen-equations,

$$\mathbf{P}^{(m)} \mathbf{P}^{(n)} = \delta^{mn} \mathbf{P}^{(m)}$$

$$\mathbf{r}^p \mathbf{P}^{(n)} = \chi_p^n \mathbf{P}^{(n)}$$

and one completeness rule: $\mathbf{P}^{(0)} + \mathbf{P}^{(1)} + \mathbf{P}^{(2)} + \dots + \mathbf{P}^{(5)} = \mathbf{1}$

2nd Step (contd.)

H diagonalized by spectral resolution of $r, r^2, \dots, r^6 = 1$

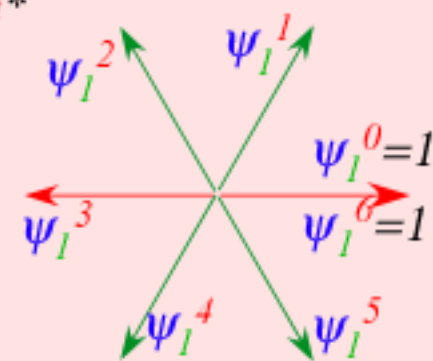
All $x=r^p$ satisfy $x^6=1$ and use **6th-roots-of-1** for eigenvalues

$$\begin{aligned} \psi_1^0 &= 1 \\ \psi_1^1 &= e^{2\pi i/6} \\ \psi_1^2 &= \psi_2^1 = e^{4\pi i/6} \\ \psi_1^3 &= \psi_3^1 = -1 \\ \psi_1^4 &= \psi_4^1 = \psi_1^{-2} = e^{-4\pi i/6} \\ \psi_1^5 &= \psi_5^1 = \psi_1^{-1} = e^{-2\pi i/6} \end{aligned}$$

$$D^m(\mathbf{r}) = e^{-2\pi i m/6} = \chi_1^m = \psi_1^{m*}$$

$$D^m(\mathbf{r}^p) = e^{-2\pi i m \cdot p/6} = \chi_p^m = \psi_p^{m*}$$

p = power (exponent)
or position point
 m = momentum
or wave-number

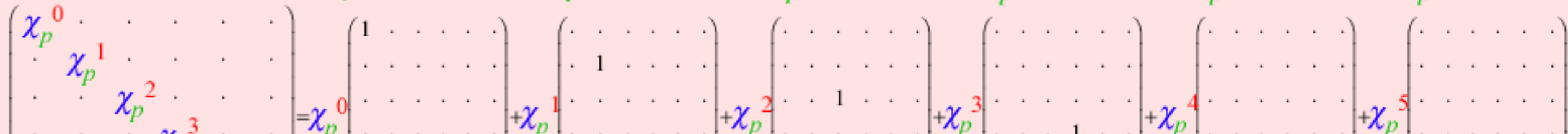


top-row flip
not needed...

$$\mathbf{P}^{(m)} = \mathbf{P}^{(m)\dagger}$$

6 ring	$\mathbf{P}^{(0)}$	$\mathbf{P}^{(1)}$	$\mathbf{P}^{(2)}$	$\mathbf{P}^{(3)}$	$\mathbf{P}^{(4)}$	$\mathbf{P}^{(5)}$
$\mathbf{P}^{(0)}$	$\mathbf{P}^{(0)}$
$\mathbf{P}^{(1)}$.	$\mathbf{P}^{(1)}$
$\mathbf{P}^{(2)}$.	.	$\mathbf{P}^{(2)}$.	.	.
$\mathbf{P}^{(3)}$.	.	.	$\mathbf{P}^{(3)}$.	.
$\mathbf{P}^{(4)}$	$\mathbf{P}^{(4)}$.
$\mathbf{P}^{(5)}$	$\mathbf{P}^{(5)}$

$$\mathbf{r}^p = \chi_p^0 \mathbf{P}^{(0)} + \chi_p^1 \mathbf{P}^{(1)} + \chi_p^2 \mathbf{P}^{(2)} + \chi_p^3 \mathbf{P}^{(3)} + \chi_p^4 \mathbf{P}^{(4)} + \chi_p^5 \mathbf{P}^{(5)}$$

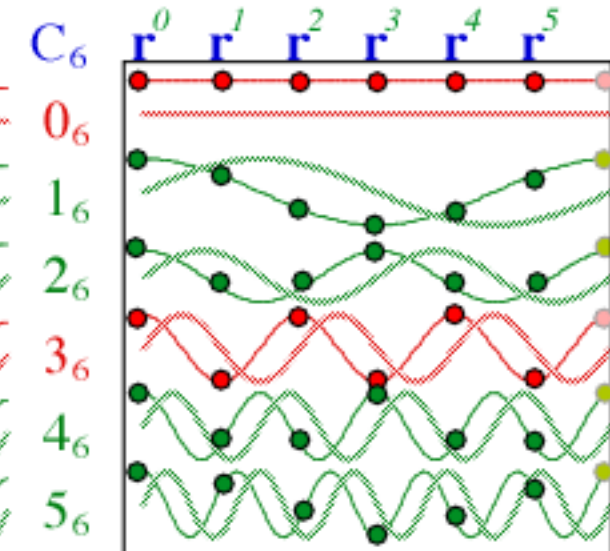
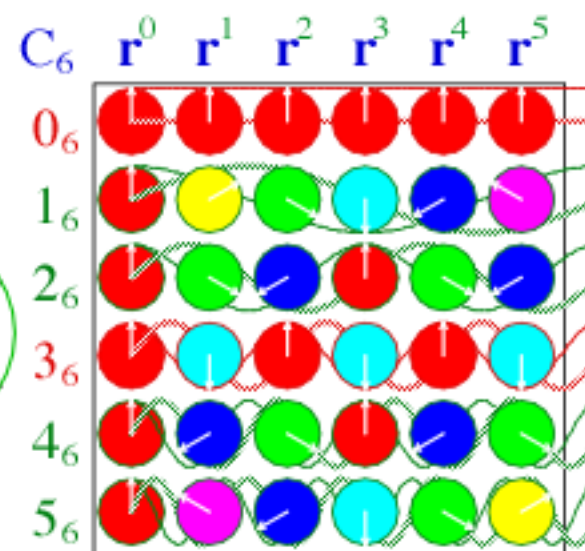
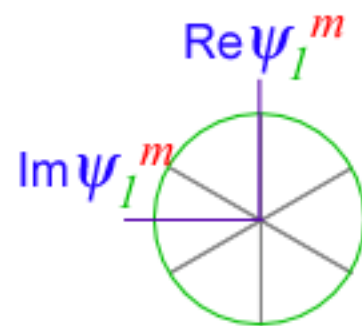


Inverse C_6 spectral resolution m -wave $\psi_p^m = D^{m*}(\mathbf{r}^p) = e^{+2\pi i m \cdot p/6}$:

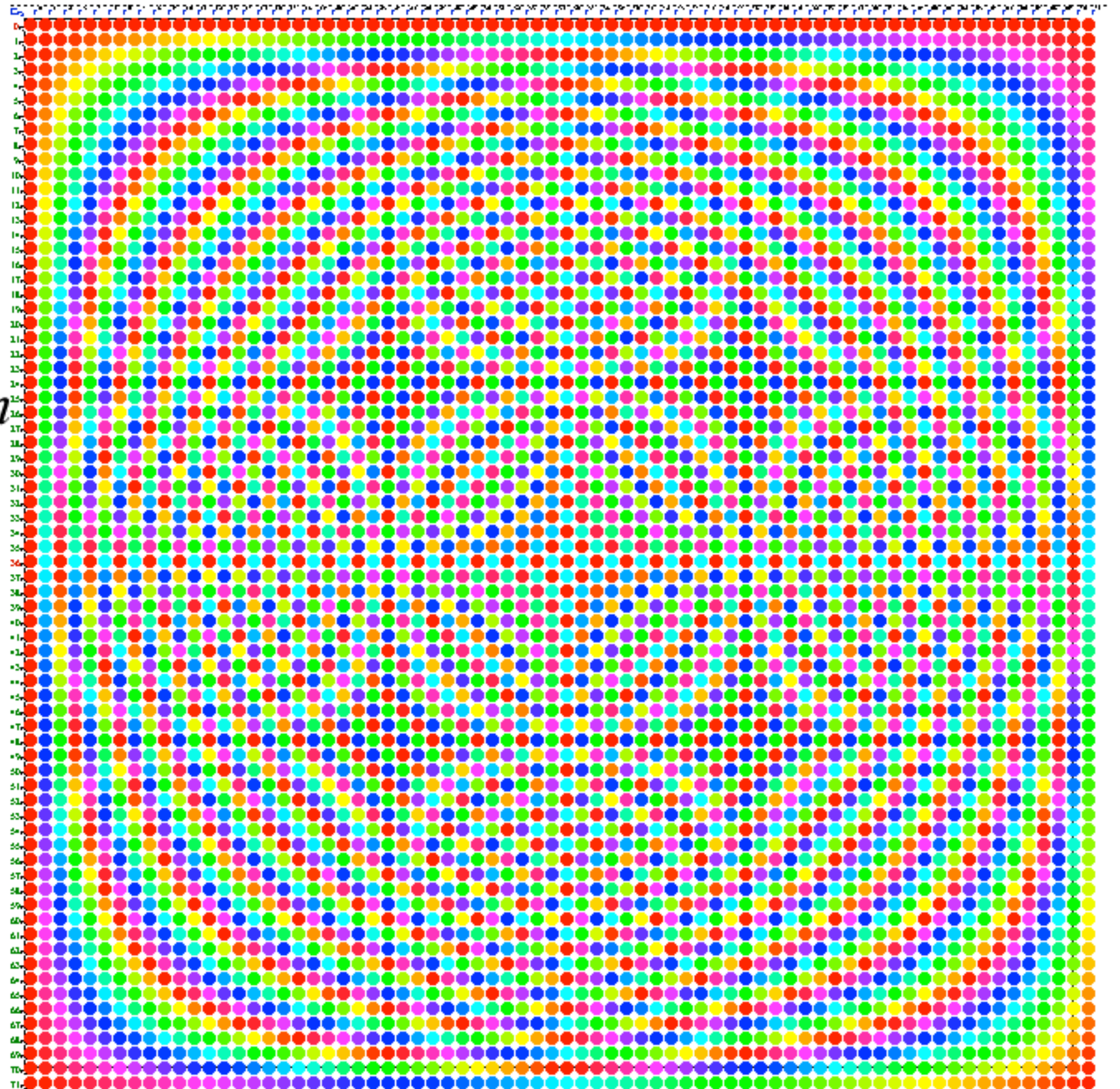
$$\mathbf{P}^{(m)} = \psi_0^m \mathbf{r}^0 + \psi_1^m \mathbf{r}^1 + \psi_2^m \mathbf{r}^2 + \psi_3^m \mathbf{r}^3 + \psi_4^m \mathbf{r}^4 + \psi_5^m \mathbf{r}^5$$

$p=0 \quad 1 \quad 2 \quad 3 \quad 4 \quad 5$
position p (or power of \mathbf{r}^p)

momentum m	ψ_0^m	ψ_1^m	ψ_2^m	ψ_3^m	ψ_4^m	ψ_5^m
$m=0$	ψ_0^0	ψ_1^0	ψ_2^0	ψ_3^0	ψ_4^0	ψ_5^0
$m=1$	ψ_0^1	ψ_1^1	ψ_2^1	ψ_3^1	ψ_4^1	ψ_5^1
$m=2$	ψ_0^2	ψ_1^2	ψ_2^2	ψ_3^2	ψ_4^2	ψ_5^2
$m=3$	ψ_0^3	ψ_1^3	ψ_2^3	ψ_3^3	ψ_4^3	ψ_5^3
$m=4$	ψ_0^4	ψ_1^4	ψ_2^4	ψ_3^4	ψ_4^4	ψ_5^4
$m=5$	ψ_0^5	ψ_1^5	ψ_2^5	ψ_3^5	ψ_4^5	ψ_5^5



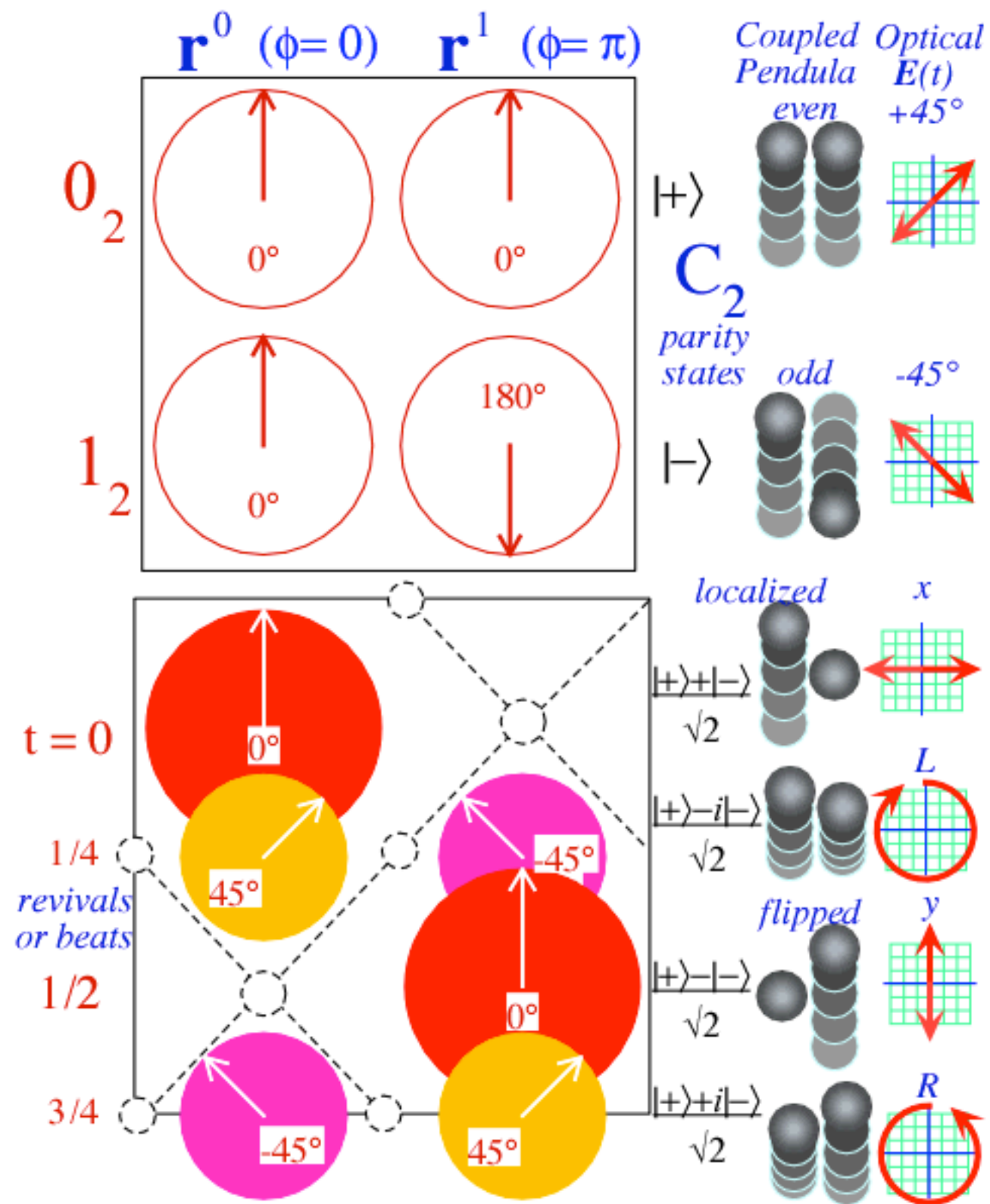
C_{72}
Fourier
transformation
matrix



C_2
Fourier
transformation
matrix

and

dynamics

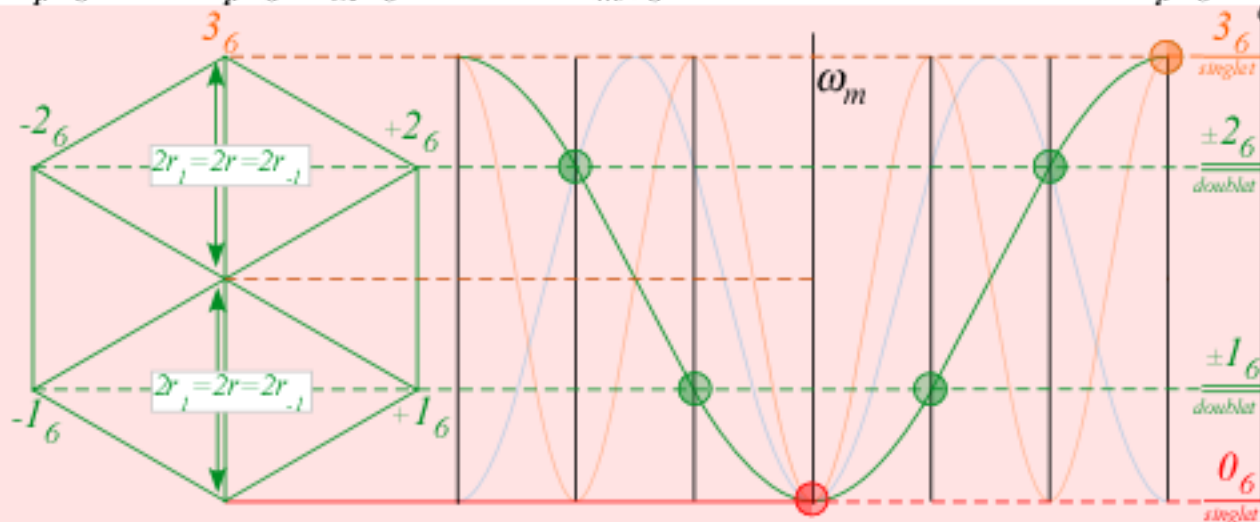
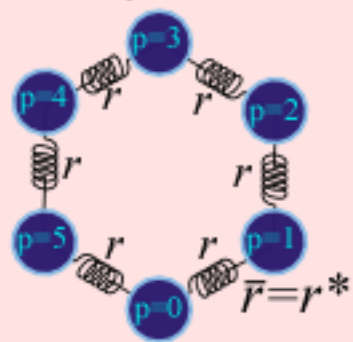


3rd Step

Display all eigensolutions for all possible C_6 symmetric real H

$$H = \sum_{p=0}^{n-1} r_p \mathbf{r}^p = \sum_{p=0}^{n-1} r_p \sum_{m=0}^{n-1} \chi_p^m \mathbf{P}^{(m)} = \sum_{m=0}^{n-1} \omega^{(m)} \mathbf{P}^{(m)} \quad \text{where: } \omega^{(m)} = \sum_{p=0}^{n-1} r_p \chi_p^m = \omega(k_m) \quad \text{(Dispersion function)}$$

Elementary Bloch Model
 $H = H_1 \mathbf{1} - r\mathbf{r} - r\mathbf{r}^{-1}$

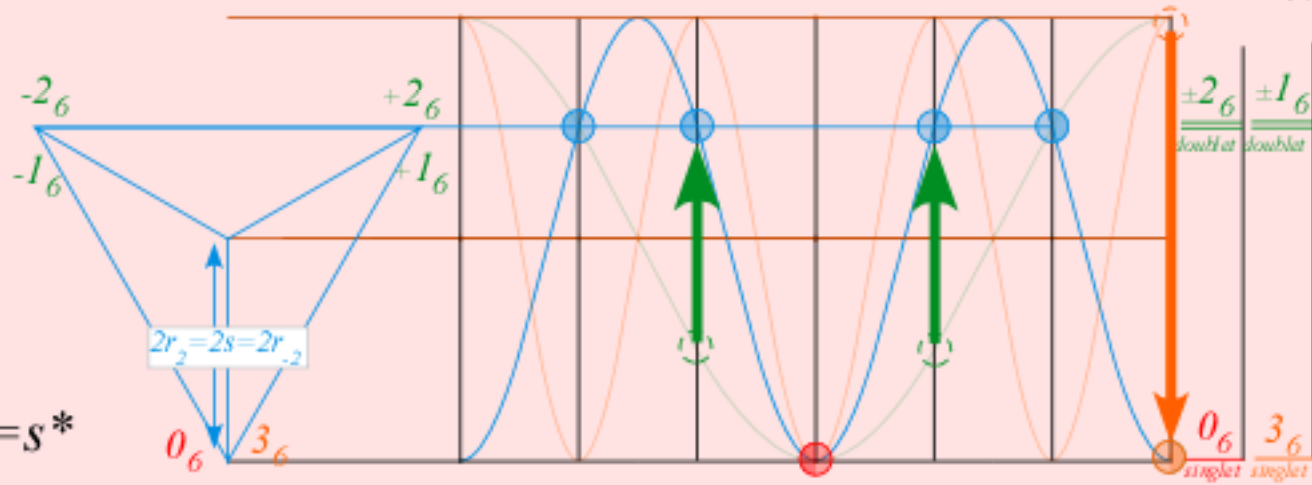
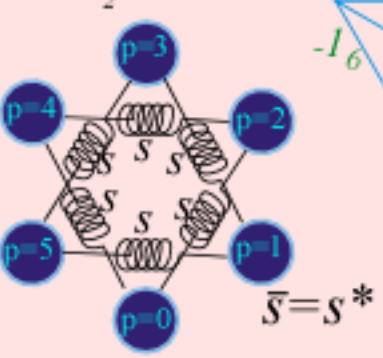


eigenvalues of $H^{B1(6)}$

$$\begin{pmatrix} H_1 - r & \cdot & \cdot & \cdot & \cdot & -r \\ -r & H_1 - r & \cdot & \cdot & \cdot & \cdot \\ \cdot & -r & H_1 - r & \cdot & \cdot & \cdot \\ \cdot & \cdot & -r & H_1 - r & \cdot & \cdot \\ \cdot & \cdot & \cdot & -r & H_1 - r & \cdot \\ -r & \cdot & \cdot & \cdot & -r & H_1 \end{pmatrix}$$

$$\begin{aligned} \omega^{B1(n)}(k_m) &= r_0 \chi_0^m + r_1 \chi_1^m + r_{-1} \chi_{-1}^m \\ &= H_1 - 2r \cos(2\pi m/6) \end{aligned}$$

2nd Neighbor coupling
 $H = H_2 \mathbf{1} - s\mathbf{r}^2 - s\mathbf{r}^{-2}$

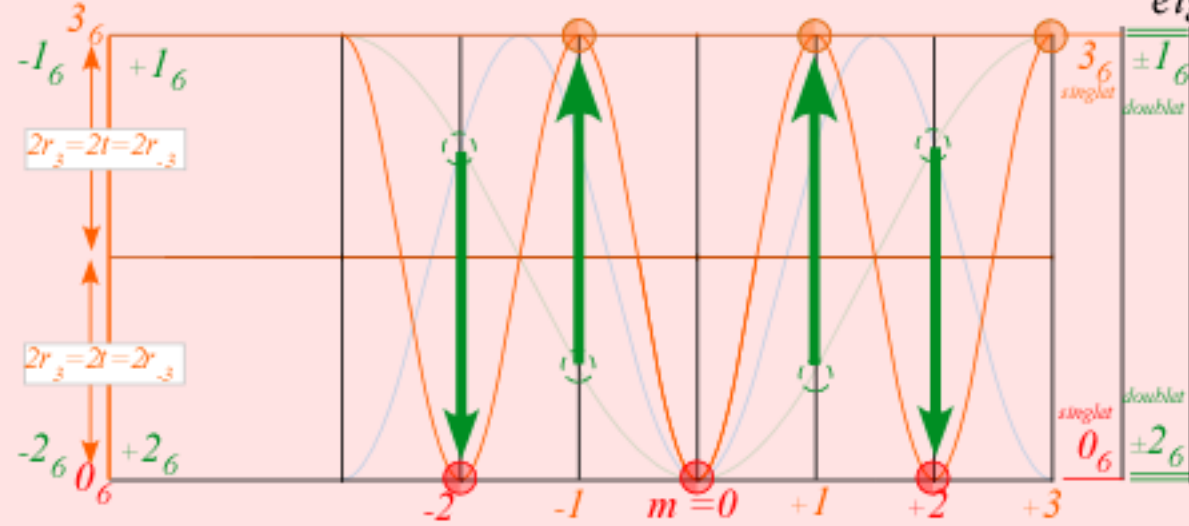
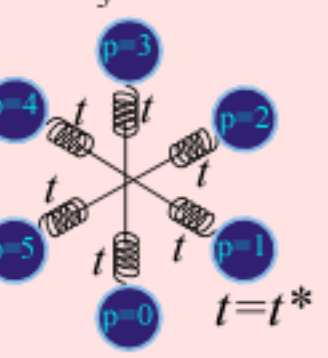


eigenvalues of $H^{B2(6)}$

$$\begin{pmatrix} H_2 & \cdot & -s & \cdot & -s & \cdot \\ \cdot & H_2 & \cdot & -s & \cdot & -s \\ -s & \cdot & H_2 & \cdot & -s & \cdot \\ \cdot & -s & \cdot & H_2 & \cdot & -s \\ -s & \cdot & -s & \cdot & H_2 & \cdot \\ \cdot & -s & \cdot & -s & \cdot & H_2 \end{pmatrix}$$

$$\begin{aligned} \omega^{B2(n)}(k_m) &= r_0 \chi_0^m + r_2 \chi_2^m + r_{-2} \chi_{-2}^m \\ &= H_2 - 2s \cos(4\pi m/6) \end{aligned}$$

3rd Neighbor coupling
 $H = H_3 \mathbf{1} - t\mathbf{r}^3 - t\mathbf{r}^{-3}$



eigenvalues of $H^{B3(6)}$

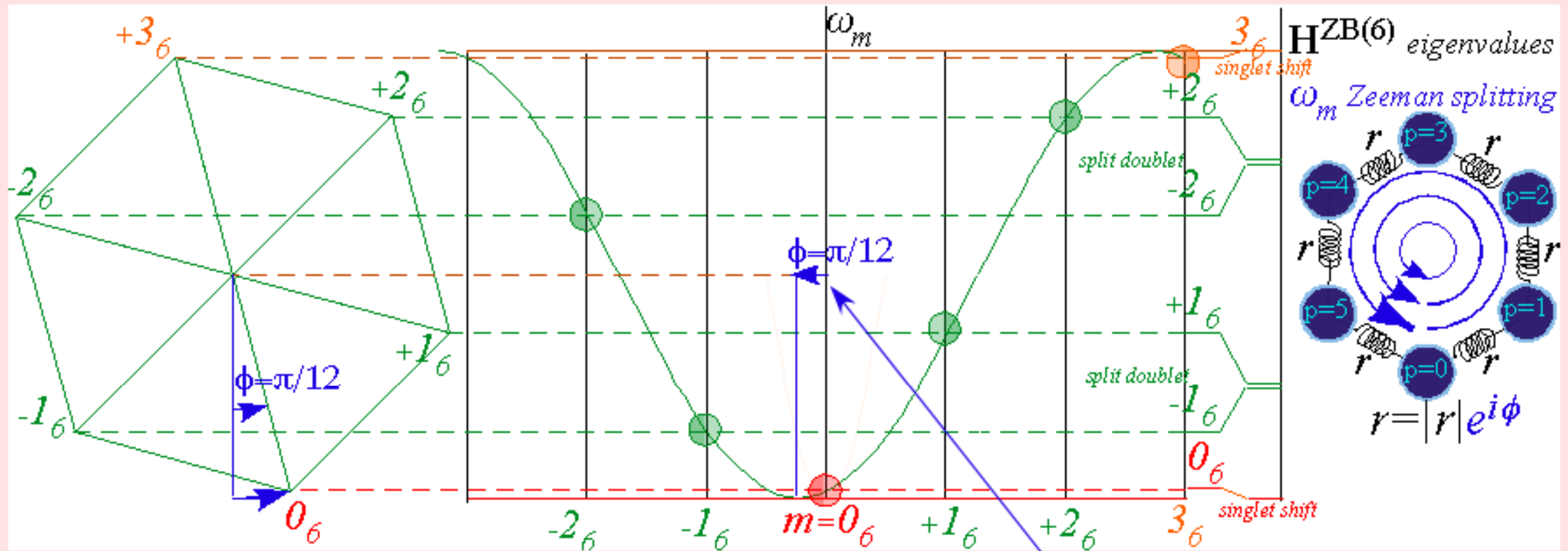
$$\begin{pmatrix} H_3 & \cdot & \cdot & -t & \cdot & \cdot \\ \cdot & H_3 & \cdot & \cdot & -t & \cdot \\ \cdot & \cdot & H_3 & \cdot & \cdot & -t \\ -t & \cdot & \cdot & H_3 & \cdot & \cdot \\ \cdot & -t & \cdot & \cdot & H_3 & \cdot \\ \cdot & \cdot & -t & \cdot & \cdot & H_3 \end{pmatrix}$$

$$\begin{aligned} \omega^{B3(n)}(k_m) &= r_0 \chi_0^m + r_3 \chi_3^m + r_{-3} \chi_{-3}^m \\ &= H_3 - 2t (-1)^m \end{aligned}$$

3rd Step (contd.)

...eigensolutions for all possible C_6 symmetric complex H

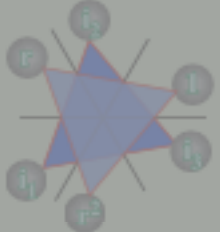
$$H = \sum_{p=0}^{n-1} r_p \mathbf{r}^p = \sum_{p=0}^{n-1} r_p \sum_{m=0}^{n-1} \chi_p^m \mathbf{P}^{(m)} = \sum_{m=0}^{n-1} \omega^{(m)} \mathbf{P}^{(m)} \quad \text{where: } \omega^{(m)} = \sum_{p=0}^{n-1} r_p \chi_p^m = \omega(k_m) \quad (\text{Dispersion function})$$

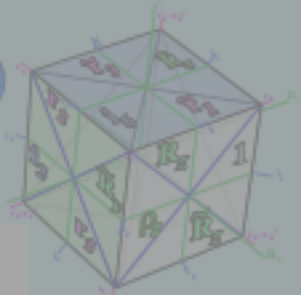



Note "gauge" shift

- (Commuting)
- **Abelian symmetry = Fourier analysis** (Back to our roots $1^{1/N} = e^{2\pi im/N}$)
 Group $\hat{\Lambda}$ product table \Rightarrow Hamiltonian \mathbf{H} -matrices (C_2 and C_6 examples)  C_2  C_6
 Group roots \Rightarrow \mathbf{H} -matrix spectral resolution by $P^{(m)}$ projectors

- Commutivity conundrum... ? $\mathbf{H} \cdot g = g \cdot \mathbf{H}$?
- **New symmetry insights:** Local vs. Global symmetry Projector invariance
 “Mock-Mach” principle Conway, et.al, May (2008) Cvitanovic, (2008)

- (Non-Commuting)
- **Non-Abelian symmetry analysis I.** (Simplest example: D_3) 
 Local vs. Global $\hat{\Lambda}$ product tables \Rightarrow \mathbf{H} -matrices
 All-commuting invariants \Rightarrow Global invariant (character) $P^{(\alpha)}$ projectors
 Mutually-commuting sets \Rightarrow Local vs. Global eigensolutions by $P_{m,n}^{(\alpha)}$ projectors
 \Rightarrow \mathbf{H} -matrix spectral resolution by $P_{m,n}^{(\alpha)}$ projectors

- **Non-Abelian symmetry analysis II.** (Octahedral example: O_h) 
 Global-local product tables \Rightarrow \mathbf{H} -matrices...
 ... and all the above ...
 \Rightarrow eigensolution formulas by local-symmetry defined $P_{n,n}^{(\alpha)}$ projectors 

- **Local vs Global symmetry in rovibronic phase space** 
 How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples)

Abelian (Commutative) $C_2, C_2, \dots, C_6 \dots$

H diagonalized by r^p symmetry operators that **COMMUTE**
with H ($r^p H = H r^p$),

and with each other ($r^p r^q = r^{p+q} = r^q r^p$).

Versus...

Non-Abelian (do not commute) D_3, O_h, \dots

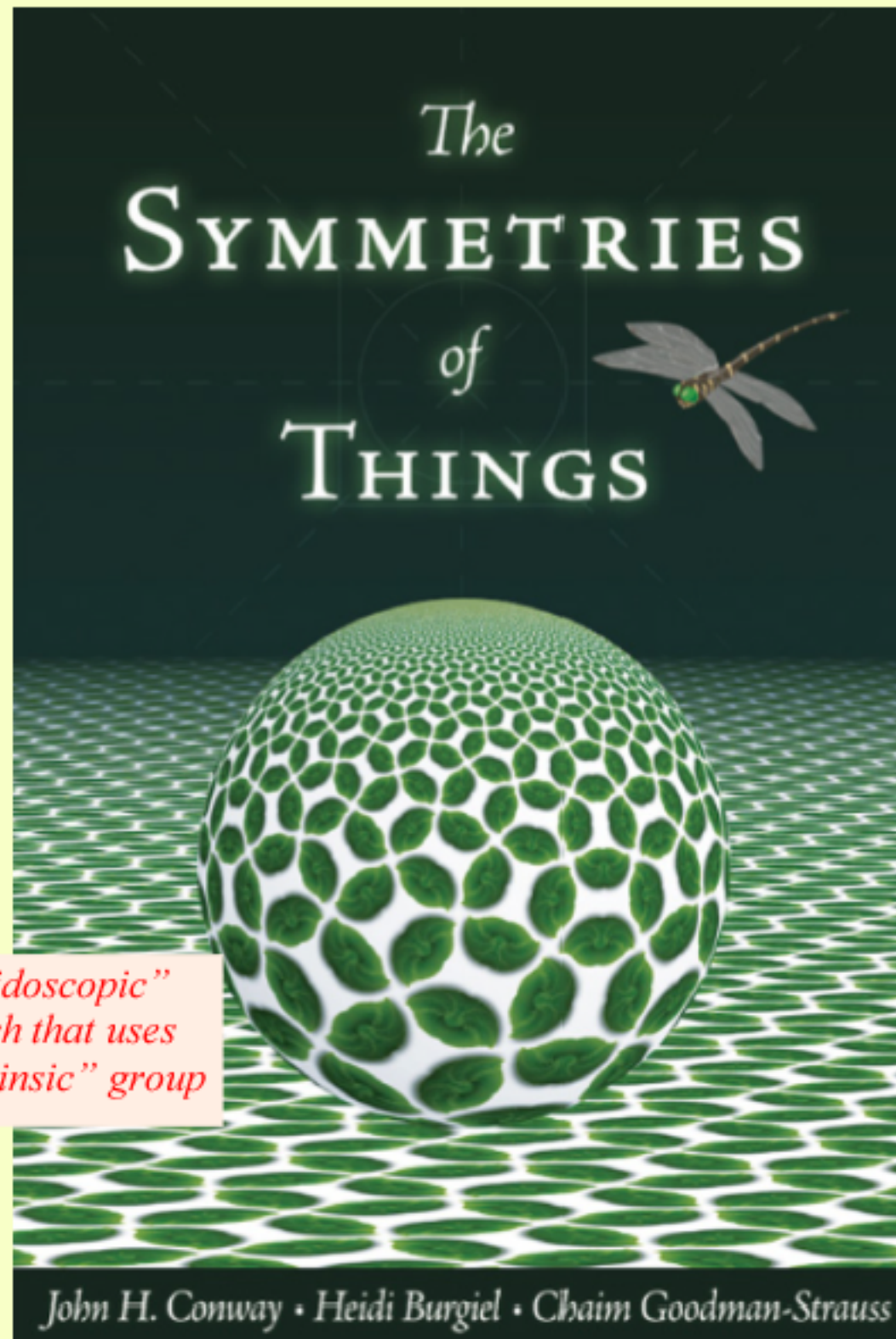
While all H symmetry operations **COMMUTE**
with H ($\mathbf{U} H = H \mathbf{U}$)

most do not with each other ($\mathbf{U} \mathbf{V} \neq \mathbf{V} \mathbf{U}$).

Q: So how do we write H in terms of non-commutative \mathbf{U} ?

Time to examine how we..
...classify symmetry
...apply it ...

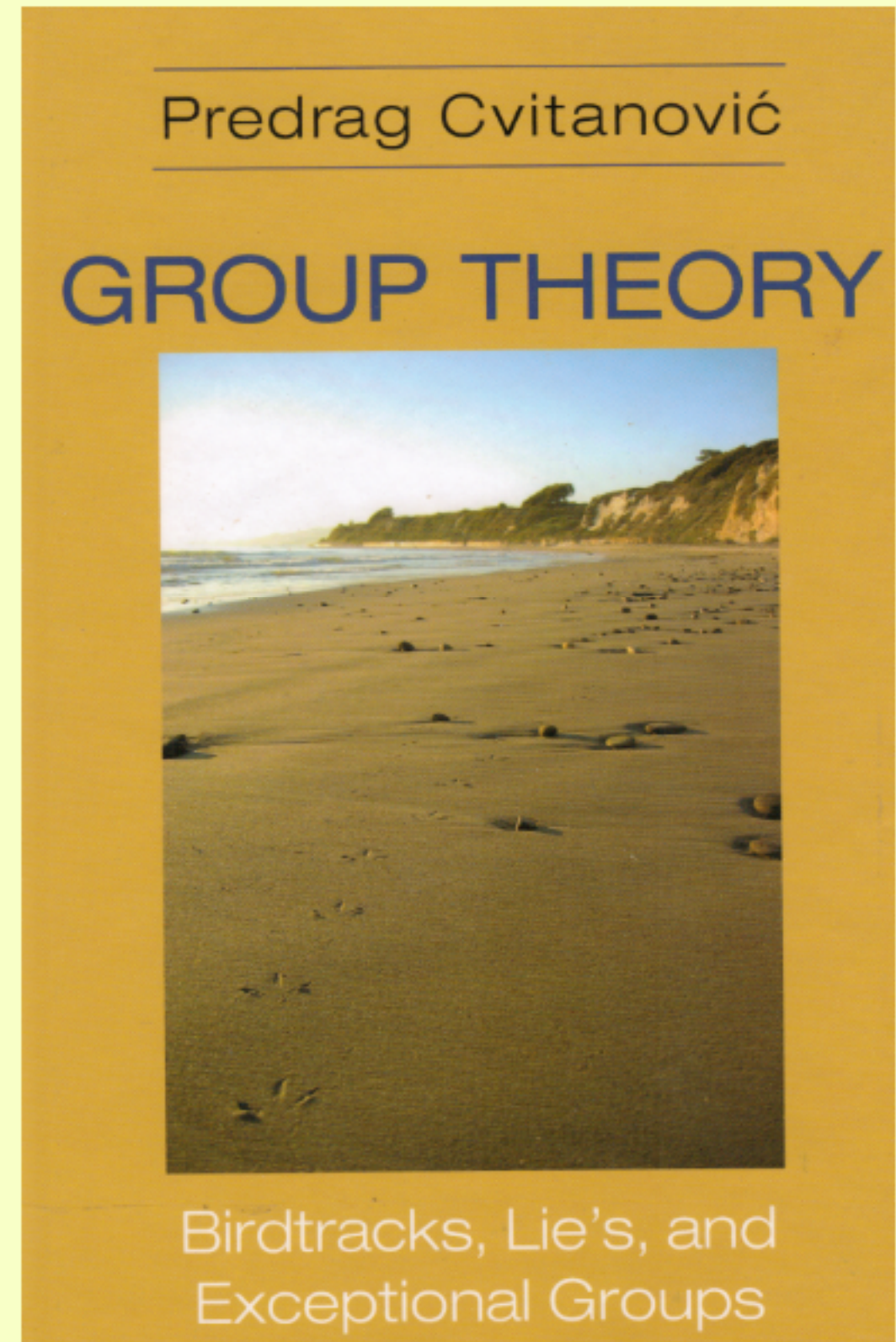
*...from PURE group theory...
A revolutionary simplification
to classify all groups and their algebras*



*A "kaleidoscopic"
approach that uses
an "intrinsic" group*

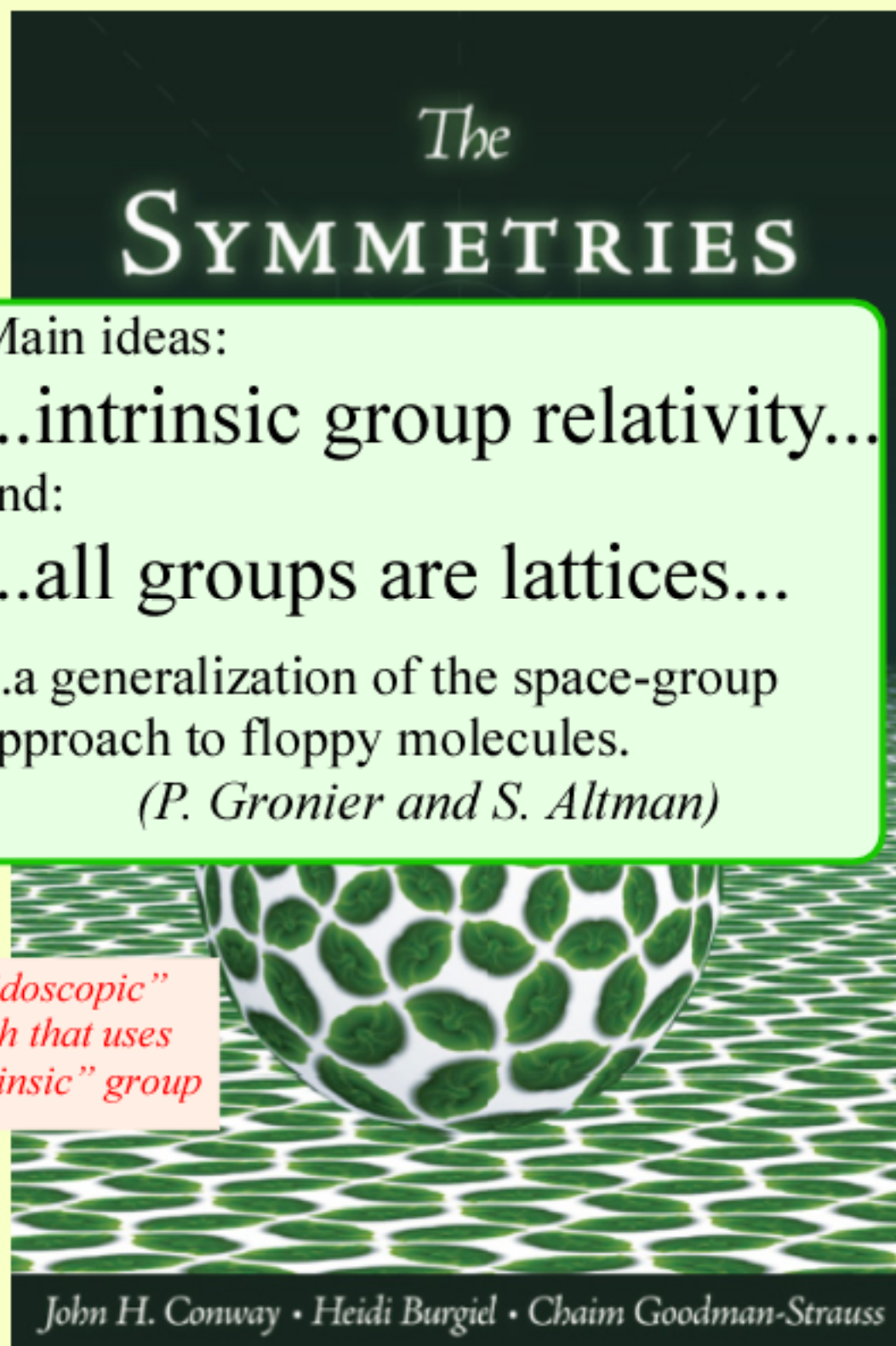
(2008) A.K. Peters Ltd. Wellesley, MA 02482

*...from APPLIED (to string theory)...
A new/old approach to Clebsch-Gordon-
Racah-Yutsis invariants*



(2008) Princeton. Oxford 0X20 1TW

...from *PURE* group theory...
*A revolutionary simplification
to classify all groups and their algebras*



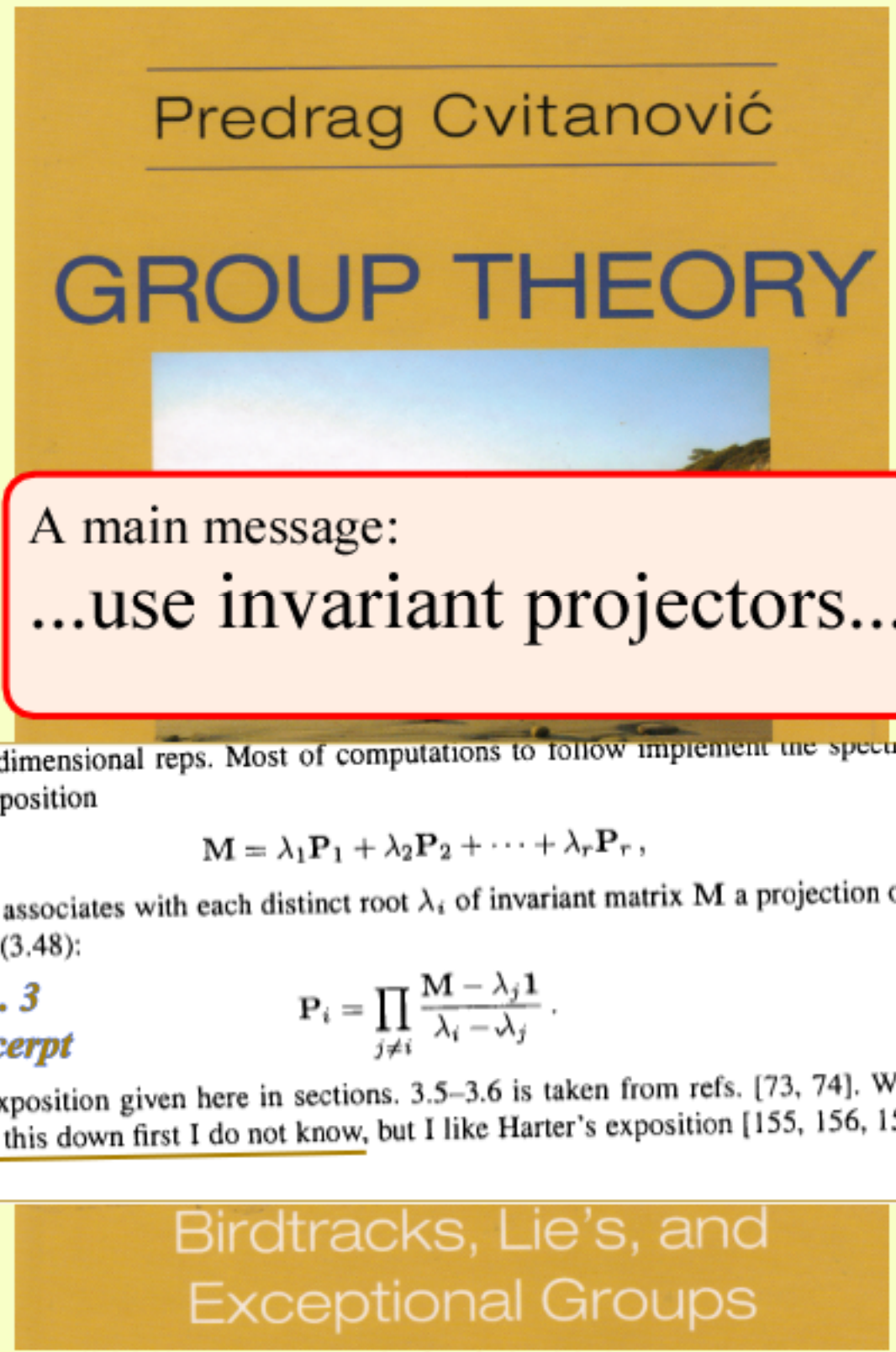
Main ideas:
...intrinsic group relativity...
and:
...all groups are lattices...
...a generalization of the space-group
approach to floppy molecules.
(P. Gronier and S. Altman)

*A "kaleidoscopic"
approach that uses
an "intrinsic" group*

John H. Conway • Heidi Burgiel • Chaim Goodman-Strauss

(2008) A.K. Peters Ltd. Wellesley, MA 02482

...from *APPLIED* (to supersymmetry)...
*A new/old approach to Clebsch-Gordan-
Racah-Yutsis invariants*



A main message:
...use invariant projectors...

lower-dimensional reps. Most of computations to follow implement the spectral decomposition

$$M = \lambda_1 P_1 + \lambda_2 P_2 + \dots + \lambda_r P_r,$$

which associates with each distinct root λ_i of invariant matrix M a projection operator (3.48):

**Ch. 3
excerpt**

$$P_i = \prod_{j \neq i} \frac{M - \lambda_j \mathbf{1}}{\lambda_i - \lambda_j}.$$

The exposition given here in sections. 3.5–3.6 is taken from refs. [73, 74]. Who wrote this down first I do not know, but I like Harter's exposition [155, 156, 157] best.

Birdtracks, Lie's, and
Exceptional Groups

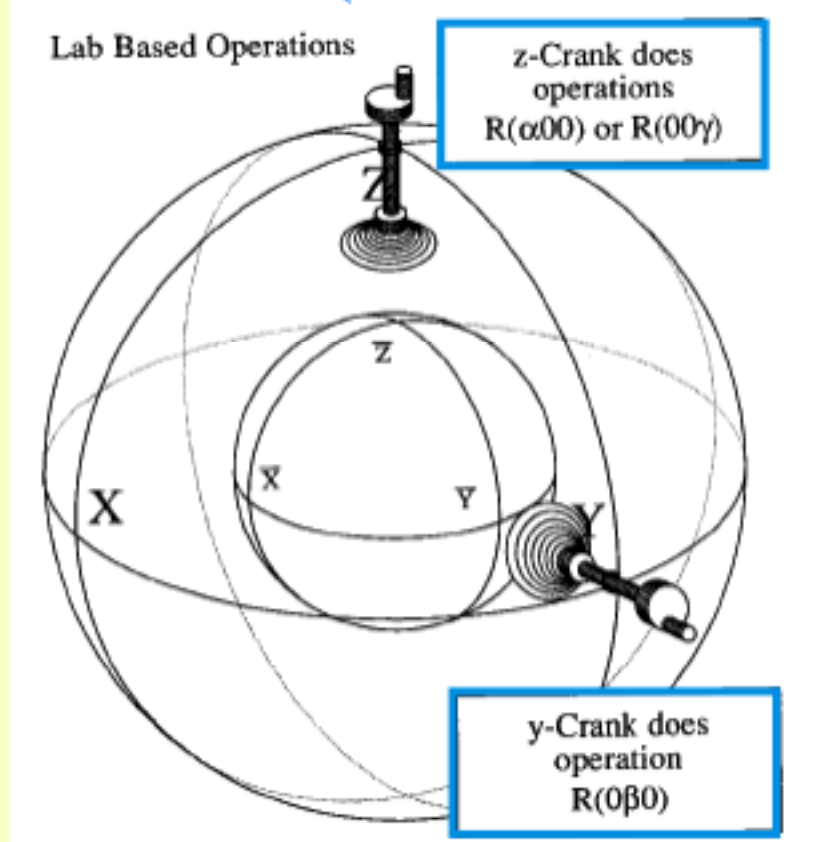
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*“Give me a place to stand...
and I will move the Earth”*

Archimedes 287-212 B.C.E

Ideas of duality/relativity go *way* back (...VanVleck, Casimir..., Mach, Newton, Archimedes...)

Lab-fixed (Extrinsic-Global)**R** vs. Body-fixed (Intrinsic-Local) **\bar{R}**

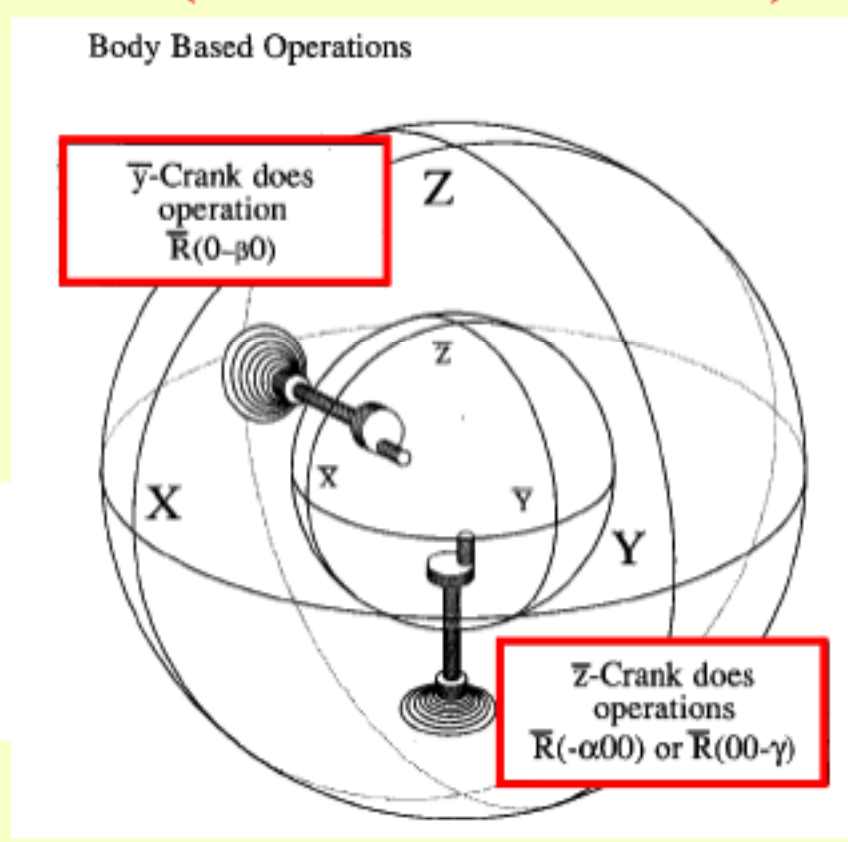


R commutes with all **\bar{R}**

Mock-Mach relativity principle


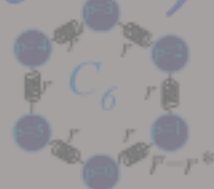
$R|1\rangle = \bar{R}^{-1}|1\rangle$

...for *one* state $|1\rangle$ only!



...But *how* do you actually *make* the **R** and **\bar{R}** operations?

(Commuting)

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 Group \hat{A} product table \Rightarrow Hamiltonian \mathbf{H} -matrices (C_2 and C_6 examples)  C_2  C_6
 Group roots \Rightarrow \mathbf{H} -matrix spectral resolution by $P^{(m)}$ projectors

Commutivity conundrum...

? $\mathbf{H} \cdot g = g \cdot \mathbf{H}$?

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- **Non-Abelian symmetry analysis II.** (Octahedral example: O_h) 

Global-local product tables \Rightarrow \mathbf{H} -matrices...

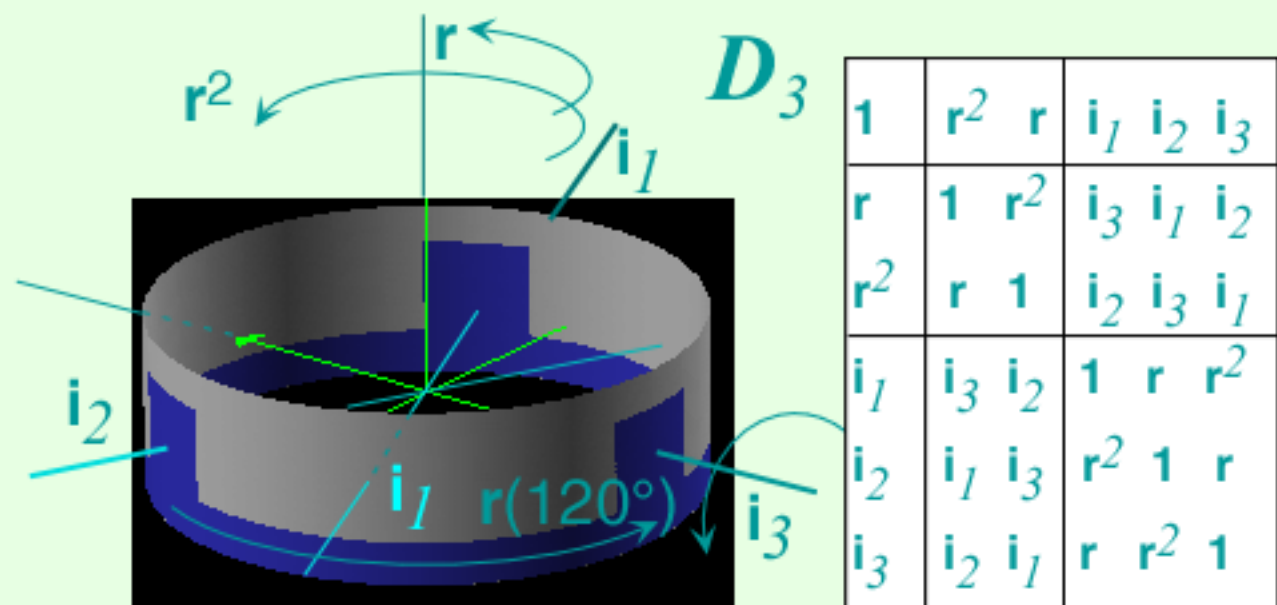
... and all the above ...

\Rightarrow eigensolution formulas by local-symmetry defined $P_{n,n}^{(\alpha)}$ projectors 

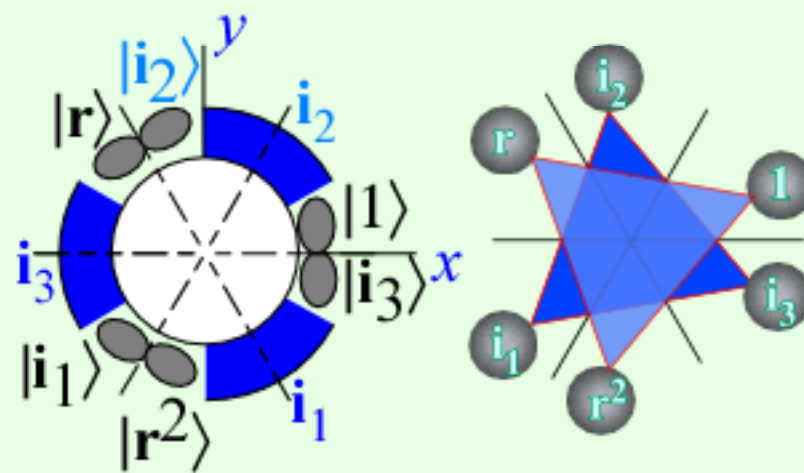
- **Local vs Global symmetry in rovibronic phase space** 

How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples)

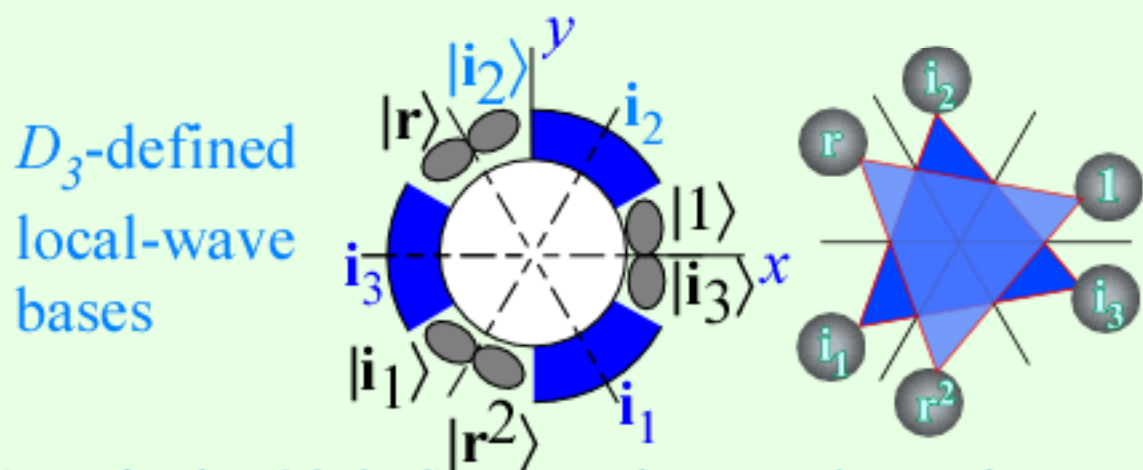
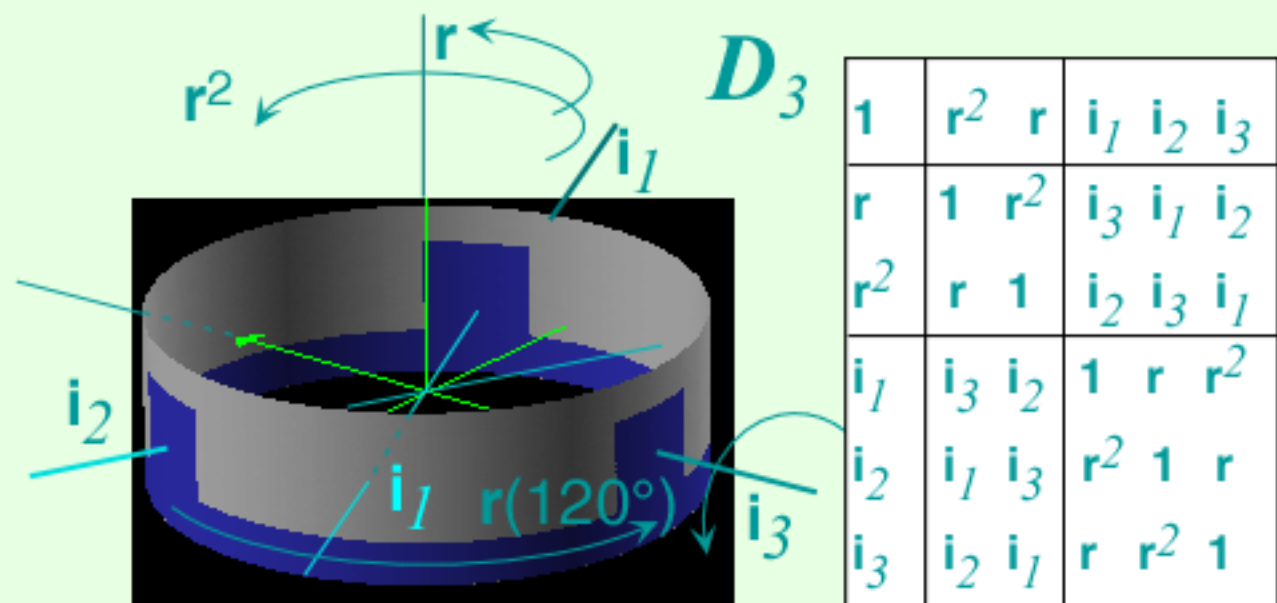
Example of GLOBAL vs LOCAL projector algebra for $D_3 \sim C_{3v}$



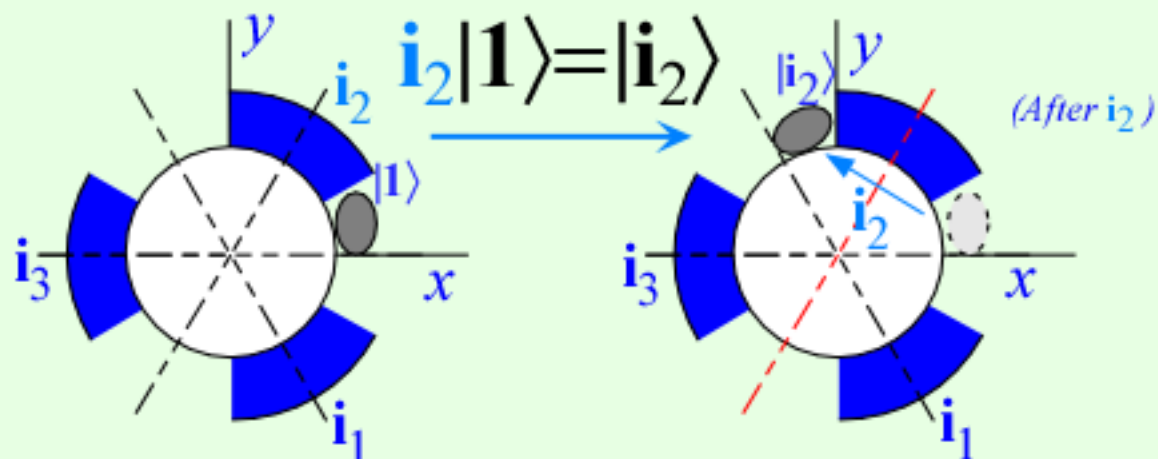
D_3 -defined
local-wave
bases



Example of GLOBAL vs LOCAL projector algebra for $D_3 \sim C_{3v}$



Lab-fixed (Extrinsic-Global) operations and rotation axes



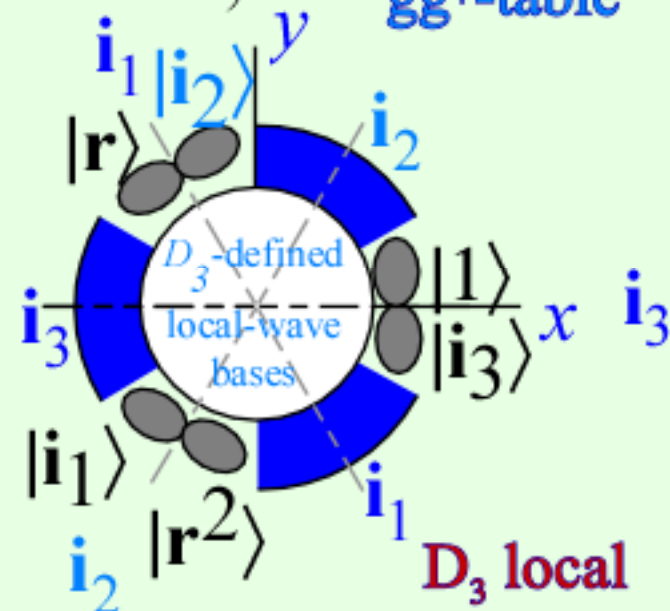
Example of RELATIVITY-DUALITY for $D_3 \sim C_{3v}$

To represent *external* {..**T,U,V**,... } switch $g \leftrightarrow g^\dagger$ on top of group table

$$\begin{aligned}
 R^G(\mathbf{1}) &= \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\mathbf{r}) &= \begin{pmatrix} & & 1 & & & \\ 1 & & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\mathbf{r}^2) &= \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\mathbf{i}_1) &= \begin{pmatrix} & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \\ 1 & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} &
 R^G(\mathbf{i}_2) &= \begin{pmatrix} & & & & 1 & \\ & & & & & 1 \\ & & & & & 1 \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\mathbf{i}_3) &= \begin{pmatrix} & & & & & 1 \\ & & & & & & 1 \\ & & & & & & 1 \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix}
 \end{aligned}$$

$\mathbf{1}$	\mathbf{r}^2	\mathbf{r}	\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3
\mathbf{r}	$\mathbf{1}$	\mathbf{r}^2	\mathbf{i}_3	\mathbf{i}_1	\mathbf{i}_2
\mathbf{r}^2	\mathbf{r}	$\mathbf{1}$	\mathbf{i}_2	\mathbf{i}_3	\mathbf{i}_1
\mathbf{i}_1	\mathbf{i}_3	\mathbf{i}_2	$\mathbf{1}$	\mathbf{r}	\mathbf{r}^2
\mathbf{i}_2	\mathbf{i}_1	\mathbf{i}_3	\mathbf{r}^2	$\mathbf{1}$	\mathbf{r}
\mathbf{i}_3	\mathbf{i}_2	\mathbf{i}_1	\mathbf{r}	\mathbf{r}^2	$\mathbf{1}$

D_3 global $g g^\dagger$ -table



D_3 local $g^\dagger g$ -table

RESULT:

Any $R(\mathbf{T})$

commute (Even if **T** and **U** do not...)

with any $R(\mathbf{U})$...

...and $\mathbf{T} \cdot \mathbf{U} = \mathbf{V}$ if & only if $\bar{\mathbf{T}} \cdot \bar{\mathbf{U}} = \bar{\mathbf{V}}$.

To represent *internal* {.. $\bar{\mathbf{T}}, \bar{\mathbf{U}}, \bar{\mathbf{V}}$,... } switch $g \leftrightarrow g^\dagger$ on side of group table

$$\begin{aligned}
 R^G(\bar{\mathbf{1}}) &= \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\bar{\mathbf{r}}) &= \begin{pmatrix} & & 1 & & & \\ 1 & & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\bar{\mathbf{r}}^2) &= \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\bar{\mathbf{i}}_1) &= \begin{pmatrix} & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \\ 1 & & & & & \\ & & & & & \\ & & & & & \end{pmatrix} &
 R^G(\bar{\mathbf{i}}_2) &= \begin{pmatrix} & & & & 1 & \\ & & & & & 1 \\ & & & & & 1 \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix} &
 R^G(\bar{\mathbf{i}}_3) &= \begin{pmatrix} & & & & & 1 \\ & & & & & & 1 \\ & & & & & & 1 \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{pmatrix}
 \end{aligned}$$

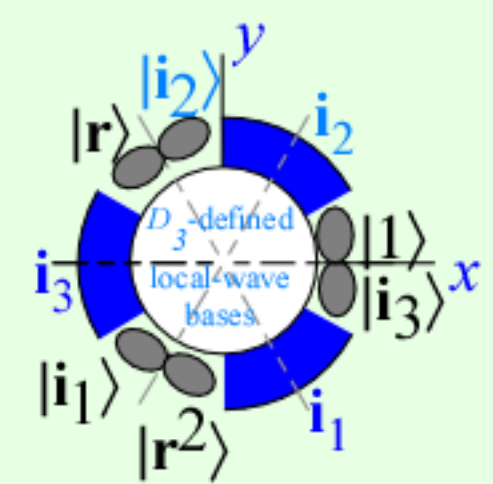
$\mathbf{1}$	\mathbf{r}	\mathbf{r}^2	\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3
\mathbf{r}^2	$\mathbf{1}$	\mathbf{r}	\mathbf{i}_2	\mathbf{i}_3	\mathbf{i}_1
\mathbf{r}	\mathbf{r}^2	$\mathbf{1}$	\mathbf{i}_3	\mathbf{i}_1	\mathbf{i}_2
\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3	$\mathbf{1}$	\mathbf{r}	\mathbf{r}^2
\mathbf{i}_2	\mathbf{i}_3	\mathbf{i}_2	\mathbf{r}^2	$\mathbf{1}$	\mathbf{r}
\mathbf{i}_3	\mathbf{i}_1	\mathbf{i}_2	\mathbf{r}	\mathbf{r}^2	$\mathbf{1}$



Example of RELATIVITY-DUALITY for $D_3 \sim C_{3v}$

To represent *external* {..**T,U,V**,... } switch $\mathbf{g} \leftrightarrow \mathbf{g}^\dagger$

$$\begin{matrix}
 R^G(\mathbf{1}) = & R^G(\mathbf{r}) = & R^G(\mathbf{r}^2) = & R^G(\mathbf{i}_1) = & R^G(\mathbf{i}_2) = & R^G(\mathbf{i}_3) = \\
 \begin{pmatrix} 1 & \dots & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}
 \end{matrix}$$



Local \mathbb{H} matrix parametrized by $\bar{\mathbf{g}}$'s

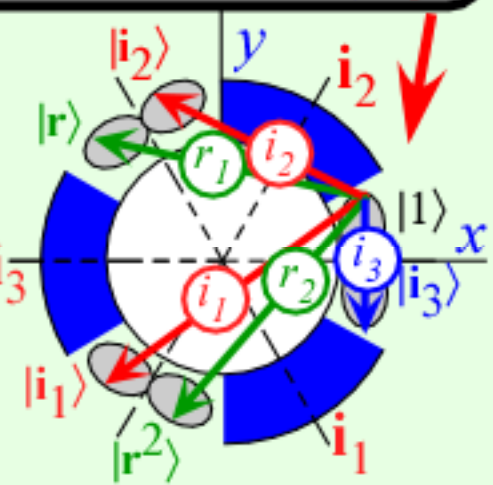
RESULT:
Any $R(\mathbf{T})$ commute with any $R(\bar{\mathbf{U}})$...

So an \mathbb{H} -matrix having *Global* symmetry D_3

$$\mathbb{H} = H\mathbf{1} + r_1\bar{\mathbf{r}}^1 + r_2\bar{\mathbf{r}}^2 + i_1\bar{\mathbf{i}}_1 + i_2\bar{\mathbf{i}}_2 + i_3\bar{\mathbf{i}}_3$$

is made from *Local* symmetry matrices

$$\begin{aligned}
 H &= \langle 1 | \mathbb{H} | 1 \rangle = H^* \\
 r_1 &= \langle r | \mathbb{H} | 1 \rangle = r_2^* \\
 r_2 &= \langle r^2 | \mathbb{H} | 1 \rangle = r_1^* \\
 i_1 &= \langle i_1 | \mathbb{H} | 1 \rangle = i_1^* \\
 i_2 &= \langle i_2 | \mathbb{H} | 1 \rangle = i_2^* \\
 i_3 &= \langle i_3 | \mathbb{H} | 1 \rangle = i_3^*
 \end{aligned}$$



All these global \mathbf{g} commute with general *local* \mathbb{H} matrix.

local D_3 defined
Hamiltonian matrix

$$\mathbb{H} \equiv \begin{matrix} & |1\rangle & |r\rangle & |r^2\rangle & |i_1\rangle & |i_2\rangle & |i_3\rangle \\ \begin{matrix} (1) \\ (r) \\ (r^2) \\ (i_1) \\ (i_2) \\ (i_3) \end{matrix} & \begin{pmatrix} H & r_1 & r_2 & i_1 & i_2 & i_3 \\ r_2 & H & r_1 & i_2 & i_3 & i_1 \\ r_1 & r_2 & H & i_3 & i_1 & i_2 \\ i_1 & i_2 & i_3 & H & r_1 & r_2 \\ i_2 & i_3 & i_1 & r_2 & H & r_1 \\ i_3 & i_1 & i_2 & r_1 & r_2 & H \end{pmatrix} \end{matrix}$$

To represent *internal* {.. $\bar{\mathbf{T}}, \bar{\mathbf{U}}, \bar{\mathbf{V}}$,... } switch $\mathbf{g} \leftrightarrow \mathbf{g}^\dagger$

$$\begin{matrix}
 R^G(\bar{\mathbf{1}}) = & R^G(\bar{\mathbf{r}}) = & R^G(\bar{\mathbf{r}}^2) = & R^G(\bar{\mathbf{i}}_1) = & R^G(\bar{\mathbf{i}}_2) = & R^G(\bar{\mathbf{i}}_3) = \\
 \begin{pmatrix} 1 & \dots & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}, &
 \begin{pmatrix} \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}
 \end{matrix}$$

Example of RELATIVITY-DUALITY

To represent *external* { ..**T,U,V**,... }

$$R^G(\mathbf{1}) = \begin{pmatrix} 1 & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & 1 \end{pmatrix}, \quad R^G(\mathbf{r}) = \begin{pmatrix} \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}, \quad R^G(\mathbf{r}^2) = \begin{pmatrix} \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}$$

RESULT:
Any $R(\mathbf{T})$

commute
with any $R(\bar{\mathbf{U}})$...

So an \mathbf{H} -matrix
having *Global* symmetry D_3

$$\mathbf{H} = H\mathbf{1}^0 + r_1\bar{\mathbf{r}}^1 + r_2\bar{\mathbf{r}}^2 + i_1\bar{\mathbf{i}}_1 + i_2\bar{\mathbf{i}}_2 + i_3\bar{\mathbf{i}}_3$$

is made from
Local symmetry matrices

$$H = \langle \mathbf{1} | \mathbf{H} | \mathbf{1} \rangle = H^*$$

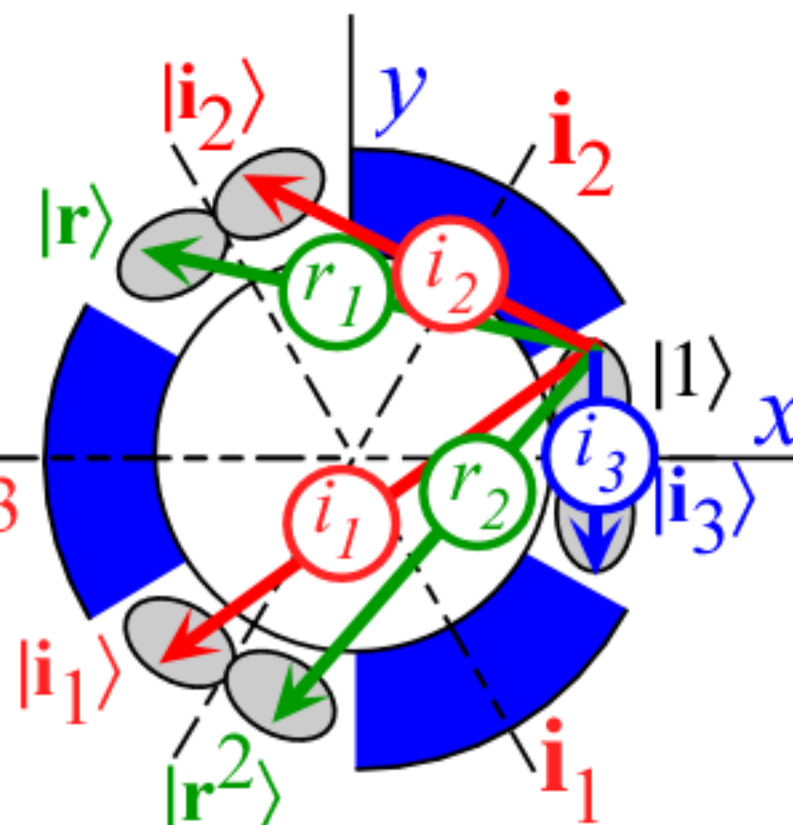
$$r_1 = \langle \mathbf{r} | \mathbf{H} | \mathbf{1} \rangle = r_2^*$$

$$r_2 = \langle \mathbf{r}^2 | \mathbf{H} | \mathbf{1} \rangle = r_1^*$$

$$i_1 = \langle \mathbf{i}_1 | \mathbf{H} | \mathbf{1} \rangle = i_1^*$$

$$i_2 = \langle \mathbf{i}_2 | \mathbf{H} | \mathbf{1} \rangle = i_2^*$$

$$i_3 = \langle \mathbf{i}_3 | \mathbf{H} | \mathbf{1} \rangle = i_3^*$$



local- D_3 -defined

Hamiltonian matrix

$$\mathbf{H} = \begin{matrix} & | \mathbf{1} \rangle & | \mathbf{r} \rangle & | \mathbf{r}^2 \rangle & | \mathbf{i}_1 \rangle & | \mathbf{i}_2 \rangle & | \mathbf{i}_3 \rangle \\ \begin{matrix} (\mathbf{1} | \\ (\mathbf{r} | \\ (\mathbf{r}^2 | \\ (\mathbf{i}_1 | \\ (\mathbf{i}_2 | \\ (\mathbf{i}_3 | \end{matrix} & \begin{matrix} H & r_1 & r_2 & i_1 & i_2 & i_3 \\ r_2 & H & r_1 & i_2 & i_3 & i_1 \\ r_1 & r_2 & H & i_3 & i_1 & i_2 \\ i_1 & i_2 & i_3 & H & r_1 & r_2 \\ i_2 & i_3 & i_1 & r_2 & H & r_1 \\ i_3 & i_1 & i_2 & r_1 & r_2 & H \end{matrix} \end{matrix}$$

To represent *internal* { .. $\bar{\mathbf{T}}, \bar{\mathbf{U}}, \bar{\mathbf{V}}$,... } sv

$$R^G(\bar{\mathbf{1}}) = \begin{pmatrix} 1 & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots \\ \dots & \dots & 1 & \dots & \dots \\ \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & 1 \end{pmatrix}, \quad R^G(\bar{\mathbf{r}}) = \begin{pmatrix} \dots & \dots & \dots & \dots & 1 \\ \dots & \dots & \dots & 1 & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}, \quad R^G(\bar{\mathbf{r}}^2) = \begin{pmatrix} \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}$$

Q: How do you reduce/diagonalize all these matrices?

$$\begin{pmatrix} R^G(\mathbf{r}) \\ \vdots \\ R^G(\mathbf{r}) \end{pmatrix} \begin{pmatrix} R^G(\mathbf{r}) \\ \vdots \\ R^G(\mathbf{r}) \end{pmatrix}$$

- A: (1) Divide & Conquer (Use subgroup chains and sub-classes)
 (2) Find commuting invariants (Using character projection algebra)
 (3) Assemble

local- D_3 -defined

Hamiltonian matrix

$$\mathbb{H} = \begin{matrix} & |1\rangle & |r\rangle & |r^2\rangle & |i_1\rangle & |i_2\rangle & |i_3\rangle \\ \begin{matrix} (1) \\ (r) \\ (r^2) \\ (i_1) \\ (i_2) \\ (i_3) \end{matrix} & \begin{matrix} H \\ r_1 \\ r_2 \\ i_1 \\ i_2 \\ i_3 \end{matrix} & \begin{matrix} r_1 \\ H \\ r_2 \\ i_2 \\ i_3 \\ i_1 \end{matrix} & \begin{matrix} r_2 \\ r_2 \\ H \\ i_3 \\ i_1 \\ i_2 \end{matrix} & \begin{matrix} i_1 \\ i_2 \\ i_3 \\ H \\ r_1 \\ r_2 \end{matrix} & \begin{matrix} i_2 \\ i_3 \\ i_1 \\ r_2 \\ H \\ r_1 \end{matrix} & \begin{matrix} i_3 \\ i_1 \\ i_2 \\ r_1 \\ r_2 \\ H \end{matrix} \end{matrix}$$

$$D_3 \kappa = \begin{matrix} \mathbf{1} & \mathbf{r^1+r^2} & \mathbf{i_1+i_2+i_3} \end{matrix}$$

$$P^{A_1} = \begin{matrix} 1 & 1 & 1 \\ /6 \end{matrix}$$

$$P^{A_2} = \begin{matrix} 1 & 1 & -1 \\ /6 \end{matrix}$$

$$P^E = \begin{matrix} 2 & -1 & 0 \\ /3 \end{matrix}$$

Important invariant numbers or “characters”

$\ell^\alpha =$ Irreducible representation (irrep) *dimension* or level *degeneracy*
 For symmetry group or algebra G

Centrum: $\kappa(G) = \sum_{\text{irrep}(\alpha)} (\ell^\alpha)^0 =$ Number of classes, invariants, irrep types, *all-commuting* ops

Rank: $\rho(G) = \sum_{\text{irrep}(\alpha)} (\ell^\alpha)^1 =$ Number of irrep idempotents $P_{n,n}^{(\alpha)}$, *mutually-commuting* ops

Order: $o(G) = \sum_{\text{irrep}(\alpha)} (\ell^\alpha)^2 =$ *Total* number of irrep projectors $P_{m,n}^{(\alpha)}$ or symmetry ops

Centrum: $\kappa(D_3) = \sum_{(\alpha)} (\ell^\alpha)^0 = 1^0 + 1^0 + 2^0 = 3$

Rank: $\rho(D_3) = \sum_{(\alpha)} (\ell^\alpha)^1 = 1^1 + 1^1 + 2^1 = 4$

Order: $o(D_3) = \sum_{(\alpha)} (\ell^\alpha)^2 = 1^2 + 1^2 + 2^2 = 6$

Example: $G = D_3$

$$\ell^{A_1} = 1$$

$$\ell^{A_2} = 1$$

$$\ell^E = 2$$

Spectral analysis of non-commutative “Group-table Hamiltonian”

D_3 Example

1st Step: Spectral resolution of Center (Class algebra of D_3)

1	r¹	r²	i₁	i₂	i₃
r²	1	r¹	i₂	i₃	i₁
r¹	r²	1	i₃	i₁	i₂
i₁	i₂	i₃	1	r¹	r²
i₂	i₃	i₁	r²	1	r¹
i₃	i₁	i₂	r¹	r²	1

Each class-sum κ_k commues with all of D_3 .

$\kappa_1 = \mathbf{1}$	$\kappa_2 = \mathbf{r}^1 + \mathbf{r}^2$	$\kappa_3 = \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3$
κ_2	$2\kappa_1 + \kappa_2$	$2\kappa_3$
κ_3	$2\kappa_3$	$3\kappa_1 + 3\kappa_2$

Class products give spectral polynomial and all-commuting projectors $\mathbf{P}^{(\alpha)} = \mathbf{P}^{A_1}$, \mathbf{P}^{A_2} , and \mathbf{P}^E

$$0 = \kappa_3^3 - 9\kappa_3 = (\kappa_3 - 3 \cdot \mathbf{1})(\kappa_3 + 3 \cdot \mathbf{1})(\kappa_3 - 0 \cdot \mathbf{1})$$

*Algebra Center like cell nucleus;
Its invariants are made here.*

- *characters* (invariant)
- *projectors* (invariant)
- *H eigenvalues* (depend on local sym.)
- *H eigenvectors* (depend on local sym.)

Spectral analysis of non-commutative “Group-table Hamiltonian”

D_3 Example

1st Step: Spectral resolution of Center (Class algebra of D_3)

1	r^1	r^2	i_1	i_2	i_3
r^2	1	r^1	i_2	i_3	i_1
r^1	r^2	1	i_3	i_1	i_2
i_1	i_2	i_3	1	r^1	r^2
i_2	i_3	i_1	r^2	1	r^1
i_3	i_1	i_2	r^1	r^2	1

Each class-sum κ_k commutes with all of D_3 .

$\kappa_1 = 1$	$\kappa_2 = r^1 + r^2$	$\kappa_3 = i_1 + i_2 + i_3$
κ_2	$2\kappa_1 + \kappa_2$	$2\kappa_3$
κ_3	$2\kappa_3$	$3\kappa_1 + 3\kappa_2$

Class products give spectral polynomial and all-commuting projectors $\mathbf{P}^{(\alpha)} = \mathbf{P}^{A_1}$, \mathbf{P}^{A_2} , and \mathbf{P}^E

$$0 = \kappa_3^3 - 9\kappa_3 = (\kappa_3 - 3 \cdot 1)(\kappa_3 + 3 \cdot 1)(\kappa_3 - 0 \cdot 1)$$

$$0 = (\kappa_3 - 3 \cdot 1)\mathbf{P}^{A_1}$$

$$\kappa_3 \mathbf{P}^{A_1} = +3 \cdot \mathbf{P}^{A_1}$$

$$0 = (\kappa_3 + 3 \cdot 1)\mathbf{P}^{A_2}$$

$$\kappa_3 \mathbf{P}^{A_2} = -3 \cdot \mathbf{P}^{A_2}$$

$$0 = (\kappa_3 - 0 \cdot 1)\mathbf{P}^E$$

$$\kappa_3 \mathbf{P}^E = +0 \cdot \mathbf{P}^E$$

Class resolution into sum of eigenvalue · Projector

$$\kappa_1 = 1 \cdot \mathbf{P}^{A_1} + 1 \cdot \mathbf{P}^{A_2} + 1 \cdot \mathbf{P}^E$$

$$\kappa_2 = 2 \cdot \mathbf{P}^{A_1} - 2 \cdot \mathbf{P}^{A_2} - 1 \cdot \mathbf{P}^E$$

$$\kappa_3 = 3 \cdot \mathbf{P}^{A_1} - 3 \cdot \mathbf{P}^{A_2} + 0 \cdot \mathbf{P}^E$$

$$\mathbf{P}^{A_1} = \frac{(\kappa_3 + 3 \cdot 1)(\kappa_3 - 0 \cdot 1)}{(+3+3)(+3-0)}$$

$$\mathbf{P}^{A_2} = \frac{(\kappa_3 - 3 \cdot 1)(\kappa_3 - 0 \cdot 1)}{(-3-3)(-3-0)}$$

$$\mathbf{P}^E = \frac{(\kappa_3 - 3 \cdot 1)(\kappa_3 + 3 \cdot 1)}{(+0-3)(+0+3)}$$

Spectral analysis of non-commutative "Group-table Hamiltonian"

D_3 Example

1st Step: Spectral resolution of Center (Class algebra of D_3)

$\mathbf{1}$	\mathbf{r}^1	\mathbf{r}^2	\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3
\mathbf{r}^2	$\mathbf{1}$	\mathbf{r}^1	\mathbf{i}_2	\mathbf{i}_3	\mathbf{i}_1
\mathbf{r}^1	\mathbf{r}^2	$\mathbf{1}$	\mathbf{i}_3	\mathbf{i}_1	\mathbf{i}_2
\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3	$\mathbf{1}$	\mathbf{r}^1	\mathbf{r}^2
\mathbf{i}_2	\mathbf{i}_3	\mathbf{i}_1	\mathbf{r}^2	$\mathbf{1}$	\mathbf{r}^1
\mathbf{i}_3	\mathbf{i}_1	\mathbf{i}_2	\mathbf{r}^1	\mathbf{r}^2	$\mathbf{1}$

Each class-sum κ_k commutes with all of D_3 .

$\kappa_1 = \mathbf{1}$	$\kappa_2 = \mathbf{r}^1 + \mathbf{r}^2$	$\kappa_3 = \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3$
κ_2	$2\kappa_1 + \kappa_2$	$2\kappa_3$
κ_3	$2\kappa_3$	$3\kappa_1 + 3\kappa_2$

Class products give spectral polynomial and all-commuting projectors $\mathbf{P}^{(\alpha)} = \mathbf{P}^{A_1}$, \mathbf{P}^{A_2} , and \mathbf{P}^E

$$0 = \kappa_3^3 - 9\kappa_3 = (\kappa_3 - 3 \cdot \mathbf{1})(\kappa_3 + 3 \cdot \mathbf{1})(\kappa_3 - 0 \cdot \mathbf{1})$$

$$0 = (\kappa_3 - 3 \cdot \mathbf{1})\mathbf{P}^{A_1}$$

$$\kappa_3\mathbf{P}^{A_1} = +3 \cdot \mathbf{P}^{A_1}$$

$$0 = (\kappa_3 + 3 \cdot \mathbf{1})\mathbf{P}^{A_2}$$

$$\kappa_3\mathbf{P}^{A_2} = -3 \cdot \mathbf{P}^{A_2}$$

$$0 = (\kappa_3 - 0 \cdot \mathbf{1})\mathbf{P}^E$$

$$\kappa_3\mathbf{P}^E = +0 \cdot \mathbf{P}^E$$

Class resolution into sum of eigenvalue · Projector

$$\kappa_1 = 1 \cdot \mathbf{P}^{A_1} + 1 \cdot \mathbf{P}^{A_2} + 1 \cdot \mathbf{P}^E$$

$$\kappa_2 = 2 \cdot \mathbf{P}^{A_1} - 2 \cdot \mathbf{P}^{A_2} - 1 \cdot \mathbf{P}^E$$

$$\kappa_3 = 3 \cdot \mathbf{P}^{A_1} - 3 \cdot \mathbf{P}^{A_2} + 0 \cdot \mathbf{P}^E$$

$$\mathbf{P}^{A_1} = \frac{(\kappa_3 + 3 \cdot \mathbf{1})(\kappa_3 - 0 \cdot \mathbf{1})}{(+3+3)(+3-0)}$$

$$\mathbf{P}^{A_2} = \frac{(\kappa_3 - 3 \cdot \mathbf{1})(\kappa_3 - 0 \cdot \mathbf{1})}{(-3-3)(-3-0)}$$

$$\mathbf{P}^E = \frac{(\kappa_3 - 3 \cdot \mathbf{1})(\kappa_3 + 3 \cdot \mathbf{1})}{(+0-3)(+0+3)}$$

Inverse resolution gives D_3 Character Table

$$\mathbf{P}^{A_1} = (\kappa_1 + \kappa_2 + \kappa_3)/6 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3)/6$$

$$\mathbf{P}^{A_2} = (\kappa_1 + \kappa_2 - \kappa_3)/6 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 - \mathbf{i}_3)/6$$

$$\mathbf{P}^E = (2\kappa_1 - \kappa_2)/3 = (2\mathbf{1} - \mathbf{r}^1 - \mathbf{r}^2)/3$$

Spectral reduction of non-commutative "Group-table Hamiltonian"

D_3 Example

2nd Step: Spectral resolution of Class Projector(s) of D_3

Correlate D_3 characters with its subgroup(s) $C_2(\mathbf{i})$ or ELSE $C_3(\mathbf{r})$ (C_2 and C_3 don't commute)

$$D_3 \quad \kappa = \mathbf{1} \quad \mathbf{r}^l + \mathbf{r}^2 \quad \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 2 & -1 & 0 \end{bmatrix} / 6$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix} / 6$$

$$\mathbf{P}^E = \begin{bmatrix} 2 & -1 & 0 \\ 2 & -1 & 0 \\ 2 & -1 & 0 \end{bmatrix} / 3$$

$$C_2 \quad \kappa = \mathbf{1} \quad \mathbf{i}_3$$

$$p^{0_2} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} / 2$$

$$p^{1_2} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} / 2$$

$$D_3 \supset C_2 \quad 0_2 \quad 1_2$$

$$n^{A_1} = \begin{bmatrix} 1 & \cdot \\ \cdot & 1 \\ 1 & 1 \end{bmatrix}$$

$$n^{A_2} = \begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \\ 1 & 1 \end{bmatrix}$$

$$n^E = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\underline{\underline{A_1}} \quad \underline{\underline{A_2}}$$

$$\underline{\underline{E}} \quad \underline{\underline{E}}$$

level
un-splitting
or
clustering

$$C_3 \quad \kappa = \mathbf{1} \quad \mathbf{r}^l \quad \mathbf{r}^2$$

$$p^{0_3} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 2 & \varepsilon^* & \varepsilon \end{bmatrix} / 3$$

$$p^{1_3} = \begin{bmatrix} 1 & \varepsilon & \varepsilon^* \\ 1 & \varepsilon & \varepsilon^* \\ 2 & \varepsilon^* & \varepsilon \end{bmatrix} / 3$$

$$p^{2_3} = \begin{bmatrix} 1 & \varepsilon^* & \varepsilon \\ 1 & \varepsilon^* & \varepsilon \\ 2 & \varepsilon & \varepsilon^* \end{bmatrix} / 3$$

$$\varepsilon = e^{2\pi i/3}$$

$$D_3 \supset C_3 \quad 0_3 \quad 1_3 \quad 2_3$$

$$n^{A_1} = \begin{bmatrix} 1 & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & 1 \end{bmatrix}$$

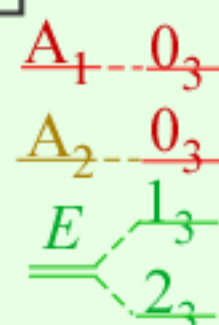
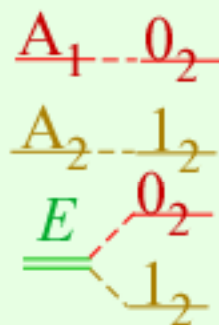
$$n^{A_2} = \begin{bmatrix} 1 & \cdot & \cdot \\ 1 & \cdot & \cdot \\ \cdot & 1 & 1 \end{bmatrix}$$

$$n^E = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & 1 & 1 \\ \cdot & 1 & 1 \end{bmatrix}$$

$$\underline{\underline{A_1}} \quad \underline{\underline{E}} \quad \underline{\underline{E}}$$

$$A_2$$

level
splitting



Spectral reduction of non-commutative "Group-table Hamiltonian"

D_3 Example

2nd Step: Spectral resolution of Class Projector(s) of D_3

Correlate D_3 characters with its subgroup(s) $C_2(\mathbf{i})$ or ELSE $C_3(\mathbf{r})$ (C_2 and C_3 don't commute)

$$D_3 \quad \kappa = \mathbf{1} \quad \mathbf{r}^l + \mathbf{r}^2 \quad \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix} / 6$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 1 \\ 2 & -1 & 0 \end{bmatrix} / 6$$

$$\mathbf{P}^E = \begin{bmatrix} 2 & -1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix} / 3$$

$$C_2 \quad \kappa = \mathbf{1} \quad \mathbf{i}_3$$

$$p^{0_2} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} / 2$$

$$p^{1_2} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} / 2$$

$$D_3 \supset C_2 \quad 0_2 \quad 1_2$$

$$n^{A_1} = \begin{bmatrix} 1 & \cdot \\ \cdot & 1 \end{bmatrix}$$

$$n^{A_2} = \begin{bmatrix} \cdot & 1 \\ 1 & \cdot \end{bmatrix}$$

$$n^E = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$C_3 \quad \kappa = \mathbf{1} \quad \mathbf{r}^l \quad \mathbf{r}^2$$

$$p^{0_3} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & \epsilon & \epsilon^* \\ 2 & \epsilon^* & \epsilon \end{bmatrix} / 3$$

$$p^{1_3} = \begin{bmatrix} 1 & \epsilon & \epsilon^* \\ 1 & \epsilon^* & \epsilon \\ 2 & \epsilon^* & \epsilon \end{bmatrix} / 3$$

$$p^{2_3} = \begin{bmatrix} 1 & \epsilon & \epsilon^* \\ 1 & \epsilon^* & \epsilon \\ 2 & \epsilon^* & \epsilon \end{bmatrix} / 3$$

$$\epsilon = e^{2\pi i/3}$$

$$D_3 \supset C_2 \quad 0_3 \quad 1_3 \quad 2_3$$

$$n^{A_1} = \begin{bmatrix} 1 & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & 1 \end{bmatrix}$$

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$$n^E = \begin{bmatrix} \cdot & 1 & 1 \\ 1 & \cdot & \cdot \\ 1 & \cdot & \cdot \end{bmatrix}$$

Correlation shows products of $\mathbf{P}^{(\alpha)}$ by the C_2 -unit or by the C_3 -unit make IRREDUCIBLE $\mathbf{P}_{n,n}^{(\alpha)}$

$$I = p^{0_2} + p^{1_2}$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} \mathbf{P}_{0_2 0_2}^{A_1} & \cdot \\ \cdot & \mathbf{P}_{1_2 1_2}^{A_1} \end{bmatrix}$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} \cdot & \mathbf{P}_{1_2 1_2}^{A_2} \\ \mathbf{P}_{0_2 0_2}^{A_2} & \cdot \end{bmatrix}$$

$$\mathbf{P}^E = \begin{bmatrix} \mathbf{P}_{0_2 0_2}^E & \mathbf{P}_{1_2 1_2}^E \\ \mathbf{P}_{1_2 1_2}^E & \mathbf{P}_{0_2 0_2}^E \end{bmatrix}$$

Rank $\rho(D_3) = 4$

idempotent

$$\mathbf{P}_{n_2 n_2}^{(\alpha)}$$

4 different

idempotent

$$\mathbf{P}_{n_3 n_3}^{(\alpha)}$$

$$I = p^{0_3} + p^{1_3} + p^{2_3}$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} \mathbf{P}_{0_3 0_3}^{A_1} & \cdot & \cdot \\ \cdot & \mathbf{P}_{1_3 1_3}^{A_1} & \cdot \\ \cdot & \cdot & \mathbf{P}_{2_3 2_3}^{A_1} \end{bmatrix}$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} \mathbf{P}_{0_3 0_3}^{A_2} & \cdot & \cdot \\ \cdot & \mathbf{P}_{1_3 1_3}^{A_2} & \cdot \\ \cdot & \cdot & \mathbf{P}_{2_3 2_3}^{A_2} \end{bmatrix}$$

$$\mathbf{P}^E = \begin{bmatrix} \cdot & \mathbf{P}_{1_3 1_3}^E & \mathbf{P}_{2_3 2_3}^E \\ \mathbf{P}_{1_3 1_3}^E & \cdot & \cdot \\ \mathbf{P}_{2_3 2_3}^E & \cdot & \cdot \end{bmatrix}$$

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$$p^{0_3} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & \epsilon & \epsilon^* \\ 2 & \epsilon^* & \epsilon \end{bmatrix} / 3$$

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$$p^{2_3} = \begin{bmatrix} 1 & \epsilon & \epsilon^* \\ 1 & \epsilon^* & \epsilon \\ 2 & \epsilon^* & \epsilon \end{bmatrix} / 3$$

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Correlation shows products of $\mathbf{P}^{(\alpha)}$ by the C_2 -unit or by the C_3 -unit make IRREDUCIBLE $\mathbf{P}_{n,n}^{(\alpha)}$

$$l = p^{0_2} + p^{1_2}$$

Rank $\rho(D_3) = 4$

idempotent

$\downarrow \mathbf{P}_{n_2, n_2}^{(\alpha)}$

$$\mathbf{P}^{A_1} = \begin{bmatrix} \mathbf{P}_{0_2, 0_2}^{A_1} & \cdot \\ \cdot & \mathbf{P}_{1_2, 1_2}^{A_2} \end{bmatrix}$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} \cdot & \mathbf{P}_{1_2, 1_2}^{A_2} \\ \mathbf{P}_{0_2, 0_2}^{E} & \mathbf{P}_{1_2, 1_2}^{E} \end{bmatrix}$$

$$\mathbf{P}^E = \begin{bmatrix} \mathbf{P}_{0_2, 0_2}^{E} & \mathbf{P}_{1_2, 1_2}^{E} \\ \mathbf{P}_{1_2, 1_2}^{E} & \mathbf{P}_{0_2, 0_2}^{E} \end{bmatrix}$$

$$\mathbf{P}_{0_2, 0_2}^{A_1} = \mathbf{P}^{A_1} p^{0_2} = \mathbf{P}^{A_1} (1 + \mathbf{i}_3) / 2 = (1 + \mathbf{r}^l + \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3) / 6$$

$$\mathbf{P}_{1_2, 1_2}^{A_2} = \mathbf{P}^{A_2} p^{1_2} = \mathbf{P}^{A_2} (1 - \mathbf{i}_3) / 2 = (1 + \mathbf{r}^l + \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 - \mathbf{i}_3) / 6$$

$$\mathbf{P}_{0_2, 0_2}^{E} = \mathbf{P}^E p^{0_2} = \mathbf{P}^E (1 + \mathbf{i}_3) / 2 = (21 - \mathbf{r}^l - \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 + 2\mathbf{i}_3) / 6$$

$$\mathbf{P}_{1_2, 1_2}^{E} = \mathbf{P}^E p^{1_2} = \mathbf{P}^E (1 - \mathbf{i}_3) / 2 = (21 - \mathbf{r}^l - \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 - 2\mathbf{i}_3) / 6$$

4 different

idempotent

$\downarrow \mathbf{P}_{n_3, n_3}^{(\alpha)}$

$$l = p^{0_3} + p^{1_3} + p^{2_3}$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} \mathbf{P}_{0_3, 0_3}^{A_1} & \cdot & \cdot \\ \mathbf{P}_{0_3, 0_3}^{A_2} & \cdot & \cdot \\ \cdot & \mathbf{P}_{1_3, 1_3}^{E} & \mathbf{P}_{2_3, 2_3}^{E} \end{bmatrix}$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} \cdot & \cdot & \cdot \\ \mathbf{P}_{0_3, 0_3}^{A_2} & \cdot & \cdot \\ \cdot & \mathbf{P}_{1_3, 1_3}^{E} & \mathbf{P}_{2_3, 2_3}^{E} \end{bmatrix}$$

$$\mathbf{P}^E = \begin{bmatrix} \cdot & \cdot & \cdot \\ \mathbf{P}_{0_3, 0_3}^{E} & \cdot & \cdot \\ \cdot & \mathbf{P}_{1_3, 1_3}^{E} & \mathbf{P}_{2_3, 2_3}^{E} \end{bmatrix}$$

$$\mathbf{P}_{0_3, 0_3}^{A_1} = \mathbf{P}^{A_1} p^{0_3} = \mathbf{P}^{A_1} (1 + \mathbf{r}^l + \mathbf{r}^2) / 3 = (1 + \mathbf{r}^l + \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3) / 6$$

$$\mathbf{P}_{0_3, 0_3}^{A_2} = \mathbf{P}^{A_2} p^{0_3} = \mathbf{P}^{A_2} (1 + \mathbf{r}^l + \mathbf{r}^2) / 3 = (1 + \mathbf{r}^l + \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 - \mathbf{i}_3) / 6$$

$$\mathbf{P}_{1_3, 1_3}^{E} = \mathbf{P}^E p^{1_3} = \mathbf{P}^E (1 + \epsilon^* \mathbf{r}^l + \epsilon \mathbf{r}^2) / 3 = (1 + \epsilon \mathbf{r}^l + \epsilon^* \mathbf{r}^2) / 6$$

$$\mathbf{P}_{2_3, 2_3}^{E} = \mathbf{P}^E p^{2_3} = \mathbf{P}^E (1 + \epsilon \mathbf{r}^l + \epsilon^* \mathbf{r}^2) / 3 = (1 + \epsilon^* \mathbf{r}^l + \epsilon \mathbf{r}^2) / 6$$

2nd Step: (contd.) While some class projectors $\mathbf{P}^{(\alpha)}$ split in two, so ALSO DO some classes κ_k

Rank $\rho(D_3)=4$
idempotents

$\mathbf{P}^{(\alpha)}$

$$\mathbf{P}_{0_2 0_2}^{A_1} = \mathbf{P}^{A_1} p^{0_2} = \mathbf{P}^{A_1} (1+i_3)/2 = \begin{pmatrix} 1 & r^1 + r^2 & i_1 + i_2 + i_3 \end{pmatrix} / 6$$

$$\mathbf{P}_{1_2 1_2}^{A_2} = \mathbf{P}^{A_2} p^{1_2} = \mathbf{P}^{A_2} (1-i_3)/2 = \begin{pmatrix} 1 & r^1 + r^2 & -i_1 - i_2 - i_3 \end{pmatrix} / 6$$

$$\mathbf{P}_{0_2 0_2}^E = \mathbf{P}^E p^{0_2} = \mathbf{P}^E (1+i_3)/2 = \begin{pmatrix} 2 & 1 - r^1 - r^2 & -i_1 - i_2 + 2i_3 \end{pmatrix} / 6$$

$$\mathbf{P}_{1_2 1_2}^E = \mathbf{P}^E p^{1_2} = \mathbf{P}^E (1-i_3)/2 = \begin{pmatrix} 2 & 1 - r^1 - r^2 & i_1 + i_2 - 2i_3 \end{pmatrix} / 6$$

\mathbf{P}^E splits into $\mathbf{P}^E = \mathbf{P}_{0_2 0_2}^E + \mathbf{P}_{1_2 1_2}^E$
class κ_i splits into $\kappa_{i_{12}}$ and κ_{i_3}

$$D_3 \kappa = \begin{pmatrix} 1 & r^1 + r^2 & i_1 + i_2 + i_3 \\ \mathbf{P}^{A_1} = \begin{pmatrix} 1 & 1 & 1 \end{pmatrix} / 6 \\ \mathbf{P}^{A_2} = \begin{pmatrix} 1 & 1 & -1 \end{pmatrix} / 6 \\ \mathbf{P}^E = \begin{pmatrix} 2 & -1 & 0 \end{pmatrix} / 3 \end{pmatrix}$$

Centrum $\kappa(D_3)=3$
idempotents
 $\mathbf{P}^{(\alpha)}$

4 different idempotent

$\mathbf{P}_{n,n}^{(\alpha)}$

$$\mathbf{P}_{0_3 0_3}^{A_1} = \mathbf{P}^{A_1} p^{0_3} = \mathbf{P}^{A_1} (1+r^1+r^2)/3 = \begin{pmatrix} 1 & r^1 + r^2 & i_1 + i_2 + i_3 \end{pmatrix} / 6$$

$$\mathbf{P}_{0_3 0_3}^{A_2} = \mathbf{P}^{A_2} p^{0_3} = \mathbf{P}^{A_2} (1+r^1+r^2)/3 = \begin{pmatrix} 1 & r^1 + r^2 & -i_1 - i_2 - i_3 \end{pmatrix} / 6$$

$$\mathbf{P}_{1_3 1_3}^E = \mathbf{P}^E p^{1_3} = \mathbf{P}^E (1+\epsilon r^1 + \epsilon r^2)/3 = \begin{pmatrix} 1 & \epsilon r^1 + \epsilon r^2 & \end{pmatrix} / 6$$

$$\mathbf{P}_{2_3 2_3}^E = \mathbf{P}^E p^{2_3} = \mathbf{P}^E (1+\epsilon r^1 + \epsilon r^2)/3 = \begin{pmatrix} 1 & \epsilon r^1 + \epsilon r^2 & \end{pmatrix} / 6$$

\mathbf{P}^E splits into $\mathbf{P}^E = \mathbf{P}_{1_3 1_3}^E + \mathbf{P}_{2_3 2_3}^E$
class κ_r splits into κ_{r^1} and κ_{r^2}

2nd Step: (contd.) While some class projectors $\mathbf{P}^{(\alpha)}$ split in two, so ALSO DO some classes κ_k

Rank $\rho(\mathbf{D}_3)=4$
idempotents

Centrum $\kappa(\mathbf{D}_3)=3$
idempotents
 $\mathbf{P}^{(\alpha)}$

$$\mathbf{D}_3 \kappa = \begin{bmatrix} \mathbf{1} & \mathbf{r}^1 + \mathbf{r}^2 & \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3 \end{bmatrix}$$

$$\mathbf{P}^{A_1} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix} / 6$$

$$\mathbf{P}^{A_2} = \begin{bmatrix} 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix} / 6$$

$$\mathbf{P}^E = \begin{bmatrix} 2 & -1 & 0 \end{bmatrix} / 3$$

$$\mathbf{P}_{0_2 0_2}^{A_1} = \mathbf{P}^{A_1} p^{0_2} = \mathbf{P}^{A_1} (\mathbf{1} + \mathbf{i}_3) / 2 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3) / 6$$

$$\mathbf{P}_{1_2 1_2}^{A_2} = \mathbf{P}^{A_2} p^{1_2} = \mathbf{P}^{A_2} (\mathbf{1} - \mathbf{i}_3) / 2 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 - \mathbf{i}_3) / 6$$

$$\mathbf{P}_{0_2 0_2}^E = \mathbf{P}^E p^{0_2} = \mathbf{P}^E (\mathbf{1} + \mathbf{i}_3) / 2 = (2\mathbf{1} - \mathbf{r}^1 - \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 + 2\mathbf{i}_3) / 6$$

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4 different idempotent $\mathbf{P}_{n,n}^{(\alpha)}$

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$$\mathbf{P}_{1_3 1_3}^E = \mathbf{P}^E p^{1_3} = \mathbf{P}^E (\mathbf{1} + \epsilon \mathbf{r}^1 + \epsilon \mathbf{r}^2) / 3 = (\mathbf{1} + \epsilon \mathbf{r}^1 + \epsilon \mathbf{r}^2) / 6$$

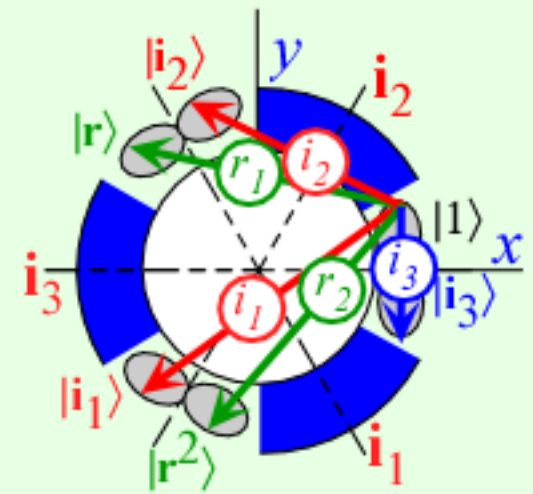
$$\mathbf{P}_{2_3 2_3}^E = \mathbf{P}^E p^{2_3} = \mathbf{P}^E (\mathbf{1} + \epsilon \mathbf{r}^1 + \epsilon \mathbf{r}^2) / 3 = (\mathbf{1} + \epsilon \mathbf{r}^1 + \epsilon \mathbf{r}^2) / 6$$

\mathbf{P}^E splits into $\mathbf{P}^E = \mathbf{P}_{0_2 0_2}^E + \mathbf{P}_{1_2 1_2}^E$
class κ_i splits into $\kappa_{i_{12}}$ and κ_{i_3}

\mathbf{P}^E splits into $\mathbf{P}^E = \mathbf{P}_{1_3 1_3}^E + \mathbf{P}_{2_3 2_3}^E$
class κ_r splits into κ_{r^1} and κ_{r^2}

$r=r_2$ $i=i_2$
must equal must equal
 r_1 i_1

For Local $D_3 \supset C_2(\mathbf{i}_3)$ symmetry
 i_3 is free parameter



Rank $\rho(\mathbf{D}_3)=4$
parameters in either case

$i=i_1=i_2=i_3$

For Local $D_3 \supset C_3(\mathbf{r}^p)$ symmetry
 r_1 and r_2 are free

Centrum $\kappa(D_3)=3$
idempotents
 $\mathbf{P}^{(\alpha)}$

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$$\mathbf{P}^E = \begin{pmatrix} 2 & -1 & 0 \\ 2 & -1 & 0 \\ 2 & -1 & 0 \end{pmatrix} / 3$$

Rank $\rho(D_3)=4$
idempotents
 $\mathbf{P}_{n,n}^{(\alpha)}$

$$\mathbf{P}_{x,x}^{A_1} = \mathbf{P}_{0_2,0_2}^{A_1} = \mathbf{P}^{A_1} \mathbf{p}^{0_2} = \mathbf{P}^{A_1} (\mathbf{1} + \mathbf{i}_3) / 2 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 + \mathbf{i}_3) / 6$$

$$\mathbf{P}_{y,y}^{A_2} = \mathbf{P}_{1_2,1_2}^{A_2} = \mathbf{P}^{A_2} \mathbf{p}^{1_2} = \mathbf{P}^{A_2} (\mathbf{1} - \mathbf{i}_3) / 2 = (\mathbf{1} + \mathbf{r}^1 + \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 - \mathbf{i}_3) / 6$$

$$\mathbf{P}_{x,x}^E = \mathbf{P}_{0_2,0_2}^E = \mathbf{P}^E \mathbf{p}^{0_2} = \mathbf{P}^E (\mathbf{1} + \mathbf{i}_3) / 2 = (2\mathbf{1} - \mathbf{r}^1 - \mathbf{r}^2 - \mathbf{i}_1 - \mathbf{i}_2 + 2\mathbf{i}_3) / 6$$

$$\mathbf{P}_{y,y}^E = \mathbf{P}_{1_2,1_2}^E = \mathbf{P}^E \mathbf{p}^{1_2} = \mathbf{P}^E (\mathbf{1} - \mathbf{i}_3) / 2 = (2\mathbf{1} - \mathbf{r}^1 - \mathbf{r}^2 + \mathbf{i}_1 + \mathbf{i}_2 - 2\mathbf{i}_3) / 6$$

3rd and Final Step:

Spectral resolution of ALL 6 of D_3 :

The old 'g-equals-1-times-g-times-1' Trick

$$\mathbf{g} = \sum_m \sum_e \sum_b D_{eb}^{(m)}(\mathbf{g}) \mathbf{P}_{eb}^{(m)}$$

$$\mathbf{P}_{eb}^{(m)} = (\text{norm}) \sum_{\mathbf{g}} D_{eb}^{(m)*}(\mathbf{g}) \mathbf{g}$$

$$\mathbf{g} = \mathbf{1} \cdot \mathbf{g} \cdot \mathbf{1} = (\mathbf{P}_{x,x}^{A_1} + \mathbf{P}_{y,y}^{A_2} + \mathbf{P}_{x,x}^E + \mathbf{P}_{y,y}^E) \cdot \mathbf{g} \cdot (\mathbf{P}_{x,x}^{A_1} + \mathbf{P}_{y,y}^{A_2} + \mathbf{P}_{x,x}^E + \mathbf{P}_{y,y}^E)$$

$$\mathbf{g} = \mathbf{P}^{A_1} \cdot \mathbf{g} \cdot \mathbf{P}^{A_1} + \mathbf{P}^{A_2} \cdot \mathbf{g} \cdot \mathbf{P}^{A_2} + \mathbf{P}_{x,x}^E \cdot \mathbf{g} \cdot \mathbf{P}_{x,x}^E + \mathbf{P}_{x,x}^E \cdot \mathbf{g} \cdot \mathbf{P}_{y,y}^E$$

$$+ \mathbf{P}_{y,y}^E \cdot \mathbf{g} \cdot \mathbf{P}_{x,x}^E + \mathbf{P}_{y,y}^E \cdot \mathbf{g} \cdot \mathbf{P}_{y,y}^E$$

Order $^0(D_3)=6$
projectors
 $\mathbf{P}_{m,n}^{(\alpha)}$

Six D_3 projectors: 4 idempotents + 2 nilpotents (off-diag.)

	$\mathbf{1}$	\mathbf{r}^1	\mathbf{r}^2	\mathbf{i}_1	\mathbf{i}_2	\mathbf{i}_3	
$\mathbf{P}_{x,x}^{A_1}$	$(1$	1	1	1	1	$1)$	$/6$
$\mathbf{P}_{y,y}^{A_2}$	$(1$	1	1	-1	-1	$-1)$	$/6$
$\mathbf{P}_{x,x}^E$	$(2$	-1	-1	-1	-1	$+2)$	$/6$
$\mathbf{P}_{y,x}^E$	$(0$	1	-1	-1	$+1$	$0)$	$/\sqrt{3}/2$
$\mathbf{P}_{x,y}^E$	$(0$	-1	1	-1	$+1$	$0)$	$/\sqrt{3}/2$
$\mathbf{P}_{y,y}^E$	$(2$	-1	-1	$+1$	$+1$	$-2)$	$/6$

$$|{}^{(m)}_{eb}\rangle = \mathbf{P}{}^{(m)}_{eb} |1\rangle$$

external LAB

internal BOD

symmetry label-e

symmetry label-b

GLOBAL

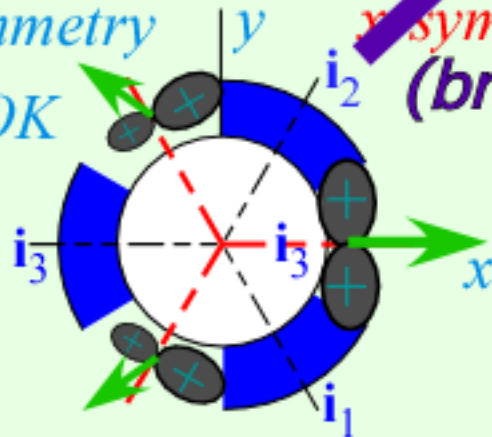
LOCAL

GLOBAL

$(i_3) = 0_2$

x-symmetry

\mathbf{i}_3 OK



~~LOCAL~~

~~$(i_3) = 0_2$~~

~~x-symmetry~~

~~(broken $\bar{\mathbf{i}}_3$)~~

~~GLOBAL~~

~~$(i_3) = 0_2$~~

~~x-symmetry~~

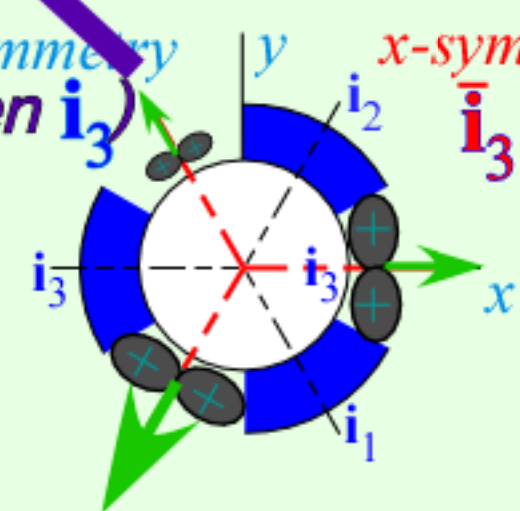
~~(broken \mathbf{i}_3)~~

LOCAL

$(i_3) = 0_2$

x-symmetry

$\bar{\mathbf{i}}_3$ OK

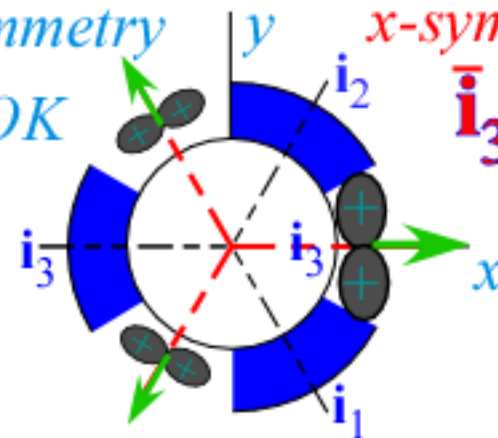


GLOBAL

$(i_3) = 0_2$

x-symmetry

\mathbf{i}_3 OK



LOCAL

$(i_3) = 0_2$

x-symmetry

$\bar{\mathbf{i}}_3$ OK

Global (LAB) symmetry

$$\mathbf{i}_3 |_{eb}^{(m)}\rangle = \mathbf{i}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = (-1)^e |^{(m)}\rangle$$

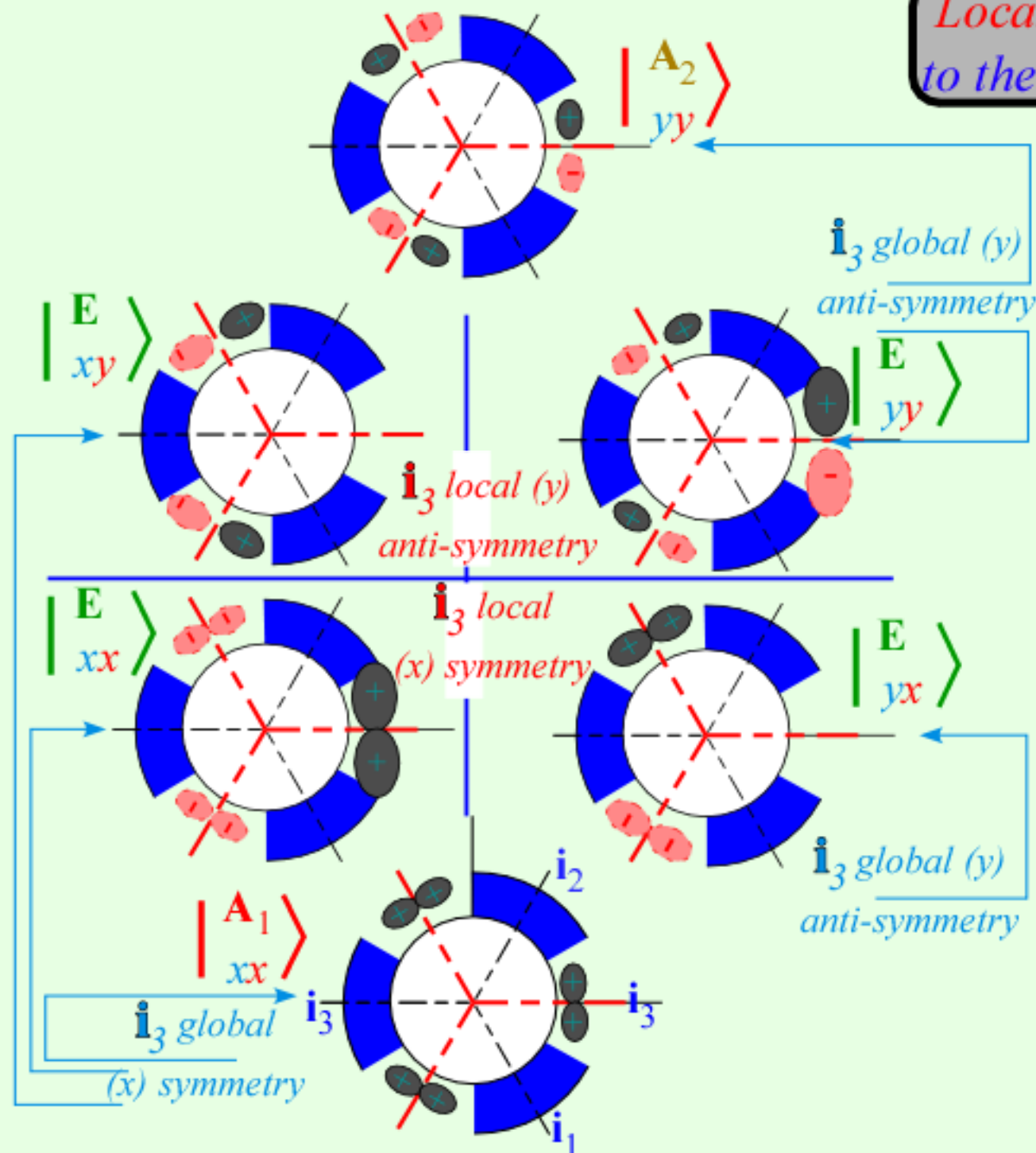
$D_3 > C_2$ \mathbf{i}_3 projector states

$$|_{eb}^{(m)}\rangle = \mathbf{P}_{eb}^{(m)} |1\rangle$$

Local (BOD) symmetry

$$\bar{\mathbf{i}}_3 |_{eb}^{(m)}\rangle = \bar{\mathbf{i}}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = \mathbf{P}_{eb}^{(m)} \bar{\mathbf{i}}_3 |1\rangle = \mathbf{P}_{eb}^{(m)} \mathbf{i}_3^\dagger |1\rangle = (-1)^b |^{(m)}\rangle$$

Local $\bar{\mathbf{g}}$ commute through to the "inside" to be a \mathbf{g}^\dagger



$$\mathbf{P}_{y,y}^{A_2} = \frac{1 \ r^1 \ r^2 \ i_1 \ i_2 \ i_3}{(1 \ 1 \ 1 \ -1 \ -1 \ -1)/6}$$

$$\mathbf{P}_{x,y}^E = (0 \ -1 \ 1 \ -1 \ +1 \ 0)/\sqrt{3/2}$$

$$\mathbf{P}_{y,y}^E = (2 \ -1 \ -1 \ +1 \ +1 \ -2)/6$$

$$\mathbf{P}_{x,x}^E = (2 \ -1 \ -1 \ -1 \ -1 \ +2)/6$$

$$\mathbf{P}_{y,x}^E = (0 \ 1 \ -1 \ -1 \ +1 \ 0)/\sqrt{3/2}$$

$$\mathbf{P}_{x,x}^{A_1} = (1 \ 1 \ 1 \ 1 \ 1 \ 1)/6$$

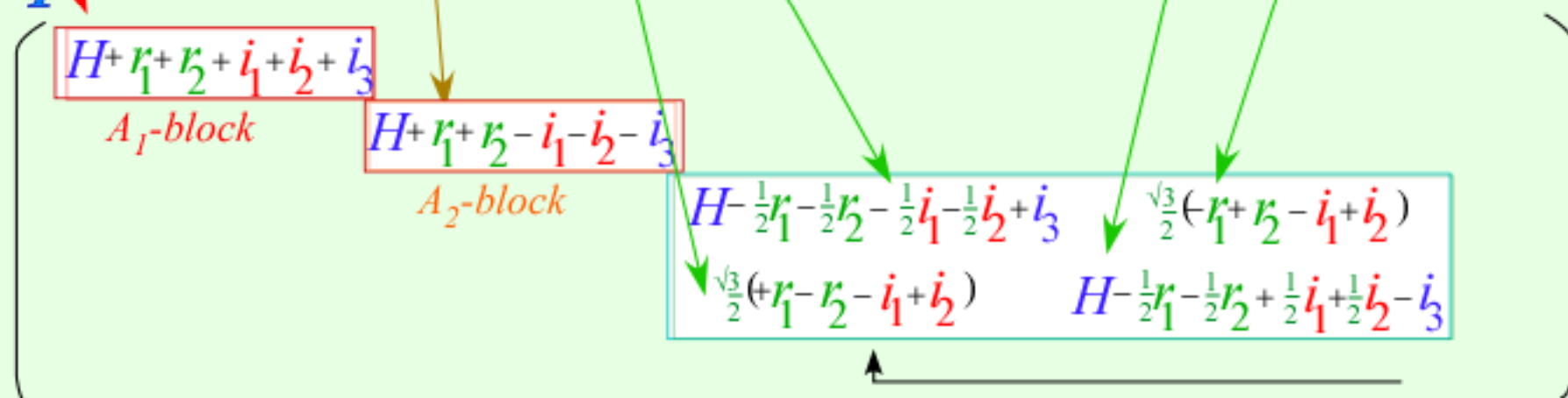
$$\mathbf{P}_{mn}^{(\alpha)} = \frac{\ell^{(\alpha)}}{G} \sum_{\mathbf{g}} D_{mn}^{(\alpha)*}(\mathbf{g}) \mathbf{g}$$

Spectral Efficiency: Same $D(a)mn$ projectors give a lot!

$$\begin{array}{c} \mathbf{1} \quad \mathbf{r}^1 \quad \mathbf{r}^2 \quad \mathbf{i}_1 \quad \mathbf{i}_2 \quad \mathbf{i}_3 \\ \mathbf{P}_{x,x}^{A_1} = (1 \ 1 \ 1 \ 1 \ 1 \ 1)/6 \\ \mathbf{P}_{y,y}^{A_2} = (1 \ 1 \ 1 \ -1 \ -1 \ -1)/6 \end{array}$$

$$\begin{array}{c} \mathbf{1} \quad \mathbf{r}^1 \quad \mathbf{r}^2 \quad \mathbf{i}_1 \quad \mathbf{i}_2 \quad \mathbf{i}_3 \\ \mathbf{P}_{x,x}^E = (2 \ -1 \ -1 \ -1 \ -1 \ +2)/6 \\ \mathbf{P}_{y,x}^E = (0 \ 1 \ -1 \ -1 \ +1 \ 0)/\sqrt{3/2} \end{array} \quad \begin{array}{c} \mathbf{1} \quad \mathbf{r}^1 \quad \mathbf{r}^2 \quad \mathbf{i}_1 \quad \mathbf{i}_2 \quad \mathbf{i}_3 \\ \mathbf{P}_{x,y}^E = (0 \ -1 \ 1 \ -1 \ +1 \ 0)/\sqrt{3/2} \\ \mathbf{P}_{y,y}^E = (2 \ -1 \ -1 \ +1 \ +1 \ -2)/6 \end{array}$$

- Eigenstates (previous slide)
- Complete Hamiltonian



- Local symmetry eigenvalue formulae (L.S. => off-diagonal zero.)

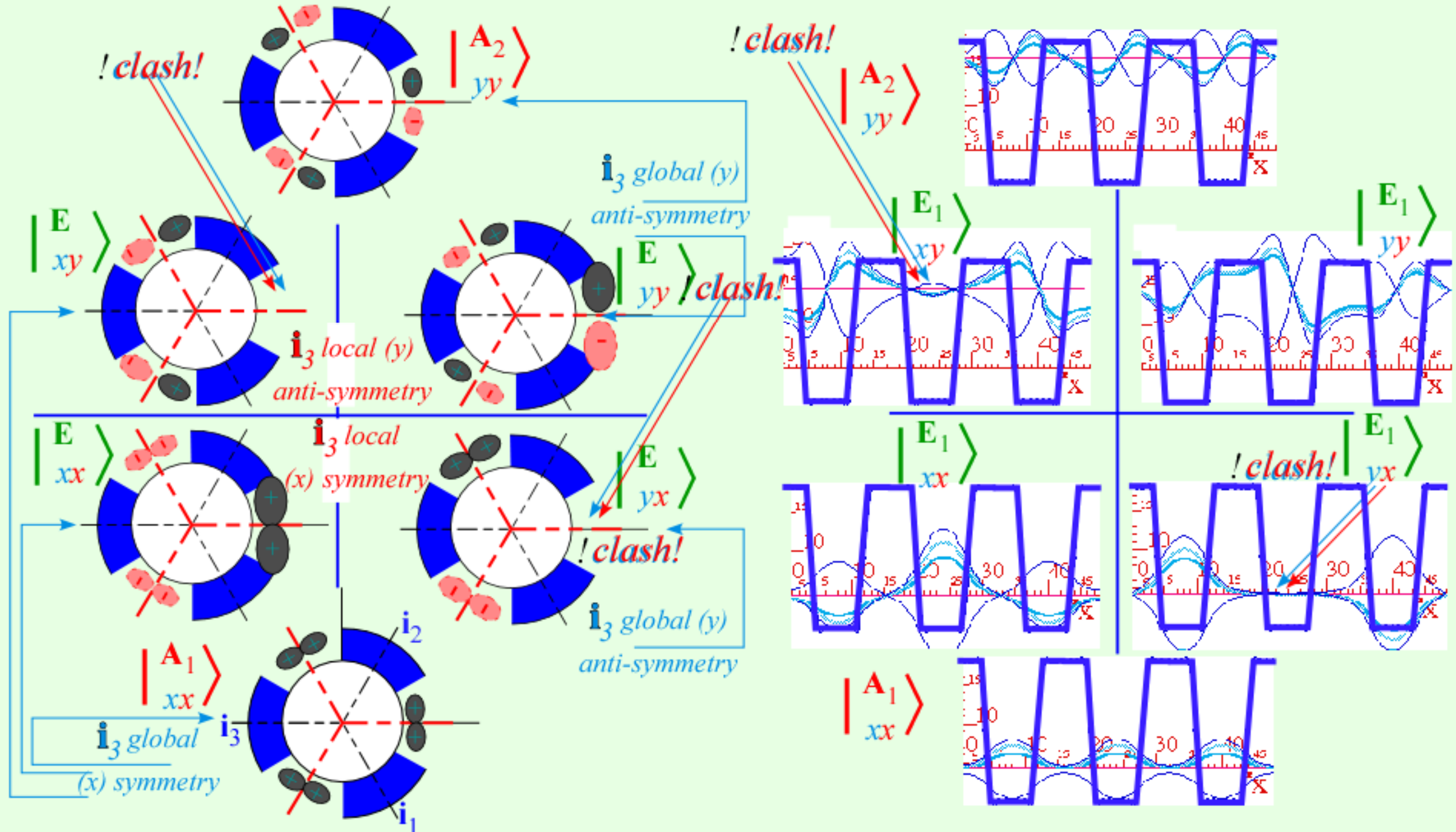
$$r_1 = r_2 = -r_1^* = r, \quad i_1 = i_2 = -i_1^* = i$$

gives:


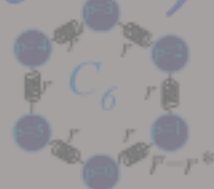
- A_1 -level: $H + 2r + 2i + i_3$
- A_1 -level: $H + 2r - 2i - i_3$
- E_x -level: $H - r - i + i_3$
- E_y -level: $H - r + i - i_3$

When there is no there, there...

Nobody Home
where LOCAL
and GLOBAL



(Commuting)

- **Abelian symmetry = Fourier analysis** (Back to our roots $1^{1/N} = e^{2\pi im/N}$)
 Group $\hat{\Lambda}$ product table \Rightarrow Hamiltonian \mathbf{H} -matrices (C_2 and C_6 examples)  C_2  C_6
 Group roots \Rightarrow \mathbf{H} -matrix spectral resolution by $P^{(m)}$ projectors

Commutivity conundrum...

? $\mathbf{H} \cdot \mathbf{g} = \mathbf{g} \cdot \mathbf{H}$?

- **New symmetry insights:** Local vs. Global symmetry Projector invariance
 "Mock-Mach" principle Conway, et.al, May (2008) Cvitanovic, (2008)

(Non-Commuting)

- **Non-Abelian symmetry analysis I.** (Simplest example: D_3) 

Local vs. Global $\hat{\Lambda}$ product tables \Rightarrow \mathbf{H} -matrices

All-commuting invariants \Rightarrow Global invariant (character) $P^{(\alpha)}$ projectors

Mutually-commuting sets \Rightarrow Local vs. Global eigensolutions by $P_{m,n}^{(\alpha)}$ projectors

\Rightarrow \mathbf{H} -matrix spectral resolution by $P_{m,n}^{(\alpha)}$ projectors

- **Non-Abelian symmetry analysis II.** (Octahedral example: O_h) 

Global-local product tables \Rightarrow \mathbf{H} -matrices...

... and all the above ...

\Rightarrow eigensolution formulas by local-symmetry defined $P_{n,n}^{(\alpha)}$ projectors 

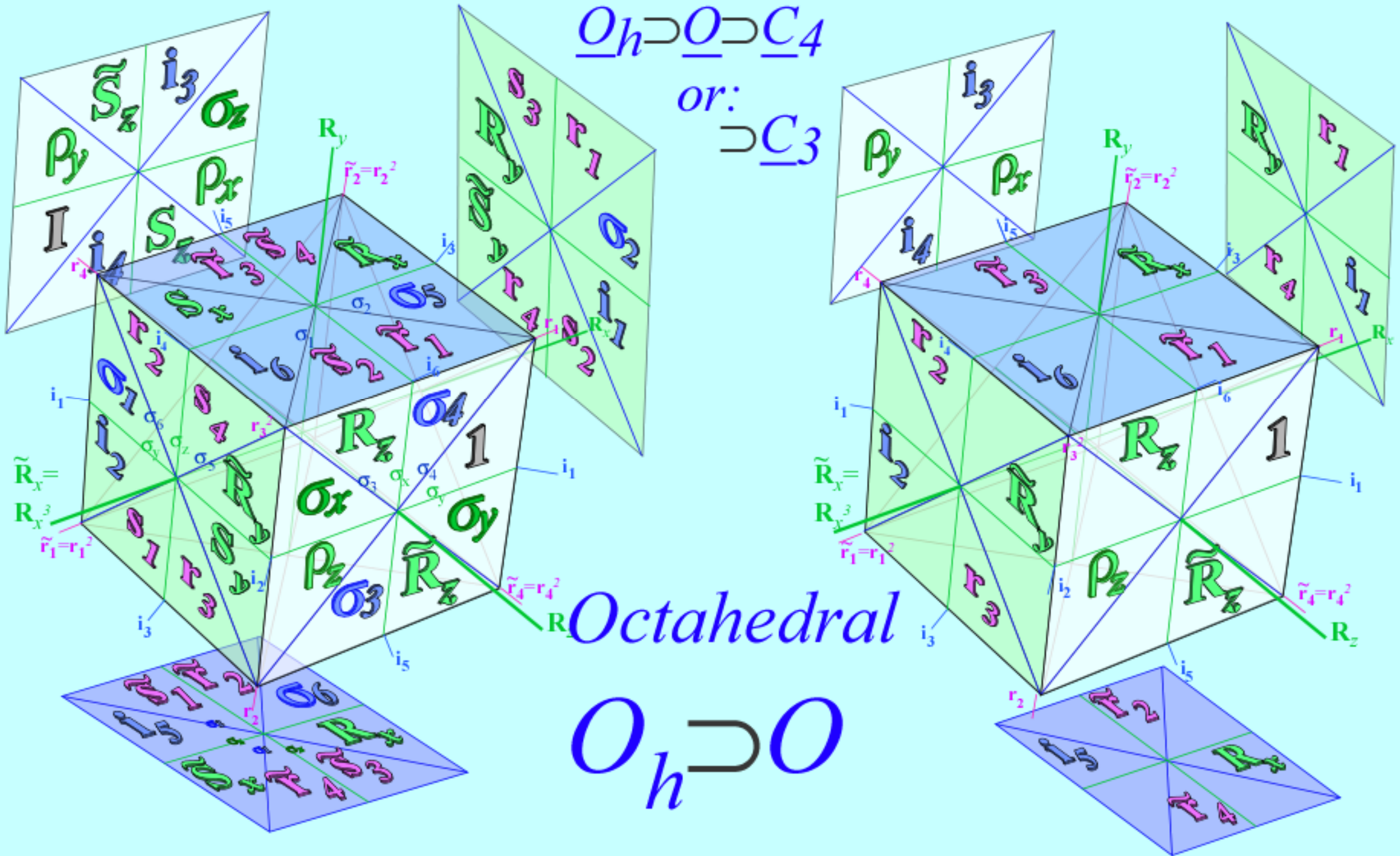
- **Local vs Global symmetry in rovibronic phase space** 

How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples)

Example of GLOBAL vs LOCAL projector algebra for

$$\underline{O}_h \supset \underline{O} \supset \underline{C}_4$$

or:
 $\supset \underline{C}_3$



Octahedral

$$O_h \supset O$$

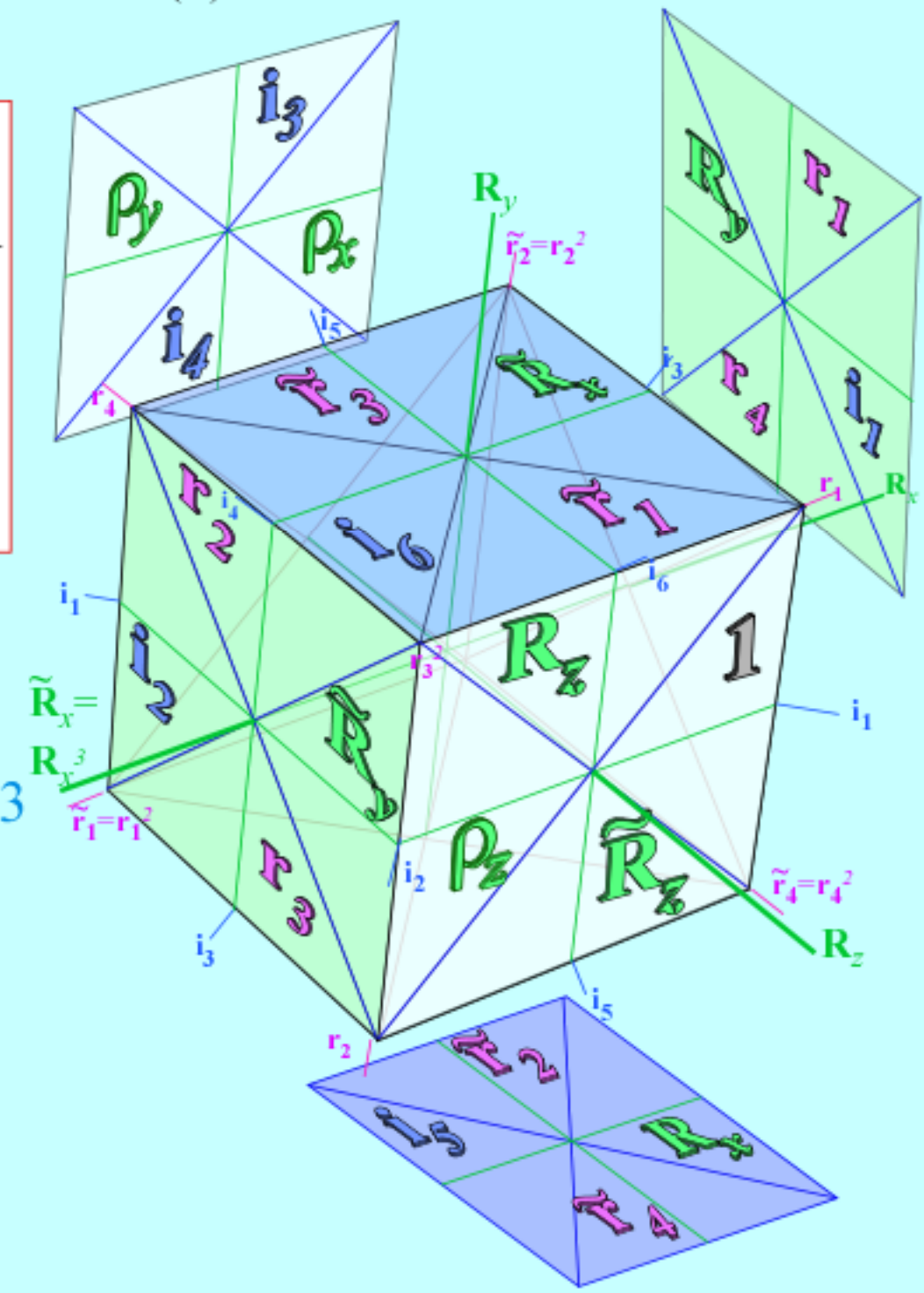
$$\begin{aligned} \ell^{A_1} &= 1 \\ \ell^{A_2} &= 1 \\ \ell^E &= 2 \\ \ell^{T_1} &= 3 \\ \ell^{T_2} &= 3 \end{aligned}$$

Example: $G=O$ Centrum: $\kappa(O) = \sum_{(\alpha)} (\ell^\alpha)^0 = 1^0 + 1^0 + 2^0 + 3^0 + 3^0 = 5$
Cubic-Octahedral Group O

Rank: $\rho(O) = \sum_{(\alpha)} (\ell^\alpha)^1 = 1^1 + 1^1 + 2^1 + 3^1 + 3^1 = 10$

Order: $o(O) = \sum_{(\alpha)} (\ell^\alpha)^2 = 1^2 + 1^2 + 2^2 + 3^2 + 3^2 = 24$

O group	$g = 1$	r_{1-4}	ρ_{xyz}	R_{xyz}	i_{1-6}
$\chi_{\kappa_g}^\alpha$		\tilde{r}_{1-4}		\tilde{R}_{xyz}	
$\alpha = A_1$ <i>s-orbital r^2</i>	1	1	1	1	1
A_2 <i>d-orbitals</i>	1	1	1	-1	-1
E $\{x^2+y^2-2z^2, x^2-y^2\}$ <i>d-orbitals</i>	2	-1	2	0	0
T_1 $\{x, y, z\}$ <i>p-orbitals</i>	3	0	-1	1	-1
T_2 $\{xz, yz, xy\}$ <i>d-orbitals</i>	3	0	-1	-1	1

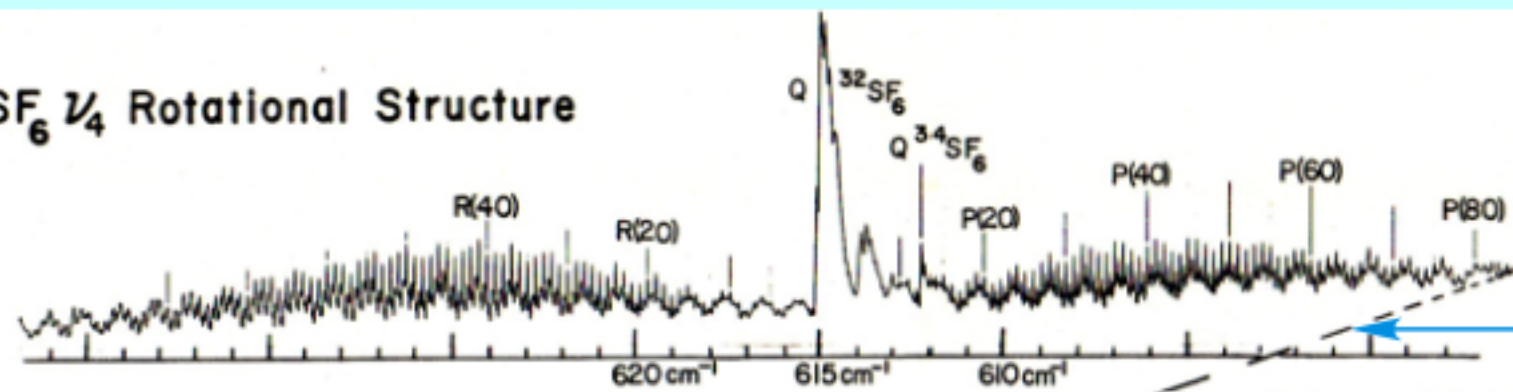


$O \supset C_4$ $(0)_4 (1)_4 (2)_4 (3)_4 = (-1)_4$ $O \supset C_3$ $(0)_3 (1)_3 (2)_3 = (-1)_3$

A_1	1	•	•	•
A_2	•	•	1	•
E	1	•	1	•
T_1	1	1	•	1
T_2	•	1	1	1

A_1	1	•	•
A_2	1	•	•
E	•	1	1
T_1	1	1	1
T_2	1	1	1

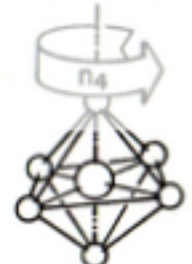
(a) SF₆ ν₄ Rotational Structure



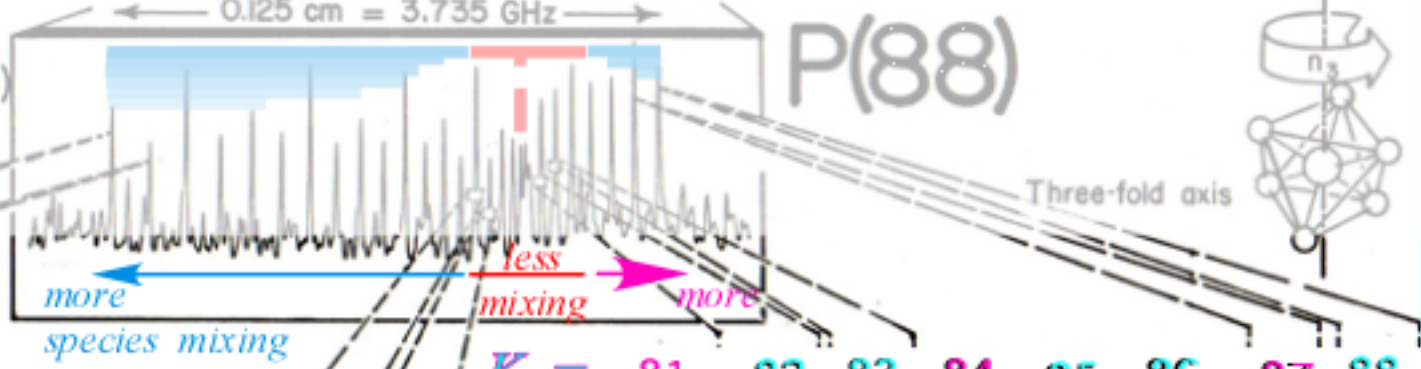
FT IR and Laser Diode Spectra
K.C. Kim, W.B. Person, D. Seitz, and B.J. Krohn
J. Mol. Spectrosc. 76, 322 (1979).

Primary AET species mixing increases with distance from "separatrix"

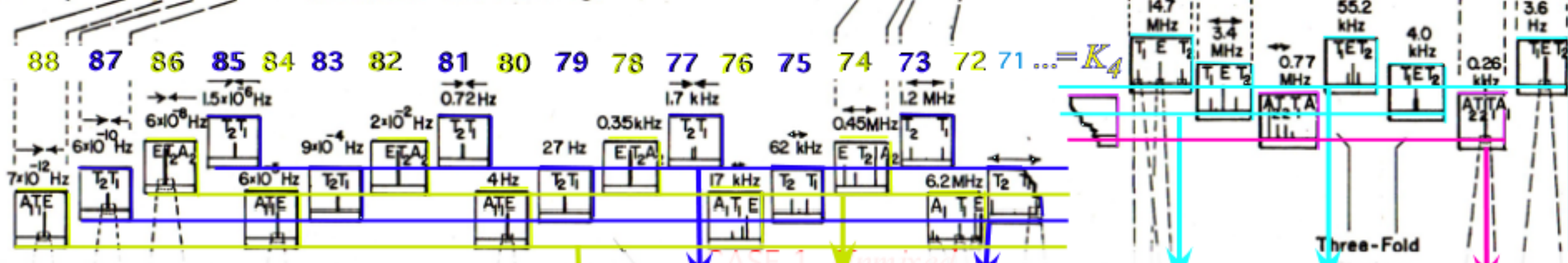
(b) P(88) Fine Structure (Rotational anisotropy effects)



SF₆ ν₃ P(88) ~ 16m



(c) Superfine Structure (Rotational axis tunneling)



Observed repeating sequence(s) .. A₁ T₁ E T₂ T₁ E T₂ A₂ T₂ T₁ A₁ T₁ E T₂ T₁ E T₂ A₂ T₂ T₁ A₁ ..

$O=C_4$ (0)₄ (1)₄ (2)₄ (3)₄ = (-1)₄

A ₁	1	•	•	•
A ₂	•	•	1	•
E	1	•	1	•
T ₁	1	1	•	1
T ₂	•	1	1	1

$O=C_3$ (0)₃ (1)₃ (2)₃ = (-1)₃

A ₁	1	•	•
A ₂	1	•	•
E	•	1	1
T ₁	1	1	1
T ₂	1	1	1

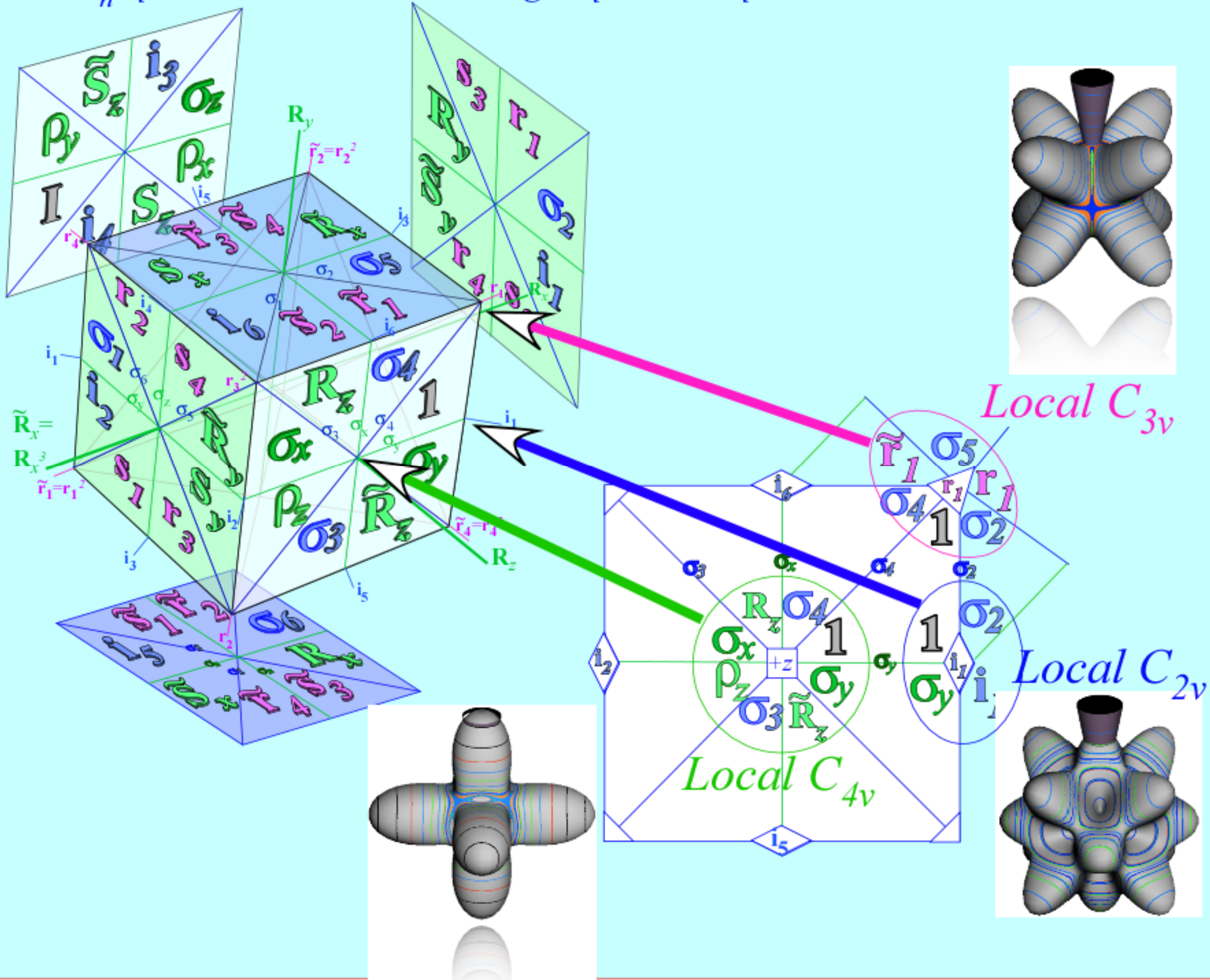
Local correlations explain clustering...
... but what about spacing and ordering?...

...and physical consequences?

Major mixing lowest two LUSTERS

(e) Superfine Structure on Correlation Frame

O_h operator slide rule and subgroup / coset-space structure



C_4 subgroup correlation to O (largest local symmetry \Rightarrow smallest level-clusters)

$O \supset C_4$

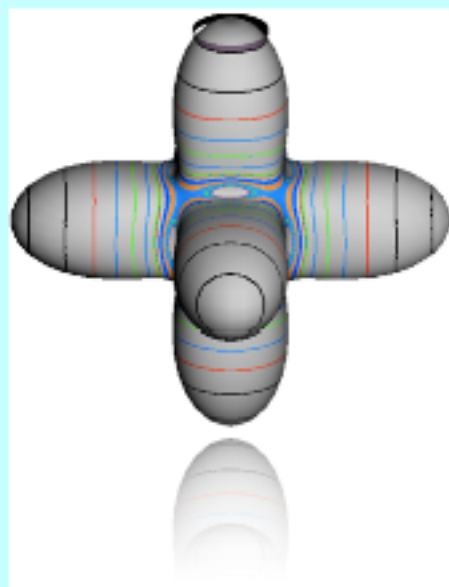
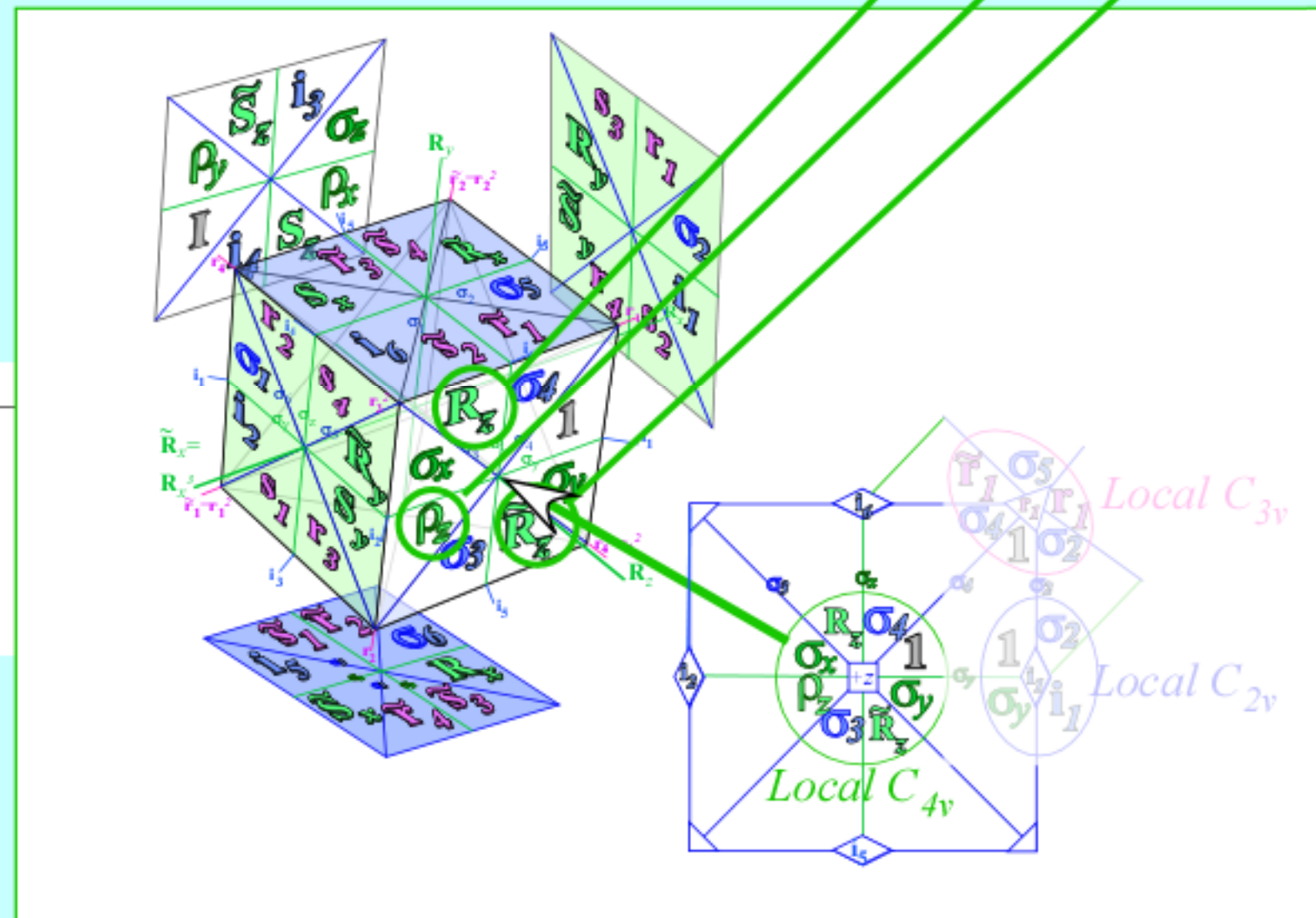
C_4 Projectors to split octahedral P^α

$(0)_4 \quad (1)_4 \quad (2)_4 \quad (3)_4 = (-1)_4$

A_1	1	•	•	•
A_2	•	•	1	•
E	1	•	1	•
T_1	1	1	•	1
T_2	•	1	1	1

$$P_{m_4} = \sum_{p=0}^3 \frac{e^{2\pi i m \cdot p/4}}{4} R_z^p = \begin{cases} P_{0_4} = (1 + R_z + \rho_z + \tilde{R}_z)/4 \\ P_{1_4} = (1 + iR_z - \rho_z - i\tilde{R}_z)/4 \\ P_{2_4} = (1 - R_z + \rho_z - \tilde{R}_z)/4 \\ P_{3_4} = (1 - iR_z - \rho_z + i\tilde{R}_z)/4 \end{cases}$$

$1 \cdot P^\alpha =$	$(P_{0_4} + P_{1_4} + P_{2_4} + P_{3_4}) \cdot P^\alpha$
$1 \cdot P^{A_1} = P_{0_4 0_4}^{A_1}$	+0 +0 +0 +0
$1 \cdot P^{A_2} = 0$	+0 + $P_{2_4 2_4}^{A_2}$ +0
$1 \cdot P^E = P_{0_4 0_4}^E$	+0 + $P_{2_4 2_4}^E$ +0
$1 \cdot P^{T_1} = P_{0_4 0_4}^{T_1}$	+ $P_{1_4 1_4}^{T_1}$ +0 + $P_{3_4 3_4}^{T_1}$
$1 \cdot P^{T_2} = 0$	+ $P_{1_4 1_4}^{T_2}$ + $P_{2_4 2_4}^{T_2}$ + $P_{3_4 3_4}^{T_2}$



largest local symmetry $C_4 \Rightarrow$ smallest level-clusters (6-levels)

C_4 subgroup correlation to O

$O \supset C_4$ $(0)_4$ $(1)_4$ $(2)_4$ $(3)_4 = (-1)_4$

A_1	1	•	•	•
A_2	•	•	1	•
E	1	•	1	•
T_1	1	1	•	1
T_2	•	1	1	1

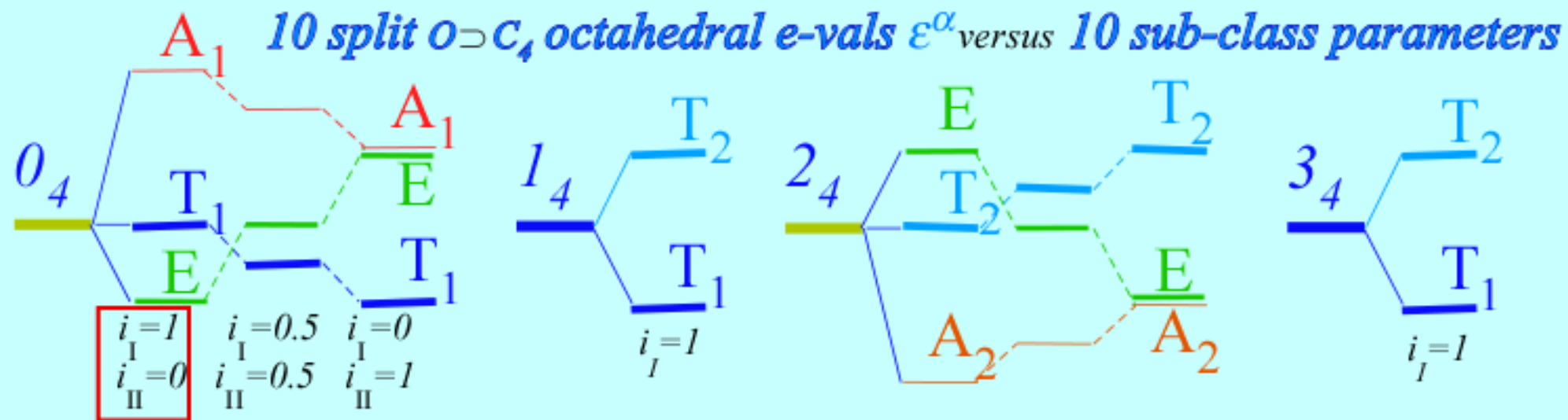
C_4 Projectors to split octahedral P^α

$$P_{m_4} = \sum_{p=0}^3 \frac{e^{2\pi i m \cdot p/4}}{4} R_z^p = \begin{cases} P_{0_4} = (1 + R_z + \rho_z + \tilde{R}_z)/4 \\ P_{1_4} = (1 + iR_z - \rho_z - i\tilde{R}_z)/4 \\ P_{2_4} = (1 - R_z + \rho_z - \tilde{R}_z)/4 \\ P_{3_4} = (1 - iR_z - \rho_z + i\tilde{R}_z)/4 \end{cases}$$

$1 \cdot P^\alpha =$	$(P_{0_4} + P_{1_4} + P_{2_4} + P_{3_4}) \cdot P^\alpha$
$1 \cdot P^{A_1} =$	$P_{0_4 0_4}^{A_1} + 0 + 0 + 0$
$1 \cdot P^{A_2} =$	$0 + 0 + P_{2_4 2_4}^{A_2} + 0$
$1 \cdot P^E =$	$P_{0_4 0_4}^E + 0 + P_{2_4 2_4}^E + 0$
$1 \cdot P^{T_1} =$	$P_{0_4 0_4}^{T_1} + P_{1_4 1_4}^{T_1} + 0 + P_{3_4 3_4}^{T_1}$
$1 \cdot P^{T_2} =$	$0 + P_{1_4 1_4}^{T_2} + P_{2_4 2_4}^{T_2} + P_{3_4 3_4}^{T_2}$

10 split $O \supset C_4$ octahedral P^α related to 10 split sub-classes

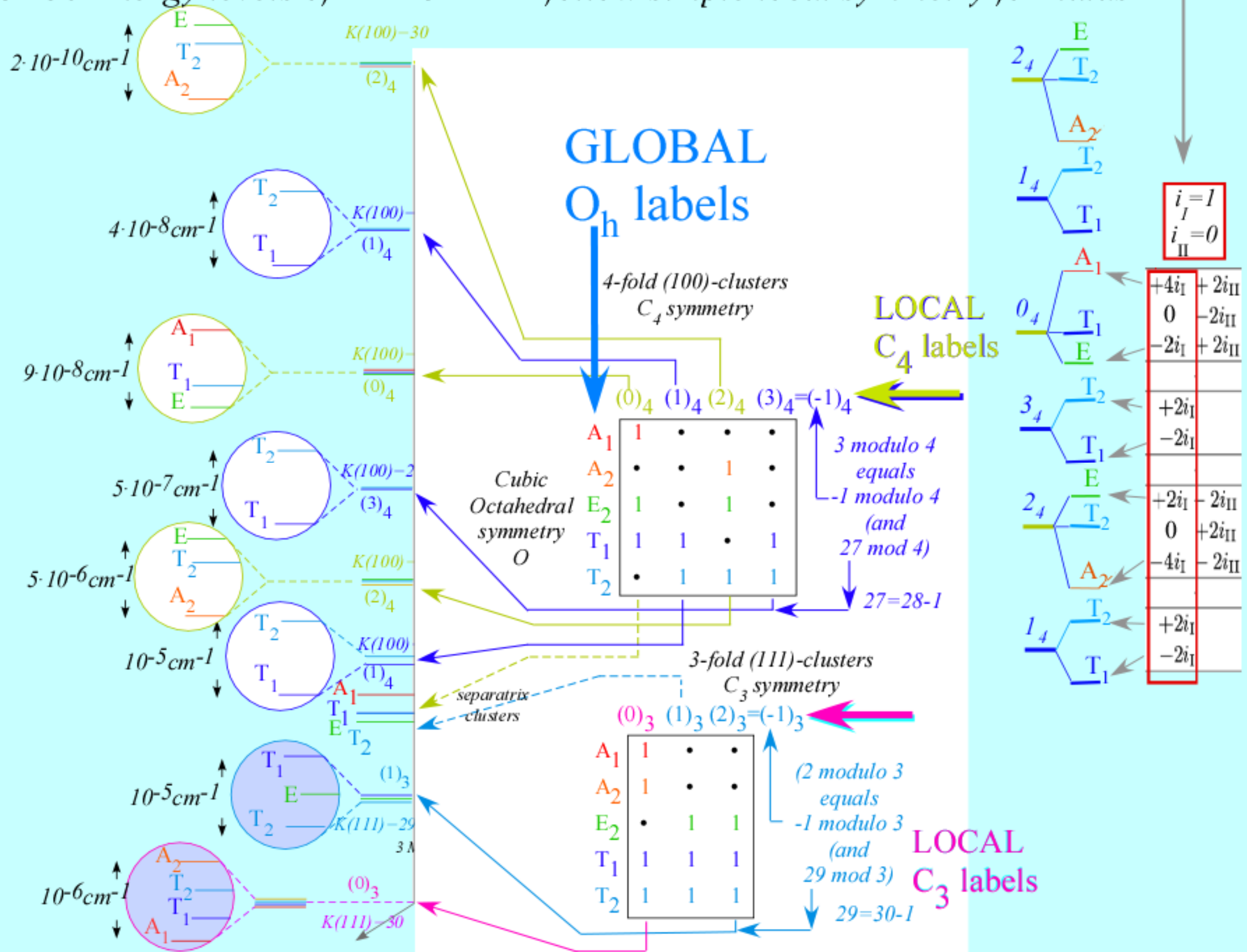
$P_{n_4 n_4}^{(\alpha)} (O \supset C_4)$	1	$r_1 r_2 \tilde{r}_3 \tilde{r}_4$	$\tilde{r}_1 \tilde{r}_2 r_3 r_4$	$\rho_x \rho_y$	ρ_z	$R_x \tilde{R}_x R_y \tilde{R}_y$	R_z	\tilde{R}_z	$i_1 i_2 i_5 i_6$	$i_3 i_4$
$24 \cdot P_{0_4 0_4}^{A_1}$	1	1	1	1	1	1	1	1	1	1
$24 \cdot P_{2_4 2_4}^{A_2}$	1	1	1	1	1	-1	-1	-1	-1	-1
$12 \cdot P_{0_4 0_4}^E$	1	$-\frac{1}{2}$	$-\frac{1}{2}$	1	1	$-\frac{1}{2}$	1	1	$-\frac{1}{2}$	1
$12 \cdot P_{2_4 2_4}^E$	1	$-\frac{1}{2}$	$-\frac{1}{2}$	1	1	$+\frac{1}{2}$	-1	-1	$+\frac{1}{2}$	-1
$8 \cdot P_{1_4 1_4}^{T_1}$	1	$-\frac{i}{2}$	$+\frac{i}{2}$	0	-1	$+\frac{1}{2}$	-i	+i	$-\frac{1}{2}$	0
$8 \cdot P_{3_4 3_4}^{T_1}$	1	$+\frac{i}{2}$	$-\frac{i}{2}$	0	-1	$+\frac{1}{2}$	+i	-i	$-\frac{1}{2}$	0
$8 \cdot P_{0_4 0_4}^{T_1}$	1	0	0	-1	1	0	1	1	0	-1
$8 \cdot P_{1_4 1_4}^{T_2}$	1	$+\frac{i}{2}$	$-\frac{i}{2}$	0	-1	$-\frac{1}{2}$	-i	+i	$+\frac{1}{2}$	0
$8 \cdot P_{3_4 3_4}^{T_2}$	1	$-\frac{i}{2}$	$+\frac{i}{2}$	0	-1	$-\frac{1}{2}$	+i	-i	$+\frac{1}{2}$	0
$8 \cdot P_{2_4 2_4}^{T_2}$	1	0	0	-1	1	0	-1	-1	0	1




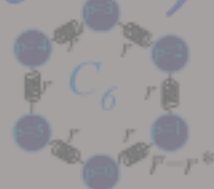
Sequence if $i_I = i_{1256}$ only non-zero parameter: $A_1 T_1 E T_2 T_1 E T_2 A_2 T_2 T_1$

$O \supset C_4$	0°	$r_n 120^\circ$	$\rho_n 180^\circ$	$R_n 90^\circ$	$i_n 180^\circ$
0_4	.	$r_I = \text{Re } r_{1234}$ $m_I = \text{Im } r_{1234}$.	$R_z = \text{Re } R_z$ $I_z = \text{Im } R_z$	$i_I = i_{1256}$ $i_{II} = i_{34}$
$\epsilon_{0_4}^{A_1} =$	g_0	$+4r_I$	$+2\rho_{xy} + \rho_z$	$+4R_{xy} + 2R_z$	$+4i_I + 2i_{II}$
$\epsilon_{0_4}^{T_1}$	g_0	0	$-2\rho_{xy} + \rho_z$	$+2R_z$	0
$\epsilon_{0_4}^E$	g_0	$-2r_I$	$+2\rho_{xy} + \rho_z$	$-2R_{xy} - R_z$	$-2i_I + 2i_{II}$
1_4
$\epsilon_{1_4}^{T_2}$	g_0	$+2m_I$	$-\rho_z$	$-R_{xy} - 2I_z$	$+2i_I$
$\epsilon_{1_4}^{T_1}$	g_0	$-2m_I$	$-\rho_z$	$+R_{xy} - 2I_z$	$-2i_I$
2_4
$\epsilon_{2_4}^E$	g_0	$-2r_I$	$+2\rho_{xy} + \rho_z$	$+2R_{xy} - R_z$	$+2i_I - 2i_{II}$
$\epsilon_{2_4}^{T_2}$	g_0	0	$-2\rho_{xy} + \rho_z$	$-2R_z$	0
$\epsilon_{2_4}^{A_2}$	g_0	$+4r_I$	$+2\rho_{xy} + \rho_z$	$-4R_{xy} - 2R_z$	$-4i_I - 2i_{II}$
3_4
$\epsilon_{3_4}^{T_2}$	g_0	$-2m_I$	$-\rho_z$	$-R_{xy} + 2I_z$	$+2i_I$
$\epsilon_{3_4}^{T_1}$	g_0	$+2m_I$	$-\rho_z$	$+R_{xy} + 2I_z$	$-2i_I$

$J=30$ Energy levels of $\mathbf{H} = B\mathbf{J}^2 + \mathbf{T}^{[4]}$ follow simple local symmetry formulas



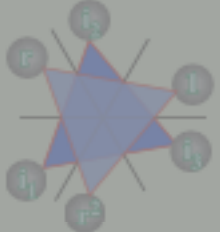
(Commuting)

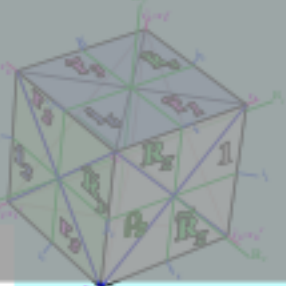
- **Abelian symmetry = Fourier analysis** (Back to our roots $1^{1/N} = e^{2\pi im/N}$)
 Group \hat{P} product table \Rightarrow Hamiltonian \mathbf{H} -matrices (C_2 and C_6 examples)  
 Group roots \Rightarrow \mathbf{H} -matrix spectral resolution by $P^{(m)}$ projectors

Commutivity conundrum... ? $\mathbf{H} \cdot g = g \cdot \mathbf{H}$?

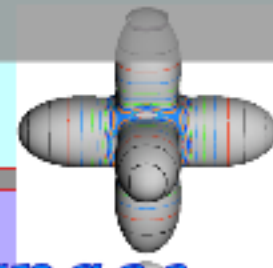
- **New symmetry insights:** Local vs. Global symmetry Projector invariance
 "Mock-Mach" principle Conway, et.al, May (2008) Cvitanovic, (2008)

(Non-Commuting)

- **Non-Abelian symmetry analysis I.** (Simplest example: D_3) 
 Local vs. Global \hat{P} product tables \Rightarrow \mathbf{H} -matrices
 All-commuting invariants \Rightarrow Global invariant (character) $P^{(\alpha)}$ projectors
 Mutually-commuting sets \Rightarrow Local vs. Global eigensolutions by $P_{m,n}^{(\alpha)}$ projectors
 \Rightarrow \mathbf{H} -matrix spectral resolution by $P_{m,n}^{(\alpha)}$ projectors

- **Non-Abelian symmetry analysis II.** (Octahedral example: O_h) 
 Global-local product tables \Rightarrow \mathbf{H} -matrices...
 ... and all the above ...

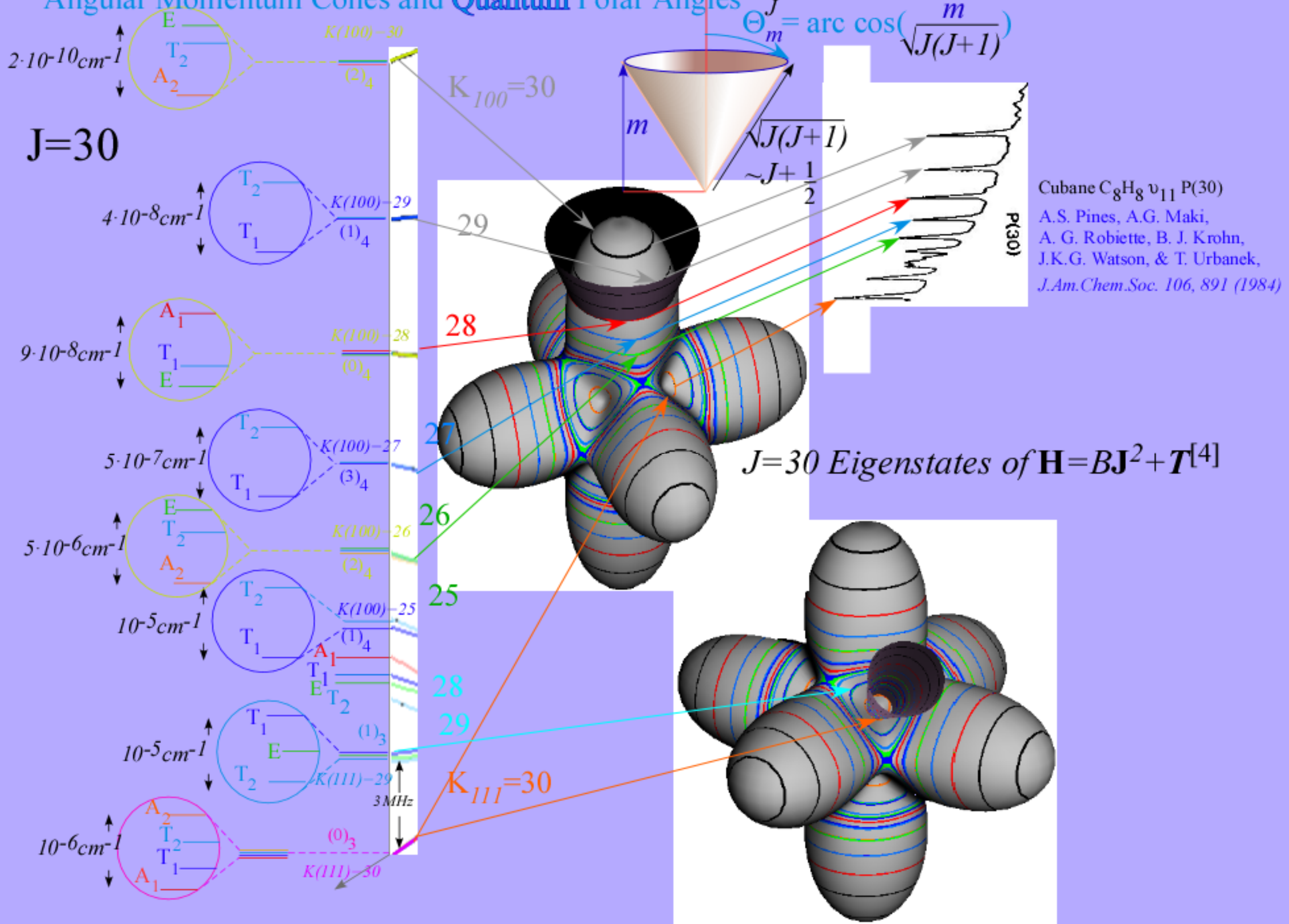
\Rightarrow eigensolution formulas by local-symmetry defined $P_{n,n}^{(\alpha)}$ projectors



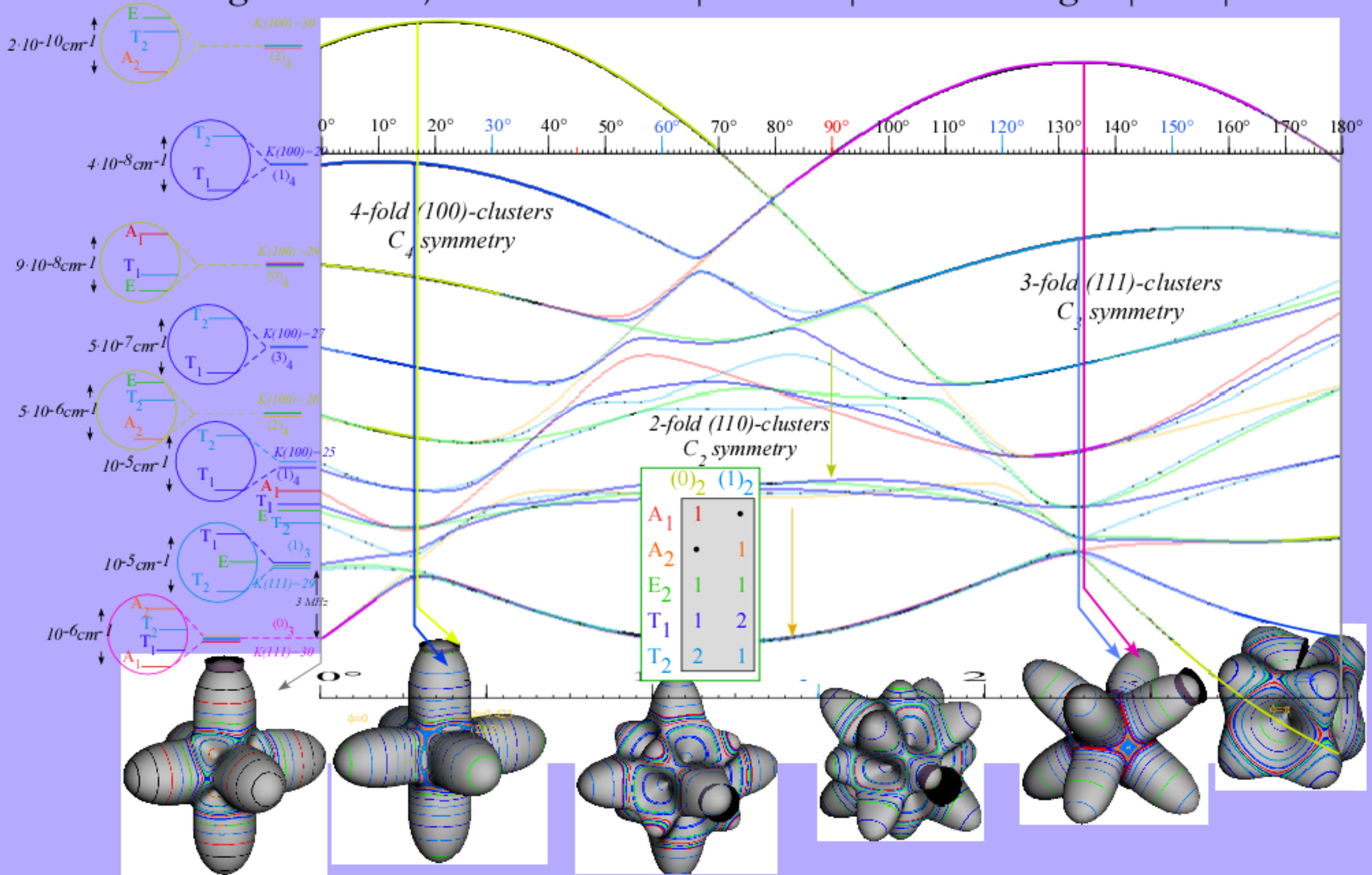
- **Local vs Global symmetry in rovibronic phase space**

How group operators analyze rovibronic tunneling effects at high J . (SF_6 examples) 

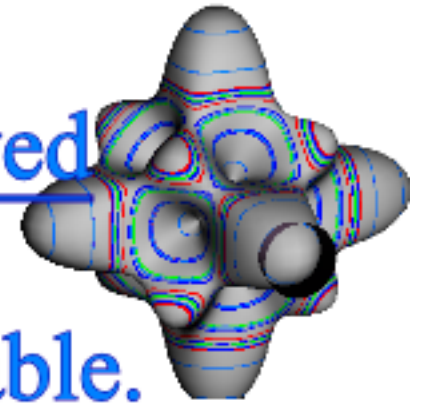
Angular Momentum Cones and Quantum Polar Angles



Eigenvalues of $\mathbf{H} = B\mathbf{J}^2 + \cos\phi\mathbf{T}^{[4]} + \sin\phi\mathbf{T}^{[6]}$ vs. mix angle $\phi: 0 < \phi < \pi$



Conclusion: H-matrix symmetry analysis greatly improved



Group space tunneling matrix defined nicely by group table.

Each tunneling path matched to group element (complete set of Feynman paths!)

When local symmetry conditions apply:

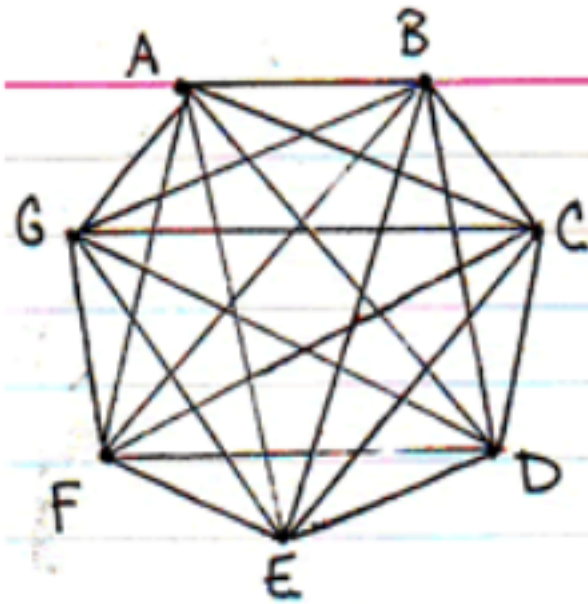
- Spectral algebra yields closed-form energies and states (using same table!) .
- Expressions easily deconvoluted (same table , again!) .

Transitions between local symmetries clearly defined.

We can now do a D_7 example (Next slide :.)

Seven-Deadly-Sin Tunneling Theory

$D_7 \supset C_7$ **sin** calculator...(not recommended)



A = Lust

B = Gluttony

C = Greed

D = Sloth

E = Wrath

F = Envy

G = Pride

\overline{AB} = Edible Undies

\overline{AC} = Prostitution

\overline{AD} = Quickie

\overline{AE} = Domestic Abuse

\overline{AF} = Adultery

\overline{AG} = Trophy Wife

\overline{BC} = Last Donut

\overline{BD} = Saturday

\overline{BE} = Bulimia

\overline{BF} = High Metabolism

\overline{BG} = Fat men in Speedos

\overline{CD} = Get Rich Quick Scams

\overline{CE} = Muggings

\overline{CF} = Advertising

\overline{CG} = Status Symbols

\overline{DE} = Passive Aggression

\overline{DF} = Welfare

\overline{DG} = Slackers

\overline{EF} = Cattiness

\overline{EG} = Boxing

\overline{GF} = 2nd Place

Effects of broken or transition local symmetry for i -class

$$D_{0_4 0_4}^{A_1}(i_k \mathbf{i}_k) = i_1 + i_2 + i_3 + i_4 + i_5 + i_6$$

$$D_{2_4 2_4}^{A_2}(i_k \mathbf{i}_k) = -(i_1 + i_2 + i_3 + i_4 + i_5 + i_6)$$

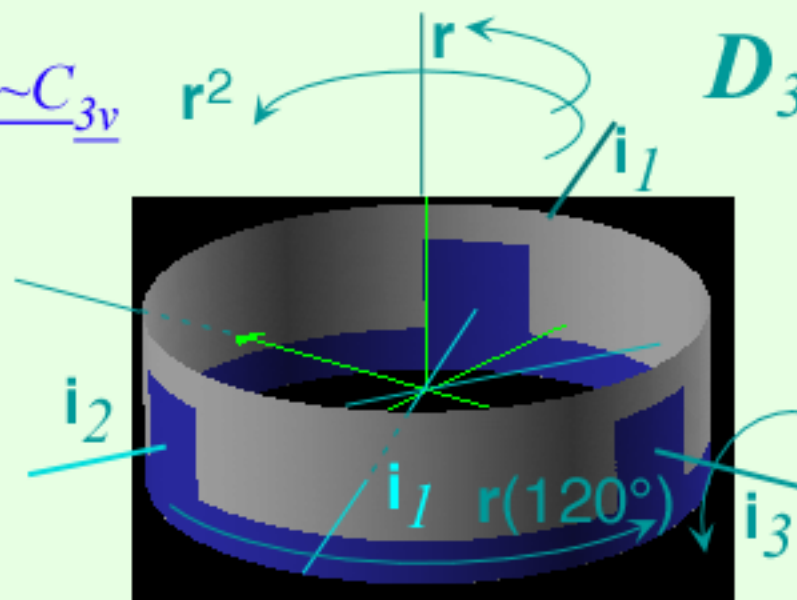
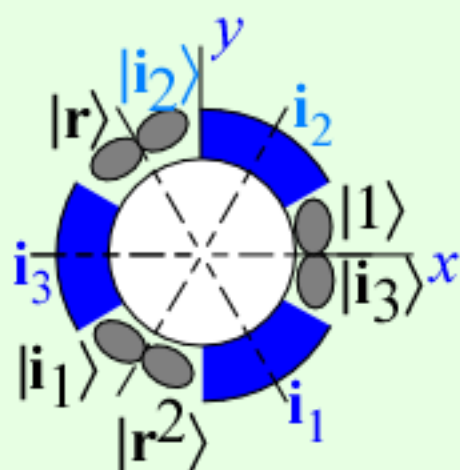
$$D^E(i_k \mathbf{i}_k) = \begin{array}{c|cc} & 0_4 & 2_4 \\ \hline 0_4 & -\frac{1}{2}(i_1 + i_2 + i_5 + i_6) + i_3 + i_4 & \frac{\sqrt{3}}{2}(i_1 + i_2 - i_5 - i_6) \\ 2_4 & h.c. & \frac{1}{2}(i_1 + i_2 + i_5 + i_6) - i_3 - i_4 \end{array}$$

$$D^{T_1^*}(i_k \mathbf{i}_k) = \begin{array}{c|ccc} & 1_4 & 3_4 & 0_4 \\ \hline 1_4 & -\frac{1}{2}(i_1 + i_2 + i_5 + i_6) & -\frac{1}{2}(i_1 + i_2 - i_5 - i_6) - i(i_3 - i_4) & -\frac{1}{\sqrt{2}}(i_1 - i_2) + \frac{i}{\sqrt{2}}(i_5 - i_6) \\ 3_4 & h.c. & -\frac{1}{2}(i_1 + i_2 + i_5 + i_6) & +\frac{1}{\sqrt{2}}(i_1 - i_2) + \frac{i}{\sqrt{2}}(i_5 - i_6) \\ 0_4 & h.c. & h.c. & -(i_3 + i_4) \end{array}$$

$$D^{T_2^*}(i_k \mathbf{i}_k) = \begin{array}{c|ccc} & 1_4 & 3_4 & 2_4 \\ \hline 1_4 & +\frac{1}{2}(i_1 + i_2 + i_5 + i_6) & +\frac{1}{2}(i_1 + i_2 - i_5 - i_6) - i(i_3 - i_4) & +\frac{1}{\sqrt{2}}(i_1 - i_2) + \frac{i}{\sqrt{2}}(i_5 - i_6) \\ 3_4 & h.c. & +\frac{1}{2}(i_1 + i_2 + i_5 + i_6) & -\frac{1}{\sqrt{2}}(i_1 - i_2) + \frac{i}{\sqrt{2}}(i_5 - i_6) \\ 0_4 & h.c. & h.c. & +(i_3 + i_4) \end{array}$$

Example of RELATIVITY-DUALITY for $D_3 \sim C_{3v}$

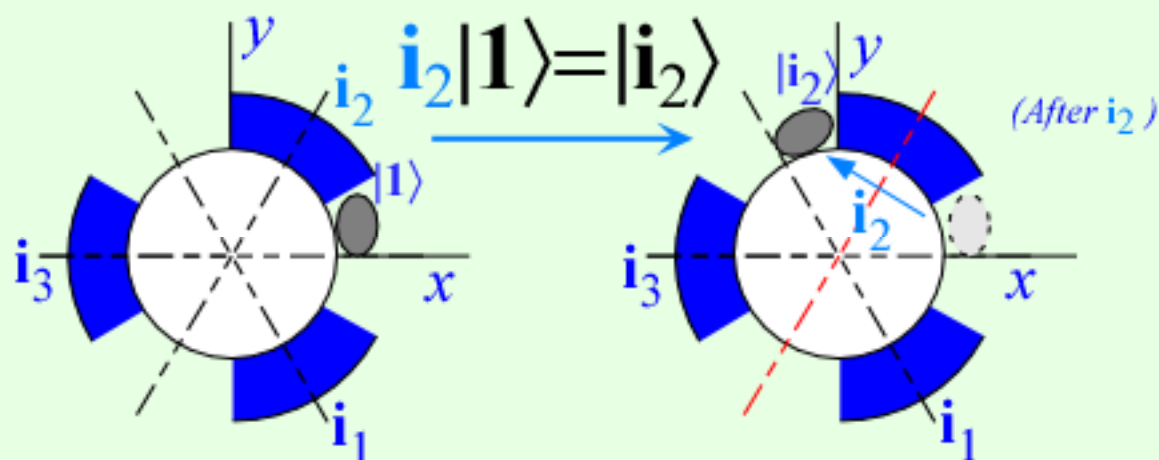
D_3 -defined local-wave bases



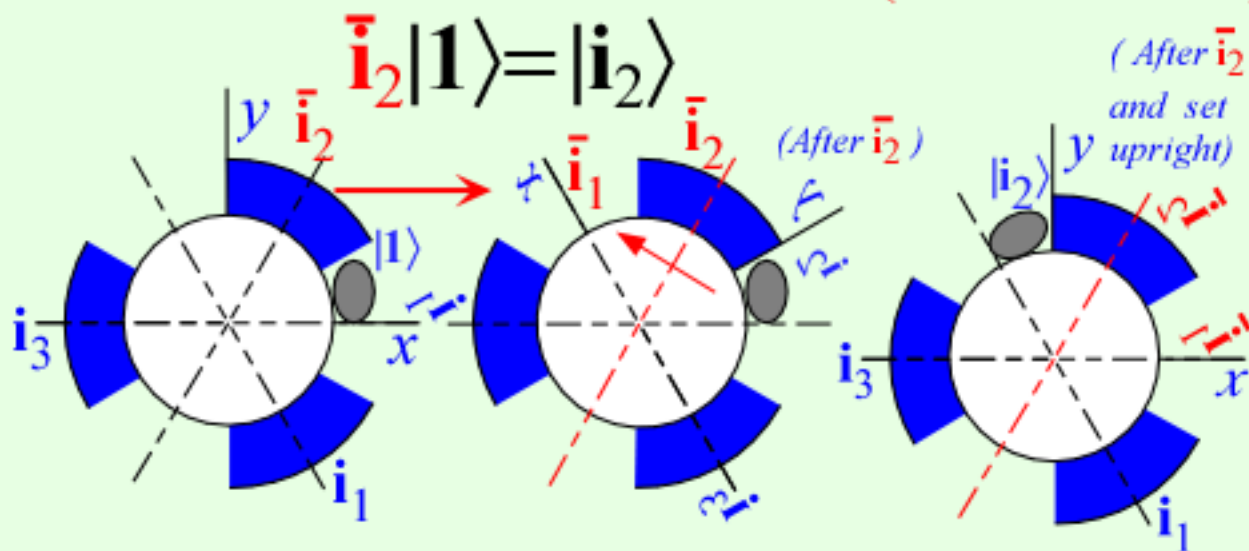
D_3

1	r^2	r	i_1	i_2	i_3
r	1	r^2	i_3	i_1	i_2
r^2	r	1	i_2	i_3	i_1
i_1	i_3	i_2	1	r	r^2
i_2	i_1	i_3	r^2	1	r
i_3	i_2	i_1	r	r^2	1

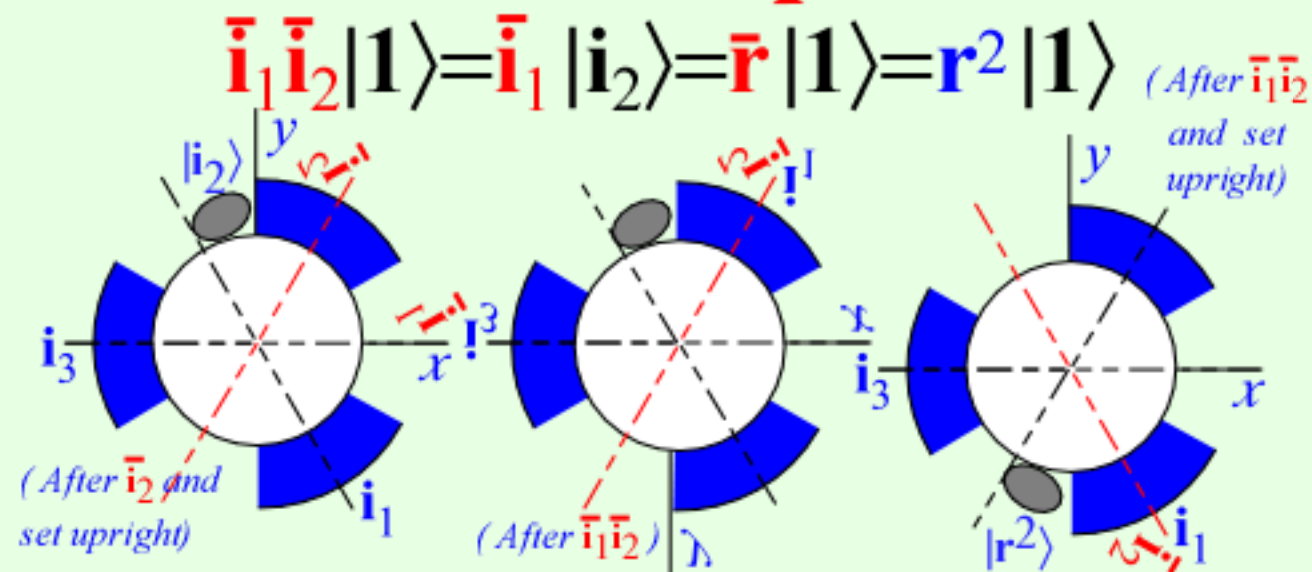
Lab-fixed (Extrinsic-Global) operations and rotation axes



Body-fixed (Intrinsic-Local) operations appear to move their rotation axes (relative to lab)



...but, THEY OBEY THE SAME GROUP TABLE



$i_1 i_2 = r$
implies:
 $\bar{i}_1 \bar{i}_2 = \bar{r}$

D_3 global group product table

1	r^2	r	i_1	i_2	i_3
r	1	r^2	i_3	i_1	i_2
r^2	r	1	i_2	i_3	i_1
i_1	i_3	i_2	1	r	r^2
i_2	i_1	i_3	r^2	1	r
i_3	i_2	i_1	r	r^2	1

D_3 global projector product table

D_3	$P_{xx}^{A_1}$	$P_{yy}^{A_2}$	P_{xx}^E	P_{xy}^E	P_{yx}^E	P_{yy}^E
$P_{xx}^{A_1}$	$P_{xx}^{A_1}$
$P_{yy}^{A_2}$.	$P_{yy}^{A_2}$
P_{xx}^E	.	.	P_{xx}^E	P_{xy}^E	.	.
P_{yx}^E	.	.	P_{yx}^E	P_{yy}^E	.	.
P_{xy}^E	P_{xx}^E	P_{xy}^E
P_y^E	P_y^E	P_y^E

Change Global to Local by switching

...column-g with column-g†

....and row-g with row-g†

(Just switch P_{yx}^E with $P_{yx}^{E\dagger} = P_{xy}^E$.)

Just switch r with $r^\dagger = r^2$. (all others are self-conjugate)

D_3 local group table

1	r	r^2	i_1	i_2	i_3
r^2	1	r	i_2	i_3	i_1
r	r^2	1	i_3	i_1	i_2
i_1	i_2	i_3	1	r	r^2
i_2	i_3	i_2	r^2	1	r
i_3	i_1	i_1	r	r^2	1

D_3 local projector product table

	$P_{xx}^{A_1}$	$P_{yy}^{A_2}$	P_{xx}^E	P_{yx}^E	P_{xy}^E	P_{yy}^E
$P_{xx}^{A_1}$	$P_{xx}^{A_1}$
$P_{yy}^{A_2}$.	$P_{yy}^{A_2}$
P_{xx}^E	.	.	P_{xx}^E	0	P_{xy}^E	0
P_{xy}^E	.	.	0	P_{xx}^E	0	P_{xy}^E
P_{yx}^E	.	.	P_{yx}^E	0	P_{yy}^E	0
P_{yy}^E	.	.	0	P_{yx}^E	0	P_{yy}^E

$$\bar{P}_{ab}^{(m)} \bar{P}_{cd}^{(n)} = \delta^{mn} \delta_{bc} \bar{P}_{ad}^{(m)}$$

Matrix "Placeholders" $\mathbf{P}_{ab}^{(m)}$ for GLOBAL \mathbf{g} operators in D_3

$$\mathbf{g} = D_{xx}^{A_1(g)} \mathbf{P}^{A_1} + D_{yy}^{A_2(g)} \mathbf{P}^{A_2} + D_{xx}^E \mathbf{P}_{xx}^E + D_{xy}^E \mathbf{P}_{xy}^E + D_{yx}^E \mathbf{P}_{yx}^E + D_{yy}^E \mathbf{P}_{yy}^E$$

$\bar{\mathbf{P}}_{ab}^{(m)}$...for LOCAL $\bar{\mathbf{g}}$ operators in \bar{D}_3

$$\bar{\mathbf{g}} = D_{xx}^{A_1(g)} \bar{\mathbf{P}}^{A_1} + D_{yy}^{A_2(g)} \bar{\mathbf{P}}^{A_2} + D_{xx}^E \bar{\mathbf{P}}_{xx}^E + D_{xy}^E \bar{\mathbf{P}}_{xy}^E + D_{yx}^E \bar{\mathbf{P}}_{yx}^E + D_{yy}^E \bar{\mathbf{P}}_{yy}^E$$

Global (LAB) symmetry

$D_3 > C_2 i_3$ projector states

Local (BOD) symmetry

$$\mathbf{i}_3 |_{eb}^{(m)} \rangle = \mathbf{i}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = (-1)^e |^{(m)} \rangle$$

$$|_{eb}^{(m)} \rangle = \mathbf{P}_{eb}^{(m)} |1\rangle$$

$$\bar{\mathbf{i}}_3 |_{eb}^{(m)} \rangle = \bar{\mathbf{i}}_3 \mathbf{P}_{eb}^{(m)} |1\rangle = \mathbf{P}_{eb}^{(m)} \bar{\mathbf{i}}_3 |1\rangle = \mathbf{P}_{eb}^{(m)} \mathbf{i}_3^\dagger |1\rangle = (-1)^b |^{(m)} \rangle$$

